NuSPADE: An Integrated Approach to Exception Freedom Proof

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Context

- Investigate the role of proof planning within the SPARK Approach to high integrity software
- Bill Ellis (Research Associate)
- Funded by the EPSRC Critical Systems Programme (GR/R24081) in collaboration with Praxis

www.macs.hw.ac.uk/nuspade

Overview

- Focus on the problems that arise when proving exception freedom verification conditions (VCs)
- Present an integrated approach to these problems
- Results and future directions

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An Example

Exception Freedom VC

```
H1: for_all (i___1: integer, ((i___1 >= ar_t__first) and
  (i___1 <= ar_t__last)) -> ((element(a, [i___1]) >=
        integer__first) and (element(a, [i___1]) <=
        integer__last))) .
H2: loop_1__i >= ar_t__first .
H3: loop_1__i <= ar_t__last .
H4: element(a, [loop_1__i]) >= 0 .
H5: element(a, [loop_1__i]) <= 100 .
H6: r >= integer__first .
H7: r <= integer__last .
    _>
C1: r + element(a, [loop_1__i]) >= integer__first .
C2: r + element(a, [loop_1__i]) <= integer__last .
C3: loop_1__i >= ar_t__first .
C4: loop_1__i <= ar_t__last .</pre>
```

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Proof Planning

- Use of high-level proof outlines, known as proof plans, to guide proof search
- proof plan = methods + critics + tactics
- Proof planning supports:
 - a flexible style of proof search, *e.g.* use of meta-variables to delay choice during proof search
 - automatic proof patching via proof-failure analysis
 - diversity of proof, *i.e.* tactics can be ported to different proof checkers

Proof Methods

Exception Freedom

elementary

simplify

transitivity

decomposition

fertilize

Loop Invariant

annotate

wave

induction

generalize

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Program Analysis

- Focus on the generation of program properties that support exception freedom proof
- Program analysis methods:
 - subtype
 - non-looping code
 - looping code
 - loop guards

Integration via Proof-Failure Analysis

- A proof method is applicable if all its preconditions are true
- A proof critic is applicable if its associated proof method fails to apply
- Proof-failure analysis is used to guide the selection of program properties that will progress the proof process

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14

Proof-Failure Analysis

Preconditions for elementary critic:

- All preconditions for the elementary method fail.
- There exists a top-level goal of the form *E Rel C*, *e.g*.

 $r + element(a,i) \leq integer_last$

• There exists a variable V_i that occurs within E such that there exists a hypothesis of the form V_i Rel E_i , e.g.

 $r \leq integer_last$

• A counter-example can be found that shows that the bound *E_i* is insufficient to prove exception freedom, *e.g.*

 $32668 \le r \le 32767$

Patch: generate schematic properties, *e.g.* $(r \ge X) \land (r \le Y)$

A Program Analysis Technique

• Recurrence relations are recursive definitions of mathematical functions or sequences, *e.g.*

$$\begin{cases} g(0) = 0 \\ g(n) = g(n-1) + (2*n) - 1 \end{cases}$$

- Solving a recurrence relation corresponds to finding a "closed form" of the function, *e.g.* $g(n) = n^2$
- Recurrence relations can be used to express the value of variables within loops, where the solutions provide loop invariants
- There are many off-the-shelf recurrence relation solvers, *e.g.* PURRS (University of Parma)

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Recurrence Relation for Variable IRecurrence RelationSolution
$$\begin{cases} I_0 = 0 \\ I_n = I_{n-1} + 1 \end{cases}$$
 $I_n = \frac{I_0 + n}{I_0 \Rightarrow 0}$ $I_n = 0 + n$ $0 + Y \Rightarrow Y$ $I_n = n$

Recurrence Relation for Variable R

Recurrence Relation

Extreme Recurrence Relation

 $\begin{cases} R_0 = 0 \\ R_n = R_{n-1} \\ R_n = R_{n-1} + \underbrace{ele(A, I)}_{\text{problem}} \\ \text{term} \end{cases}$

 $\begin{cases} R_0 = 0 \\ R_n = R_{n-1} \\ R_n = R_{n-1} + 0 \\ R_n = R_{n-1} + 100 \end{cases}$

Note problem term is eliminated by generalizing the recurrence relation, *i.e.* by considering the bounds of ele(A, I).

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20

Revised Filter Code procedure Filter(A: in A_T; R: out Integer) is



Planning Proof		
Given: $r \le i * 100 \land ele(a, i) \le 100$		
Proof: $r + ele(a, i) \leq integer last$		
	transitivity	
$r + ele(a, i) \le X_0 \land X_0 \le integer \ last$		
	decomposition	
$r \leq X_1 \wedge ele(a, i) \leq X_2 \wedge X_1 + X_2 \leq integer Last$	fertilize	
$((i*100)+100) \leq integer_last$		
	simplify	
$((i*100) + 100) \le 32767$		
	elementary	
Note: fertilize produces $\{i * 100/X_1, 100/X_2\}$,



24

Results

- Our evaluation was based upon examples drawn from the literature and industrial data provided by Praxis, *e.g.* SHOLIS
- SPADE Simplifier is very effective on exception freedom VCs, *i.e.* typical hit-rate of 90%
- NuSPADE targeted the VCs which the SPADE Simplifier failed to prove *i.e.* typically loop-based code
- While critical software is engineered to minimize the number and complexity of loops, we found that 80% of the loops we encountered were provable using our techniques

Phase	Coal	Plan			Critic				PropGen		
	Gual	a1	a2	b1	b2	b3	b 4	c1	c2	c3	
P1	P1_1	0		•				•			
	P1_2	0		•				•			
	P1_3		0		•				•		
	P1_4		0				•			•	
	P1_5		0				٠			•	
P2	P2_1	•									
	P2_2	•									
	P2_3		•								
	P2_4		•								

Limitations & Future Work

- Constraint solving fails when reasoning with "big numbers", *i.e.* integers out with $-(2^{25}) \dots 2^{25} 1$
- Precondition strengthening would improve our hit-rate, constraint solving may have a role to play
- We could make greater use of constraint solving for debugging
- Integrating decision procedures within NuSPADE would also improve our hit-rate
- A follow-on "knowledge transfer" project, funded by the EPSRC RAIS Scheme starts early 2005
- "Critical Software Components in SPARK", in collaboration with Kung-Kiu Lau (University of Manchester) and Praxis

Conclusion

- NuSPADE = Proof Planning + Program Analysis
- Proof planning guides proof search
- Proof-failure analysis coupled with program analysis selectively strengthens program specifications
- NuSPADE increases automation for exception freedom proof

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Results Table Key loop invariant a1 Plan exception freedom a2 fertilize **b**1 b2 elementary Critic b3 transitivity **b**4 decomposition entry c1 PropGen for-loop range c2 c3 range constraint Note that \bullet denotes the successful application of a proof plan while \circ

denotes partial success