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- The basic building blocks of Promela programs are:
 - processes
 - channels
 - variables
- Processes model the behaviour of components of a system and are by definition **global** objects.
- Channels and variables define the environment in which processes exist and can be either **local** of **global**.





Variable Declarations

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- Like all well-structured programming languages, Promela requires that variables must be declared before they can be used.
- Variable declarations follow the style of the C programming language, *i.e.* a basic data type followed by one or more identifiers and optional initializer:

```
byte count, total = 0;
```

An initializer must be an expression of the appropriate basic type.

• By default all variables of the basic types are initialized to 0. Note that as in C, 0 (zero) is interpreted as false while any non-zero value is interpreted as true.



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Identifiers, Constants & Expressions

- Identifiers: An identifier is a single letter, a period symbol, or underscore followed by zero or more letters, digits, periods or underscores.
- Constants: A constant is a sequence of digits that represents a decimal integer. Symbolic constants can be defined by means of mtype or via a C-style macro definition, *e.g.*

#define MAX 999

• Expressions: An expression is built up from variables, identifiers and constants using the following operators:

+, -, *, /, %, --, ++, arith
>, >=, <, <=, ==, !=, relational
&&, ||, !, logicals
&, |, ~, ^, >>, <<, bits
!, ?, channels
(), [], group/index</pre>







```
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```







Deterministic & Non-Deterministic Behaviour

- **Deterministic behaviour:** a process is deterministic if for a given start state it behaves in exactly the same way if supplied with the same stimuli from its environment.
- Non-deterministic behaviour: a process is non-deterministic if it need not always behave in exactly the same way each time it executes from a given start state with the same stimuli from its environment.

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More Non-Deterministic Behaviour

• Consider the following two process system:

```
byte state = 1;
proctype A() { (state == 1) -> state = state + 1 }
proctype B() { (state == 1) -> state = state - 1 }
init { run A(); run B() }
```

note that S1 -> S2 and S1; S2 are equivalent.

- Note that if process A (B) terminates before process B (A) begins execution then B (A) will be blocked forever on the initial condition, *i.e.* (state == 1).
- Note that if both A and B pass the condition simultaneously then both processes can terminate but the final value of state is unpredictable, *i.e.* 0, 1 or 2.

Dekker's Solution

```
#define true
                 1
#define false
                0
#define Aturn
                false
#define Bturn
                true
bool Aruns, Bruns, t;
proctype A()
{Aruns = true;
 t = Bturn;
 (Bruns == false || t == Aturn); /* S1 */
 /* critical section */
 Aruns = false
}
proctype B()
{Bruns = true;
 t = Aturn;
 (Aruns == false || t == Bturn); /* S2 */
 /* critical section */
 Bruns = false
}
init { run A(); run B() }
```

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Observations on Dekker's Solution

- Statements S1 and S2 ensure synchronization between A and B on critical section access.
- Consider the case of S1 which occurs within the definition of process A: (Bruns == false || t == Aturn)
 - If the left disjunct holds then process B is not executing so it is safe for A to enter the critical section.
 - Else if the right disjunct holds t must be false so it is safe for A to enter the critical section because both disjuncts of S2 must be false, *i.e.* process B is blocked.
 - Else process A is blocked. However, the right disjunct of S2 must hold so it is safe for B to enter the critical section.
 - On exiting the critical section process A sets Aruns to false which has the effect of unblocking process B.





