

**Generalised β -reduction and explicit
substitutions**
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Abstract. Extending the λ -calculus with either explicit substitution or generalised reduction has been the subject of extensive research recently which still has many open problems. Due to this reason, the properties of a calculus combining both generalised reduction and explicit substitutions have never been studied. This paper presents such a calculus λsg and shows that it is a desirable extension of the λ -calculus. In particular, we show that λsg preserves strong normalisation, is sound and it simulates classical β -reduction. Furthermore, we study the simply typed λ -calculus extended with both generalised reduction and explicit substitution and show that well-typed terms are strongly normalising and that other properties such as subtyping and subject reduction hold.

1 Introduction

1.1 The λ -calculus with generalised reduction

In $((\lambda_x.\lambda_y.N)P)Q$, the function starting with λ_x and the argument P result in the redex $(\lambda_x.\lambda_y.N)P$ which when contracted will turn the function starting with λ_y and Q into a redex. This fact has been exploited by many researchers and reduction has been extended so that the future redex based on the matching λ_y and Q is given the same priority as the other redex. Attempts at generalising reduction can be summarized by three axioms:

$$\begin{array}{ll} (\theta) & ((\lambda_x.N)P)Q \rightarrow (\lambda_x.NQ)P, & (\gamma) & (\lambda_x.\lambda_y.N)P \rightarrow \lambda_y.(\lambda_x.N)P, \\ & & (\gamma_C) & ((\lambda_x.\lambda_y.N)P)Q \rightarrow (\lambda_y.(\lambda_x.N)P)Q. \end{array}$$

These rules attempt to make more redexes visible. γ_C e.g., makes sure that λ_y and Q form a redex even before the redex based on λ_x and P is contracted. By compatibility, γ implies γ_C . Moreover, $((\lambda_x.\lambda_y.N)P)Q \rightarrow_\theta (\lambda_x.(\lambda_y.N)Q)P$ and hence both θ and γ_C put λ adjacently next to its matching argument. θ

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moves the argument next to its matching λ whereas γ_C moves the λ next to its matching argument. θ can be equally applied to explicitly and implicitly typed systems. The transfer of γ or γ_C to explicitly typed systems is not straightforward however, since in these systems, the type of y may be affected by the reducible pair λ_x, P . E.g., it is fine to write $((\lambda_{x:*.}\lambda_{y:x.}y)z)u \rightarrow_{\theta} (\lambda_{x:*.}(\lambda_{y:x.}y)u)z$ but not to write $((\lambda_{x:*.}\lambda_{y:x.}y)z)u \rightarrow_{\gamma_C} (\lambda_{y:x.}(\lambda_{x:*.}y)z)u$. Hence, we study θ -like rules in this paper. Now, we discuss where generalised reduction has been used (cf. [24]).

[32] introduces the notion of a *premier redex* which is similar to the redex based on λ_y and Q above (which we call *generalised redex*). [33] uses θ and γ (and calls the combination σ) to show that the perpetual reduction strategy finds the longest reduction path when the term is Strongly Normalising (SN). [37] also introduces reductions similar to those of [33]. Furthermore, [22] uses θ (and other reductions) to show that typability in ML is equivalent to acyclic semi-unification. [35] uses a reduction which has some common themes with θ . [30] and [11] use θ whereas [25] uses γ to reduce the problem of β -strong normalisation to the problem of weak normalisation (WN) for related reductions. [23] uses θ and γ to reduce typability in the rank-2 restriction of the 2nd order λ -calculus to the problem of acyclic semi-unification. [27, 38, 36, 26] use related reductions to reduce SN to WN and [21] uses similar notions in SN proofs. [2] uses θ (called “let-C”) as a part of an analysis of how to implement sharing in a real language interpreter in a way that directly corresponds to a formal calculus. [16] uses a more extended version of θ where Q and N are not only separated by the redex $(\lambda_x.N)P$ but by many redexes (ordinary and generalised). [16] shows that generalised reduction makes more redexes visible allowing flexibility in reducing a term. [6] shows that with generalised reduction one may indeed avoid size explosion without the cost of a longer reduction path and that λ -calculus can be elegantly extended with definitions which result in shorter type derivations. Generalised reduction is strongly normalising (cf. [6]) for all systems of the cube (cf. [3]) and preserves strong normalisation of classical reduction (cf. [13]).

1.2 The λ -calculus with explicit substitution

Functional programming and in particular partial evaluation may benefit from explicit substitution. For example, given $xx[x := y]$, we may not be interested in having yy as the result of $xx[x := y]$ but rather only $yx[x := y]$. In other words, we only substitute one occurrence of x by y and continue the substitution later. This issue of being able to follow substitution and decide how much to do and how much to postpone, has become a major one in functional language implementation (cf. [31]). Another wish is to execute substitutions only when necessary. For this purpose one may decide to postpone substitutions as long as possible (“lazy evaluations”). This can yield profits, since substitution is an inefficient, maybe even exploding, process by the many repetitions it causes. This is the ground for the so-called graph reduction (cf. [31]). Most theorem provers (Nuprl [7], Coq [12]) use explicit substitutions in their implementation in order to replace locally (rather than globally) some abbreviated term. This

avoids explosion when it is necessary that a variable be replaced by a huge term only in specific places so that a certain theorem can be proved.

Most literature on the λ -calculus considers substitution as an implicit operation: the computations to perform substitution are usually described with operators which do not belong to the language of the λ -calculus. The last fifteen years have seen an interest in formalising substitution explicitly; various calculi including new operators to denote substitution have been proposed. Amongst these calculi we mention $C\lambda\xi\phi$ (cf. [10]); the calculi of categorical combinators (cf. [8]); $\lambda\sigma$, $\lambda\sigma_{\uparrow}$, $\lambda\sigma_{SP}$ (cf. [1, 9, 34]) referred to as the $\lambda\sigma$ -family; $\lambda\nu$ (cf. [4]), a descendant of the $\lambda\sigma$ -family; $\varphi\sigma BLT$ (cf. [15]), $\lambda\mathbf{exp}$ (cf. [5]), λs (cf. [17]), λs_e (cf. [19]) and $\lambda\zeta$ (cf. [29]). All these calculi (except $\lambda\mathbf{exp}$) are described in a de Bruijn setting where natural numbers play the role of the classical variables.

In [17], we extended the λ -calculus with explicit substitutions by turning de Bruijn’s meta-operators into object-operators offering a style of explicit substitution that differs from that of $\lambda\sigma$. The resulting calculus λs remains as close as possible to the λ -calculus from an intuitive point of view. The main interest in introducing the λs -calculus (cf. [17]) was to provide a calculus of explicit substitutions which would both preserve strong normalisation and have a confluent extension on open terms (cf. [19]). There are calculi of explicit substitutions which are confluent on open terms: the $\lambda\sigma_{\uparrow}$ -calculus (cf. [9]), but the non-preservation of strong normalisation for $\lambda\sigma_{\uparrow}$, for the rest of the $\lambda\sigma$ -family and for the categorical combinators, has been proved (cf. [28]). There are also calculi which satisfy the preservation property: the $\lambda\nu$ -calculus (cf. [4]), but this calculus is not confluent on open terms. Recently, the $\lambda\zeta$ -calculus (cf. [29]) has been proposed as a calculus which preserves strong normalisation and is itself confluent on open terms. It works with two new applications that allow the passage of substitutions within classical applications only if these applications have a head variable. This is done to cut the branch of the critical pair which is responsible for the non-confluence of $\lambda\nu$ on open terms. Unfortunately, $\lambda\zeta$ is not able to simulate one step β -reduction as shown in [29], it simulates only a “big step” β -reduction. This lack of the simulation property is an uncommon feature among calculi of explicit substitutions. On the other hand, λs has been extended to λs_e which is confluent on open terms (cf. [19]) and simulates one step β -reduction but the preservation of strong normalisation is still an open problem.

1.3 Combining generalised reduction and explicit substitution

All the research mentioned above is a living proof for the importance and usefulness of generalised reduction and explicit substitutions. Moreover, a system where reduction is generalised and substitution is explicit, gives a more flexible way of evaluating programs thanks to the advantages of step-wise substitution and the ability of reducing more redexes.

Before such a combination can be used as a powerful basis for programming, we need to check that this combination is sound and safe exactly like we checked that each of explicit substitutions and generalised reductions are sound and safe.

This paper shows that extending the λ -calculus with both concepts results in theories that are confluent, preserve termination, and simulate β -reduction.

Generalised reduction $g\beta$, has never been introduced in a de Bruijn setting. Explicit substitution, has almost always been presented in a de Bruijn setting. For this reason, we combine $g\beta$ -reduction and explicit substitution in a de Bruijn setting giving the first calculus of generalised reduction à la de Bruijn. As we need to describe generalised redexes in an elegant way, we use a notation suitable for this purpose *the item notation* (cf. [14]).

In Section 2 we introduce the calculus of generalised reduction, the λg -calculus, in item notation with de Bruijn indices and prove its confluence.

In Section 3 we extend the λs -calculus with $\rightarrow_{g\beta}$ into the λsg -calculus. We show that λsg is sound with respect to λg , simulates $g\beta$ and is confluent.

In Section 4 we prove that the λsg -calculus preserves λs -strong normalisation and conclude that a is λ -SN $\Leftrightarrow a$ is λs -SN $\Leftrightarrow a$ is λg -SN $\Leftrightarrow a$ is λsg -SN.

In Section 5 the simply typed versions of the λs - and λsg -calculi are presented and subject reduction, subtyping, and SN of well typed terms are proved.

This article is an abridged version of [20], where more detailed proofs are given.

2 The λg -calculus

We assume familiarity with de Bruijn notation. Since generalised β -reduction is easily described in item notation, we adopt the item syntax (cf. [16, 14] for the advantages of item notation) and write ab as $(b\delta)a$ and $\lambda.a$ as $(\lambda)a$.

Definition 1 *The set of terms A , is defined as follows: $A ::= \mathbb{N} | (A\delta)A | (\lambda)A$. We let a, b, \dots range over A and m, n, \dots over \mathbb{N} (positive natural numbers). $a = b$ means that a and b are syntactically identical. We write $a \triangleleft b$ when a is a subterm of b . We assume the usual definition of compatibility.*

$(\lambda x\lambda y.zxy)(\lambda x.yx) \rightarrow_{\beta} \lambda u.z(\lambda x.yx)u$ translates to $(\lambda\lambda 521)(\lambda 31) \rightarrow_{\beta} \lambda 4(\lambda 41)1$. Note that we did not simply replace 2 in $\lambda 521$ by $\lambda 31$. Instead, we decreased 5 as one λ disappeared, and incremented the free variables of $\lambda 31$ as they occur within the scope of one more λ . For incrementing the free variables we need updating functions U_k^i , where k tests for free variables and $i - 1$ is the value by which a variable, if free, must be incremented:

Definition 2 $U_k^i : A \rightarrow A$ for $k \geq 0$ and $i \geq 1$ are defined inductively:

$$\begin{aligned} U_k^i((a\delta)b) &= (U_k^i(a)\delta)U_k^i(b) & U_k^i(\mathbf{n}) &= \begin{cases} \mathbf{n} + i - 1 & \text{if } \mathbf{n} > k \\ \mathbf{n} & \text{if } \mathbf{n} \leq k \end{cases} \\ U_k^i((\lambda)a) &= (\lambda)(U_{k+1}^i(a)) \end{aligned}$$

Now we define meta-substitution. The last equality substitutes the intended variable (when $n = j$) by the updated term. If n is not the intended variable, it is decreased by 1 if it is free (case $n > j$) as one λ has disappeared and if it is bound (case $n < j$) it remains unaltered.

Definition 3 The meta-substitutions at level j , for $j \geq 1$, of a term $b \in \Lambda$ in a term $a \in \Lambda$, denoted $a\{\{j \leftarrow b\}\}$, is defined inductively on a as follows:

$$\begin{aligned} ((a_1\delta)a_2)\{\{j \leftarrow b\}\} &= ((a_1\{\{j \leftarrow b\}\})\delta)(a_2\{\{j \leftarrow b\}\}) \\ ((\lambda)c)\{\{j \leftarrow b\}\} &= (\lambda)(c\{\{j+1 \leftarrow b\}\}) \end{aligned} \quad n\{\{j \leftarrow b\}\} = \begin{cases} n-1 & \text{if } n > j \\ U_0^j(b) & \text{if } n = j \\ n & \text{if } n < j \end{cases}$$

The following gives the properties of meta-substitution and updating (cf. [17]):

Lemma 1 Let $a, b, c \in \Lambda$. We have:

1. for $k < n < k+i$: $U_k^{i-1}(a) = U_k^i(a)\{\{n \leftarrow b\}\}$.
2. for $l \leq k < l+j$: $U_k^i(U_l^j(a)) = U_l^{j+i-1}(a)$.
3. for $k+i \leq n$: $U_k^i(a)\{\{n \leftarrow b\}\} = U_k^i(a)\{\{n-i+1 \leftarrow b\}\}$.
4. for $i \leq n$: $a\{\{i \leftarrow b\}\}\{\{n \leftarrow c\}\} = a\{\{n+1 \leftarrow c\}\}\{\{i \leftarrow b\}\}\{\{n-i+1 \leftarrow c\}\}$.
5. for $l+j \leq k+1$: $U_k^i(U_l^j(a)) = U_l^j(U_{k+1-j}^i(a))$.
6. for $n \leq k+1$: $U_k^i(a\{\{n \leftarrow b\}\}) = U_{k+1}^i(a)\{\{n \leftarrow U_{k-n+1}^i(b)\}\}$.

In order to introduce generalised β -reduction we need some definitions (cf. [14]).

Definition 4 Items, segments and well-balanced segments (w.b.) are defined respectively by: $\mathcal{I} ::= (\Lambda\delta) \mid (\lambda) \quad \mathcal{S} ::= \phi \mid \mathcal{I}\mathcal{S} \quad \mathcal{W} ::= \phi \mid (\Lambda\delta)\mathcal{W}(\lambda) \mid \mathcal{W}\mathcal{W}$ where ϕ is the empty segment. Hence, a segment is a sequence of items. $(a\delta)$ and (λ) are called δ - and λ -item respectively. We let I, J, \dots range over \mathcal{I} ; S, S', \dots over \mathcal{S} and W, U, \dots over \mathcal{W} . For a segment S , $\text{lg } S$, is given by: $\text{lg } \phi = 0$, $\text{lg}(IS) = 1 + \text{lg } S$. The number of main λ -items in S , $N(S)$, is given by: $N(\phi) = 0$, $N((a\delta)S) = N(S)$ and $N((\lambda)S) = 1 + N(S)$.

Definition 5 λ -calculus is the reduction system $(\Lambda, \rightarrow_\beta)$, where \rightarrow_β is the least compatible reduction on Λ generated by the β -rule: $(a\delta)(\lambda)b \rightarrow a\{\{1 \leftarrow b\}\}$.

Definition 6 Generalised β , $\rightarrow_{g\beta}$, is the least compatible reduction on Λ generated by the $g\beta$ -rule: $(a\delta)W(\lambda)b \rightarrow W(b\{\{1 \leftarrow U_0^{N(W)+1}(a)\}\})$ where W is w.b. The λg -calculus is the reduction system $(\Lambda, \rightarrow_{g\beta})$.

Remark 1 The β -rule is an instance of the $g\beta$ -rule.

Proof: Take $W = \phi$ and check $U_0^1(a) = a$. □

Now, let us briefly explain the relation between $\rightarrow_{g\beta}$ and $\rightarrow_\theta, \rightarrow_\gamma, \rightarrow_{\gamma C}$ given in the introduction. As \rightarrow_γ implies $\rightarrow_{\gamma C}$, we ignore the latter. It would be helpful if we write \rightarrow_θ and \rightarrow_γ in item notation:

$$(Q\delta)(P\delta)(\lambda_x)N \rightarrow_\theta (P\delta)(\lambda_x)(Q\delta)N \quad (P\delta)(\lambda_x)(\lambda_y)N \rightarrow_\gamma (\lambda_y)(P\delta)(\lambda_x)N$$

Note how in \rightarrow_θ , the start of a redex $(P\delta)(\lambda_x)$ is moved (or reshuffled) giving $(Q\delta)$ the chance to find its matching (λ) in N . In \rightarrow_γ the same happens but now it is (λ_y) which is given the chance to look for its matching $(-\delta)$. Only once reshuffling has taken place, can the newly found redex be contracted. $\rightarrow_{g\beta}$ on the other hand avoids reshuffling and contracts the redex as soon as it sees the matching of δ and λ .

We define segments' updating and meta-substitution and prove some properties.

Definition 7 Let $S \in \mathcal{S}$, $a, b \in \Lambda$, $k \geq 0$ and $n, i \geq 1$.

We define $U_k^i(S)$ and $S\{\mathbf{n} \leftarrow a\}$ by:

$$\begin{aligned} U_k^i(\phi) &= \phi & \phi\{\mathbf{n} \leftarrow a\} &= \phi \\ U_k^i((b \delta)S) &= (U_k^i(b) \delta)U_k^i(S) & ((b \delta)S)\{\mathbf{n} \leftarrow a\} &= (b\{\mathbf{n} \leftarrow a\} \delta)(S\{\mathbf{n} \leftarrow a\}) \\ U_k^i((\lambda)S) &= (\lambda)(U_{k+1}^i(S)) & ((\lambda)S)\{\mathbf{n} \leftarrow a\} &= (\lambda)(S\{\mathbf{n}+1 \leftarrow a\}) \end{aligned}$$

Lemma 2 Let S, T be segments and $a, b \in \Lambda$. The following hold:

1. $U_k^i(ST) = U_k^i(S)U_{k+N(S)}^i(T)$ and $U_k^i(Sa) = U_k^i(S)U_{k+N(S)}^i(a)$
2. $\lg(S) = \lg(U_k^i(S))$, $N(S) = N(U_k^i(S))$ and if S w.b. then $U_k^i(S)$ w.b.
3. $(S \xi)\{\mathbf{n} \leftarrow a\} = S\{\mathbf{n} \leftarrow a\} \xi\{\mathbf{n} + N(S) \leftarrow a\}$ for ξ a segment or a term
4. If $r \in \{\lg, N\}$ then $r(S) = r(S\{\mathbf{n} \leftarrow a\})$. If S w.b. then $S\{\mathbf{n} \leftarrow a\}$ w.b.

Proof: All by induction on S . For 2. and 4. use 1. and 3. respectively. \square

Lemma 3 Let $a, b \in \Lambda$. If $a \rightarrow_{g\beta} b$ then $a =_\beta b$.

Proof: First prove by induction on a that $a \rightarrow_{g\beta} b$ implies $a =_\beta b$. To show the case $(c\delta)W(\lambda)d \rightarrow_{g\beta} W(d\{\mathbf{1} \leftarrow U_0^{N(W)+1}(c)\})$ use induction on $\lg W$. \square

Theorem 1 (Confluence of λg) The λg -calculus is confluent.

Proof: Use Lemma 3 and Remark 1 (cf. [16]). \square

Next, we ensure the good passage of $g\beta$ -reduction through $\{\mathbf{n} \leftarrow a\}$ and U_k^i :

Lemma 4 Let $a, b, c, d \in \Lambda$. The following hold:

1. If $c \rightarrow_{g\beta} d$ then $U_k^i(c) \rightarrow_{g\beta} U_k^i(d)$.
2. If $c \rightarrow_{g\beta} d$ then $a\{\mathbf{n} \leftarrow c\} \rightarrow_{g\beta} a\{\mathbf{n} \leftarrow d\}$.
3. If $a \rightarrow_{g\beta} b$ then $a\{\mathbf{n} \leftarrow c\} \rightarrow_{g\beta} b\{\mathbf{n} \leftarrow c\}$.

Proof: 1. By induction on c . 2. and 3. By induction on a . \square

3 The λs - and λsg -calculi

The idea is to handle explicitly the meta-operators of definitions 2 and 3. Hence, the syntax of the λs -calculus is obtained by adding two families of operators:

1. Explicit substitution operators $\{\sigma^j\}_{j \geq 1}$ where $(b \sigma^j)a$ stands for a where all free occurrences of the variable representing j are to be substituted by b .
2. Updating operators $\{\varphi_k^i\}_{k \geq 0, i \geq 1}$ needed for working with de Bruijn indices.

Definition 8 The set of terms, noted As , of the λs -calculus is given as follows:

$$As ::= \mathbb{N} \mid (As \delta)As \mid (\lambda)As \mid (As \sigma^j)As \mid (\varphi_k^i)As \quad \text{where } j, i \geq 1, k \geq 0.$$

We let a, b, c range over As . A term $(a \sigma^j)b$ is called a closure. Furthermore, a term containing neither σ 's nor φ 's is called a pure term. \mathcal{A} denotes the set of pure terms. $\delta\lambda$ -segments are those whose main items are either δ - or λ -items, i.e. $\mathcal{DL} ::= \phi \mid (As \delta)\mathcal{DL} \mid (\lambda)\mathcal{DL}$. Compatibility is extended by adding:

$$(a \sigma^j)c \rightarrow (b \sigma^j)c, (c \sigma^j)a \rightarrow (c \sigma^j)b \text{ and } (\varphi_k^i)a \rightarrow (\varphi_k^i)b \text{ whenever } a \rightarrow b.$$

Definition 9 Items, segments and well-balanced segments for λ_s are defined as follows: $\mathcal{I}s ::= (As \delta) \mid (\lambda) \mid (As \sigma^j) \mid (\varphi_k^i)$ $\mathcal{S}s ::= \phi \mid \mathcal{I}s \mathcal{S}s$
 $\mathcal{W}s ::= \phi \mid (As \delta) \mathcal{W}s(\lambda) \mid \mathcal{W}s \mathcal{W}s$

We let I, J, \dots range over $\mathcal{I}s$; S, S', \dots over $\mathcal{S}s$ and W, U, \dots over $\mathcal{W}s$. We call $(a \sigma^j)$ and (φ_k^i) , σ - and φ -item respectively. $\text{lg}(S)$ is trivially extended to $S \in \mathcal{S}s$ and $N(S)$ is extended by: $N((a \sigma^j)S) = N(S)$ and $N((\varphi_k^i)S) = N(S)$.

As the λ_s -calculus updates and substitutes explicitly, we include a set of rules which are the equations in definitions 2 and 3 oriented from left to right.

Definition 10 The λ_s -calculus is the reduction system $(\lambda_s, \rightarrow_{\lambda_s})$, where \rightarrow_{λ_s} is the least compatible reduction on λ_s generated by the following rules:

<i>σ-generation</i>	$(b \delta)(\lambda)a \longrightarrow (b \sigma^1)a$
<i>σ-λ-transition</i>	$(b \sigma^j)(\lambda)a \longrightarrow (\lambda)(b \sigma^{j+1})a$
<i>σ-app-transition</i>	$(b \sigma^j)(a_1 \delta)a_2 \longrightarrow ((b \sigma^j)a_1 \delta)(b \sigma^j)a_2$
<i>σ-destruction</i>	$(b \sigma^j)\mathbf{n} \longrightarrow \begin{cases} \mathbf{n} - 1 & \text{if } n > j \\ (\varphi_0^j)b & \text{if } n = j \\ \mathbf{n} & \text{if } n < j \end{cases}$
<i>φ-λ-transition</i>	$(\varphi_k^i)(\lambda)a \longrightarrow (\lambda)(\varphi_{k+1}^i)a$
<i>φ-app-transition</i>	$(\varphi_k^i)(a_1 \delta)a_2 \longrightarrow ((\varphi_k^i)a_1 \delta)(\varphi_k^i)a_2$
<i>φ-destruction</i>	$(\varphi_k^i)\mathbf{n} \longrightarrow \begin{cases} \mathbf{n} + i - 1 & \text{if } n > k \\ \mathbf{n} & \text{if } n \leq k \end{cases}$

We use λ_s to denote this set of rules. The calculus of substitutions associated with the λ_s -calculus is the reduction system generated by the set of rules $s = \lambda_s - \{\sigma\text{-generation}\}$ and we call it the s -calculus.

The λ_{sg} -calculus is the calculus whose set of rules is $\lambda_{sg} = \lambda_s + \{g\sigma\text{-generation}\}$:

$$g\sigma\text{-generation} \quad (b \delta)W(\lambda)a \longrightarrow W((\varphi_0^{N(W)+1})b \sigma^1)a \quad W \text{ w.b.}, W \neq \phi$$

Note that in the λ_{sg} -calculus we do not merge σ -generation and $g\sigma$ -generation in a new $g\sigma$ -generation which admits $W = \phi$ because in that case we would obtain, when $W = \phi$, the rule $(b \delta)(\lambda)a \rightarrow ((\varphi_0^1 b) \sigma^1)a$, and this is not a generalisation of the original σ -generation of the λ_s -calculus.

σ -generation starts β -reduction by generating a substitution operator (σ^1) . σ -app and σ - λ allow this operator to travel throughout the term until its arrival to the variables. If a variable should be affected by the substitution, σ -destruction (case $j = n$) carries out the substitution by the updated term, thus introducing the updating operators. Finally the φ -rules compute the updating. We state now the following theorem of the λ_s -calculus (cf. [19]).

Theorem 2 The s -calculus is strongly normalising and confluent on λ_s , hence s -normal forms are unique. The set of s -normal forms is exactly Λ . If $s(a)$

denotes the s -normal form of a , then for $a, b \in \Lambda s$: $s((a \delta)b) = (s(a) \delta)s(b)$, $s((\lambda)a) = (\lambda)(s(a))$, $s((\varphi_k^i)a) = U_k^i(s(a))$ and $s((b \sigma^j)a) = s(a)\{\! \{ j \leftarrow s(b) \} \}$.

Lemma 5 *Let $a, b \in \Lambda s$, if $a \rightarrow_{(g)\sigma\text{-gen}} b$ then $s(a) \rightarrow_{(g)\beta} s(b)$.*

Proof: Induction on a using Lemma 4 and Theorem. 2. For the case with g , note that if W is w.b then $s(W a) = s(W)s(a)$, where the s -nf of a $\delta\lambda$ -segment is given by: $s(\phi) = \phi$, $s((a \delta)S) = (s(a) \delta)s(S)$ and $s((\lambda)S) = (\lambda)s(S)$. \square

Corollary 1 *Let $a, b \in \Lambda s$, if $a \rightarrow_{\lambda s g} b$ then $s(a) \rightarrow_{g\beta} s(b)$.*

Corollary 2 (Soundness) *Let $a, b \in \Lambda$, if $a \rightarrow_{\lambda s g} b$ then $a \rightarrow_{g\beta} b$.*

Hence, the $\lambda s g$ -calculus is correct w.r.t. the λg -calculus, i.e. $\lambda s g$ -derivations of pure terms ending with pure terms can also be derived in the λg -calculus.

Moreover, the $\lambda s g$ -calculus is powerful enough to simulate $g\beta$ -reduction.

Lemma 6 (Simulation of $\rightarrow_{g\beta}$) *Let $a, b \in \Lambda$, if $a \rightarrow_{g\beta} b$ then $a \rightarrow_{\lambda s g} b$.*

Proof: Induction on a using Lemma 4. \square

Theorem 3 (Confluence of $\lambda s g$) *The $\lambda s g$ -calculus is confluent on Λs .*

Proof: Use the interpretation method (cf. [9]), Corollary 1, confluence of the λg -calculus and Lemma 6. \square

4 The $\lambda s g$ -calculus preserves λs -SN

The technique used here to prove preservation of strong normalisation (PSN) is the same used in [4] to prove PSN for λv and in [17] to prove PSN for λs .

Notation 1 *We write $a \in \lambda$ -SN resp. $a \in \lambda r$ -SN when a is strongly normalising in the λ -calculus resp. in the λr -calculus for $r \in \{g, sg, s\}$. We write $a \xrightarrow[p]{\epsilon} b$ to denote that p is the occurrence of the redex which is contracted. Therefore $a \xrightarrow{\epsilon} b$ means that the reduction takes place at the root. If no specification is made the reduction must be understood as a $\lambda s g$ -reduction. We denote by \prec the prefix order between occurrences of a term. Hence if p, q are occurrences of the term a such that $p \prec q$, and we write a_p (resp. a_q) for the subterm of a at occurrence p (resp. q), then a_q is a subterm of a_p . E.g., if $a = 2\sigma^3((\lambda 1)4)$, we have $a_1 = 2$, $a_2 = (\lambda 1)4$, $a_{21} = \lambda 1$, $a_{211} = 1$, $a_{22} = 4$. Since $2 \prec 21$, a_{21} is a subterm of a_2 .*

The following three lemmas assert that all the σ 's in the last term of a derivation beginning with a λ -term must have been created at some previous step by a (generalised) σ -generation and trace the history of these closures. The first lemma deals with one-step derivation where the redex is at the root; the second generalises the first; the third treats arbitrary derivations.

Lemma 7 *If $a \rightarrow C[(e \sigma^i)d]$ then one of the following must hold:*

1. $a = (e \delta)(\lambda)d$, $C = \square$ and $i = 1$.
2. $a = (e' \delta)W(\lambda)d$, $W \neq \phi$, $C = W\square$, $e = (\varphi_0^{N(W)+1})e'$ and $i = 1$.
3. $a = C'[(e \sigma^j)d']$ for some context C' , some term d' and some natural j .

Proof: Since the reduction is at the root, check for every rule $a \rightarrow a'$ in λsg that if $(e \sigma^i)d$ occurs in a' then either 1. or 2. or 3. follows. \square

Lemma 8 *If $a \rightarrow C[(e \sigma^i)d]$ then one of the following must hold:*

1. $a = C[(e \delta)(\lambda)d]$ and $i = 1$.
2. $a = C'[(e' \delta)W(\lambda)d]$, $C = C'[W\square]$, $e = (\varphi_0^{N(W)+1})e'$ and $i = 1$.
3. $a = C'[(e' \sigma^i)d']$ where $e' = e$ or $e' \rightarrow e$.

Proof: Induction on a , using lemma 7 for the reductions at the root. \square

Lemma 9 *If $a_1 \rightarrow \dots \rightarrow a_{n+1} = C[(e \sigma^i)d]$, there exist $e', d' \in \Lambda s$ with $e' \twoheadrightarrow e$ and, either $a_1 = C'[(e' \sigma^j)d']$ or for some $k \leq n$ and W w.b., $a_k = C'[(e' \delta)W(\lambda)d']$ and $a_{k+1} = C'[W((\varphi_0^{N(W)+1})e' \sigma^1)d']$ or, if $W = \phi$, $a_{k+1} = C'[(e' \sigma^1)d']$.*

Proof: Induction on n and use the previous lemma. \square

We define now internal and external reductions. An internal reduction takes place at the left of a σ^i operator. An external reduction is a non-internal one. Our definition is inductive rather than starting from the notion of internal and external position as in [4].

Definition 11 *The reduction $\xrightarrow{\text{int}}_{\lambda sg}$ is defined by the following rules:*

$$\begin{array}{ccc} \frac{a \rightarrow_{\lambda sg} b}{(a \sigma^i)c \xrightarrow{\text{int}}_{\lambda sg} (b \sigma^i)c} & \frac{a \xrightarrow{\text{int}}_{\lambda sg} b}{(a \delta)c \xrightarrow{\text{int}}_{\lambda sg} (b \delta)c} & \frac{a \xrightarrow{\text{int}}_{\lambda sg} b}{(c \delta)a \xrightarrow{\text{int}}_{\lambda sg} (c \delta)b} \\ \\ \frac{a \xrightarrow{\text{int}}_{\lambda sg} b}{(\lambda)a \xrightarrow{\text{int}}_{\lambda sg} (\lambda)b} & \frac{a \xrightarrow{\text{int}}_{\lambda sg} b}{(c \sigma^i)a \xrightarrow{\text{int}}_{\lambda sg} (c \sigma^i)b} & \frac{a \xrightarrow{\text{int}}_{\lambda sg} b}{(\varphi_k^i)a \xrightarrow{\text{int}}_{\lambda sg} (\varphi_k^i)b} \end{array}$$

Definition 12 *The reduction $\xrightarrow{\text{ext}}_s$ is defined by induction. The axioms are the rules of the s -calculus and the inference rules are the following:*

$$\begin{array}{ccc} \frac{a \xrightarrow{\text{ext}}_s b}{(a \delta)c \xrightarrow{\text{ext}}_s (b \delta)c} & \frac{a \xrightarrow{\text{ext}}_s b}{(c \delta)a \xrightarrow{\text{ext}}_s (c \delta)b} & \frac{a \xrightarrow{\text{ext}}_s b}{(\lambda)a \xrightarrow{\text{ext}}_s (\lambda)b} \\ \\ \frac{a \xrightarrow{\text{ext}}_s b}{(c \sigma^i)a \xrightarrow{\text{ext}}_s (c \sigma^i)b} & \frac{a \xrightarrow{\text{ext}}_s b}{(\varphi_k^i)a \xrightarrow{\text{ext}}_s (\varphi_k^i)b} & \end{array}$$

An external (generalised) σ -generation is defined by the rule $(g)\sigma$ -generation and the five inference rules above where $\xrightarrow{\text{ext}}_s$ is replaced by $\xrightarrow{\text{ext}}_{(g)\sigma\text{-gen}}$.

Remark 2 *By inspection of the inference rules, $a \xrightarrow{\text{int}}_{\lambda sg} \mathbf{n}$ is impossible and:*

- If $a \xrightarrow{\text{int}}_{\lambda sg} (\lambda)b$ then $a = (\lambda)c$ and $c \xrightarrow{\text{int}}_{\lambda sg} b$.
- If $a \xrightarrow{\text{int}}_{\lambda sg} (c \delta)b$ then $a = (e \delta)d$ and $((d \xrightarrow{\text{int}}_{\lambda sg} b \text{ and } e = c) \text{ or } (e \xrightarrow{\text{int}}_{\lambda sg} c \text{ and } d = b))$.

Note that $\frac{a \xrightarrow{\text{ext}}_s b}{(a \sigma^i)c \xrightarrow{\text{ext}}_s (b \sigma^i)c}$ and $\frac{a \xrightarrow{\text{ext}}_{(g)\sigma\text{-gen}} b}{(a \sigma^i)c \xrightarrow{\text{ext}}_{(g)\sigma\text{-gen}} (b \sigma^i)c}$ are excluded from the definitions of external s -reduction and external (generalised) σ -generation, respectively. Thus external reductions will not occur at the left of a σ^i operator and we write $\xrightarrow{\dagger}_\beta$ instead of \rightarrow_β in the following (compare with Lemma 5):

Proposition 1 *Let $a, b \in \Lambda s$, if $a \xrightarrow{\text{ext}}_{(g)\sigma\text{-gen}} b$ then $s(a) \xrightarrow{\dagger}_{(g)\beta} s(b)$.*

Proof: Induction on a (as in Lemma 5). Note that when $a = c \sigma^i d$, the reduction cannot take place within d because it is external, and this is the only case that forced us to consider the reflexive-transitive closure because of lemma 4.2. \square

The following is needed in Lemma 11 and hence in the Preservation Theorem.

Lemma 10 (Commutation Lemma) *Let $a, b \in \Lambda s$ such that $s(a) \in \lambda\text{-SN}$ and $s(a) = s(b)$. If $a \xrightarrow{\text{int}}_{\lambda s g} \cdot \xrightarrow{\text{ext}}_s b$ then $a \xrightarrow{\text{ext}}_s^+ \cdot \xrightarrow{\text{int}}_{\lambda s g} b$.*

Proof: By a careful induction on a analysing the positions of the redexes. The proof is exactly the same as that of the Commutation Lemma in [17] \square

Lemma 11 *Let $a \in \lambda g\text{-SN} \cap \Lambda$ and $a \rightarrow_{\lambda s g} b_1 \rightarrow_{\lambda s g} \dots \rightarrow_{\lambda s g} b_n \rightarrow_{\lambda s g} \dots$, an infinite derivation. There exists N such that for every $i \geq N$, the reductions $b_i \rightarrow_{\lambda s g} b_{i+1}$ are internal.*

Proof: Analogous to the proof of the corresponding lemma in [17]. \square

In order to prove the Preservation Theorem we need two definitions.

Definition 13 *An infinite $\lambda s g$ -derivation $a_1 \rightarrow \dots \rightarrow a_n \rightarrow \dots$ is minimal if for every step $a_i \xrightarrow{p} a_{i+1}$, any derivation starting with $a_i \xrightarrow{q} a'_{i+1}$, if $p \prec q$, is finite.*

The idea of a minimal derivation is that if one rewrites at least one of its steps within a subterm of the actual redex, then an infinite derivation is impossible.

Definition 14 *The syntax of skeletons and the skeleton of a term are as follows:*

Skeletons $K ::= \mathbb{N} \mid (K \delta)K \mid (\lambda)K \mid ([.] \sigma^j)K \mid (\varphi_k^i)K$

$$\begin{aligned} Sk(\mathbb{n}) &= \mathbb{n} & Sk((a \delta)b) &= (Sk(a) \delta)Sk(b) & Sk((b \sigma^i)a) &= ([.] \sigma^i)Sk(a) \\ Sk((\lambda)a) &= (\lambda)Sk(a) & Sk((\varphi_k^i)a) &= (\varphi_k^i)Sk(a) \end{aligned}$$

Remark 3 *Let $a, b \in \Lambda s$. If $a \xrightarrow{\text{int}}_{\lambda s g} b$ then $Sk(a) = Sk(b)$.*

Theorem 4 (Preservation of $\lambda s\text{-SN}$) *For every $a \in \Lambda$, if a is strongly normalising in the λs -calculus then a is strongly normalising in the $\lambda s g$ -calculus.*

Proof: Assume $a \in \lambda s\text{-SN}$, $a \notin \lambda s g\text{-SN}$ and take a minimal infinite $\lambda s g$ -derivation $\mathcal{D} : a \rightarrow a_1 \rightarrow \dots \rightarrow a_n \rightarrow \dots$. Lemma 11 gives N such that for $i \geq N$, $a_i \rightarrow a_{i+1}$ is internal. By Remark 3, $Sk(a_i) = Sk(a_{i+1})$ for $i \geq N$. As there are only a finite number of closures in $Sk(a_N)$ and as the reductions within these closures are independent, an infinite subderivation \mathcal{D}' of \mathcal{D} must take place within

the same and unique closure in $Sk(a_N)$ and \mathcal{D}' is also minimal. Let C be the context such that $a_N = C[(d \sigma^i)c]$ and $(d \sigma^i)c$ is the closure where \mathcal{D}' takes place:
 $\mathcal{D}' : a_N = C[(d \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} C[(d_1 \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} \cdots \xrightarrow{\text{int}}_{\lambda sg} C[(d_n \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} \cdots$

Since a is a pure term, Lemma 9 ensures the existence of $I \leq N$ such that either

$$a_I = C'[(d' \delta)(\lambda)c'] \rightarrow a_{I+1} = C'[(d' \sigma^1)c'] \text{ and } d' \twoheadrightarrow d \text{ or}$$

$$a_I = C'[(d' \delta)W(\lambda)c'] \rightarrow a_{I+1} = C'[W((\varphi_0^{N(W)+1})d' \sigma^1)c'] \text{ and } d' \twoheadrightarrow d.$$

Let us consider in the first and second cases respectively, the infinite derivations:

$$\mathcal{D}'' : a \twoheadrightarrow a_I \twoheadrightarrow C'[(d\delta)(\lambda)c'] \rightarrow C'[(d_1\delta)(\lambda)c'] \rightarrow \cdots \rightarrow C'[(d_n\delta)(\lambda)c'] \cdots$$

$$\mathcal{D}''' : a \twoheadrightarrow a_I \twoheadrightarrow C'[(d\delta)W(\lambda)c'] \rightarrow C'[(d_1\delta)W(\lambda)c'] \rightarrow \cdots \rightarrow C'[(d_n\delta)W(\lambda)c'] \cdots$$

In \mathcal{D}'' and \mathcal{D}''' , the redex in a_I is within d' which is a proper subterm of $(d' \delta)(\lambda)c'$ (of $(d' \delta)W(\lambda)c'$ in the second case), whereas in \mathcal{D} the redex in a_I is $(d' \delta)(\lambda)c'$ (in the second case $(d' \delta)W(\lambda)c'$) and this contradicts the minimality of \mathcal{D} . \square

Corollary 3 *For every $a \in \Lambda$, the following equivalences hold:*

$$a \in \lambda g\text{-SN} \text{ iff } a \in \lambda sg\text{-SN} \text{ iff } a \in \lambda\text{-SN} \text{ iff } a \in \lambda s\text{-SN}$$

Proof: By Remark 1 and Theorem 4, $a \in \lambda s\text{-SN}$ iff $a \in \lambda sg\text{-SN}$. Due to [13], $a \in \lambda\text{-SN}$ iff $a \in \lambda g\text{-SN}$. Due to [17], $a \in \lambda\text{-SN}$ iff $a \in \lambda s\text{-SN}$. \square

5 The typed λs - and λsg -calculi

We prove $\lambda sg\text{-SN}$ of well typed terms using the technique developed in [18] to prove $\lambda s\text{-SN}$ and suggested to us by P.-A. Mellies as a successful technique to prove $\lambda v\text{-SN}$ (personal communication). We recall the syntax and typing rules for the simply typed λ -calculus in de Bruijn notation. The types are generated from a set of basic types T with the binary type operator \rightarrow . Environments are lists of types. Typed terms differ from the untyped ones only in the abstractions which are now marked with the type of the abstracted variable.

Definition 15 *The syntax for the simply typed λ -terms is given as follows:*

$$\begin{array}{ll} \text{Types} & \mathcal{T} ::= T \mid \mathcal{T} \rightarrow \mathcal{T} \\ \text{Environments} & \mathcal{E} ::= \text{nil} \mid \mathcal{T}, \mathcal{E} \\ \text{Terms} & A_t ::= \mathbf{n} \mid (A_t \delta)A_t \mid (\mathcal{T} \lambda)A_t \end{array}$$

We let A, B, \dots range over \mathcal{T} ; E, E_1, \dots over \mathcal{E} and a, b, \dots over A_t .

The typing rules are given by the typing system **L1** as follows:

$$\begin{array}{ll} (\mathbf{L1} - \text{var}) & A, E \vdash \mathbf{1} : A \\ (\mathbf{L1} - \lambda) & \frac{A, E \vdash b : B}{E \vdash (A \lambda)b : A \rightarrow B} \\ (\mathbf{L1} - \text{varn}) & \frac{E \vdash \mathbf{n} : B}{A, E \vdash \mathbf{n} + 1 : B} \\ (\mathbf{L1} - \text{app}) & \frac{E \vdash b : A \rightarrow B \quad E \vdash a : A}{E \vdash (a \delta)b : B} \end{array}$$

If E is the environment E_1, E_2, \dots, E_n , we shall use the notation $E_{\geq i}$ for the environment E_i, E_{i+1}, \dots, E_n , analogously $E_{\leq i}$ stands for E_1, \dots, E_i , etc.

Definition 16 *The syntax for the simply typed λ s-terms is given as follows:*

$$As_t ::= \mathbb{N} \mid (As_t \delta)As_t \mid (\mathcal{T} \lambda)As_t \mid (As_t \sigma^i)As_t \mid (\varphi_k^i)As_t \quad i \geq 1, k \geq 0.$$

*Types and environments are as above. The typing rules of the system **Ls1** are: The rules **Ls1-var**, **Ls1-varn**, **Ls1- λ** and **Ls1-app** are exactly the same as **L1-var**, **L1-varn**, **L1- λ** and **L1-app**, respectively. The new rules are:*

$$(\mathbf{Ls1} - \sigma) \quad \frac{E_{\geq i} \vdash b : B \quad E_{< i}, B, E_{\geq i} \vdash a : A}{E \vdash (b \sigma^i) a : A} \quad (\mathbf{Ls1} - \varphi) \quad \frac{E_{\leq k}, E_{\geq k+i} \vdash a : A}{E \vdash (\varphi_k^i) a : A}$$

The simply typed λ s- and λ sg-calculi are defined by the same rules of the untyped versions, except that abstractions in the typed versions are marked with types.

Definition 17 *$a \in As_t$ is a well typed term if for some environment E and type A , $E \vdash_{\mathbf{Ls1}} a : A$. We note As_{wt} the set of well typed terms.*

The aim of this section is to prove that every well typed λ s-term a is λ sg-SN (and hence λ s-SN). To do so, we show $As_{wt} \subseteq \Xi \subseteq \lambda$ sg-SN, where

$$\Xi = \{a \in As_t : \text{for every subterm } b \text{ of } a, s(b) \in \lambda$$
sg-SN\}.

To prove $As_{wt} \subseteq \Xi$ (Proposition 2) we need to establish some useful results such as subject reduction, soundness of typing and typing of subterms:

Lemma 12 *Let S be a segment, A, B types and $a, b, c \in As_t$. We have:*

1. $E \vdash S((\varphi_0^i) a \delta)(c \delta)(B \lambda) b : A$ iff $E \vdash S(c \delta)(B \lambda)((\varphi_0^{i+1}) a \delta) b : A$
2. $E \vdash S((\varphi_0^i)(\varphi_0^j) a \delta) b : A$ iff $E \vdash S((\varphi_0^{i+j-1}) a \delta) b : A$
3. $E \vdash S(a \delta)(B \lambda) b : A$ iff $E \vdash S(a \sigma^1) b : A$

Proof: All by induction on S . □

Lemma 13 (Shuffle Lemma) *Let S be an arbitrary segment, W a w.b. segment and $a, b \in As_t$, then $E \vdash S(a \delta)W b : A$ iff $E \vdash SW((\varphi_0^{N(W)+1}) a \delta) b : A$.*

Proof: By induction on W using Lemma 12. If $W = \phi$, it is immediate since $E' \vdash d : D$ iff $E' \vdash (\varphi_0^1) d : D$. Let us assume $W = (c \delta)U(B \lambda)V$, with U, V w.b..

$$E \vdash S(a \delta)(c \delta)U(B \lambda)V b : A \quad \text{iff (IH)}$$

$$E \vdash S(a \delta)U((\varphi_0^{N(U)+1}) c \delta)(B \lambda)V b : A \quad \text{iff (IH)}$$

$$E \vdash SU((\varphi_0^{N(U)+1}) a \delta)((\varphi_0^{N(U)+1}) c \delta)(B \lambda)V b : A \quad \text{iff (Lemma 12.1)}$$

$$E \vdash SU((\varphi_0^{N(U)+1}) c \delta)(B \lambda)((\varphi_0^{N(U)+2}) a \delta)V b : A \quad \text{iff (IH, twice)}$$

$$E \vdash S(c \delta)U(B \lambda)V((\varphi_0^{N(V)+1}) (\varphi_0^{N(U)+2}) a \delta) b : A \quad \text{iff (Lemma 12.2)}$$

$$E \vdash S(c \delta)U(B \lambda)V((\varphi_0^{N(V)+N(U)+2}) a \delta) b : A \quad \square$$

Lemma 14 (Subject reduction) *If $E \vdash_{\mathbf{Ls1}} a : A$, $a \rightarrow_{\lambda$ sg b then $E \vdash_{\mathbf{Ls1}} b : A$.*

Proof: Induction on a . If the reduction is not at the root, use IH. Else, show for every rule $a \rightarrow b$ that $E \vdash_{\mathbf{Ls1}} a : A$ implies $E \vdash_{\mathbf{Ls1}} b : A$. Case σ -gen, use Lemma 12.3. Case $g\sigma$ -gen: If $E \vdash (a \delta)W(B \lambda) b : A$ then, by Lemma 13, we have $E \vdash W((\varphi_0^{N(W)+1}) a \delta)(B \lambda) b : A$ and, by Lemma 12.3, we conclude $E \vdash W((\varphi_0^{N(W)+1}) a \sigma^1) b : A$. □

Corollary 4 *Let $E \vdash_{\mathbf{Ls1}} a : A$, if $a \rightarrow_{\lambda sg} b$ then $E \vdash_{\mathbf{Ls1}} b : A$.*

Lemma 15 (Typing of subterms) *If $a \in As_{wt}$ and $b \triangleleft a$ then $b \in As_{wt}$.*

Proof: By induction on a . If b is not an immediate subterm of a , use IH. Else, the last rule used to type a has a premise in which b is typed. \square

Lemma 16 (Soundness of typing) *If $a \in \Lambda_t$, $E \vdash_{\mathbf{Ls1}} a : A$ then $E \vdash_{\mathbf{L1}} a : A$.*

Proof: Easy induction on a . \square

Proposition 2 $As_{wt} \subseteq \Xi$.

Proof: Let $a \in As_{wt}$ and b a subterm of a . By Lemma 15, $b \in As_{wt}$ and by Corollary 4, $s(b) \in As_{wt}$. Since $s(b) \in \Lambda$ (Thm. 2), Lemma 16 gives $s(b)$ is **L1**-typable. But classical typable λ -terms are strongly normalising in the λ -calculus. Hence, $s(b) \in \lambda$ -SN and, by Corollary 3, $s(b) \in \lambda g$ -SN. Therefore $a \in \Xi$. \square

We prove now $\Xi \subseteq \lambda sg$ -SN.

Lemma 17 *Let $a \in \Xi$ and $a \rightarrow_{\lambda s} b_1 \rightarrow_{\lambda s} \dots \rightarrow_{\lambda s} b_n \rightarrow_{\lambda s} \dots$, an infinite λs -derivation. There exists N such that for $i \geq N$ all the reductions $b_i \rightarrow_{\lambda s} b_{i+1}$ are internal.*

Proof: The proof is almost the same as the proof of lemma 11. \square

Proposition 3 *For every $a \in As_t$, if $a \in \Xi$ then $a \in \lambda sg$ -SN.*

Proof: Assume $a' \in \Xi$ and $a' \notin \lambda sg$ -SN, then there exists a term a of minimal size such that $a \in \Xi$ and $a \notin \lambda sg$ -SN. Let $\mathcal{D} : a \rightarrow a_1 \rightarrow \dots \rightarrow a_n \rightarrow \dots$ be a minimal infinite λsg -derivation and follow the proof of Theorem 4 to obtain:

$$\mathcal{D}' : a_N = C[(d \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} C[(d_1 \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} \dots \xrightarrow{\text{int}}_{\lambda sg} C[(d_n \sigma^i)c] \xrightarrow{\text{int}}_{\lambda sg} \dots$$

Now three possibilities arise from lemma 9. Two of them have been considered in the proof of Theorem 4 and contradicted the minimality of \mathcal{D} . Take the third one: $a = C'[(d' \sigma^i)c']$ where $d' \twoheadrightarrow d$. Now we have $d' \twoheadrightarrow d \rightarrow d_1 \rightarrow \dots \rightarrow d_n \rightarrow \dots$. As d' is a subterm of a , $d' \in \Xi$, contradicting that a has minimal size. \square

Therefore we conclude, using Propositions 2 and 3 and Corollary 3:

Theorem 5 *Well typed λs -term are strongly normalising in the λsg -calculus.*

Corollary 5 *Well typed λs -term are strongly normalising in the λs -calculus.*

6 Conclusion

In this paper, we started from the fact that generalised reduction and explicit substitution play a vital role in useful extensions of the λ -calculus but have never been combined together. We commented that the combination might indeed join both benefits and hence a λ -calculus extended with both needs to be studied.

We presented such a calculus and showed that it possesses the important properties that have been the center of research for each concept on its own. In particular, we showed that the resulting calculus is confluent, sound and simulates β -reduction. We showed moreover that it preserves strong normalisation of the unextended λ -calculus and of the λ -calculus extended with each of the two concepts independently. We studied furthermore, the simply typed version of our calculus of explicit substitution and generalised reduction and showed that it has again the important properties such as subject reduction, soundness of subtyping, typing of subterms and strong normalisation of well typed terms.

Now that a calculus combining both concepts have been shown to be theoretically correct, it would be interesting to extend our calculus λ_{sg} to one that is confluent on open terms as is the tradition with calculi of explicit substitution. It would be also interesting to study the polymorphically (rather than the simply) typed version of λ_{sg} . These are issues we are investigating at the moment. We are also investigating the correspondence of our calculus to methods that implement sharing and parallelism to test if the analysis of sharing given in [2] can be recast in an elegant fashion in our calculus.

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