

Biologically Inspired Computing: Neural Computation

Lecture 6

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Lecture 6

- I. Lecture 5 – Revision
- II. Artificial Neural Networks (Part IV)
 - I. Recurrent Artificial Networks
 - I. GasNet models
 - II. Evolving Artificial Neural Networks
 - I. MLPs
 - II. GasNet models

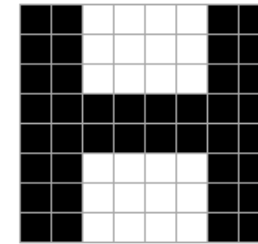
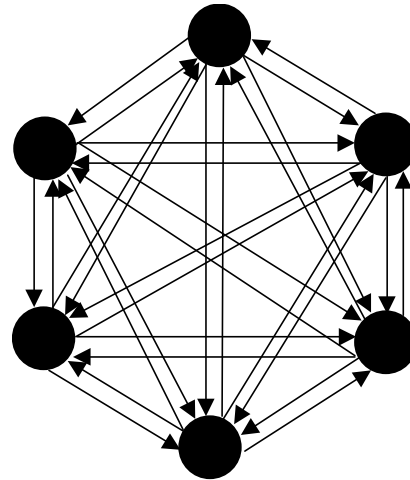
Artificial Neural Networks

Recurrent Neural Networks

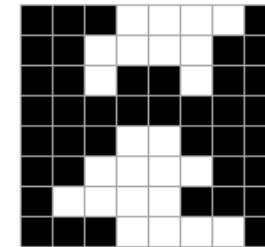
- Hopfield Neural Network

$$w_{ij} = \frac{1}{N} \sum_{k=1}^n p_i^k p_j^k$$

$$s_i = \text{sign} \left(\sum_{j=1}^N w_{ij} s_j \right)$$

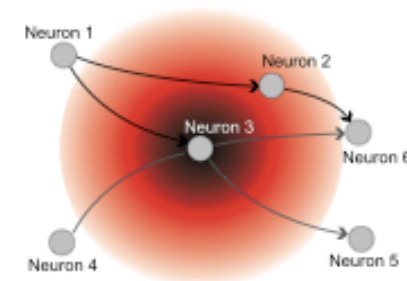
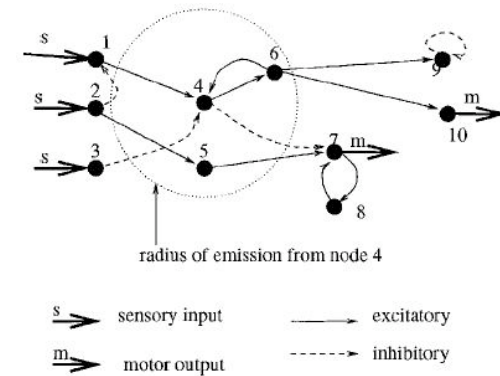
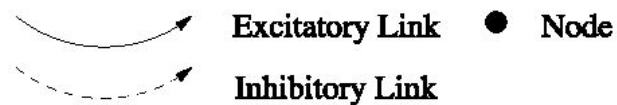
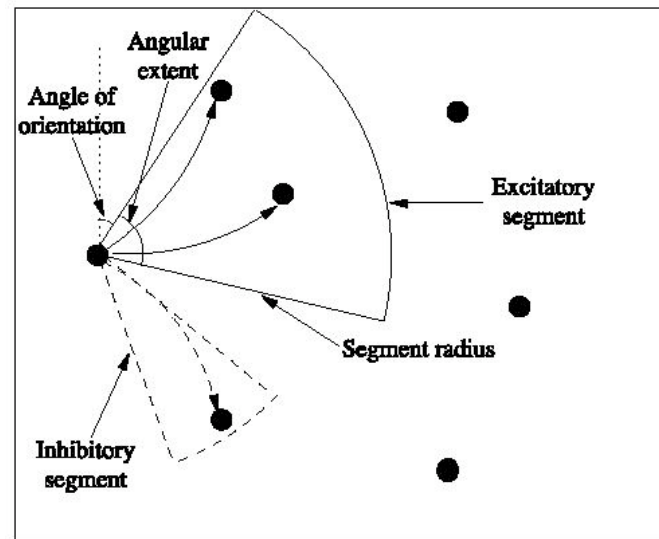
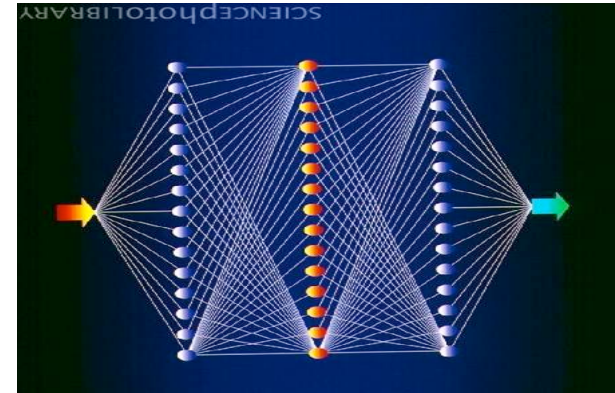
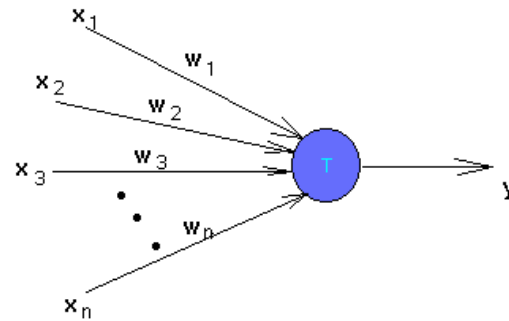
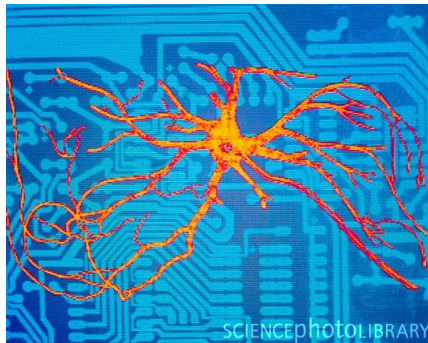


64 pixel image of an "H"



Same image with 10 pixels altered
(I.e. approximately 16% noise added)

GasNet Models x Classical ANN





GasNet models

Original

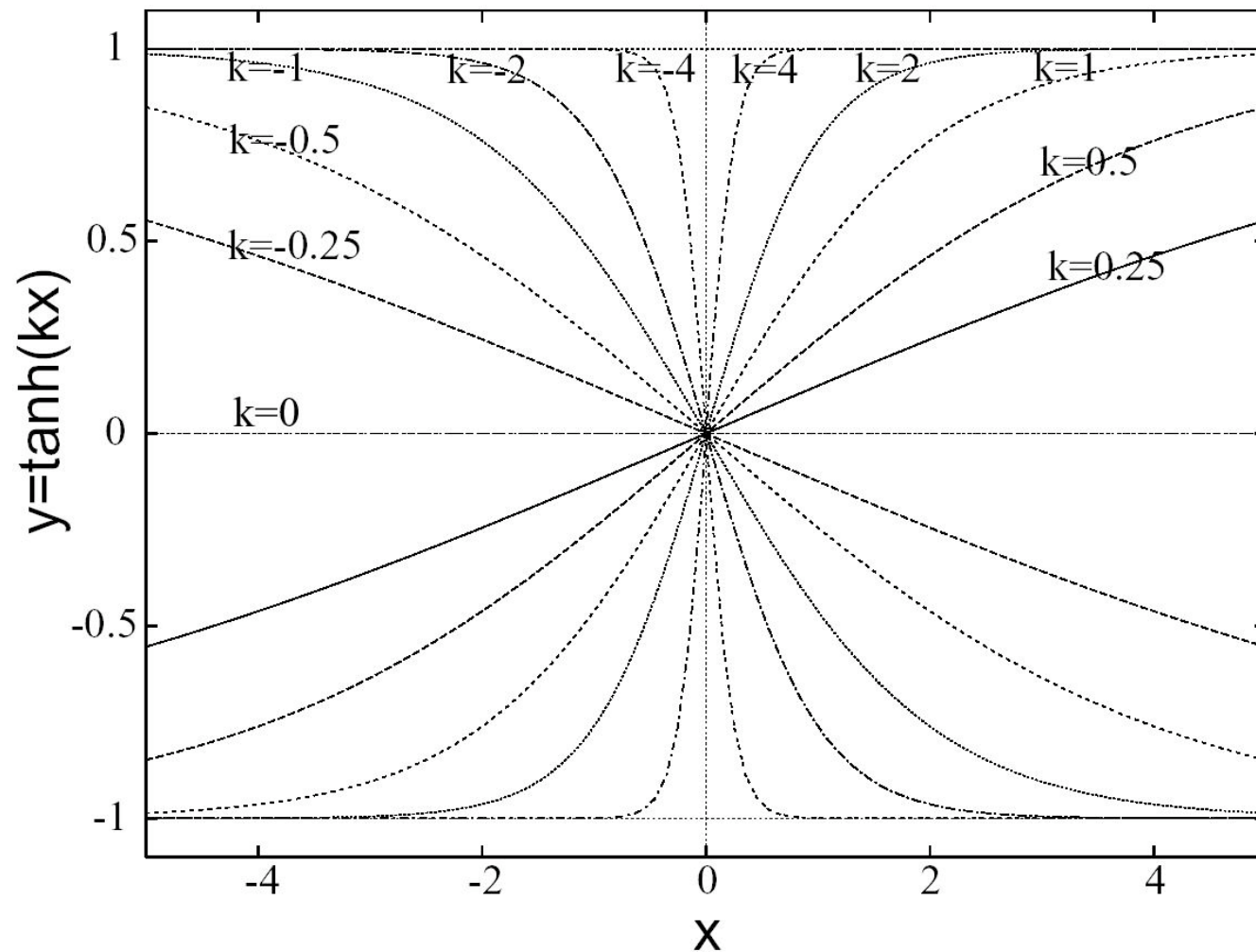
Plexus

Receptor

NSGasNet

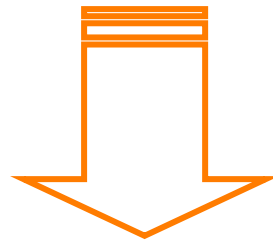
Original Model

$$O_i^n = \tanh \left[k_i^n \left(\sum_{j \in C_i} w_{ji} O_j^{n-1} + I_i^n \right) + b_i \right] \quad k_i^n = k_i^0 + \alpha C_1^n - \beta C_2^n$$



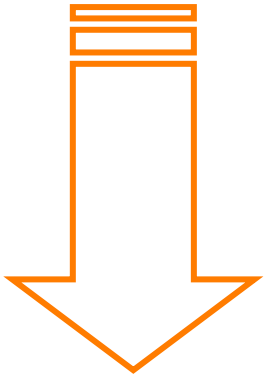
Original Model

$$k_i^n = k_i^0 + \alpha C_1^n - \beta C_2^n$$



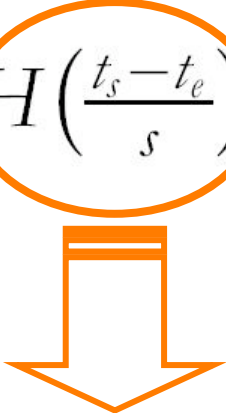
$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$

Original Model

$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$


$$T(t) = \begin{cases} H\left(\frac{t-t_e}{s}\right), & \text{emitting} \\ H\left[H\left(\frac{t_s-t_e}{s}\right) - H\left(\frac{t-t_s}{s}\right)\right], & \text{not emitting} \end{cases}$$

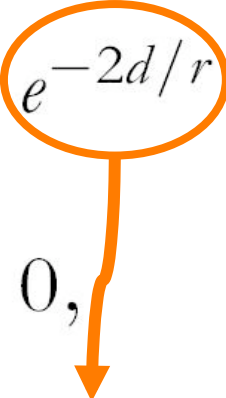
Original Model

$$T(t) = \begin{cases} H\left(\frac{t-t_e}{s}\right), & \text{emitting} \\ H\left[H\left(\frac{t_s-t_e}{s}\right) - H\left(\frac{t-t_s}{s}\right)\right], & \text{not emitting} \end{cases}$$


$$H(x) = \begin{cases} 0, & x \leq 0 \\ x, & 0 < x < 1 \\ 1, & \text{else} \end{cases}$$

Plexus Model

Gas dispersion NOT centred on the node

$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$


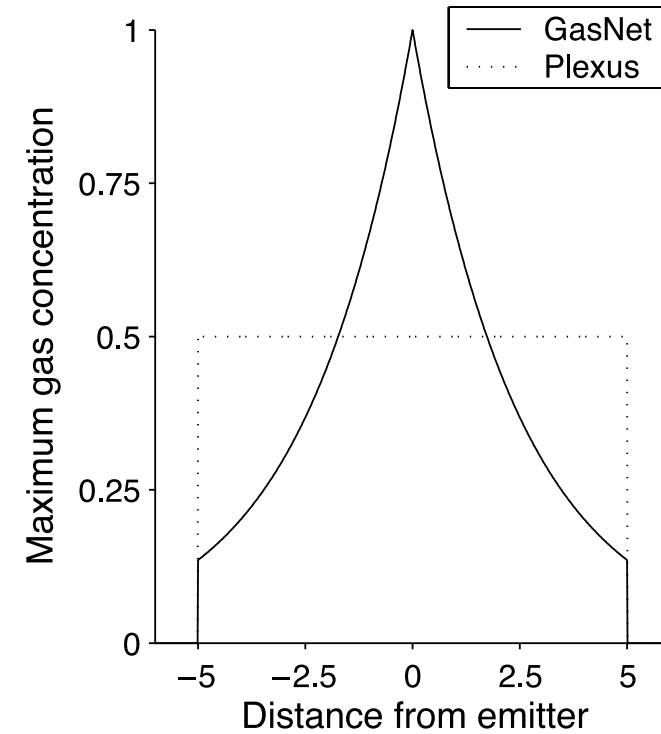
$$C(d, t) = \begin{cases} 0.5 \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$

Original X Plexus

Gas Concentration around emitter

$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$

$$C(d, t) = \begin{cases} 0.5 \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$

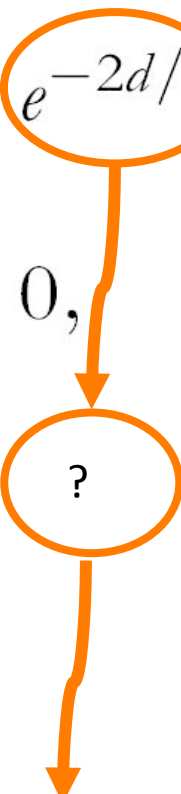


Receptor Model

$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$

$$\Delta M_j^n = \rho_i C_i^n R_j$$

Nodes do NOT have a spatial relation

$$C(d, t) = \begin{cases} e^{-2d/r} \times T(t), & d < r \\ 0, & \text{else} \end{cases}$$


The diagram consists of an orange circle containing the term $e^{-2d/r}$ from the equation above. A vertical orange arrow points down from this circle to another orange circle containing a question mark. A second vertical orange arrow points down from the question mark circle towards the text below.

$[0,1]$ is called the *Mbias* or Modulator Bias

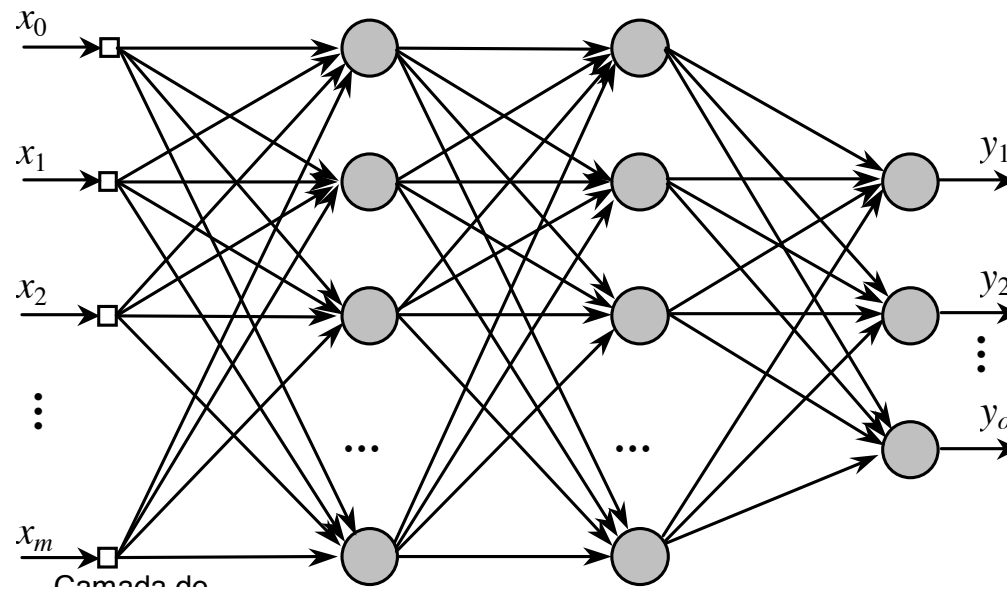
Artificial Neural Networks

I. Evolving Artificial Neural Networks

I. MLPs

I. Topology and weights

II. Example: Evolving (training) MLPs to learn some functions



Artificial Neural Networks

I. Evolving Artificial Neural Networks

I. GasNet models

- I. Topology + all network parameters + task dependent parameters

$\langle genotype \rangle :: (\langle genes \rangle)$

$\langle gene \rangle = \langle node \rangle$

I. Evolving GasNets models - Original

Node variables	Description	[Range]DiscreteValues	Gene locus	Description
Coordinates	Node coordinates on the Euclidean plane (100x100)	[0, 99]	$\langle x \rangle$	$\langle x \text{ value} \rangle$
		[0, 99]	$\langle y \rangle$	$\langle y \text{ value} \rangle$
Electrical connectivity	Defines the parameters of the two segments of circle centred on the node that will determine the excitatory and inhibitory links	[0, 50]	$\langle r_p \rangle$	$\langle radius \rangle$
		[0, 2π]	$\langle r_p \rangle$	$\langle angular \text{ extent} \rangle$
			$\langle \theta_e \rangle$	
			$\langle \theta_e \rangle$	
			$\langle \theta_p \rangle$	$\langle orientation \rangle$
			$\langle \theta_p \rangle$	
Recurrence status	Determines whether the node has an inhibitory, none or excitatory recurrent connection	{-1,0,1}	$\langle rec \rangle$	$\langle recurrent \text{ status} \rangle$
Emitting status	Determines the circumstances under which the node will emit gas {none, electrical, gas}	{0,1,2}	$\langle E_s \rangle$	$\langle emitting \text{ status} \rangle$
Type of gas	Determines which gas the node will emit	{1, 2}	$\langle G_t \rangle$	$\langle gas \text{ type} \rangle$
Rate of build up/decay	Determines the rate of gas build up and decay	[1, 11]	$\langle s \rangle$	$\langle build \text{ up/decay rate} \rangle$
Radius of emission	Maximum radius of gas emission	[10%,60%]* * of plane dimension 100x100	$\langle G_r \rangle$	$\langle gas \text{ radius} \rangle$
Transfer function parameter default value K_i^0	Used in (2) to determine the transfer parameter value K_i^n	[1, 11]	$\langle K^0 \rangle$	$\langle transfer \text{ function default value} \rangle$
Bias	The b_i term ? on 1	[-1.0, 1.0]	$\langle b \rangle$	$\langle bias \text{ value} \rangle$
Task parameters	Parameters which depend on the task, e.g. a robot vision sensors input area ([1])	?	$\langle ? \rangle$	?

I. Evolving GasNets models - NSGasNet

Node variables	Description	[Range] DiscreteValues	Gene locus	Description
Recurrence status	Determines whether the node has an inhibitory, none or excitatory recurrent connection	$\{-1,0,1\}$	$\langle rec \rangle$	$\langle recurrent\ status \rangle$
Emitting status	Determines the circumstances under which the node will emit gas {none, electrical, gas}	$\{0,1,2\}$	$\langle E_s \rangle$	$\langle emitting\ status \rangle$
Type of gas	Determines which gas the node will emit	$\{1, 2\}$	$\langle G_t \rangle$	$\langle gas\ type \rangle$
Rate of build up/ decay	Determines the rate of gas build up and decay	$[1, 11]$	$\langle s \rangle$	$\langle build\ up/decay\ rate \rangle$
Transfer function parameter default value K_i^0	Used in (2) to determine the transfer parameter value K_i^n	$[1, 11]$	$\langle K^0 \rangle$	$\langle transfer\ function\ default\ value \rangle$
Bias	The term b_i on 1	$[-1.0, 1.0]$	$\langle b \rangle$	$\langle bias\ value \rangle$
Task parameters	Parameters which depend on the task, e.g. a robot vision sensors input area ([1])	?	$\langle ? \rangle$	?
Modulator Bias ($Mbias_n$)	Parameter which depend on the number of nodes, i.e. there will be as many $Mbias$ as the number of network nodes	$[0, 1]$	$\langle Mbias_n \rangle$	$\langle Modulator\ bias\ for\ node\ n \rangle$

Lecture 6

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- Vargas, P.A.**, Di Paolo, E. A. & Husbands, P. (2007). "Preliminary Investigations on the Evolvability of a Non-spatial GasNet Model". In *Proceedings of the 9th European Conference on Artificial life, ECAL'2007*, Springer-Verlag, Lisbon, Portugal, September 2007, pp: 966-975.
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- Husbands, P., Philippides, A., **Vargas, P. A.**, Buckley, C, Fine, P., Di Paolo, E. & O'Shea, M. (2011). "Spatial, Temporal and Modulatory Factors affecting GasNet Evolvability", *Complexity* 16(2):35-44, Wiley Periodicals, Inc. (invited paper).

Lecture 6

- I. Artificial Neural Networks (Part IV)
 - I. Recurrent Neural Networks
 - I. GasNet Models
 - II. Evolving ANN
 - I. MLP
 - II. GasNet models