

Convergence rates for the numerical approximation of the 2D stochastic Navier–Stokes equations

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Stochastic Navier–Stokes equations

Velocity field \mathbf{u} and pressure π on $Q = (0, T) \times \mathbb{T}^2$

$$\begin{cases} d\mathbf{u} = [\mu\Delta\mathbf{v} - \operatorname{div}(\mathbf{u} \otimes \mathbf{u}) - \nabla\pi] dt + \mathbb{G} dW & \text{in } Q, \\ \operatorname{div} \mathbf{u} = 0 & \text{in } Q. \end{cases}$$

- Cylindrical Wiener process W on a separable Hilbert space with basis $(e_k)_{k \geq 0}$ (e.g. $L^2(\mathbb{T}^2)$): $W = \sum_{k \geq 0} \beta_k e_k$;
- Coefficient \mathbb{G} is a Hilbert-Schmidt operator;
- Multiplicative noise $\mathbb{G} = \mathbb{G}(\mathbf{u})$ has to be Lipschitz;
- Defined on filtered probability space $(\Omega, \mathfrak{F}, (\mathfrak{F}_t)_{t \geq 0}, \mathbb{P})$;
- Initial datum \mathbf{u}_0 can be random.

Stochastic perturbations

- It can be understood as turbulence in the fluid motion.
 - Mikulevicius and Rozovskii (2004): Dynamics of fluid particles contain turbulent part $\sigma \circ dW$ (Kraichnan's turbulence model)

$$d\mathbf{u} = \dots + [\sigma \nabla \mathbf{u} - \nabla \tilde{\pi} + \mathbf{g}(\mathbf{u})] \circ dW;$$

- Birner (2013): uses the ansatz ($e_k(x) = e^{2\pi tk \cdot x}$)

$$d\mathbf{u} = \dots + \sum_{k \in \mathbb{Z}^3} c_k^{1/2} e_k dW_k + \mathbf{v} \sum_{k \in \mathbb{Z}^3, |k| \leq m} \int_{-\infty}^{\infty} h_k \bar{N}^k dz dt$$

to derive Kolmogorov–Obukhov Statistical Theory of Turbulence.

- Can be interpreted as a perturbation from the physical model.
- Apart from the force \mathbf{f} , which we are observing, there are further quantities with (usually small) influence on the motion.

Weak formulation

Find \mathbf{u} such that for all $\varphi \in C_{\text{div}}^{\infty}(\mathbb{T}^2)$ and all $t \in [0, T]$

$$\int_{\mathbb{T}^2} \mathbf{u}(t) \cdot \varphi \, dx = \int_{\mathbb{T}^2} \mathbf{u}_0 \cdot \varphi \, dx + \int_0^t \int_{\mathbb{T}^2} \mathbf{u} \otimes \mathbf{u} : \nabla \varphi \, dx \, d\sigma$$

$$- \mu \int_0^t \int_{\mathbb{T}^2} \nabla \mathbf{u} : \nabla \varphi \, dx \, d\sigma + \int_{\mathbb{T}^2} \varphi \cdot \int_0^t \mathbb{G} \, dW \, dx.$$

- Pressure disappears in weak formulation;
- By Itô-isometry if $\mathbb{G} \in L_2(L_x^2; L_x^2)$

$$\mathbb{E} \left\| \int_0^T \mathbb{G} \, dW \right\|_{L_x^2}^2 = \mathbb{E} \int_0^T \|\mathbb{G}\|_{L_2(L_x^2; L_x^2)}^2 \, dt = \sum_{k \geq 0} \mathbb{E} \int_0^T \|\mathbb{G} e_k\|_{L_x^2}^2 \, dt.$$

Concept of solution

A stochastically strong solution

is an (\mathfrak{F}_t) -adapted stochastic process \mathbf{u} with

$$\mathbf{u} \in C([0, T]; L^2_{\text{div}}(\mathbb{T}^2)) \cap L^2(0, T; W^{1,2}_{\text{div}}(\mathbb{T}^2))$$

\mathbb{P} -a.s. which solves the momentum equation in the weak sense.

- Exists on a given stochastic basis $(\Omega, \mathfrak{F}, (\mathfrak{F}_t), \mathbb{P})$;
- W is a given (\mathfrak{F}_t) -cylindrical Wiener process;
- We have $\mathbf{u}(0, \cdot) = \mathbf{u}_0$ \mathbb{P} -a.s. where \mathbf{u}_0 is \mathfrak{F}_0 -measurable with $\mathbf{u}_0 \in L^2(\Omega; L^2_{\text{div}}(\mathbb{T}^2))$;
- First results by Capiński and Capiński-Cutland (1991/1993).

Qualitative properties

Find \mathbf{u} such that for all $\varphi \in C_{\text{div}}^{\infty}(\mathbb{T}^2)$ and all $t \in [0, T]$

$$\mathbb{E} \left[\sup_{0 \leq t \leq T} \int_{\mathbb{T}^2} |\nabla \mathbf{u}|^2 + \int_0^T \int_{\mathbb{T}^2} |\nabla^2 \mathbf{u}|^2 \right]^r \leq c_r \mathbb{E} \left[1 + \|\mathbf{u}_0\|_{W_x^{1,2}}^2 \right]^r.$$

- “Test” by $\Delta \mathbf{u}$ (apply Itô’s formula to $t \mapsto \|\mathbf{u}\|_{W_x^{1,2}}^2$);
- Higher order estimates: $\mathbf{u}_0 \in W_x^{k,2} \Rightarrow \mathbf{u} \in L_t^{\infty}(W_x^{k,2}) \cap L_t^2(W_x^{k+1,2})$;
- Dirichlet-problem: not known if $\mathbb{E}[\|\mathbf{u}(T)\|_{W_x^{1,2}}^2] < \infty$ for ANY finite T (only for a random T which is large).

Finite-element spaces

\mathcal{T}_h is quasi-uniform subdivision of \mathbb{T}^2 into triangles S , $i, j \in \mathbb{N}$

$$V^h(\mathbb{T}^2) := \{\mathbf{v}_h \in W^{1,2}(\mathbb{T}^2) : \mathbf{v}_h|_S \in \mathcal{P}_i(S) \forall S \in \mathcal{T}_h\},$$

$$P^h(\mathbb{T}^2) := \{\pi_h \in L^2(\mathbb{T}^2) : \pi_h|_S \in \mathcal{P}_j(S) \forall S \in \mathcal{T}_h\}.$$

- $V^h(\mathbb{T}^2)$ and $P^h(\mathbb{T}^2)$ linked by inf-sup condition:

$$\sup_{\mathbf{v}_h \in V^h(\mathbb{T}^2)} \frac{\int_{\mathbb{T}^2} \operatorname{div} \mathbf{v}_h \pi_h \, dx}{\|\nabla \mathbf{v}_h\|_{L^2_x}} \geq C \|\pi_h\|_{L^2_x} \quad \forall \pi_h \in P^h(\mathbb{T}^2);$$

- Discretely solenoidal finite element functions by

$$V_{\operatorname{div}}^h(\mathbb{T}^2) := \left\{ \mathbf{v}_h \in V^h(\mathbb{T}^2) : \int_{\mathbb{T}^2} \operatorname{div} \mathbf{v}_h \pi_h \, dx = 0 \forall \pi_h \in P^h(\mathbb{T}^2) \right\}.$$

The algorithm

Find r.v. $\mathbf{u}_{h,m}$ with values in $V_{\text{div}}^h(\mathbb{T}^2)$ s.t. for all $\varphi \in V_{\text{div}}^h(\mathbb{T}^2)$

$$\begin{aligned} \int_{\mathbb{T}^2} \mathbf{u}_{h,m} \cdot \varphi \, dx + \Delta t \int_{\mathbb{T}^2} ((\nabla \mathbf{u}_{h,m}) \mathbf{u}_{h,m-1} + (\text{div} \mathbf{u}_{h,m-1}) \mathbf{u}_{h,m}) \cdot \varphi \, dx \\ + \mu \Delta t \int_{\mathbb{T}^2} \nabla \mathbf{u}_{h,m} : \nabla \varphi \, dx = \int_{\mathbb{T}^2} \mathbf{u}_{h,m-1} \cdot \varphi \, dx \\ + \int_{\mathbb{T}^2} \mathbb{G}(\mathbf{u}_{h,m-1}) \Delta_m W \cdot \varphi \, dx. \end{aligned}$$

- Initial datum $\mathbf{u}_{h,0} \in V_{\text{div}}^h(\mathbb{T}^2)$ given (e.g. $\mathbf{u}_{h,0} = \Pi_h \mathbf{u}_0$);
- Here $\Delta_m W = W(t_m) - W(t_{m-1})$ where $t_m = m \frac{T}{M}$;
- First analysed by Carelli-Prohl (2012).

Error estimate

Breit-Dodgson (2019): for any $\alpha < \frac{1}{2}$

$$\mathbb{E} \left[\mathbf{1}_{\Omega^\varepsilon} \left(\max_{1 \leq m \leq M} \|\mathbf{u}(t_m) - \mathbf{u}_{h,m}\|_{L_x^2}^2 + \sum_{m=1}^M \Delta t \|\nabla \mathbf{u}(t_m) - \nabla \mathbf{u}_{h,m}\|_{L_x^2}^2 \right) \right] \leq c (h^2 + (\Delta t)^{2\alpha}).$$

- Control first error to time-discrete solution \mathbf{u}_m ;
- $\mathbf{1}_{\Omega^\varepsilon}$ controls blow-up of $\max_m \|\nabla \mathbf{u}_m\|_{L_x^2}$ and $\max_m \|\mathbf{u}_{h,m}\|_{L_x^2}$ with bound $\log(\Delta t)^{-\varepsilon}$.
- Convergence in probability with rates (almost) 1/2 and 1.
- Carelli-Prohl (2012): same estimate with $(h^2 + \frac{h^2}{\Delta t} + (\Delta t)^\alpha)$.

Assumptions Breit-Dodgson

Convergence rate in time (almost) 1/2 provided

- $\mathbb{E}[\|\mathbf{u}\|_{C^\alpha([0, T]; L_x^4)}^4] < \infty$: if $\mathbb{E}[\|\mathbf{u}_0\|_{W_x^{1,2}}^8] < \infty$ and $\mathbb{G}(\mathbf{u})$ has linear growth on $W_x^{1,2}$;
- $\mathbb{E}[\|\mathbf{u}\|_{C^\alpha([0, T]; W_x^{1,2})}^2] < \infty$: if $\mathbb{E}[\|\mathbf{u}_0\|_{W_x^{2,2}}^4] + \mathbb{E}[\|\mathbf{u}_0\|_{W_x^{1,2}}^{20}] < \infty$ and $\mathbb{G}(\mathbf{u})$ has linear growth on $W_x^{2,2}$;
- $P^h(\mathbb{T}^2)$ with elements locally from \mathcal{P}_j for $j \geq 1$.

Assumptions Carelli-Prohl

Convergence rate in time (almost) 1/4 provided

- $\mathbb{E} [\|\mathbf{u}\|_{C^\alpha([0, T]; L_x^4)}^4] < \infty$ and $\mathbb{E} [\|\mathbf{u}\|_{C^{\frac{\alpha}{2}}([0, T]; W_x^{1,2})}^4] < \infty$: if $\mathbb{E} [\|\mathbf{u}_0\|_{W_x^{1,2}}^8] < \infty$ and $\mathbb{G}(\mathbf{u})$ has linear growth on $W_x^{1,2}$;
- $P^h(\mathbb{T}^2)$ with elements locally from \mathcal{P}_j for $j \geq 0$.

Carelli-Prohl: the term $\frac{h^2}{\Delta t}$ disappears provided additionally

- Noise is solenoidal, that is $\operatorname{div} \mathbb{G} = 0$;
- Exactly divergence-free elements, that is $V^h(\mathbb{T}^2) \subset W_{\operatorname{div}}^{1,2}(\mathbb{T}^2)$.

The algorithm

Find r.v. \mathbf{u}_m with values in $W_{\text{div}}^{1,2}(\mathbb{T}^2)$ s.t. for all $\varphi \in W_{\text{div}}^{1,2}(\mathbb{T}^2)$

$$\begin{aligned} \int_{\mathbb{T}^2} \mathbf{u}_m \cdot \varphi \, dx + \Delta t \int_{\mathbb{T}^2} (\nabla \mathbf{u}_m) \mathbf{u}_{m-1} \cdot \varphi \, dx \\ + \mu \Delta t \int_{\mathbb{T}^2} \nabla \mathbf{u}_m : \nabla \varphi \, dx = \int_{\mathbb{T}^2} \mathbf{u}_{m-1} \cdot \varphi \, dx \\ + \int_{\mathbb{T}^2} \mathbb{G}(\mathbf{u}_{m-1}) \Delta_m W \cdot \varphi \, dx. \end{aligned}$$

- Initial datum $\mathbf{u}_0 \in W_{\text{div}}^{1,2}(\mathbb{T}^2)$.
- Here $\Delta_m W = W(t_m) - W(t_{m-1})$ where $t_m = m \frac{T}{M}$.

Uniform bounds

Brzeźniak-Carelli-Prohl (2013): if $\mathbf{u}_0 \in L^{2^q}(\Omega; W_{\text{div}}^{1,2}(\mathbb{T}^2))$

$$\mathbb{E} \left[\max_{1 \leq m \leq M} \|\mathbf{u}_m\|_{W_x^{1,2}}^{2^q} + \Delta t \sum_{k=1}^M \|\mathbf{u}_m\|_{W_x^{1,2}}^{2^q-2} \|\nabla^2 \mathbf{u}_m\|_{L_x^2}^2 \right] \leq c,$$

$$\mathbb{E} \left[\sum_{k=1}^M \|\mathbf{u}_m - \mathbf{u}_{m-1}\|_{W_x^{1,2}}^2 \|\nabla \mathbf{u}_m\|_{L_x^2}^2 \right] \leq c,$$

$$\mathbb{E} \left[\left(\sum_{k=1}^M \|\mathbf{u}_m - \mathbf{u}_{m-1}\|_{W_x^{1,2}}^2 \right)^4 + \left(\Delta t \sum_{k=1}^M \|\nabla \mathbf{u}_m\|_{L_x^2}^2 \right)^4 \right] \leq c.$$

Error estimate

Breit-Dodgson (2019): for any $\alpha < \frac{1}{2}$

$$\mathbb{E} \left[\mathbf{1}_{\Omega_{\Delta t}^\varepsilon} \left(\max_{1 \leq m \leq M} \|\mathbf{u}(t_m) - \mathbf{u}_m\|_{L_x^2}^2 + \sum_{m=1}^M \Delta t \|\nabla \mathbf{u}(t_m) - \nabla \mathbf{u}_m\|_{L_x^2}^2 \right) \right] \leq c (\Delta t)^{2\alpha}.$$

- $\operatorname{div} \mathbf{u}_m = 0$, so pressure is not seen;
- $\mathbf{1}_{\Omega_{\Delta t}^\varepsilon}$ controls blow-up of $\max_m \|\nabla \mathbf{u}_m\|_{L_x^2}$;
- Carelli-Prohl (2012): same estimate with $(\Delta t)^\alpha$. Difference:

$$\mathbb{E} \left[\sum_{m=1}^M \int_{t_{m-1}}^{t_m} \int_{\mathbb{T}^2} |\nabla \mathbf{u}(t_m) - \nabla \mathbf{u}(t)|^2 dx dt \right] \leq c (\Delta t)^{2\alpha}.$$

Time-discrete pressure (1)

There is r.v. π_m with values in $\in L^2(\mathbb{T}^2)$ s.t. for all $\varphi \in W^{1,2}(\mathbb{T}^2)$

$$\begin{aligned} \int_{\mathbb{T}^2} \mathbf{u}_m \cdot \varphi \, dx + \Delta t \int_{\mathbb{T}^2} (\nabla \mathbf{u}_m) \mathbf{u}_{m-1} \cdot \varphi \, dx \\ + \mu \Delta t \int_{\mathbb{T}^2} \nabla \mathbf{u}_m : \nabla \varphi \, dx = \int_{\mathbb{T}^2} \mathbf{u}_{m-1} \cdot \varphi \, dx \\ + \Delta t \int_{\mathbb{T}^2} \pi_m \operatorname{div} \varphi \, dx + \int_{\mathbb{T}^2} \mathbb{G}(\mathbf{u}_{m-1}) \Delta_m W \cdot \varphi \, dx. \end{aligned}$$

Apply formerly div to get

$$\Delta \pi_m \Delta t = \operatorname{div} \operatorname{div} (\mathbf{u}_m \otimes \mathbf{u}_m) \Delta t + \operatorname{div} (\mathbb{G}(\mathbf{u}_{m-1}) \Delta_m W)$$

determine regularity of $\nabla \pi_m$.

Assumptions Carelli-Prohl

General case:

$$\begin{aligned} \Delta t \sum_{m=1}^M \mathbb{E} \|\nabla \pi_m\|_{L_x^2}^2 &\sim (\Delta t)^{-1} \sum_{m=1}^M \mathbb{E} \|\mathbb{G}(\mathbf{u}_{m-1}) \Delta_m W\|_{L_x^2}^2 \\ &\sim (\Delta t)^{-1} \sum_{m=1}^M \Delta t \sim (\Delta t)^{-1}. \end{aligned}$$

Solenoidal noise ($\operatorname{div} \mathbb{G}(\mathbf{u}) = 0$):

$$\begin{aligned} \Delta t \sum_{m=1}^M \mathbb{E} \|\nabla \pi_m\|_{L_x^2}^2 &\sim \Delta t \sum_{m=1}^M \mathbb{E} \|(\nabla \mathbf{u}_m) \mathbf{u}_m\|_{L_x^2}^2 \\ &\sim \Delta t \sum_{m=1}^M \mathbb{E} \|\mathbf{u}_m\|_{L_x^2} \|\nabla \mathbf{u}_m\|_{L_x^2}^2 \|\nabla^2 \mathbf{u}_m\|_{L_x^2} \leq c. \end{aligned}$$

Equation for the error

The error $\mathbf{e}_{h,m} = \mathbf{u}_m - \mathbf{u}_{h,m}$ satisfies for all $\varphi \in V_{\text{div}}^h(\mathbb{T}^2)$

$$\begin{aligned} \int_{\mathbb{T}^2} \mathbf{e}_{h,m} \cdot \varphi \, dx + \mu \Delta t \int_{\mathbb{T}^2} \nabla \mathbf{e}_{h,m} : \nabla \varphi \, dx &= \int_{\mathbb{T}^2} \mathbf{e}_{h,m-1} \cdot \varphi \, dx \\ &+ \dots + \Delta t \int_{\mathbb{T}^2} \pi_m \operatorname{div} \varphi \, dx \\ &+ \int_{\mathbb{T}^2} (\mathbb{G}(\mathbf{u}_{m-1}) - \mathbb{G}(\mathbf{u}_{h,m-1})) \Delta_m W \cdot \varphi \, dx. \end{aligned}$$

- Use test-function $\Pi_h \mathbf{e}_{h,m} = \Pi_h \mathbf{u}_m - \mathbf{u}_{h,m}$;
- Carelli-Prohl: critical term is

$$\Delta t \sum_{m=1}^M \|\pi_m - \Pi_h^\pi \pi_m\|_{L_x^2}^2 \leq c h^2 \Delta t \sum_{m=1}^M \|\nabla \pi_m\|_{L_x^2}^2.$$

Stochastic pressure decomposition

The error $\mathbf{e}_{h,m} = \mathbf{u}_m - \mathbf{u}_{h,m}$ satisfies for all $\varphi \in V_{\text{div}}^h(\mathbb{T}^2)$

$$\begin{aligned} \int_{\mathbb{T}^2} \mathbf{e}_{h,m} \cdot \varphi \, dx + \mu \Delta t \int_{\mathbb{T}^2} \nabla \mathbf{e}_{h,m} : \nabla \varphi \, dx &= \int_{\mathbb{T}^2} \mathbf{e}_{h,m-1} \cdot \varphi \, dx \\ &+ \dots + \Delta t \int_{\mathbb{T}^2} \pi_m^{\text{det}} \operatorname{div} \varphi \, dx \\ &+ \int_{\mathbb{T}^2} (\mathbb{G}(\mathbf{u}_{m-1}) - \mathbb{G}(\mathbf{u}_{h,m-1})) \Delta_m W \cdot \varphi \, dx \\ &- \int_{\mathbb{T}^2} \nabla \Delta^{-1} \operatorname{div} \mathbb{G}(\mathbf{u}_{m-1}) \Delta_m W \cdot \varphi \, dx \end{aligned}$$

Deterministic pressure $\pi_m^{\text{det}} = \Delta^{-1} \operatorname{div} \operatorname{div} (\mathbf{u}_m \otimes \mathbf{u}_m)$.

Stochastic pressure estimate (1)

Testing with $\varphi = \Pi_h \mathbf{e}_{h,m}$

$$\begin{aligned}
 \mathcal{M}_{m,2} &= \sum_{n=1}^m \int_{\mathbb{T}^2} \int_{t_{n-1}}^{t_n} (\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div } \mathbb{G}(\mathbf{u}_{n-1}) \, dW \, \text{div } \Pi_h \mathbf{e}_{h,n} \, dx \\
 &= \sum_{n=1}^m \int_{\mathbb{T}^2} \int_{t_{n-1}}^{t_n} (\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div } \mathbb{G}(\mathbf{u}_{n-1}) \, dW \, \text{div } \Pi_h \mathbf{e}_{h,n-1} \, dx \\
 &+ \sum_{n=1}^m \int_{\mathbb{T}^2} \int_{t_{n-1}}^{t_n} (\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div } \mathbb{G}(\mathbf{u}_{n-1}) \, dW \, \text{div } \Pi_h (\mathbf{e}_{h,n} - \mathbf{e}_{h,n-1}) \, dx \\
 &=: \mathcal{M}_{m,2}^1 + \mathcal{M}_{m,2}^2.
 \end{aligned}$$

Stochastic pressure estimate (2)

$$\begin{aligned}
 & \mathbb{E} \left[\max_{1 \leq m \leq M} |\mathcal{M}_{m,2}^1| \right] \\
 & \leq c \mathbb{E} \left[\sum_{n=1}^M \int_{t_{n-1}}^{t_n} \|(\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div } \Phi(\mathbf{u}_{n-1})\|_{L_2}^2 \|\nabla \Pi_h \mathbf{e}_{h,n-1}\|_{L_x^2}^2 \right]^{\frac{1}{2}} \\
 & \leq c h^2 \mathbb{E} \left[\max_n \|\nabla^2 \Delta^{-1} \text{div } \Phi(\mathbf{u}_{n-1})\|_{L_2} \left(\sum_{n=1}^M \int_{t_{n-1}}^{t_n} \|\nabla \Pi_h \mathbf{e}_{h,n-1}\|_{L_x^2}^2 \right)^{\frac{1}{2}} \right] \\
 & \leq c_\kappa h^4 \mathbb{E} \left[\max_n \|\nabla \mathbf{u}_{n-1}\|_{L_x^2}^2 \right] + \kappa \mathbb{E} \left[\Delta t \sum_{n=1}^M \|\nabla \mathbf{e}_{h,n-1}\|_{L_x^2}^2 \right].
 \end{aligned}$$

Stochastic pressure estimate (3)

$$\begin{aligned}
 &\leq \kappa h^2 \mathbb{E} \left[\sum_{n=1}^M \left\| \nabla (\Pi_h \mathbf{e}_{h,n} - \Pi_h \mathbf{e}_{h,n-1}) \right\|_{L_x^2}^2 \right] \\
 &+ c_\kappa h^{-2} \mathbb{E} \left[\sum_{n=1}^M \left\| \int_{t_{n-1}}^{t_n} (\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div} \Phi(\mathbf{u}_{n-1}) dW \right\|_{L_x^2}^2 \right] \\
 &\leq c \kappa \mathbb{E} \left[\sum_{n=1}^M \left\| \Pi_h \mathbf{e}_{h,n} - \Pi_h \mathbf{e}_{h,n-1} \right\|_{L_x^2}^2 \right] \\
 &+ c_\kappa h^{-2} \mathbb{E} \left[\sum_{n=1}^M \int_{t_{n-1}}^{t_n} \left\| (\text{Id} - \Pi_h^\pi) \Delta^{-1} \text{div} \Phi(\mathbf{u}_{n-1}) \right\|_{L_2(\mathcal{U}; L_x^2)}^2 dt \right] \\
 &\leq \dots + c_\kappa h^2 \mathbb{E} \left[\sum_{n=1}^M \int_{t_{n-1}}^{t_n} \left\| \nabla^2 \Delta^{-1} \text{div} \Phi(\mathbf{u}_{n-1}) \right\|_{L_2(\mathcal{U}; L_x^2)}^2 dt \right].
 \end{aligned}$$