Rigorous Methods for Software Engineering (F21RS-F20RS) Promela (Part 2)

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Overview

- Control flow constructs.
- Channel based process communication.

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Assertions.

Control Flow

- In the "Promela I" lecture three ways for achieving control flow were introduced:
 - Statement sequencing;
 - Atomic sequencing;
 - Concurrent process execution.
- **Promela** supports three additional control flow constructs:

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- Case selection
- Repetition
- Unconditional jumps

Case Selection

What follows is an example of case selection involving two statement sequences:

Note that each statement sequence is prefixed by a ::. The executability of the first statement (guard) in each sequence determines sequence is executed.

Guards need not be mutually exclusive:

Note: if x and y are equal then the selection of which statement sequence is executed is decided at random, giving rise to non-deterministic choice.

Repetition

What follows is an example of repetition involving two statement sequences:

```
do
:: (x >= y) -> x = x - y; q = q + 1;
:: (y > x) -> break;
od
```

Note that the first statement sequence denotes the body of the loop while the second denotes the termination condition.

Termination, however, is not always a desirable property of a system, in particular, when dealing with reactive systems:

do

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Unconditional Jumps

- Promela supports the notion of an unconditional jump via the goto statement.
- Consider the following refinement of the division program given above:

```
do
:: (x >= y) -> x = x - y; q = q + 1;
:: (y > x) -> goto done;
od;
```

done:

skip

Note that done denotes a label. A label can only appear before a statement. Note also that a goto, like a skip, is always executable.

Timeouts

- Reactive systems typically require a means of aborting/rebooting when a system deadlocks. Promela provides a primitive statement called timeout which enables such a feature to be modelled.
- To illustrate, consider the following process definition:

```
proctype watchdog ()
{
    do
    :: timeout -> guard!reset
    od
}
```

The timeout condition becomes true when no other statements within the overall system being modelled are executable.

Exceptions

- Another useful exception handling feature is supported by the unless statement which takes the following general form: { statements-1 } unless { statements-2 } Execution begins with statements-1. Before execution of each statement the executability of the first statement within statements-2 is checked. If the first statement is executable then control is passed to statements-2. If however the execution of statements-1 terminates successfully then statements-2 is ignored.
- Consider an alternative watchdog process:

```
proctype watchdog ()
{ do
    process_data() unless guard?reset; process_reset()
    od
}
```

Message Channels

- So far global variables have provided the only means of achieving communication between distinct processes.
- However, Promela supports message channels which provide a more natural and sophisticated means of modelling inter-process communication (data transfer).
- A channel can be defined to be either local or global. An example of a channel declaration is: chan in_data = [8] of { byte } which declares a channel that can store up to 8 messages of type byte.
- Multiple field messages are also possible: chan out_data = [8] of { byte, bool, chan }

Sending Messages

- Sending messages is achieved by the ! operator, *e.g.* in_data ! 4; This has the effect of appending the value 4 onto the end of the in_data channel.
- If multiple data values are to be transferred via each message then commas are used to separate the values, e.g. out_data ! x + 1, true, in_data; where x is of type byte.
- Note that the executability of a send statement is dependent upon the associated channel being non-full, *e.g.* the following statement will be blocked:

```
in_data ! 4;
```

unless in_data contains at least one empty location.

Receiving Messages

- Receiving messages is achieved by the ? operator, e.g. in_data ? msg; This has the effect of retrieving the first message (FIFO) within the in_data channel and assigning it to the variable msg.
- If multiple data values are to be transferred via each message then commas are used to separate the values, e.g. out_data ? value1, value2, value3;
- Note that the executability of a receive statement is dependent upon the associated channel being non-empty, *e.g.* the following statement will be blocked: in_data ? value; unless in_data contains at least one message.

Some Observations & Notations

- If more data values are sent per message than can be stored by a channel then the extra data values are lost, *e.g.* in_data ! msg1, msg2; here the msg2 will be lost.
- If fewer data values are sent per message than are expected then the missing data values are undefined, *e.g.*

```
out_data ! 4, true;
out_data ? x, y, z;
```

here x and y will be assigned the values 4 and true respectively while the value of z will be undefined.

Alternative (& equivalent) notations:

out_data!exp1,exp2,exp3; out_data!exp1(exp2,exp3); out_data?var1,var2,var3; out_data?var1(var2,var3);

Additional Channel Operations

Determining the number of messages in a channel is achieved by the len operator, *e.g.* len(in_data)

If the channel is empty then the statement will block.

- The empty, full operators determine whether or not messages can be received or sent respectively, *e.g.* empty(in_data); full(in_data)
- Non-destructive retrieve: out_data ? [x, y, z]
 Returns 1 if out_data?x,y,z is executable otherwise 0.
 Purely evaluation, *i.e.* no message retrieved.

run and init

- The operator run provides an alternative way of instantiating a process type.
- The the use of run is typically restricted to init a special process that has no parameters and is the first process to be executed.
- init is analogous to the main function within a C program.
- An init process takes the form:

init { /* local declarations and statements */ }
The simplest and may be one of the least useful of Promela
programs takes the form:

init { skip }

Note: skip denotes the null statement.

proctype hello(){ printf("Hello\n") }

proctype world(){ printf("World\n") }

init { atomic{ run hello(); run world () } }

Note that the use of atomic ensures that all enclosed processes are instantiated before any of the process begin to execute.

Processes with Parameters

 Note also that init and run allow us to instantiate process types with parameters.

```
Consider the following:
    proctype A(byte x)
    Ł
         x = x+1;
         printf("The value of x is %d\n", x)
    }
    init { atomic{ run A(9);
                     run A(99):
                     run A(199) }}
What will be the effect of running this program?
```

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The effect is ...

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Channels as Parameters

```
Consider the following:
  proctype A(chan q1)
  \{ chan q2;
       q1?q2; q2!99
  }
  proctype B(chan qforb)
  Ł
       int x;
       qforb?x; x++;
       printf("x == %d n", x)
  }
  init {chan qname = [1] of { chan };
         chan qforb = [1] of { int };
        run A(qname); run B(qforb);
        qname!qforb
       }
```

What will be the effect of running this program?

The effect is ...



Observations on MSCs

- Provides a graphical presentation of inter-process communication over time.
- Each process is associated with a vertical time line within a MSC, i.e. moving down the MSC corresponds to the passing of time.
- The temporal ordering of events is represented by the relative ordering of arrows between process execution lines.
- The start of an arrow denotes the relative point in time when a process sends a message to a channel while the arrow head denotes the relative point in time when the message is removed from the channel by a process.
- The vertical distance between the start of an arrow and the arrow head represents the relative time that the associated message was stored in the channel.
- Clicking on a step within the MSC will highlight the corresponding position within the code, data and channel panels.

Rendezvous Communication

- Our discussion of message channels so far has implicitly focussed upon asynchronous communication between processes, e.g. chan name = [N] of { byte } where N is a positive constant that defines the number of locations allocated to the channel.
- However, synchronous communication between processes can be achieved by setting N to be 0, e.g. chan name = [0] of { byte } This is known as a rendezvous, a channel where a message can be passed but not stored, e.g. name!2 is blocked until a corresponding name?msg is executable.
- Note: rendezvous communication is binary.

A Rendezvous Example

```
Consider the following:
#define msgtype 33
chan name = [0] of { byte, byte }
active proctype A()
{ name!msgtype(124); name!msgtype(121) }
active proctype B()
{ byte state;
name?msgtype(state)
}
```

Channel name is a global rendezvous. Both A and B will synchronous on their first statements. The effect will be to transfer the value 124 from A to the local variable state within B. Further execution is blocked because the second send within A has no matching receive within B.

Dijkstra's Semaphores

```
#define p 0
#define v 1
chan sema = [0] of { bit };
active proctype semaphore()
ſ
        do
        :: sema!p -> sema?v
        od
}
active [3] proctype user()
ſ
        sema?p;
        /* critical section */
        sema!v;
        /* non-critical section */
        skip
}
```

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MSC for Dijkstra's Semaphore Example



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Assertions

While the Spin simulator does not represent a formal analysis tool, it does provide a limited form support for verification in terms of assertion checking, *i.e.* the checking of local and global system assertions during particular simulation runs.

An assertion is a statement which can be either true or false.

- Interleaving assertion evaluation with code execution provides a simple yet very useful mechanism for checking **desirable** as well as **erroneous** behaviour with respect to our models.
- The syntax for an assertion within Promela takes the form: assert(<logical-statement>) for example: assert(!(doors == open && lift == moving))
- Within Promela we can express local assertions as well global system assertions.

Will the assertion checking succeed or fail?

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Local Assertion - Violation



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Global Assertions

- A global assertion or system invariant is a property that is true in the initial system state and remains true in all possible execution paths.
- To express a system invariant within Promela one must define a monitor process that contains the desired system invariant.
- Running an instance of the monitor process along with the rest of the system model means that the global assertion can be checked at any point during the execution.
- Note that in the case of a simulation the checking is not exhaustive, this is achieved within verification mode.

Semaphores Revisited

```
#define p 0
#define v 1
byte count = 0;
chan sema = [0] of { bit };
active proctype semaphore(){
        do
        :: sema!p -> sema?v
        od}
active [3] proctype user(){
        /* non-critical section */
        sema?p;
        count = count + 1;
        /* critical section */
        count = count - 1;
        sema!v:
        /* non-critical section */
        skip}
active proctype monitor()
ſ
      do :: assert(count == 0 || count == 1) od}
                                    (ロト・日本)
```

Semaphores Revisited



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Summary

Learning outcomes:

- To be able to understand and construct simple programs exploiting **Promela**'s control flow constructs, including timeout and unless.
- To be able to understand and construct asynchronous and synchronous behaviour between processes using message channels;
- Understand how to construct and use both local and global system assertions with in the context of the **Spin** simulator.

Recommended reading:

Spin homepage:

http://spinroot.com

Books on Spin and model checking in general:

http://spinroot.com/spin/books.html

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