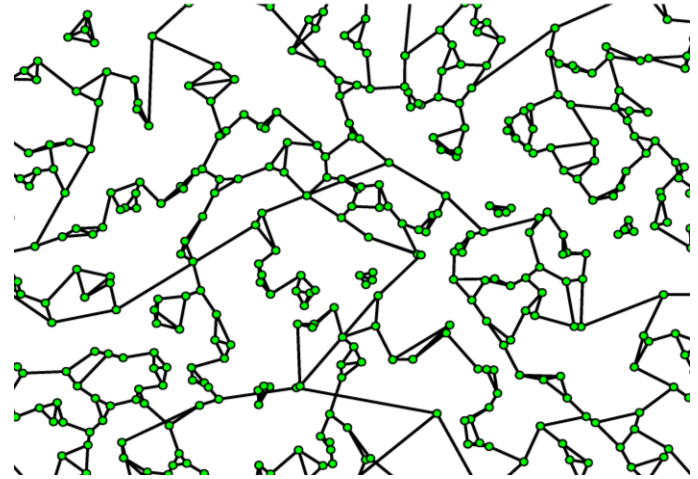
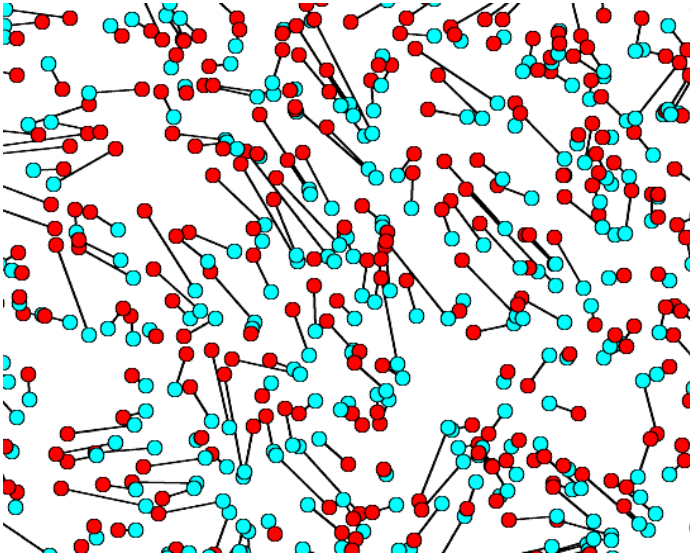


Invariant Matching

Alexander E. Holroyd, Microsoft Research



Red points

Blue points

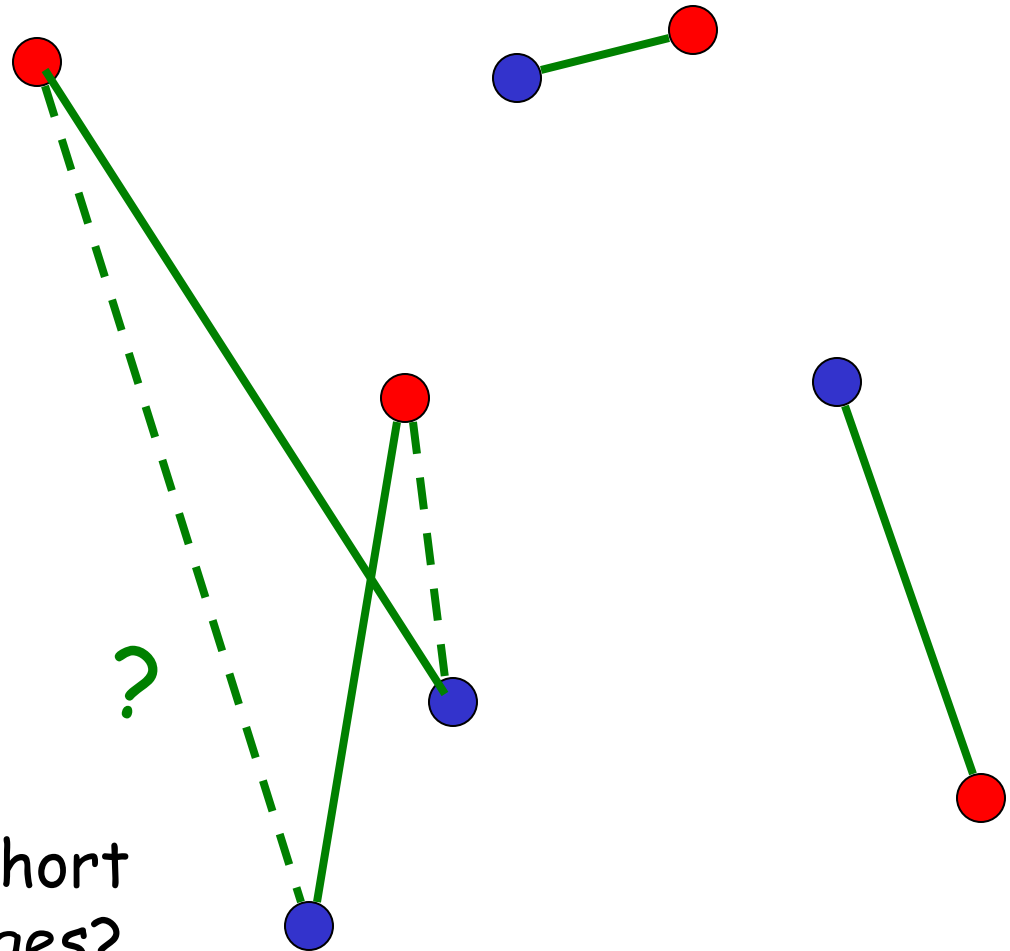
Perfect matching

Questions:

Quantitative- how short
can we make the edges?

Geometric...

Local/greedy/non-random
matching rules?



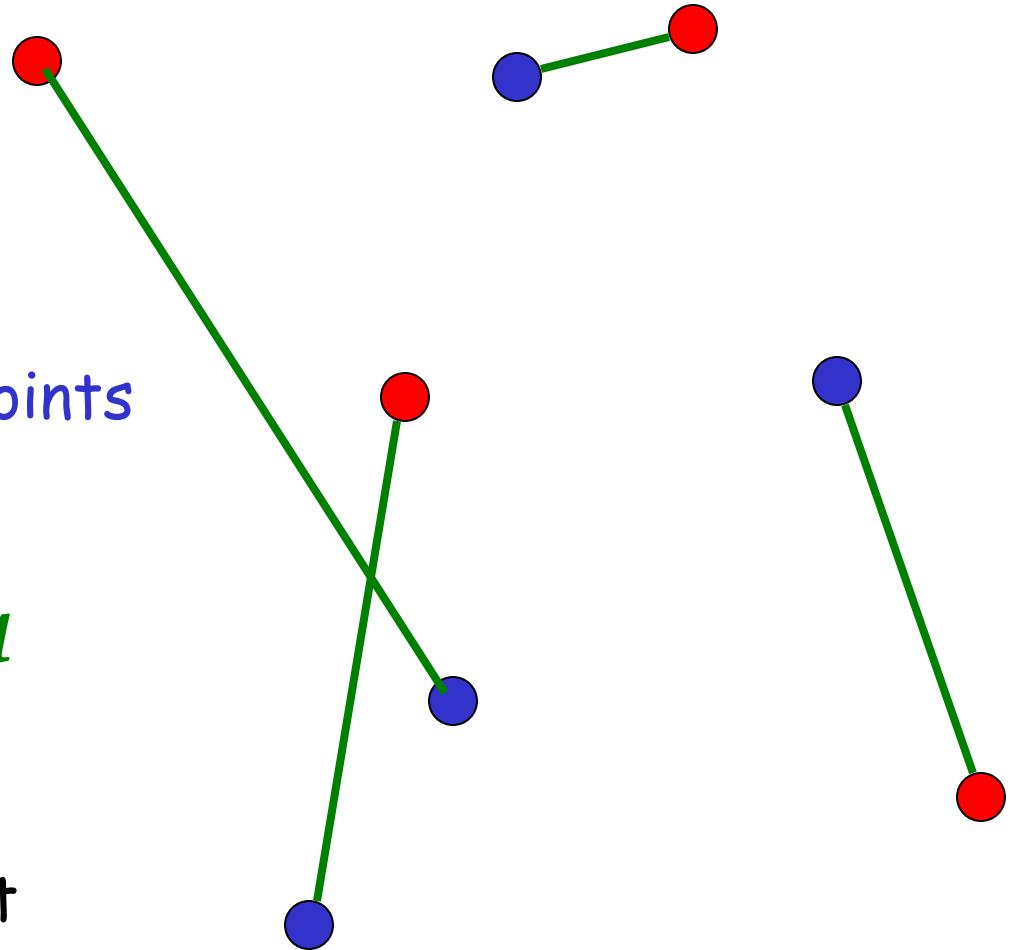
Intensity-1 Poisson
process $\mathcal{R}$ of
red points

$\mathbb{R}^d$

Independent
intensity-1 Poisson
process $\mathcal{B}$ of blue points

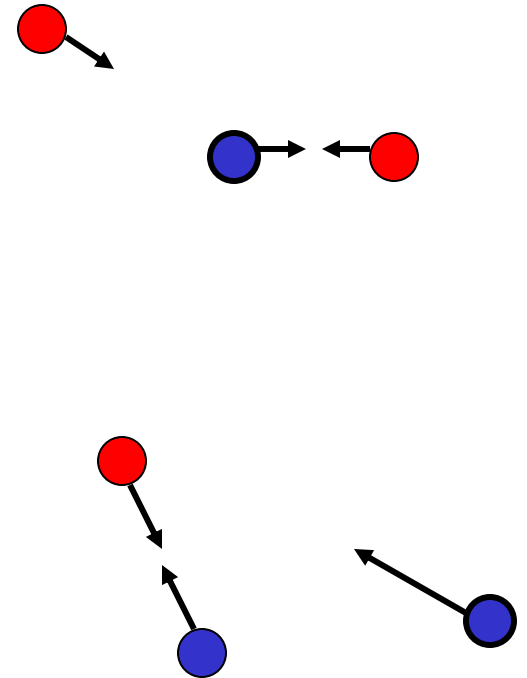
Random perfect
matching scheme $\mathcal{M}$

Assume $(\mathcal{R}, \mathcal{B}, \mathcal{M})$
translation-invariant
in law



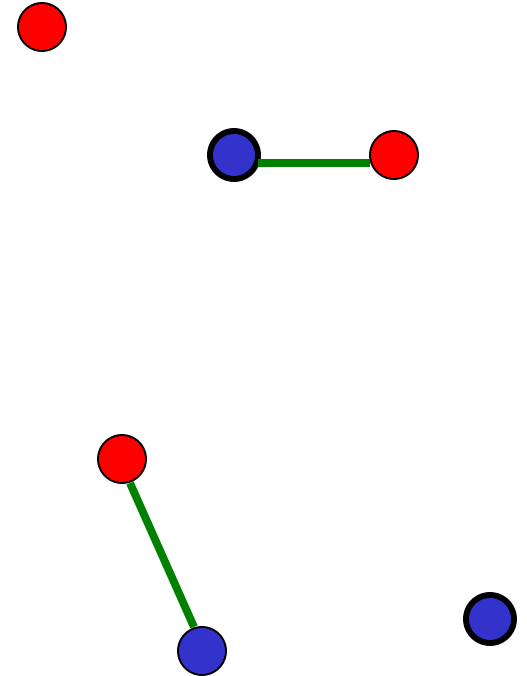
Example: Gale-Shapley stable matching.

- Match all *mutually closest* red/blue pairs.



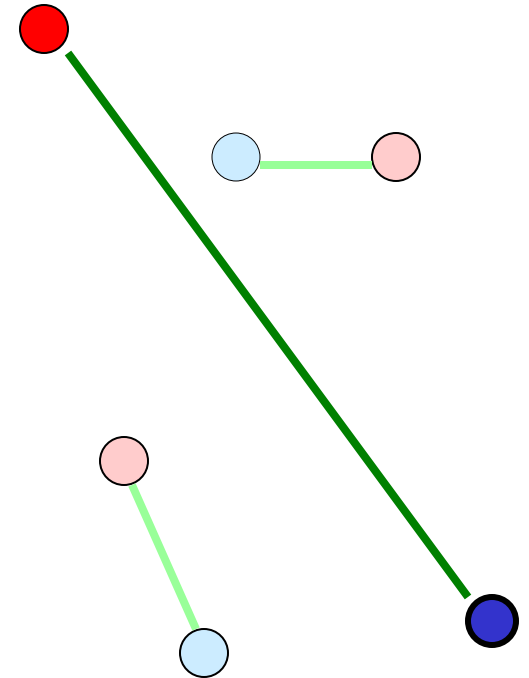
Example: Gale-Shapley stable matching.

- Match all *mutually closest* red/blue pairs.



Example: Gale-Shapley stable matching.

- Match all *mutually closest* red/blue pairs.
- Remove them
- Repeat indefinitely



Example: Gale-Shapley stable matching.

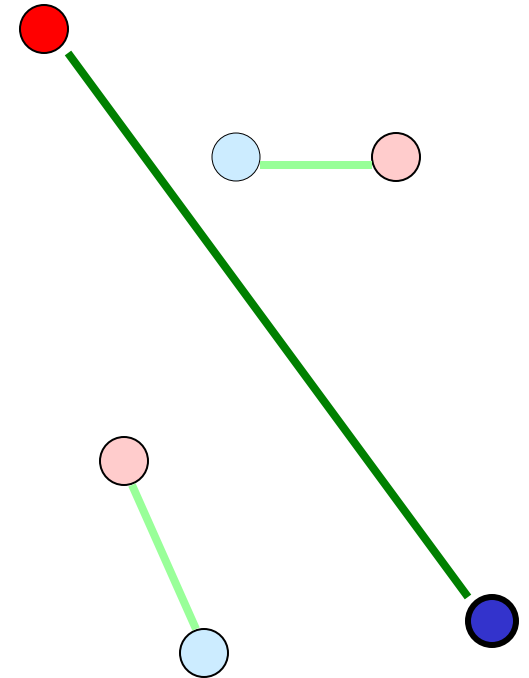
- Match all *mutually closest* red/blue pairs.
- Remove them
- Repeat indefinitely

Why does every point get matched?

$R = \{\exists \text{ unmatched red point}\}$

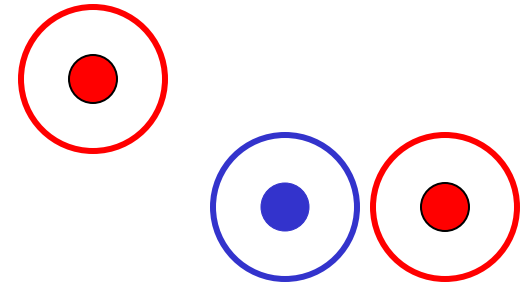
$B = \{\exists \text{ unmatched blue point}\}$

- **Ergodicity** $\Rightarrow P(R), P(B) \in \{0, 1\}$
- **Algorithm** $\Rightarrow$ cannot have $P(R) = P(B) = 1$
- **Averaging/Mass-transport/Fubini**: unmatched red & blue points have equal intensity, so cannot have one=1, other=0

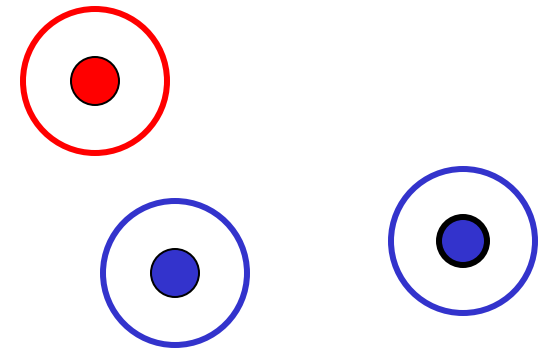


Example: Gale-Shapley stable matching.

- Match all *mutually closest* red/blue pairs.
- Remove them
- Repeat indefinitely



Alternative description:
ball-growing

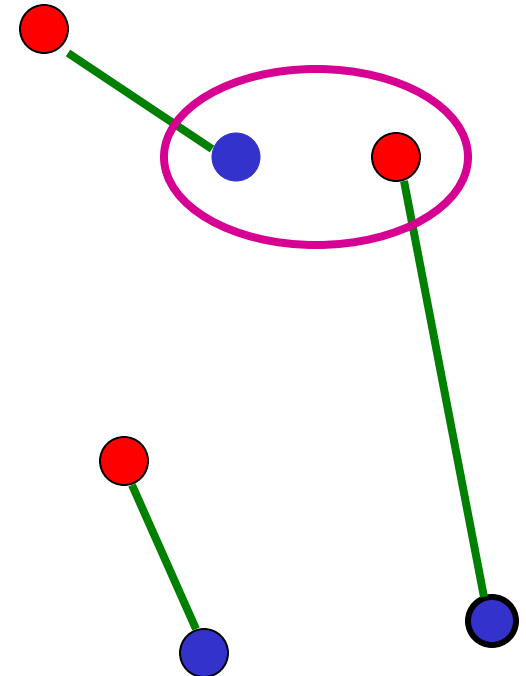


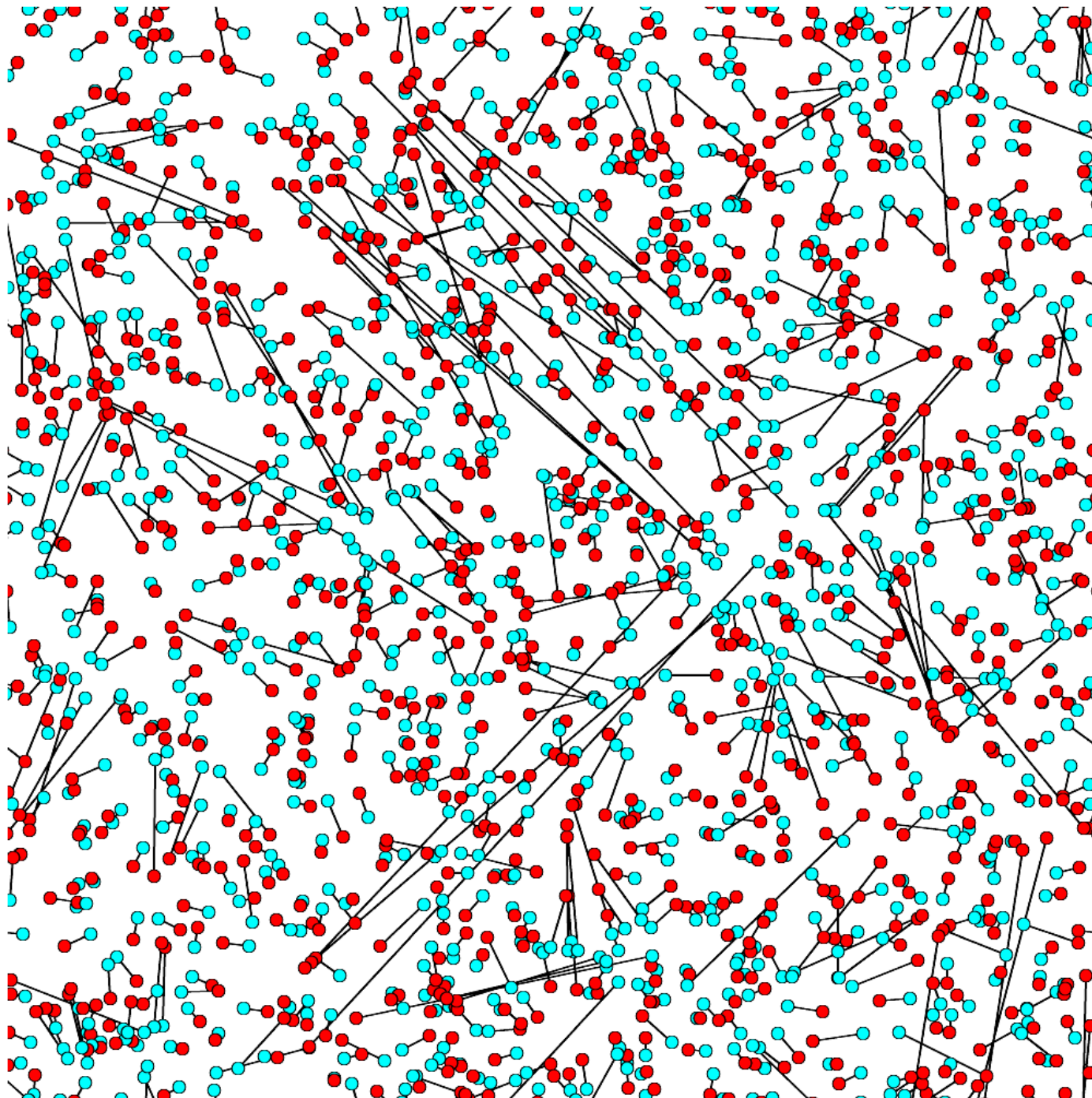
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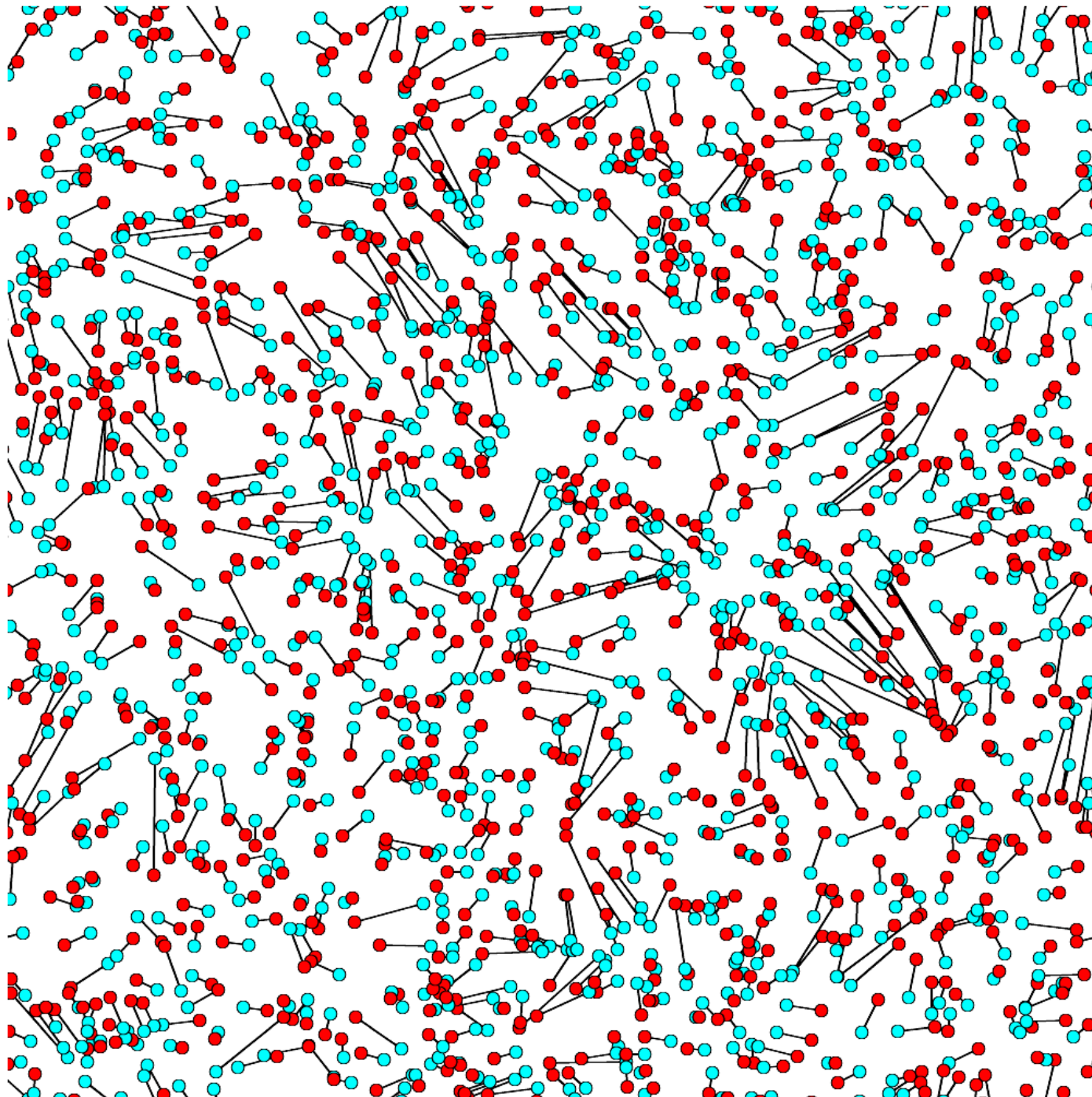
Alternative description:
unique matching with
no *unstable* pairs





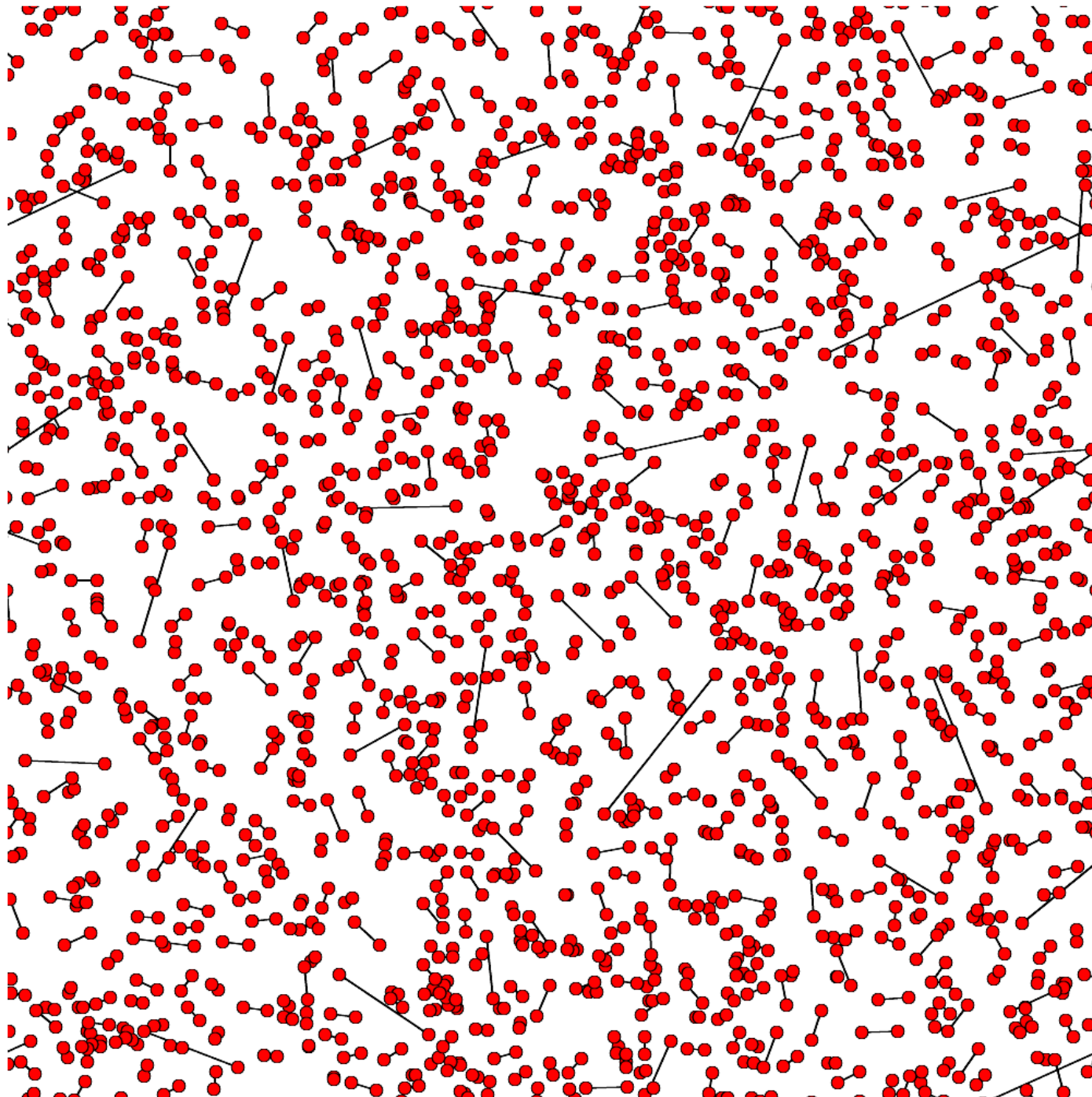
Two-colour
stable
matching

(on torus)



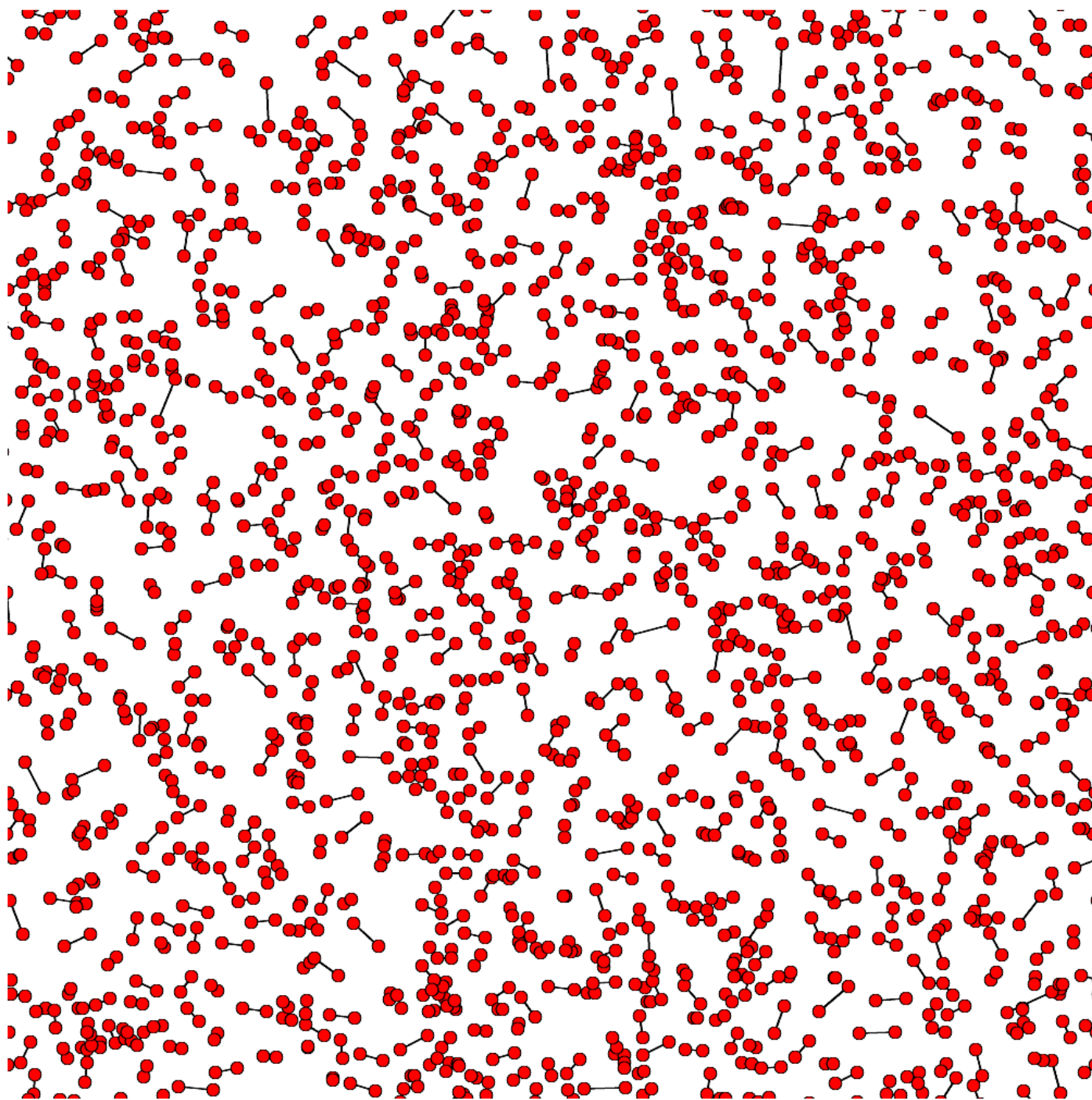
Two-colour
minimum-
length
matching

(on torus)



One-colour
stable
matching

(on torus)



One-colour
minimum-
length
matching

(on torus)

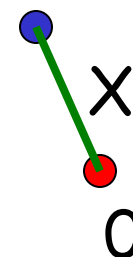
Call a matching scheme

- a *factor* if $\mathcal{M} = f(\mathcal{R}, \mathcal{B})$
(e.g. stable matching)
- *randomized* if not

Given a matching scheme $\mathcal{M}$,

denote X = length of "typical edge"

$= |0 - \mathcal{M}(0)|$ "conditioned" on $\{0 \text{ is red}\}$
(i.e. under Palm measure P^*)



i.e. $P^*(X \leq r) :=$

$E \# \{\text{red points } z \in [0,1]^d \text{ with } |z - \mathcal{M}(z)| \leq r\}$

Question: how small can we make X
(in terms of tail behaviour)?

A trivial lower bound: for any matching,

$$P^*(X > r) \geq P^*(\exists \text{ no other point in } B(0, r)) \geq e^{-cr^d}$$

i.e. $E^* e^{cX^d} = \infty$

More results (H., Pemantle, Peres, Schramm 2008):

One color		Lower bound	Upper bound
Randomized	d=1		
	$d \geq 2$		
Factor	d=1		
	$d \geq 2$		
Stable	All d		

Two color		Lower bound	Upper bound
Randomized	d=1		
	d=2		
	$d \geq 3$		
Factor	d=1		
	d=2		
	$d \geq 3$		
Stable	d=1		
	d=2		
	$d \geq 3$		

One color		Lower bound	Upper bound
Randomized	$d=1$	$E^* e^{cX^d} = \infty$	
	$d \geq 2$	$E^* e^{cX^d} = \infty$	
Factor	$d=1$	$E^* e^{cX^d} = \infty$	
	$d \geq 2$	$E^* e^{cX^d} = \infty$	
Stable	All d	$E^* e^{cX^d} = \infty$	

Two color		Lower bound	Upper bound
Randomized	$d=1$	$E^* e^{cX^d} = \infty$	
	$d=2$	$E^* e^{cX^d} = \infty$	
	$d \geq 3$	$E^* e^{cX^d} = \infty$	
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Stable	$d=1$	$E^* e^{cX^d} = \infty$	
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Two color		Lower bound	Upper bound
Randomized	$d=1$	$E^* e^{cX^d} = \infty$	$P^*(X > r) < C r^{-1/2}$
	$d=2$	$E^* e^{cX^d} = \infty$	$P^*(X > r) < C r^{-1}$
	$d \geq 3$	$E^* e^{cX^d} = \infty$	$P^*(X > r) < C r^{-d/2}$
Factor	$d=1$	$E^* e^{cX^d} = \infty$	
	$d=2$	$E^* e^{cX^d} = \infty$	
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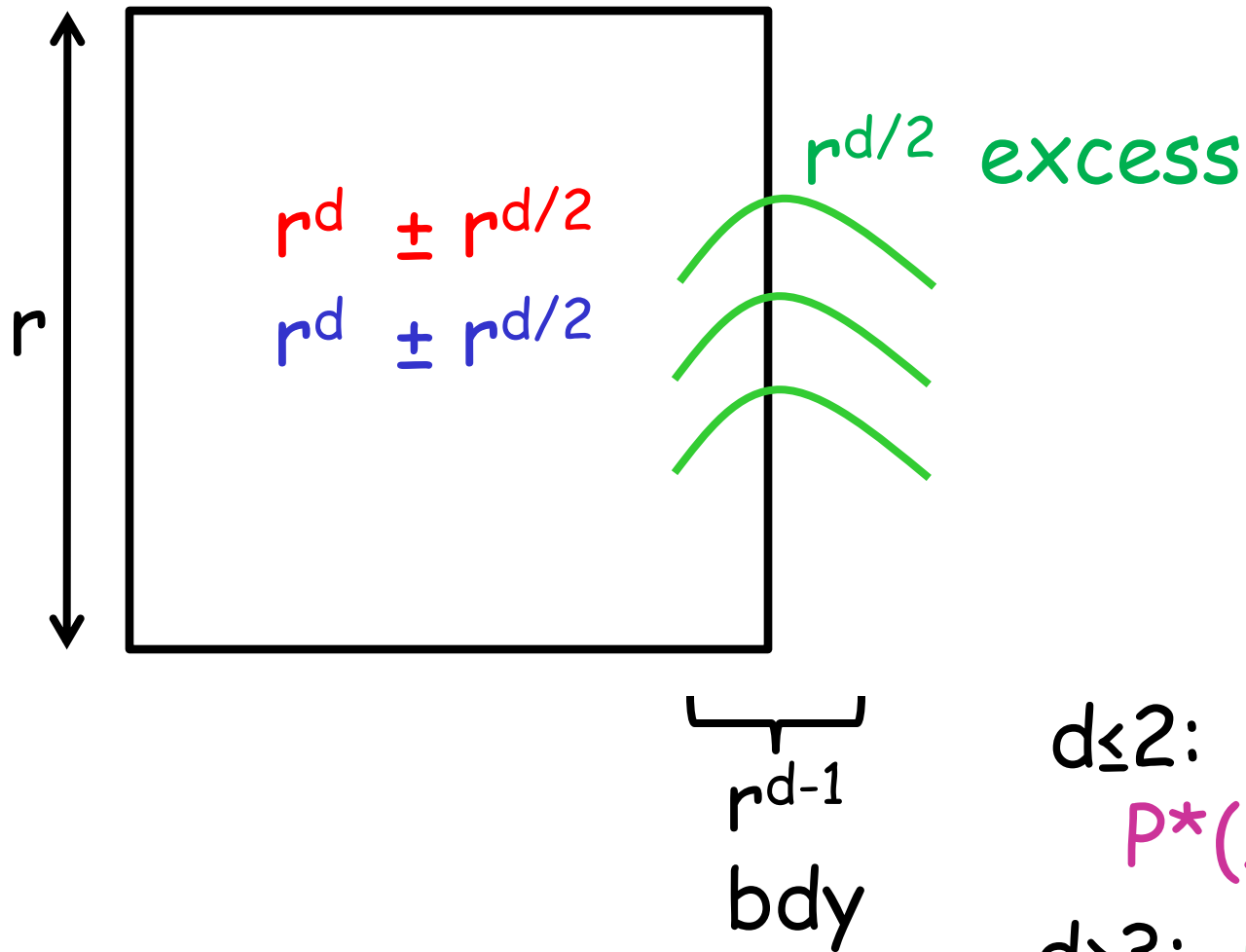
One color		Lower bound	Upper bound
Randomized	$d=1$	$E^* e^{cX^d} = \infty$	
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	$d \geq 3$	$E^* e^{cX^d} = \infty$	$E^* e^{cX^d} < \infty$ [from Talagrand]
Factor	$d=1$	$E^* e^{cX^d} = \infty$	
	$d=2$	$E^* e^{cX^d} = \infty$	
	$d \geq 3$	$E^* e^{cX^d} = \infty$	
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One color		Lower bound	Upper bound
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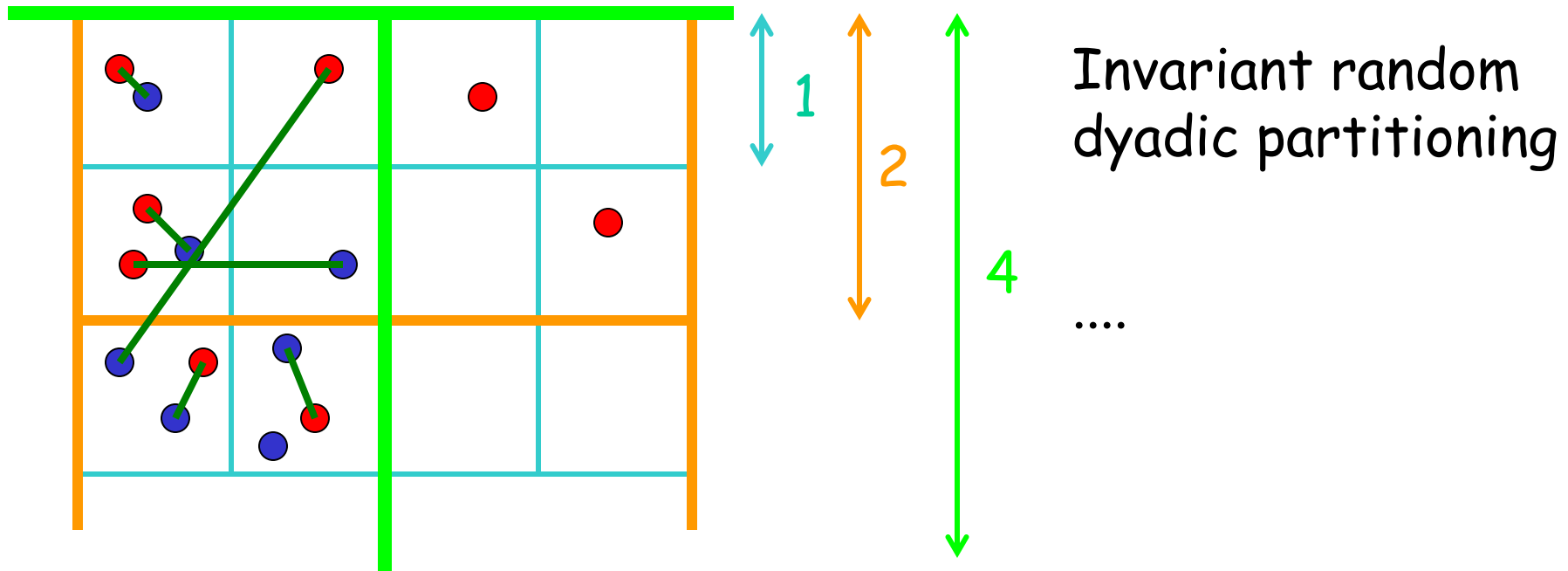
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	$d=2$	$E^* e^{cX^d} = \infty$	
	$d \geq 3$	$E^* e^{cX^d} = \infty$	

Heuristic reason:



$$\begin{aligned} d \leq 2: & \quad r^{d/2} \geq r^{d-1} \\ & \quad P^*(X > r) \approx r^{d/2} / r^d \\ d \geq 3: & \quad r^{d/2} \ll r^{d-1} \\ & \quad \text{match "locally"} \end{aligned}$$

Two-color randomized matching



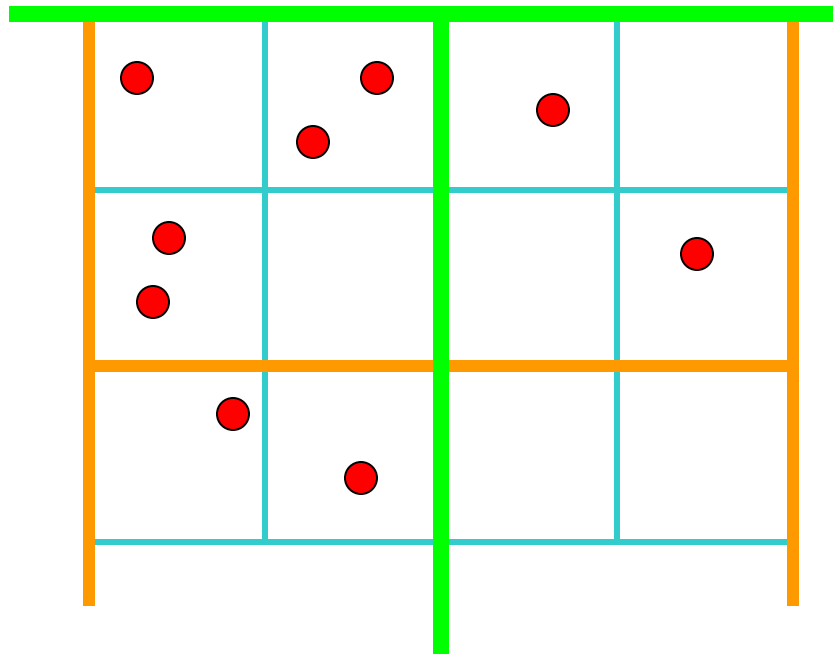
Match as much as possible within level-1 cubes

Match as much as possible within level-2 cubes

Etc.

$$\begin{aligned}
 P^*(X > c2^k) &\leq P^*(0 \text{ not matched by stage } k) \\
 &\leq P^*(0 \text{ in "excess" in its level-}k \text{ cube}) \leq C \sqrt{[2^{kd}]/2^{kd}} = C(2^k)^{d/2}
 \end{aligned}$$

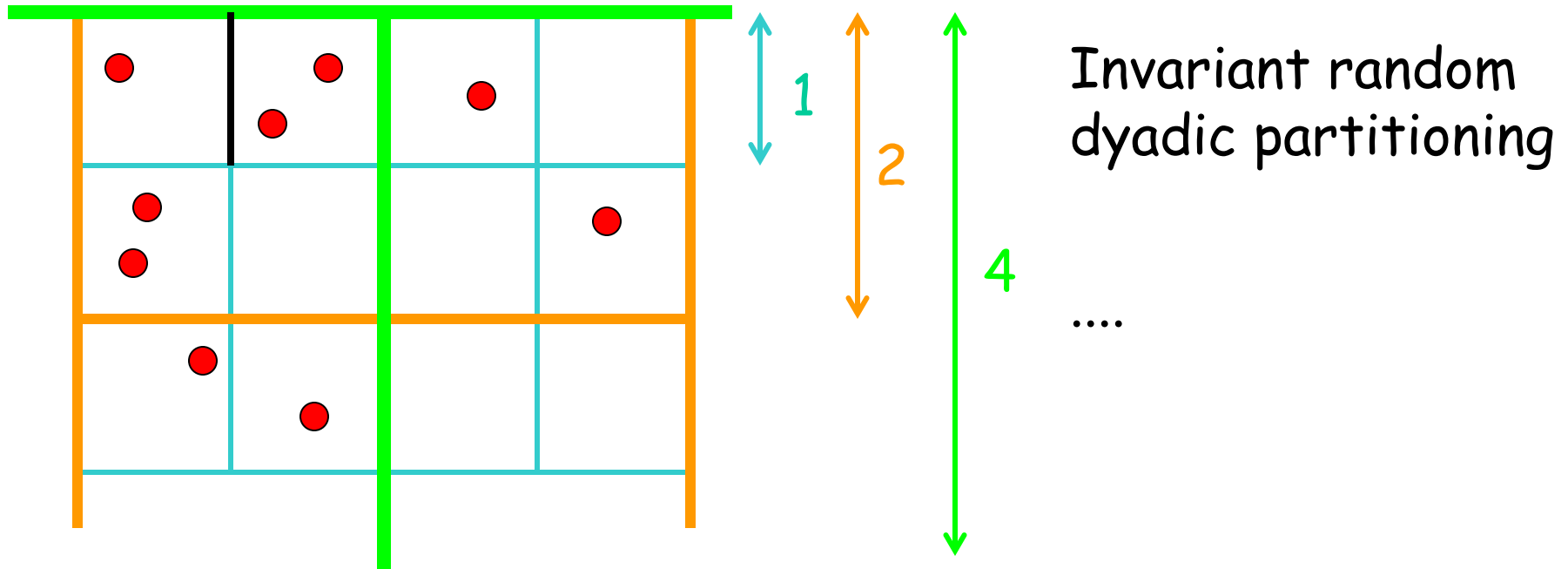
Two-color randomized matching: better method for $d \geq 3$
(based on Ajtai-Komlos-Tusnady)



Invariant random
dyadic partitioning

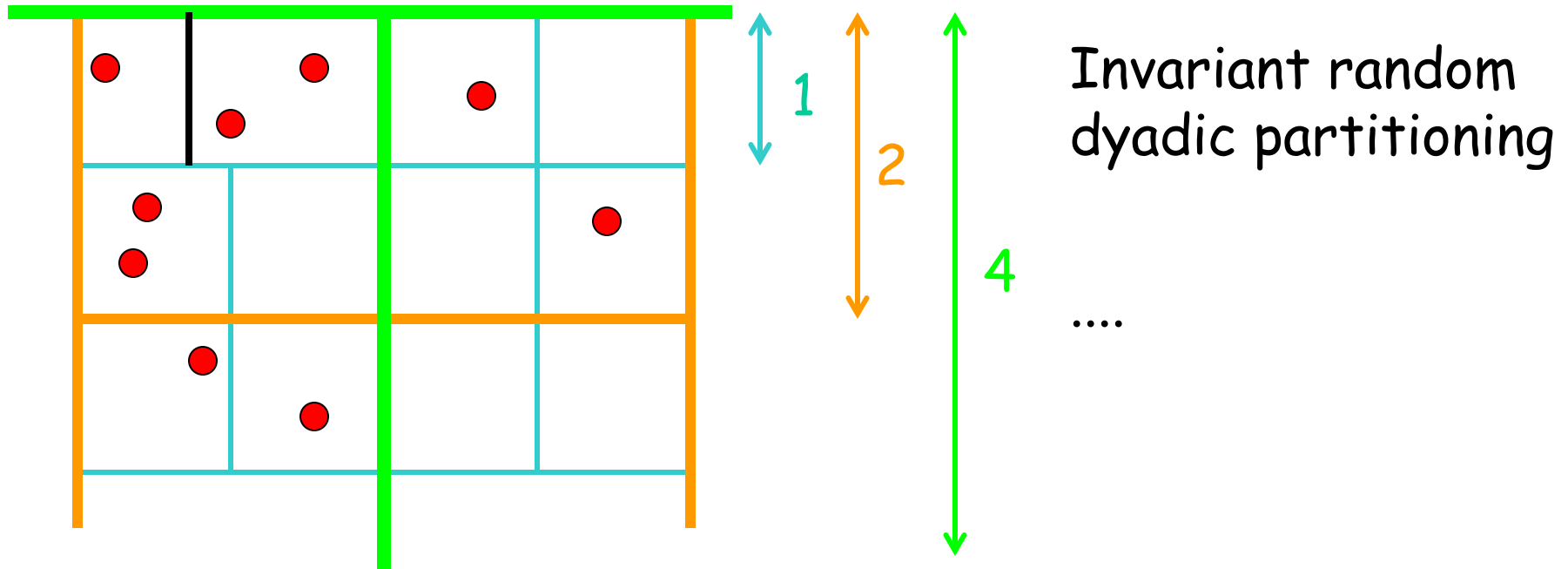
....

Two-color randomized matching: better method for $d \geq 3$
(based on Ajtai-Komlos-Tusnady)



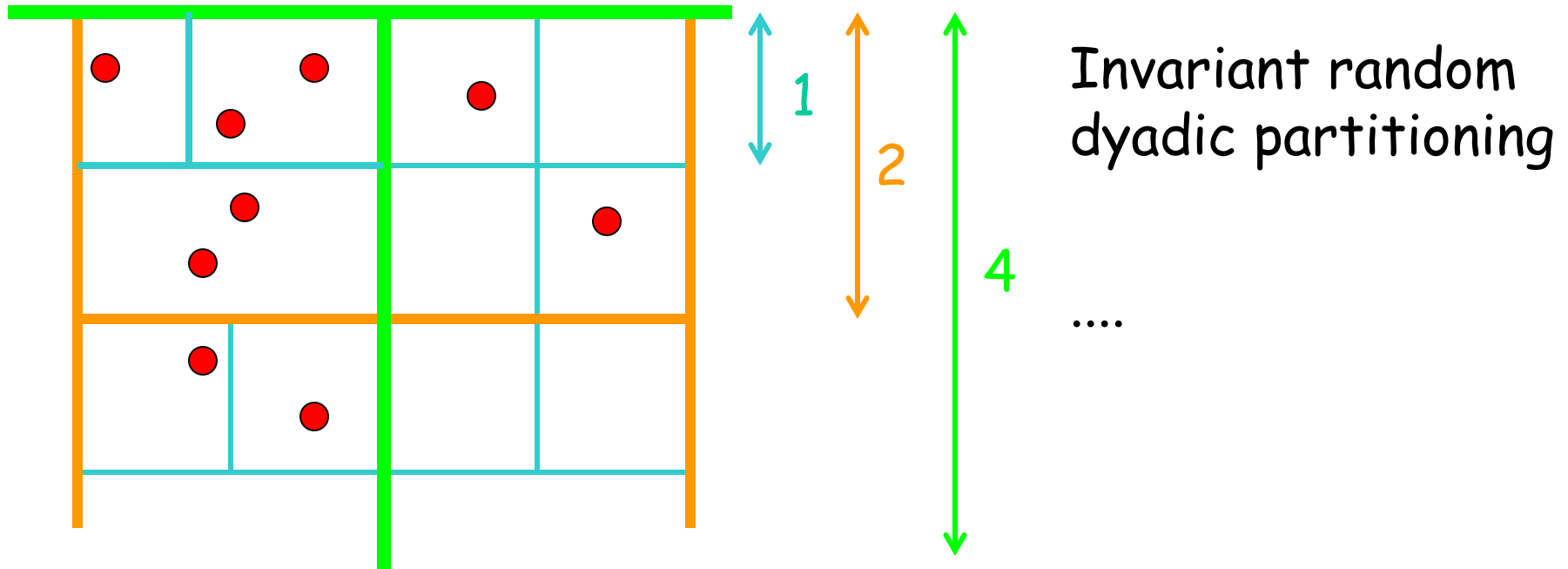
Repartition to equalize points per unit volume,
affinely shift points

Two-color randomized matching: better method for $d \geq 3$
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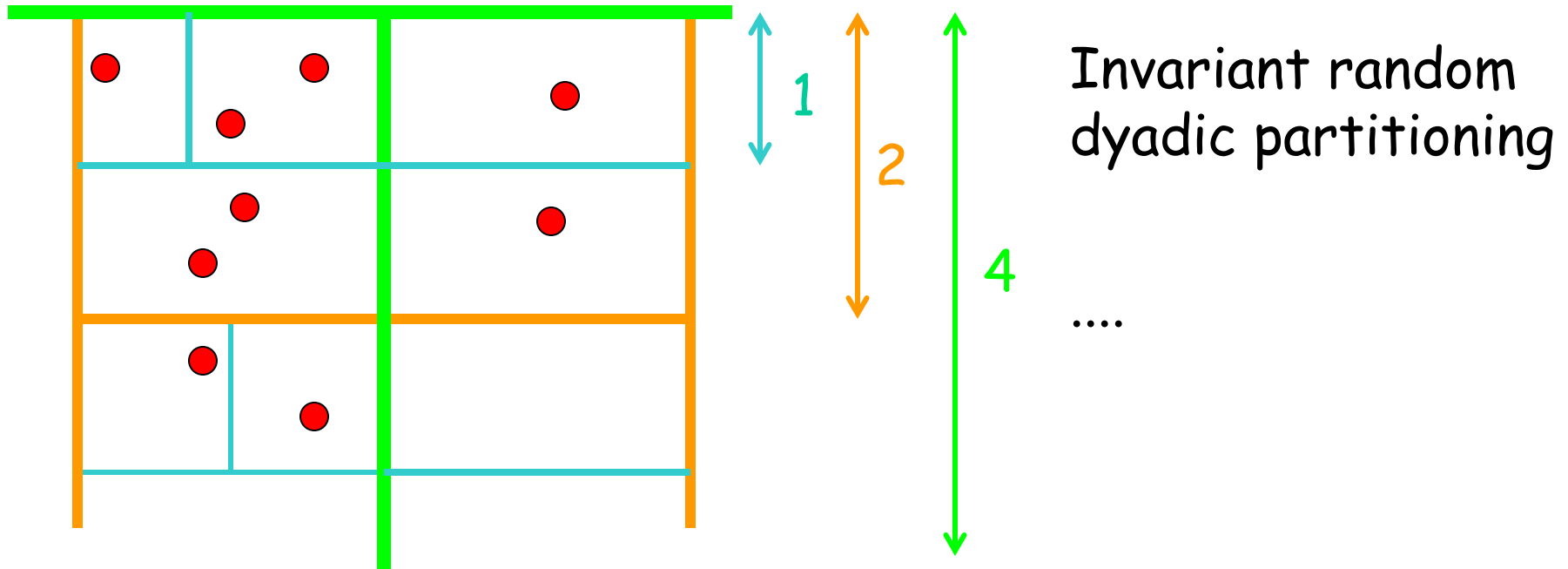
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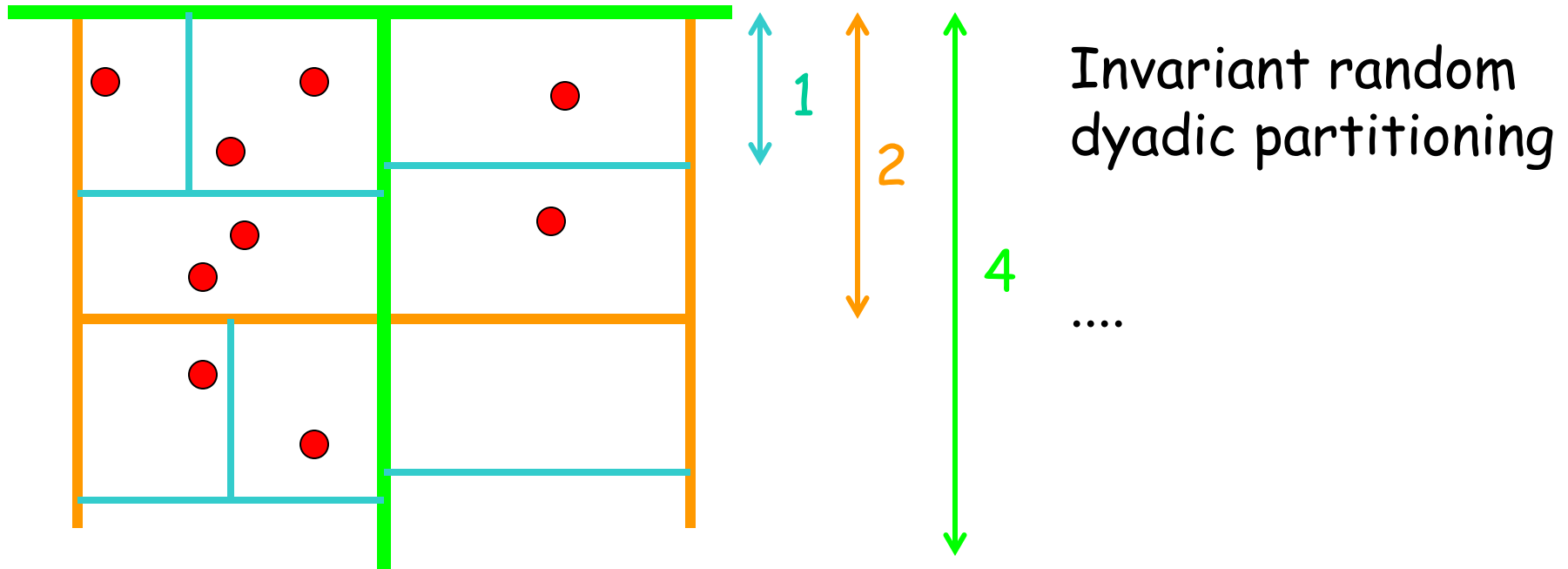
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Repartition to equalize points per unit volume,
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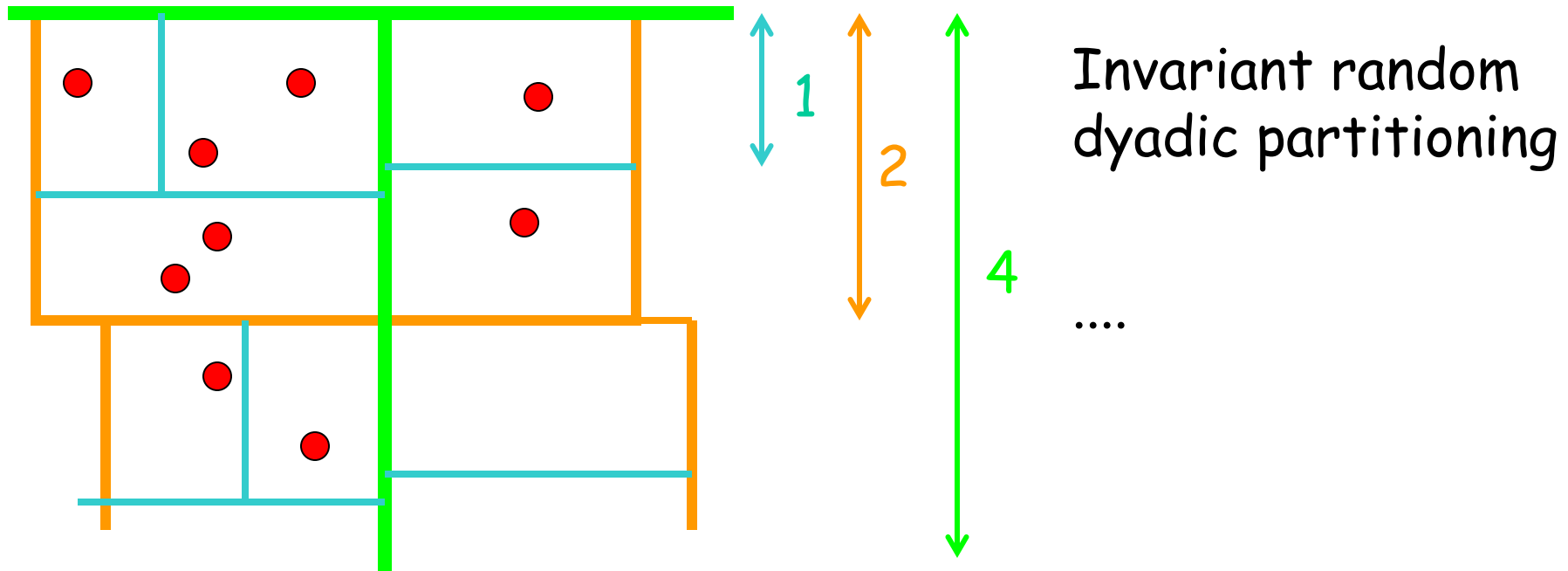
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Repartition to equalize points per unit volume,
affinely shift points

Iterate

Two-color randomized matching: better method for $d \geq 3$ (based on Ajtai-Komlos-Tusnady)

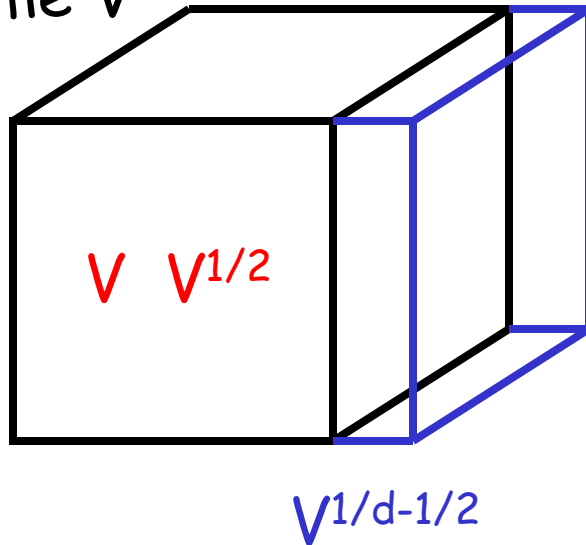


Repartition to equalize points per unit volume,
affinely shift points

Iterate...

Get allocation of 1 unit volume to each point
... abstract arguments $\Rightarrow$ matching

Volume V



Total distance moved by a typical point

$< \infty$ for $d \geq 3$

$$\sum_{k=1}^{\infty} (2^k)^{1/d-1/2}$$

Biggest deviation: empty cubes...

One color		Lower bound	Upper bound
Randomized	$d=1$	$E^* e^{cX^d} = \infty$	
	$d \geq 2$	$E^* e^{cX^d} = \infty$	
Factor	$d=1$	$E^* e^{cX^d} = \infty$	
	$d \geq 2$	$E^* e^{cX^d} = \infty$	
Stable	All d	$E^* e^{cX^d} = \infty$	

Two color		Lower bound	Upper bound
Randomized	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$ $P^*(X > r) < C r^{-1}$ $E^* e^{cX^d} < \infty$
	$d=2$	$E^* X = \infty$	
	$d \geq 3$	$E^* e^{cX^d} = \infty$	
Factor	$d=1$	$E^* X^{1/2} = \infty$	
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Two color		Lower bound	Upper bound
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Factor	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
	$d=2$	$E^* X = \infty$	$P^*(X > r) < C r^{-2/3+\varepsilon}$ [Soo]
	$d \geq 3$	$E^* e^{cX^d} = \infty$	$P^*(X > r) < C r^{-2d/(d+4)+\varepsilon}$ [Soo]
Stable	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
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	$d=2$	$E^* X = \infty$	$P^*(X > r) < C r^{-1}$ [Timar]
	$d \geq 3$	$E^* e^{cX^d} = \infty$	$E^* e^{cX^{d-2}} < \infty$ [Timar]
Stable	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
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Factor	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
	$d=2$	$E^* X = \infty$	$P^*(X > r) < C r^{-1}$ [Timar]
	$d \geq 3$	$E^* e^{cX^d} = \infty$	$E^* e^{cX^{d-2}} < \infty$ [Timar]
Stable	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
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	$d \geq 2$	$E^* e^{cX^d} = \infty$	
Factor	$d=1$	$E^* X = \infty$	$P^*(X > r) < C r^{-1}$
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Stable	All d	$E^* e^{cX^d} = \infty$	

Two color		Lower bound	Upper bound
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	$d \geq 3$	$E^* e^{cX^d} = \infty$	$E^* e^{cX^{d-2}} < \infty$ [Timar]
Stable	$d=1$	$E^* X^{1/2} = \infty$	$P^*(X > r) < C r^{-1/2}$
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Two color		Lower bound	Upper bound
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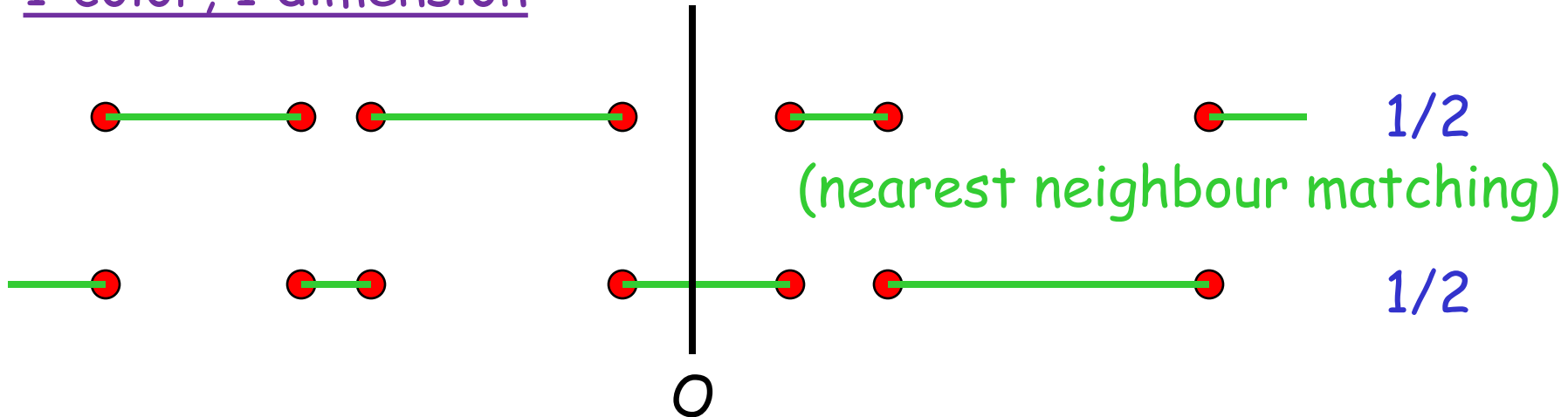
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	$d=2$	$E^* X = \infty$	$P^*(X > r) < C r^{-0.496...}$
	$d \geq 3$	$E^* X^d = \infty$	$P^*(X > r) < C r^{-s(d)}$

One color		Lower bound	Upper bound
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1-color, 1 dimension

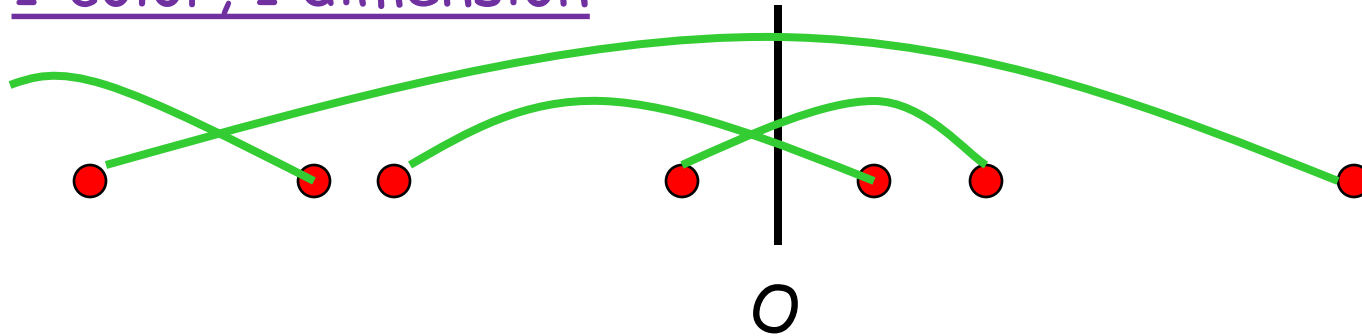


- a randomized matching with $P^*(X > r) = e^{-r}$

But $\nexists$ a factor nearest neighbour matching

Any factor matching has $E^*X = \infty$. Proof:

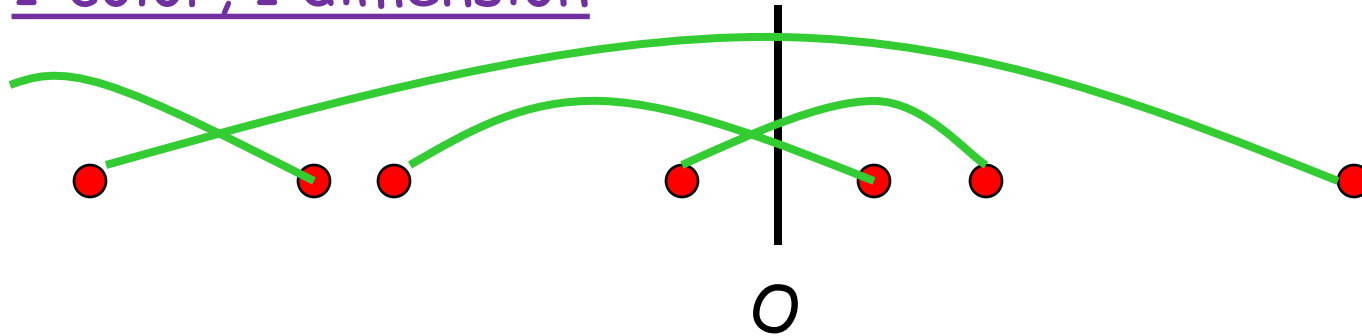
1-color, 1 dimension



Enough to show:

$$E(\# \text{ edges crossing } O) = \infty$$

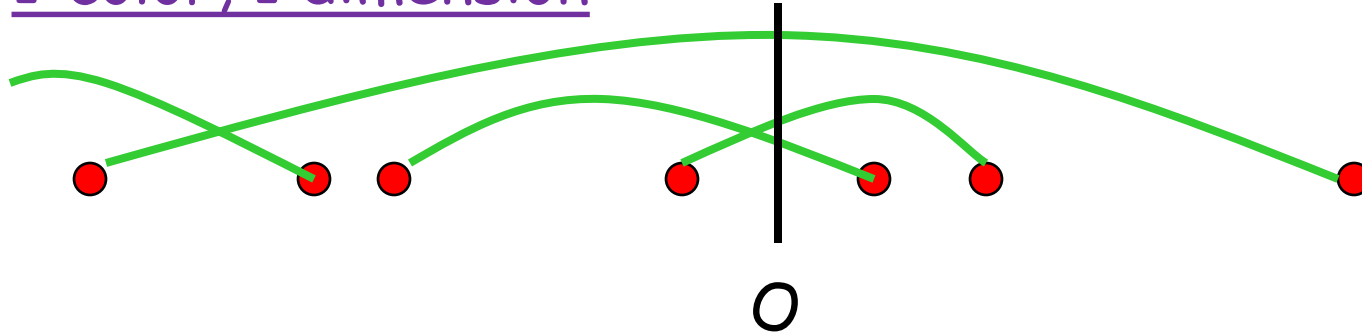
1-color, 1 dimension



Enough to show:

$$P(\# \text{ edges crossing } O = \infty) = 1$$

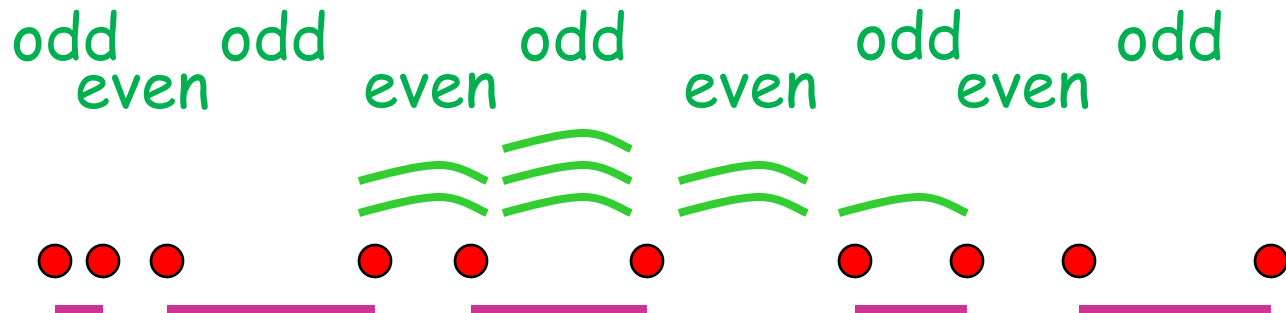
1-color, 1 dimension



Suppose:

$$P(\# \text{ edges crossing } O < \infty) > 0$$

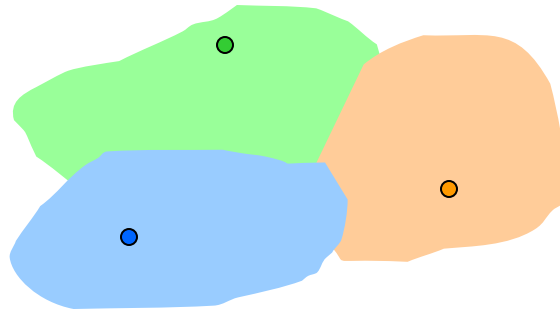
$$\Rightarrow P(< \infty \text{ edges crossing every site}) = 1$$



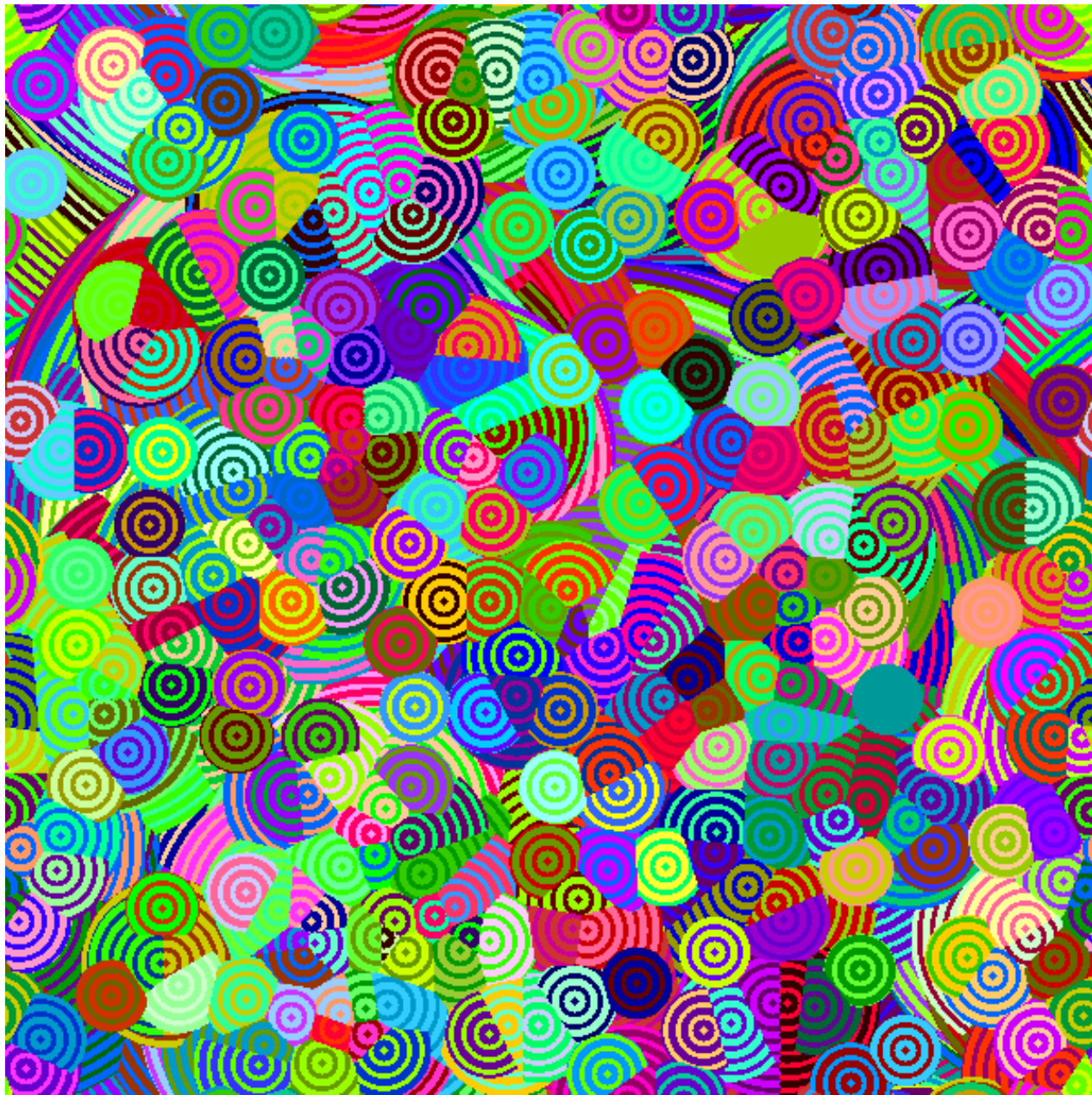
Rematch $\Rightarrow$ factor nearest neighbour matching! #

Variant problem: **allocation**

Given a point process of intensity 1 in $\mathbb{R}^d$, partition space into cells of volume 1, with each cell allocated to a point, in a translation-invariant way.



Applications to Palm processes, shift coupling:
H., Peres; Thorisson, Last



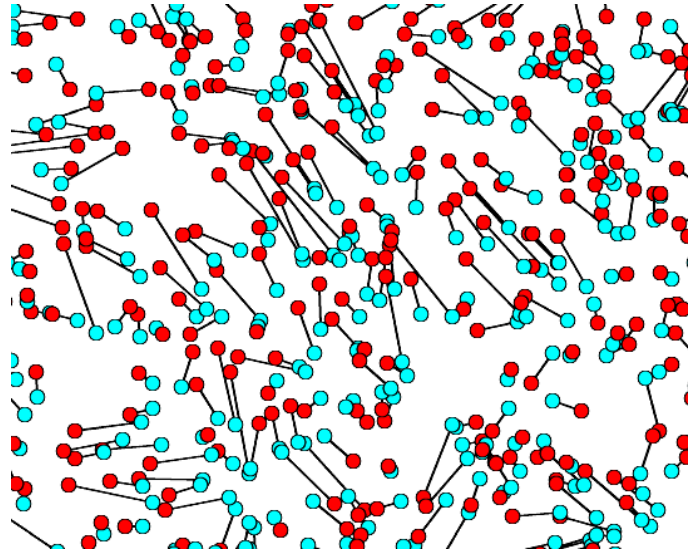
Stable allocation (Hoffman, H., Peres, 2005, 2009)

Gravtiation allocation, for Poisson process in $d \geq 3$.
(Chatterjee, Peled, Peres, Romik, 2010).



Geometric questions for matchings:

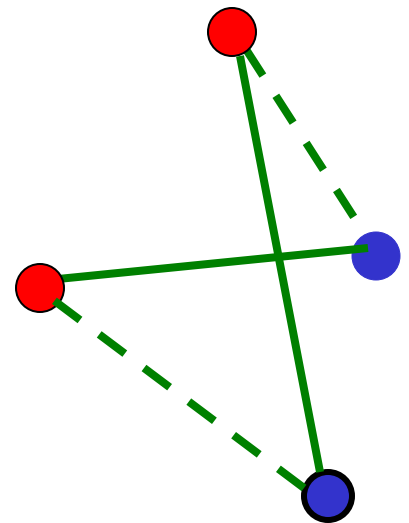
Q: For independent **red** and **blue** intensity-1 Poisson processes in $\mathbb{R}^2$, does there exist a translation-invariant matching in which line segments joining matched pairs **do not cross**?



Proposition (H. 2009) Yes if we drop invariance, or for one color, or allow partial matching, or curved edges!

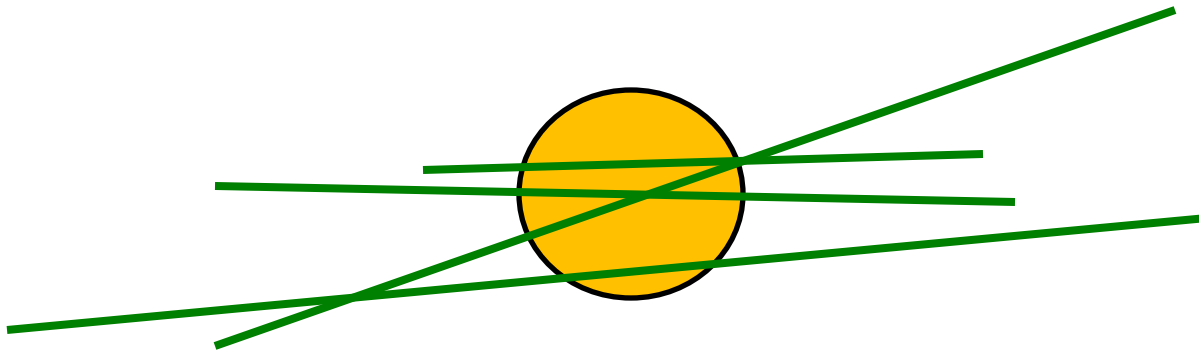
Q: For independent **red** and **blue** intensity-1 Poisson processes in $\mathbb{R}^2$, does there exist a **minimal** translation-invariant matching, i.e. s.t. every finite set of edges minimizes the total length?

(If yes, then it would have no crossings)



Theorem (H. 2009) Yes in $\mathbb{R}^d$, $d=1$ and $d \geq 3$
No in strip $\mathbb{R} \times [0,1]$

For independent **red** and **blue** intensity-1 Poisson processes, does there exist a **locally finite** translation-invariant matching, i.e. s.t. any bounded set meets only finitely many edges?

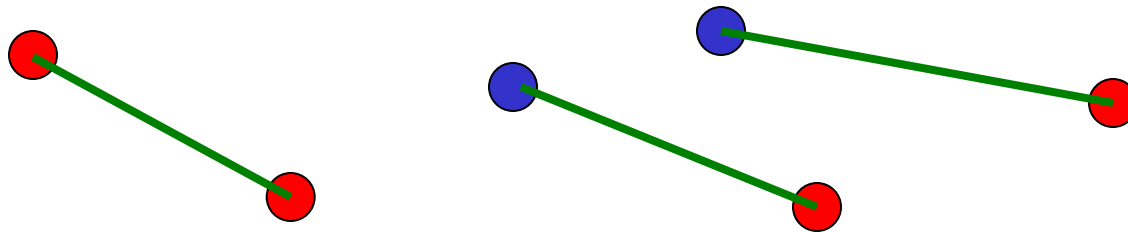


Theorem (H. 2009) Yes in $\mathbb{R}^d$, $d \geq 2$
No in $d=1$, and strip

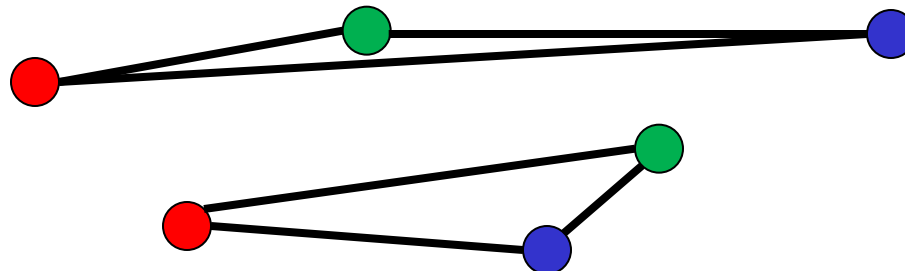
Multi-colour matching (Amir, Angel, H., in preparation)

Given independent Poisson processes of several colours.
E.g.

may match red-blue or red-red



must match in red-green-blue families



families of RBB or RRRGB or GGY

$X :=$ diameter of "typical" family

$\lambda = (\lambda_1, \lambda_2, \dots, \lambda_q)$ intensities of points each colour

Theorem

$\lambda \notin S \Rightarrow$ no translation-invariant matching possible

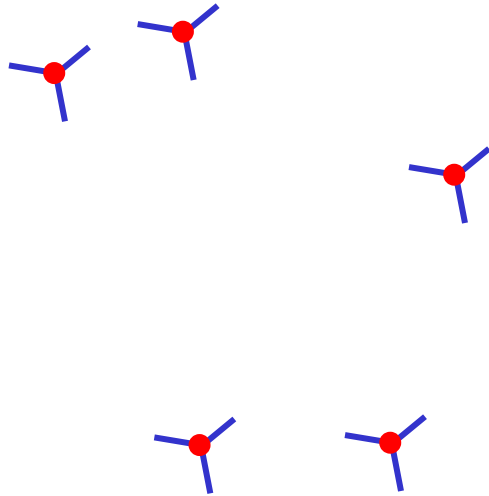
$\lambda \in \partial S \Rightarrow$ upper/lower bounds like 2-colour matching
($d/2$ power in $d \leq 2$, exponential in volume in $d \geq 3$)

$\lambda \in S^\circ \Rightarrow$ upper/lower bounds like 1-colour matching
(exponential in volume)

where $S \subset R^q$

is the cone generated by the allowed family vectors

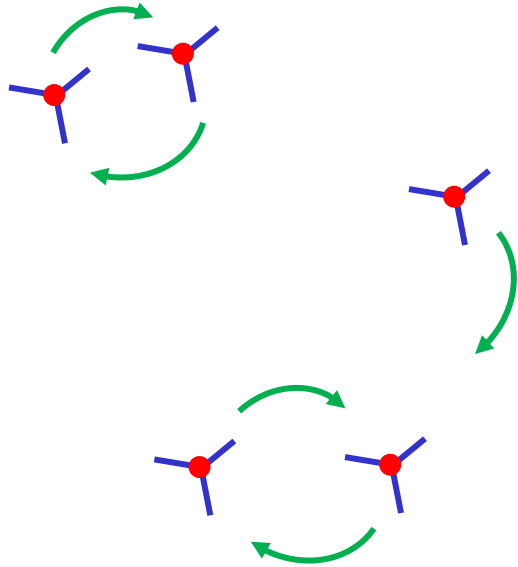
Stable Simple Graphs



Assign each Poisson point x
a (deterministic or iid) degree D_x

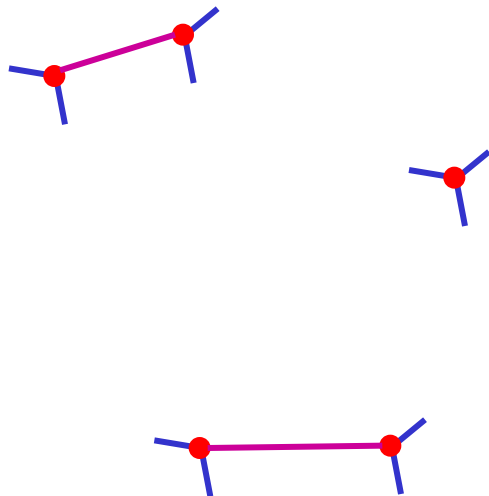
$$D = 3$$

Want a translation-invariant *simple* graph on the
point process s.t. x has degree D_x



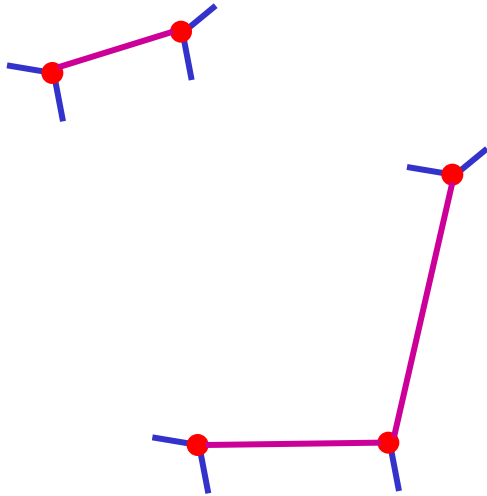
Stable matching :

- start with D_x stubs at each x
- each point x *looks at* closest other point with unused stubs and no edge to x already



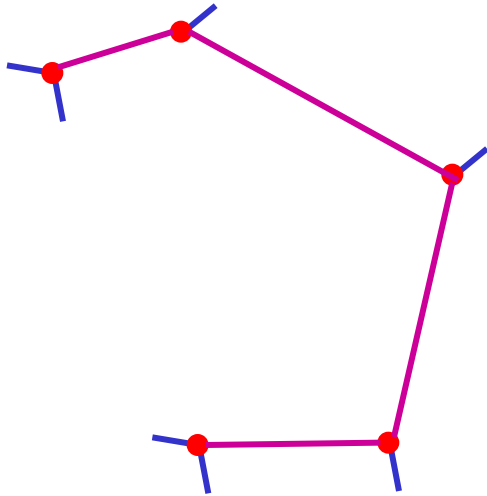
Stable matching:

- start with D stubs at every point
- each point x *looks at* closest other point with unused stubs and no edge to x already
- if x, y are looking at each other, match them, remove one stub from each



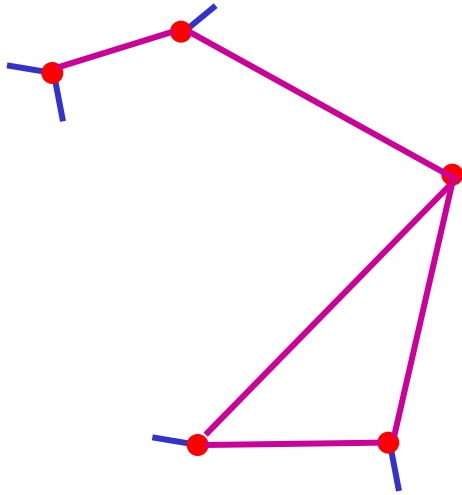
Stable matching:

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- iterate



Stable matching:

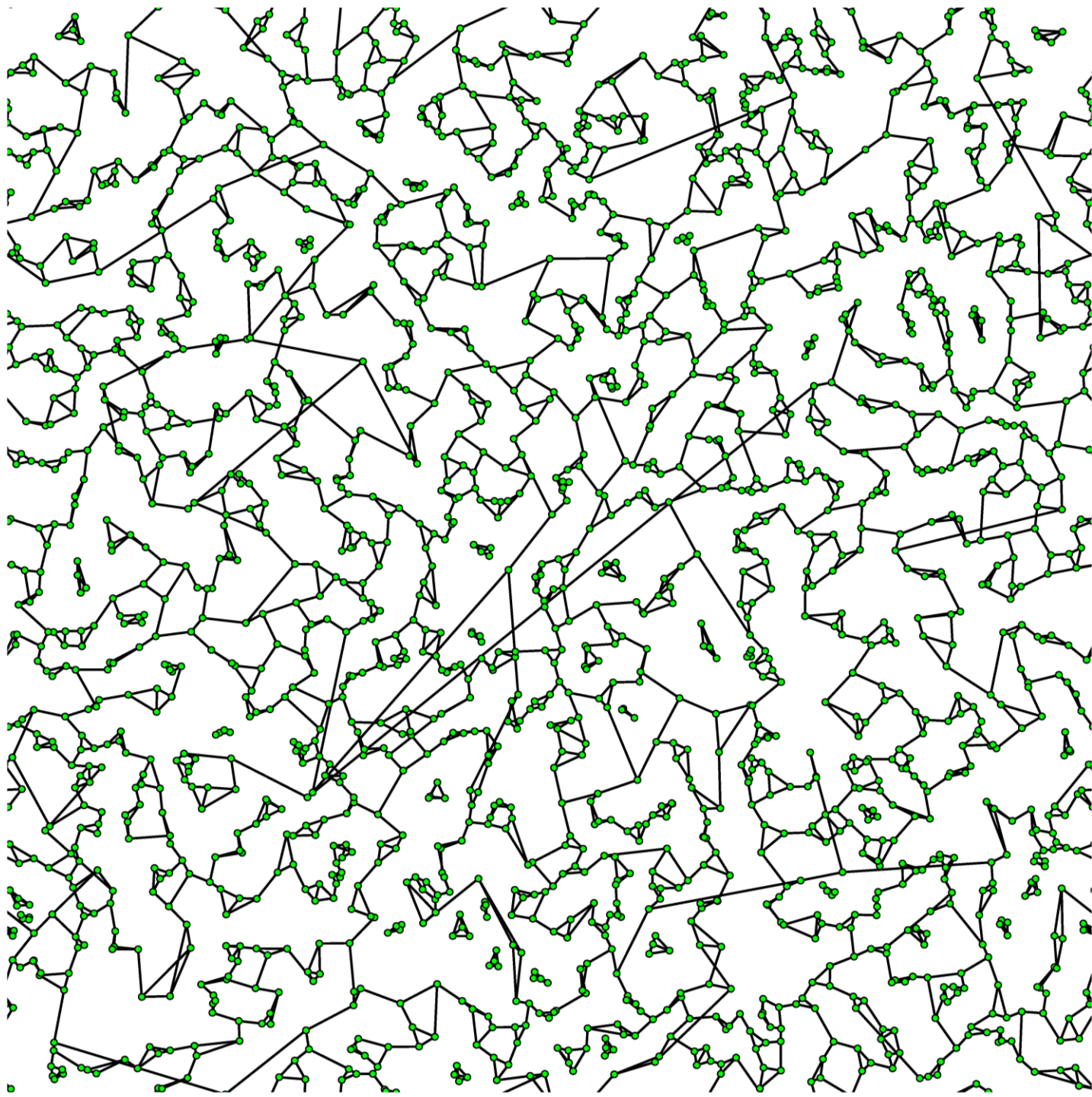
- start with D stubs at every point
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Stable matching:

- start with D stubs at every point
- each point x *looks at* closest other point with unused stubs
and no edge to x already
- if x, y are looking at each other, match them, remove stubs
- iterate

E.g.:
 $\mathbb{R}^2, D=3$

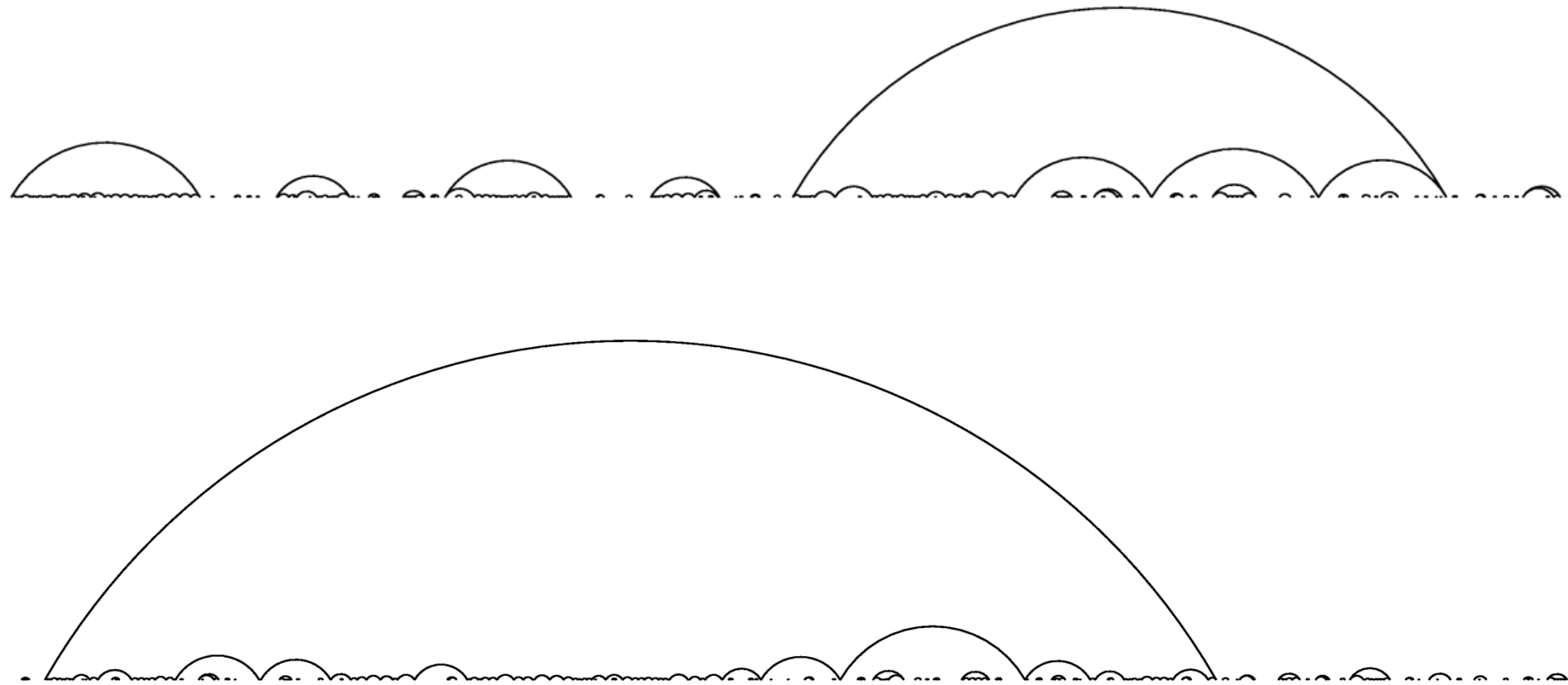


Central question: is there an infinite component

Theorem (Deijfen, Häggstrom, H., 2010)

- **Yes** if $d \geq 2$ and $P(D > k(d)) = 1$
- **No** if $P(D \in \{1, 2\}) = 1$ with $P(D=1) > 0$.

Basic case: $\mathbb{R}^1$, $D=2$:



Is there an infinite path?

not rigorously known in the case, but...

Theorem (Deijfen, H., Peres, 2011)

$\mathbb{R}^1$, $D=2$. For a certain event A_L , defined in terms of Poisson process on the *finite* interval $[0,L]$,

if $P(A_L) > 0.97$ for some L , then

$P(\text{there is an infinite path}) = 1$.

Simulations support $P(A_{13000}) > 0.97$
at the 99.9999% confidence level

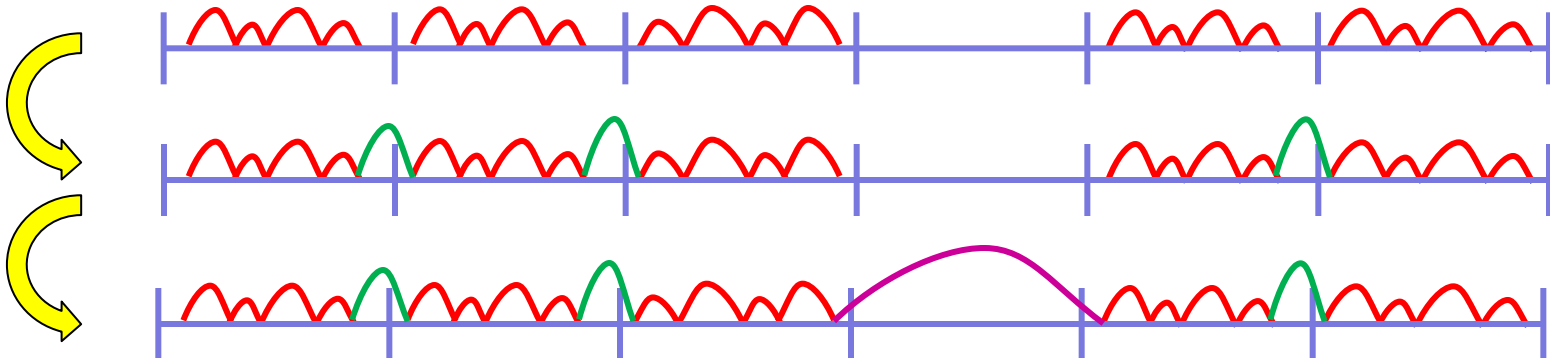
(subject to trusting the software and the
pseudo-random number generator)

In fact:

$A_L = \left\{ \text{there is a connection from } [0, \frac{L}{4}] \text{ to } [\frac{3L}{4}, L] \right.$
in subgraph constructed in $[0, L]$
assuming nothing about $[0, L]^c \left. \right\}$



Proof proceeds by “hooking up” such intervals
on successively larger scales...



Open problems

Non-crossing 2-colour matching in $\mathbb{R}^2$?

Better bounds for 2-colour stable matching?

e.g. $d=2$: $E^* X = \infty$ $P^*(X > r) < C r^{-0.496\dots}$

Infinite component for stable Poisson graph
in $\mathbb{R}$ with degree $D=2$?

Stable multi-colour matching....?