

Compressible fluids interacting with a linear-elastic shell

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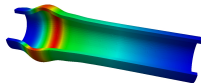
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Fluid structure interaction

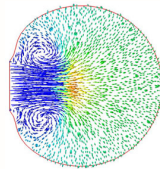
In this talk we will consider a compressible fluid which is floating in a flexible body.

- The fluid forces are interacting with a membrane that is assumed to be a part of the boundary.
- The geometry changes in time.

Examples:



Blood vessels:



Gas balloon:



Airplane wing:

The Setting

- $\Omega \in \mathbb{R}^3$ is the **initial geometry** and the **reference geometry**
- $\partial\Omega = \Gamma \cup M$, Γ is the fixed part of the boundary.
- M is the flexible part of the boundary—hence the **domain of definition** for the time-changing coordinates.
- The displacement of the boundary is prescribed via a two dimensional surface representing a **Kirchhoff-Love** plate.
- It is a model reduction assuming small strains and plane stresses parallel to the middle surface.
- $\eta : I \times M \rightarrow \mathbb{R}^3$ defines the change of the domain.
- $\Omega_{\eta(t)}$ defines the changed domain: $\partial\Omega_{\eta(t)} = \Gamma \cup \eta(t, M)$.
- Inside the domain we assume a **compressible** fluid. Its motion is characterized by its **velocity**: $\mathbf{u} : I \times \Omega_{\eta(t)} \rightarrow \mathbb{R}^3$ and **density**: $\varrho : I \times \Omega_{\eta(t)} \rightarrow \mathbb{R}^+$.

The PDE in the interior

The fluid is compressible and viscous

$$\begin{aligned} \partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) &= 0, & \text{in } I \times \Omega_\eta, \\ \partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) &= \mu \Delta \mathbf{u} - a \nabla \varrho^\gamma + \varrho \mathbf{f} & \text{in } I \times \Omega_\eta, \\ \mathbf{u}(t, x + \boldsymbol{\eta}(x)) &= \partial_t \boldsymbol{\eta}(t, x) & \text{in } I \times M. \end{aligned}$$

The shell is driven by the **Koiter-energy**

$$K(\boldsymbol{\eta}) = \frac{1}{2} \varepsilon_0 \int_M \mathbf{C} : \boldsymbol{\sigma}(\boldsymbol{\eta}) \otimes \boldsymbol{\sigma}(\boldsymbol{\eta}) \, d\mathcal{H}^2 + \frac{1}{6} \varepsilon_0^3 \int_M \mathbf{C} : \boldsymbol{\theta}(\boldsymbol{\eta}) \otimes \boldsymbol{\theta}(\boldsymbol{\eta}) \, d\mathcal{H}^2.$$

If $\boldsymbol{\eta}(t, x) \equiv \boldsymbol{\eta}(t, x) \nu(x)$ the corresponding equation for the shell is

$$\begin{aligned} \partial_t^2 \boldsymbol{\eta} + \Delta^2 \boldsymbol{\eta} &= \mathbf{g} + \nu \cdot \left(-\boldsymbol{\tau} \nu_\eta \right) \circ \boldsymbol{\Psi}_{\boldsymbol{\eta}(t)} \big| \det D\boldsymbol{\Psi}_{\boldsymbol{\eta}(t)} \big| \quad \text{in } I \times M, \\ \boldsymbol{\tau} &= \mathbf{S}(\nabla \mathbf{u}) - a \varrho^\gamma \mathcal{I}. \end{aligned}$$

Weak formulation (1)

Let $\eta : I \times M \rightarrow \mathbb{R}$ and $\partial\Omega_{\eta(t)} = \Gamma \cup \{x + \eta(t, x)\nu(x) : x \in M\}$.
consider a coordinate map $\Psi_\eta : \Omega \rightarrow \Omega_\eta$.

Reynolds transport theorem:

$$\frac{d}{dt} \int_{\Omega_{\eta(t)}} g \, dx = \int_{\Omega_{\eta(t)}} \partial_t g \, dx + \int_{\partial\Omega_{\eta(t)}} \partial_t \eta \circ \Psi_\eta^{-1} \nu \cdot \nu_\eta g \, d\mathcal{H}^2,$$

The weak continuity equation: integration by parts implies for $\psi \in C^\infty(I \times \bar{\Omega})$

$$\int_I \frac{d}{dt} \int_{\Omega_\eta} \rho \psi \, dx \, dt - \int_I \int_{\Omega_\eta} \left(\rho \partial_t \psi + \rho \mathbf{u} \cdot \nabla \psi \right) \, dx \, dt = 0,$$

if $\mathbf{u} \circ \Psi_\eta = \partial_t \eta \nu$ on $\partial\Omega_{\eta(t)}$.

Weak formulation (2)

The weak momentum equation:

For $(b, \varphi) \in C_0^\infty(M) \times C^\infty(\bar{I} \times \mathbb{R}^3)$ with $\text{tr}_\eta \varphi = b\nu$

$$\begin{aligned} & \int_I \left(\frac{d}{dt} \int_{\Omega_\eta} \varrho \mathbf{u} \cdot \varphi \, dx - \int_{\Omega_\eta} \varrho \mathbf{u} \cdot \partial_t \varphi + \varrho \mathbf{u} \otimes \mathbf{u} : \nabla \varphi \, dx \right) dt \\ & + \int_I \int_{\Omega_\eta} \left(\mu \nabla \mathbf{u} : \nabla \varphi + (\lambda + \mu) \text{div} \mathbf{u} \text{div} \varphi - \varrho^\gamma \text{div} \varphi \right) dx \, dt \\ & + \int_I \left(\frac{d}{dt} \int_M \partial_t \eta b \, d\mathcal{H}^2 - \int_M \partial_t \eta \partial_t b \, d\mathcal{H}^2 + \int_M K'(\eta) b \, d\mathcal{H}^2 \right) dt \\ & = \int_I \int_{\Omega_\eta} \varrho \mathbf{f} \cdot \varphi \, dx \, dt + \int_I \int_M \mathbf{g} b \, d\mathcal{H}^2 \, dt. \end{aligned}$$

Renormalized continuity equation

The renormalized continuity equation:

For $\psi \in C^\infty(I \times \bar{\Omega})$ and $\theta \in C^1(\mathbb{R}^+)$ positive

$$0 = \int_I \frac{d}{dt} \int_{\Omega_\eta} \theta(\varrho) \psi \, dx \, dt - \int_I \int_{\Omega_\eta} \left(\theta(\varrho) \partial_t \psi + \theta(\varrho) \mathbf{u} \cdot \nabla \psi \right) \, dx \, dt \\ + \int_I \int_{\Omega_\eta} (\varrho \theta'(\varrho) - \theta(\varrho)) \operatorname{div} \mathbf{u} \psi \, dx \, dt.$$

- Major ingredient for compressible Navier–Stokes equations.
- Introduced by Di Perna-Lions '89.

Main theorem

Theorem (Breit, Schwarzacher, ARMA '18)

Let $\gamma > \frac{12}{7}$ ($\gamma > 1$ in two dimensions). There is a weak solution $(\eta, \mathbf{u}, \varrho)$. The interval of existence is restricted only in case Ω_η approaches a self intersection. The solution satisfies the energy estimate

$$\begin{aligned} & \sup_{t \in I} \int_{\Omega_\eta} \varrho |\mathbf{u}|^2 dx + \sup_{t \in I} \int_{\Omega_\eta} \varrho^\gamma dx + \int_I \int_{\Omega_\eta} |\nabla \mathbf{u}|^2 dx dt \\ & + \sup_{t \in I} \int_M |\partial_t \eta|^2 d\mathcal{H}^2 + \sup_{t \in I} \int_M |\nabla^2 \eta|^2 \leq c(\mathbf{q}_0, \varrho_0, \mathbf{f}, g, \eta_0, \eta_1). \end{aligned}$$

The incompressible analogue: Lengeler & Růžička, (ARMA, '14).

Remarks

- The function space for a weak solutions is determined by the left-hand side of energy estimate taking into account the variable domain.
- The bound $\gamma > \frac{12}{7}$ is less restrictive than the bound $\gamma \geq \frac{9}{5}$ appearing in the pioneering work of Lions, but more restrictive than the bound $\gamma > \frac{3}{2}$ arising in the theory by Feireisl et al.
- A major mathematical difficulty is the parabolic-hyperbolic nature of the system \Rightarrow regularity incompatibilities between the fluid- and the solid-phase.
- The boundary only belongs to $W^{2,2}$ and is not Lipschitz!

Strategy

- Understand sequential compactness of weak solutions.
- Construct them by means of a multi-layer approximation scheme inspired by Feireisl et al.
- Apply a fixed point argument on the basic level taking into account a coupling of the system
($\eta \mapsto (\mathbf{u}, \varrho)$ vs. $(\zeta, \mathbf{v}) \mapsto (\eta, \mathbf{u})$).
- For the fixed point to work linearise equation
(replace \mathbf{u} by \mathbf{v} in the convective terms).

Sequential compactness (1)

Assume there a sequence of solutions $(\eta_n, \mathbf{u}_n, \varrho_n)$ which enjoys suitable regularity properties and satisfies the energy estimate uniformly in n .

How can we pass to the limit in the equation?

- passage to the limit in the convective terms $\varrho_n \mathbf{u}_n$ and $\varrho_n \mathbf{u}_n \otimes \mathbf{u}_n$ by local arguments and global integrability
No problems with the moving boundary!
Much easier than incompressible case!
- Main problem (typical for compressible Navier–Stokes):
Passing to the limit in the nonlinear pressure $p(\varrho_n) = a\varrho_n^\gamma$.

Higher integrability of the pressure (1)

- A priori $p(\varrho_n)$ only bounded in $L^\infty(L^1)$
 \Rightarrow Concentrations possible!
- Improve integrability by “computing the pressure”: Use globally Bogovskiĭ-operator $\approx \operatorname{div}^{-1}$ or locally $\Delta^{-1}\operatorname{div}$.
- Bogovskiĭ-operator requires Lipschitz boundary \Rightarrow standard approach only gives higher integrability locally.
- How to exclude concentrations at the boundary?

Higher integrability of the pressure (2)

Lemma

There is a measurable set $A_\kappa \in I \times \Omega_{\eta_n}$ such that for all $n \geq n_0$

$$\int_{I \times \mathbb{R}^3 \setminus A_\kappa} a \varrho_n^\gamma \chi_{\Omega_{\eta_n}} \, dx \, dt \leq \kappa.$$

Construct test-function φ_n such that:

- zero boundary conditions on $\partial\Omega_{\eta_n}$;
- $\operatorname{div} \varphi_n \geq K_\kappa$ close to the boundary;
- Critical term $\int_I \int_{\Omega_{\eta_n}} \varrho_n \mathbf{u}_n \partial_t \varphi_n \, dx \, dt$ with $\partial_t \varphi_n \sim \partial_t \eta_n = \mathbf{u}_n \circ \Psi_n|_{\partial\Omega_{\eta_n}} \in L^2(L^{4^-})$;
- Since $\varrho_n \mathbf{u}_n \in L^2(L^{\frac{6\gamma}{\gamma+6}})$ we need $\gamma > \frac{12}{7}$.

Strong convergence of the pressure (1)

Effective viscous flux identity (Lions '93) with cut-off T_k

$$\int_{I \times \Omega_{\eta_n}} (a \varrho_n^\gamma - (\lambda + 2\mu) \operatorname{div} \mathbf{u}_n) T_k(\varrho_n) \, dx \, dt \\ \longrightarrow \int_{I \times \Omega_\eta} (\overline{a \varrho^\gamma} - (\lambda + 2\mu) \operatorname{div} \mathbf{u}) \overline{T_k(\varrho)} \, dx \, dt.$$

- Locally by standard method (commutator, div-curl-lemma);
- Globally by uniform integrability;
- Needs renormalized continuity equation to conclude (note that $\varrho \mapsto \varrho^\gamma$ is monotone);
- DiPerna-Lions theory does not apply for small γ .

Strong convergence of the pressure (2)

Oscillation defect measures (Feireisl '01)

$$\limsup_{n \rightarrow \infty} \int_{I \times \mathbb{R}^3} |T_k(\varrho_n) - T_k(\varrho)|^{\gamma+1} dx dt \leq C.$$

- By standard method (using effective viscous flux identity);
- Implies renormalized continuity equation in the limit

$$\begin{aligned} 0 &= \int_I \frac{d}{dt} \int_{\Omega_\eta} \theta(\varrho) \psi dx dt - \int_I \int_{\Omega_\eta} \left(\theta(\varrho) \partial_t \psi + \theta(\varrho) \mathbf{u} \cdot \nabla \psi \right) dx dt \\ &\quad + \int_I \int_{\Omega_\eta} (\varrho \theta'(\varrho) - \theta(\varrho)) \operatorname{div} \mathbf{u} \psi dx dt \end{aligned}$$

- Extension to \mathbb{R}^3 requires no-slip boundary conditions (“no slip boundary conditions w.r.t. to the moving shell”).

Four layer approximation scheme

- Artificial pressure (δ -layer): replace $p(\varrho) = a\varrho^\gamma$ by $p_\delta(\varrho) = a\varrho^\gamma + \delta\varrho^\beta$ where β is chosen large enough.
- Artificial viscosity (ε -layer): add $\varepsilon\Delta\varrho$ to the right-hand side of the continuity equation.
- Regularization of the boundary (κ -layer): Replace the underlying domain Ω_η by Ω_{η_κ} where η_κ is a suitable regularization of η . Accordingly, the convective terms and the pressure have to be regularized as well.
- Finite-dimensional approximation (N -layer): the momentum equation has to be solved by means of a Galerkin-approximation.

The first two layers are common in the theory of compressible Navier–Stokes equations, see Feireisl et al. Third layer is needed due to the low regularity of η .

The last layer

- Function space depends on the solution itself \Rightarrow Galerkin approximation not possible.
- Lengeler-Růžička: Apply a fixed point argument in η and \mathbf{u} for a linearised problem (replace $\varrho \mathbf{u} \otimes \mathbf{u}$ by $\varrho \mathbf{u} \otimes \mathbf{v}$ and $\varrho \mathbf{u}$ by $\varrho \mathbf{v}$ for \mathbf{v} given).
- It is crucial for our fixed point argument that the momentum equation is linear in \mathbf{u} .

For (ζ, \mathbf{v}) given we solve the system on the domain Ω_ζ . The domain still varies in time but is independent of the solution. Note here, that ϱ is independent of \mathbf{u} .

Fixed point argument

Show that the map $(\zeta, \mathbf{v}) \mapsto (\eta, \mathbf{u})$ has a fixed point:




- Uniqueness not known \Rightarrow set-valued mapping;
- Needs compactness of \mathbf{u}_n in $L^2(I \times \mathbb{R}^3)$;
- Compactness of ϱ_n easy as $\varepsilon > 0$;
- We can show (as for convective term $\varrho \mathbf{u} \otimes \mathbf{u}$)

$$\int_I \int_{\mathbb{R}^3} \varrho_n |\mathbf{u}_n|^2 \, dx \, dt \longrightarrow \int_I \int_{\mathbb{R}^3} \varrho |\mathbf{u}|^2 \, dx \, dt$$

- What happens in the vacuum? \Rightarrow replace $\partial_t(\varrho \mathbf{u})$ by $\partial_t((\varrho + \kappa) \mathbf{u})$ in the momentum equation!

Open problems

- Local strong solutions for both compressible and incompressible model;
- Global strong solutions for incompressible 2D;
- Navier–Stokes–Fourier equations for compressible, heat conducting fluids (in progress): sequential compactness seems fine, problems with the fixed point (regularity incompatibilities).

-  D. Breit & S. Schwarzacher: *Compressible fluids interacting with a linear-elastic shell*. **Arch. Rational Mech. Anal.** 228, 495–562. (2018)
-  E. Feireisl, A. Novotný & H. Petzeltová: *On the existence of globally defined weak solutions to the Navier–Stokes equations of compressible isentropic fluids*. **J. Math. Fluid. Mech.** 3, 358–392. (2001)
-  D. Lengeler & M. Růžička: *Weak Solutions for an Incompressible Newtonian Fluid Interacting with a Koiter Type Shell*. **Arch. Rational Mech. Anal.** 211, 205–255. (2014)