

Parameters in Pure Type Systems

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The Low Level approach of functions

- Historically, **functions** have long been treated as a kind of **meta-objects**.
- Function *values* have always been important, but **abstract functions** have not been recognised in their own right until the third of the 20th century.
- In the *low level approach* or *operational* view on functions, there are no functions as such, but only function values.
- E.g., the **sine-function**, is always expressed together with a value: $\sin(\pi)$, $\sin(x)$ and properties like: $\sin(2x) = 2 \sin(x) \cos(x)$.
- It has long been usual to call $f(x)$ —and not f —the **function** and this is still the case in many introductory mathematics courses.

The revolution of treating functions as first class citizens

- In the nowadays accepted view on functions, they are 'first class citizens'.
- **Abstraction** and **application** form the basis of the λ -calculus and type theory.
- This is **rigid** and does not represent the development of logic in 20th century.
- Frege and Russell's conceptions of functional abstraction, instantiation and application **do not fit well with the λ -calculus approach**.
- In *Principia Mathematica* [Whitehead and Russell, 1910¹, 1927²]: **If, for some a , there is a proposition ϕa , then there is a function $\phi \hat{x}$, and vice versa.**
- The function **ϕ is not a separate entity** but always has an argument.

λ -calculus does not fully represent functionalisation

1. **Abstraction from a subexpression** $2 + 3 \mapsto x + 3$
 2. **Function construction** $x + 3 \mapsto \lambda x. x + 3$
 3. **Application construction** $(\lambda x. (x + 3))2$
 4. **Concretisation to a subexpression** $(\lambda x. (x + 3))2 \rightarrow 2 + 3$
- Cannot identify the original term from which a function has been abstracted.
$$\text{let add}_2 = (\lambda x. x + 2) \text{ in add}_2(x) + \text{add}_2(y)$$
 - cannot abstract only half way: $x + 3$ is not a function, $\lambda x. x + 3$ is.
 - cannot apply $x + 3$ to an argument: $(x + 3)2$ does not evaluate to $2+3$.

Parameters: What and Why

- we speak about *functions with parameters* when referring to functions with variable values in the *low-level* approach. The x in $f(x)$ is a parameter.
- Parameters enable the same expressive power as the high-level case, while allowing us to stay at a lower order. Cf. [Laan and Franssen, 2001] and [Kamareddine et al., 2001].
- Desirable properties of the lower order theory (**decidability, easiness of calculations, typability**) can be maintained, without losing the flexibility of the higher-order aspects.
- This **low-level approach is still worthwhile for many exact disciplines**. It has not been wiped out in logic and in computer science, and for good reasons.

Automath

- The first tool for mechanical representation and verification of mathematical proofs, **AUTOMATH**, has a parameter mechanism.
- The representation of a **mathematical text** in **AUTOMATH** consists of a **finite list of lines** where every line has the following format:

$$x_1 : A_1, \dots, x_n : A_n \vdash g(x_1, \dots, x_n) = t : T.$$

Here g is a new name, an abbreviation for the expression t of type T and x_1, \dots, x_n are the parameters of g , with respective types A_1, \dots, A_n .

- Each line introduces a new definition which is inherently parametrised by the variables occurring in the context needed for it.

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- Developments of ordinary mathematical theory in AUTOMATH [Benthem Jutting, 1977] revealed that this combined definition and **parameter mechanism is vital for keeping proofs manageable and sufficiently readable for humans.**

The Barendregt Cube

- $\mathcal{T}_P ::= \mathcal{V} \mid \mathcal{S} \mid \mathcal{T}_P \mathcal{T}_P \mid \lambda \mathcal{V} : \mathcal{T}_P . \mathcal{T}_P \mid \Pi \mathcal{V} : \mathcal{T}_P . \mathcal{T}_P$
- \mathcal{V} is a set of variables and $\mathcal{S} = \{*, \square\}$.

$$\text{(axiom)} \quad \langle \rangle \vdash * : \square$$

$$\text{(start)} \quad \frac{\Gamma \vdash A : s}{\Gamma, x:A \vdash x : A} \quad x \notin \text{DOM}(\Gamma)$$

$$\text{(weak)} \quad \frac{\Gamma \vdash A : B \quad \Gamma \vdash C : s}{\Gamma, x:C \vdash A : B} \quad x \notin \text{DOM}(\Gamma)$$

$$\text{(II)} \quad \frac{\Gamma \vdash A : s_1 \quad \Gamma, x:A \vdash B : s_2}{\Gamma \vdash (\Pi x:A.B) : s_2} \quad (s_1, s_2) \in \mathbf{R}$$

$$\text{(\lambda)} \quad \frac{\Gamma, x:A \vdash b : B \quad \Gamma \vdash (\Pi x:A.B) : s}{\Gamma \vdash (\lambda x:A.b) : (\Pi x:A.B)}$$

$$\text{(appl)} \quad \frac{\Gamma \vdash F : (\Pi x:A.B) \quad \Gamma \vdash a : A}{\Gamma \vdash Fa : B[x:=a]}$$

$$\frac{\Gamma \vdash A : B \quad \Gamma \vdash B' : s \quad B =_{\beta} B'}{\Gamma \vdash A : B'}$$

Different type formation conditions

$$(II) \quad \frac{\Gamma \vdash A : s_1 \quad \Gamma, x:A \vdash B : s_2}{\Gamma \vdash (\Pi x:A.B) : s_2} \quad (s_1, s_2) \in \mathbf{R}$$

- $(\square, *)$ takes care of **polymorphism**. $\lambda 2$ is weakest on cube satisfying this.
- (\square, \square) takes care of **type constructors**. $\lambda \underline{\omega}$ is weakest on cube satisfying this.
- $(*, \square)$ takes care of **term dependent types**. λP is weakest on cube satisfying this.

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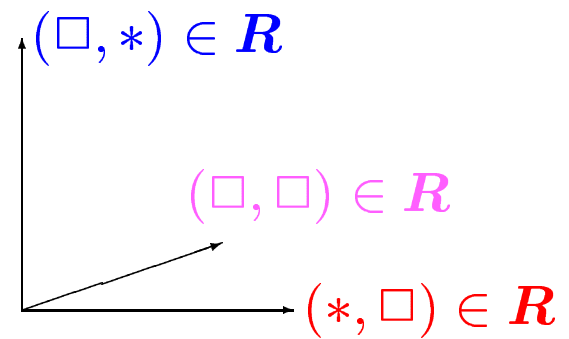
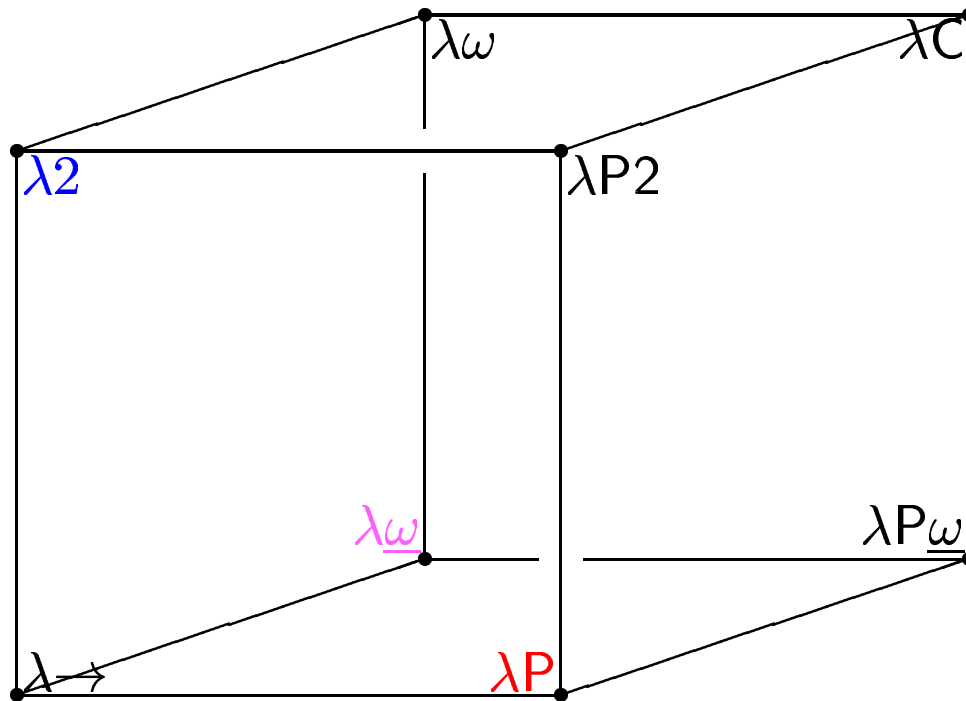
$\lambda \rightarrow$	$(*, *)$			
$\lambda 2$	$(*, *)$	$(\square, *)$		
λP	$(*, *)$		$(*, \square)$	
$\lambda \underline{\omega}$	$(*, *)$			(\square, \square)
$\lambda P 2$	$(*, *)$	$(\square, *)$	$(*, \square)$	
$\lambda \omega$	$(*, *)$	$(\square, *)$		(\square, \square)
$\lambda P \underline{\omega}$	$(*, *)$		$(*, \square)$	(\square, \square)
λC	$(*, *)$	$(\square, *)$	$(*, \square)$	(\square, \square)

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Systems of the Barendregt Cube

System	Rel. system	Names, references
$\lambda \rightarrow$	λ^τ	simply typed λ -calculus; [Church, 1940], [Barendregt, 1984] (Appendix A), [Hindley and Seldin, 1986] (Chapter 14)
$\lambda 2$	F	second order typed λ -calculus; [Girard, 1972], [Reynolds, 1974]
λP	AUT-QE LF	[Bruijn, 1968] [Harper et al., 1987]
$\lambda P2$		[Longo and Moggi, 1988]
$\lambda \underline{\omega}$	POLYREC	[Renardel de Lavalette, 1991]
$\lambda \omega$	$F\omega$	[Girard, 1972]
λC	CC	Calculus of Constructions; [Coquand and Huet, 1988]

The Barendregt Cube



LF

- **LF** (see [Harper et al., 1987]) is often described as λP of the Barendregt Cube.
- [Geuvers, 1993] shows that the **use of the Π -formation rule $(*, \square)$ is very restricted in the practical use of LF.**
- This use is in fact based on a **parametric construct rather than on Π -formation.**
- We will find a more precise position of **LF** on the Cube (**between $\lambda \rightarrow$ and λP**).

ML

- We only consider an explicit version of a subset of ML.
- **In ML**, One can define the polymorphic identity by:

$$\text{Id}(\alpha:*) = (\lambda x:\alpha.x) : (\alpha \rightarrow \alpha) \quad (1)$$

- **But in ML**, it is **not possible** to make an explicit λ -abstraction over $\alpha : *$ by:

$$\text{Id} = (\lambda \alpha:*. \lambda x:\alpha.x) : (\Pi \alpha:*. \alpha \rightarrow \alpha) \quad (2)$$

- The type $\Pi \alpha:*. \alpha \rightarrow \alpha$ **does not belong to** the language of **ML** and hence the λ -abstraction of equation (2) is not possible in ML.

ML

- Therefore, we can state that **ML does not have a Π -formation rule $(\square, *)$.**
- Nevertheless, **ML has some parameter mechanism** (α parameter of Id)
- **ML has limited access to the rule $(\square, *)$ enabling equation (1) to be defined.**
- **ML's type system is none of those of the eight systems of the Cube.**
- We place the **type system of ML** on our refined Cube (**between $\lambda 2$ and $\lambda \underline{\omega}$**).

Extending PTSs with parameters and definitions

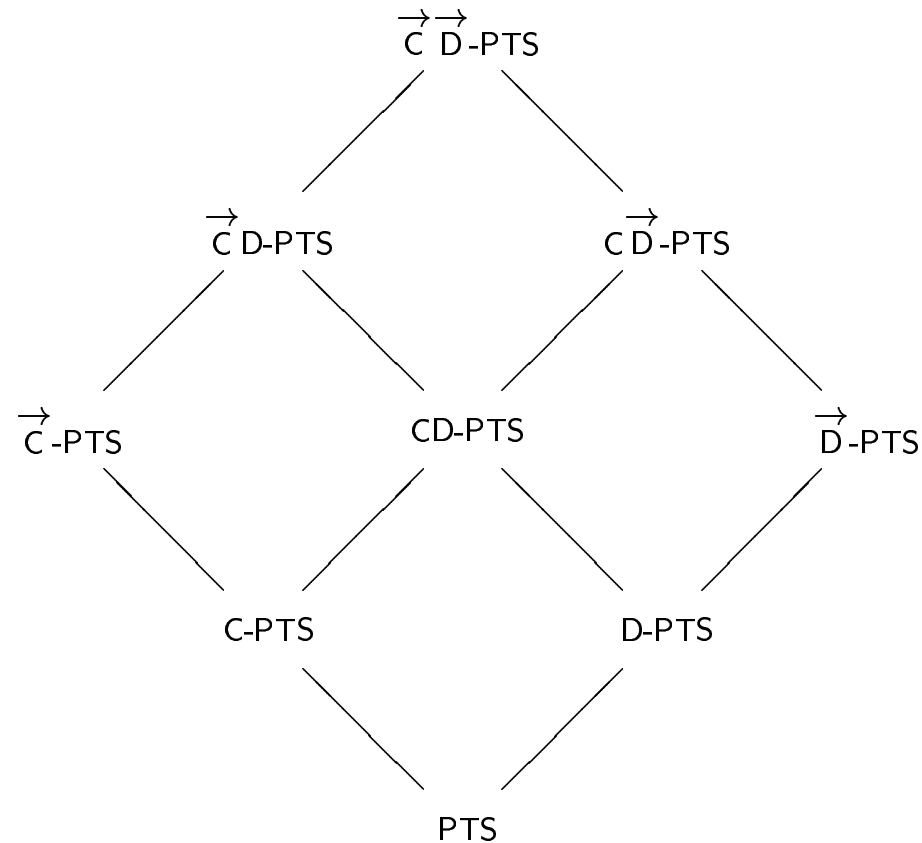


Figure 1: The hierarchy of parameters, constants and definitions

- $\mathcal{T}_P ::= \mathcal{V} \mid \mathcal{S} \mid \mathcal{C}(\mathcal{L}_T) \mid (\mathcal{T}_P \mathcal{T}_P) \mid (\lambda \mathcal{V} : \mathcal{T}_P. \mathcal{T}_P)$
 $\mid (\Pi \mathcal{V} : \mathcal{T}_P. \mathcal{T}_P) \mid (\mathcal{C}(\mathcal{L}_V) = \mathcal{T}_P : \mathcal{T}_P \text{ in } \mathcal{T}_P);$
- $\mathcal{L}_V ::= \emptyset \mid \langle \mathcal{L}_V, \mathcal{V} : \mathcal{T}_P \rangle;$ $\mathcal{L}_T ::= \emptyset \mid \langle \mathcal{L}_T, \mathcal{T}_P \rangle.$
- **Parametric constructs** are $c(b_1, \dots, b_n)$ with b_1, \dots, b_n terms of certain types. \mathcal{C} is a set of constants, b_1, \dots, b_n are called the *parameters* of $c(b_1, \dots, b_n)$.
- **R allows** several kinds of **Π -constructs**. We also use a set **P** of (s_1, s_2) where $s_1, s_2 \in \{*, \square\}$ to **allow** several kinds of **parametric constructs**.
- $(s_1, s_2) \in \mathbf{P}$ means that we **allow** parametric constructs $c(b_1, \dots, b_n) : A$ where b_1, \dots, b_n have types B_1, \dots, B_n of sort s_1 , and A is of type s_2 .

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- If both $(*, s_2) \in \mathbf{P}$ and $(\square, s_2) \in \mathbf{P}$ then combinations of parameters allowed. For example, it is allowed that B_1 has type $*$, whilst B_2 has type \square .

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$$(\delta 1): \quad \Gamma_1, c(\Delta)=a:A, \Gamma_2 \vdash c(b_1, \dots, b_n) \rightarrow_\delta a[x_i:=b_i]_{i=1}^n$$

$$(\delta 2): \quad \frac{c \notin \text{CONS}(b)}{\Gamma \vdash c(\Delta)=a:A \text{ in } b \rightarrow_\delta b}$$

$$(\delta 3): \quad \frac{\Gamma, c(\Delta)=a:A \vdash b \rightarrow_\delta b'}{\Gamma \vdash c(\Delta)=a:A \text{ in } b \rightarrow_\delta c(\Delta)=a:A \text{ in } b'}$$

$$\frac{\Gamma, \Delta \vdash a \rightarrow_\delta a'}{\Gamma \vdash c(\Delta)=a:A \text{ in } b \rightarrow_\delta c(\Delta)=a':A \text{ in } b} \quad \frac{\Gamma, \Delta \vdash A \rightarrow_\delta A'}{\Gamma \vdash c(\Delta)=a:A \text{ in } b \rightarrow_\delta c(\Delta)=a:A' \text{ in } b}$$

$$\frac{\Gamma, \Delta_i \vdash B_i \rightarrow_\delta B'_i}{\Gamma \vdash c(\Delta)=a:A \text{ in } b \rightarrow_\delta c(x_1:B_1, \dots, x_i:B'_i, \dots, x_n:B_n)=a:A \text{ in } b}$$

$$\frac{\Gamma \vdash a \rightarrow_\delta a'}{\Gamma \vdash ab \rightarrow_\delta a'b}$$

$$\frac{\Gamma \vdash b \rightarrow_\delta b'}{\Gamma \vdash ab \rightarrow_\delta ab'}$$

$$\frac{\Gamma, x:A \vdash a \rightarrow_\delta a'}{\Gamma \vdash \lambda x:A.a \rightarrow_\delta \lambda x:A.a'}$$

$$\frac{\Gamma \vdash A \rightarrow_\delta A'}{\Gamma \vdash \lambda x:A.a \rightarrow_\delta \lambda x:A'.a}$$

$$\frac{\Gamma, x:A \vdash a \rightarrow_\delta a'}{\Gamma \vdash \Pi x:A.a \rightarrow_\delta \Pi x:A.a'}$$

$$\frac{\Gamma \vdash A \rightarrow_\delta A'}{\Gamma \vdash \Pi x:A.a \rightarrow_\delta \Pi x:A'.a}$$

$$\frac{\Gamma \vdash a_j \rightarrow_\delta a'_j}{\Gamma \vdash c(a_1, \dots, a_n) \rightarrow_\delta c(a_1, \dots, a'_j, \dots, a_n)}$$

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$$\begin{array}{c}
 \begin{array}{c}
 \vec{C}\text{-weak} \\
 \frac{\Gamma \vdash^{\vec{C}} b:B \quad \Gamma, \Delta \vdash^{\vec{C}} A:s \quad \Gamma, \Delta_i \vdash^{\vec{C}} B_i:s_i \quad (s_i, s) \in \mathbf{P} \quad (i = 1, \dots, n)}{\Gamma, c(\Delta) : A \vdash^{\vec{C}} b : B}
 \end{array} \\
 \\
 \begin{array}{c}
 \vec{C}\text{-app} \\
 \frac{\Gamma_1, c(\Delta):A, \Gamma_2 \vdash^{\vec{C}} b_i:B_i[x_j:=b_j]_{j=1}^{i-1} \quad (i = 1, \dots, n) \quad \Gamma_1, c(\Delta):A, \Gamma_2 \vdash^{\vec{C}} A : s \quad (\text{if } n = 0)}{\Gamma_1, c(\Delta):A, \Gamma_2 \vdash^{\vec{C}} c(b_1, \dots, b_n) : A[x_j:=b_j]_{j=1}^n}
 \end{array}
 \end{array}$$

Figure 2: Typing rules for parametric constants

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$$\begin{array}{l}
 \begin{array}{c}
 \vec{D}\text{-weak} \\
 \vec{D}\text{-app} \\
 \vec{D}\text{-form} \\
 \vec{D}\text{-intro} \\
 \vec{D}\text{-conv}
 \end{array}
 \quad
 \frac{\Gamma \vdash^{\vec{D}} b : B \quad \Gamma, \Delta \vdash^{\vec{D}} a : A : s \quad \Gamma, \Delta_i \vdash^{\vec{D}} B_i : s_i \quad (s_i, s) \in \mathbf{P} \quad (i=1, \dots, n)}{\Gamma, c(\Delta)=a : A \vdash^{\vec{D}} b : B} \\
 \\
 \frac{\Gamma_1, c(\Delta)=a : A, \Gamma_2 \vdash^{\vec{D}} b_i : B_i[x_j := b_j]_{j=1}^{i-1} \quad (i = 1, \dots, n) \quad \Gamma_1, c(\Delta)=a : A, \Gamma_2 \vdash^{\vec{D}} a : A \quad (\text{if } n = 0)}{\Gamma_1, c(\Delta)=a : A, \Gamma_2 \vdash^{\vec{D}} c(b_1, \dots, b_n) : A[x_j := b_j]_{j=1}^n} \\
 \\
 \frac{\Gamma, c(\Delta)=a : A \vdash^{\vec{D}} B : s}{\Gamma \vdash^{\vec{D}} c(\Delta)=a : A \text{ in } B : s} \\
 \\
 \frac{\Gamma, c(\Delta)=a : A \vdash^{\vec{D}} b : B \quad \Gamma \vdash^{\vec{D}} c(\Delta)=a : A \text{ in } B : s}{\Gamma \vdash^{\vec{D}} c(\Delta)=a : A \text{ in } b : c(\Delta)=a : A \text{ in } B} \\
 \\
 \frac{\Gamma \vdash^{\vec{D}} b : B \quad \Gamma \vdash^{\vec{D}} B' : s \quad \Gamma \vdash B =_{\delta} B'}{\Gamma \vdash^{\vec{D}} b : B'}
 \end{array}$$

Conclusions

- Parameters enable the same expressive power as the high-level case, while allowing us to stay at a lower order. E.g. **first-order with parameters** versus **second-order without** [Laan and Franssen, 2001].
- Desirable properties of the lower order theory (**decidability, easiness of calculations, typability**) can be maintained, without losing the flexibility of the higher-order aspects.
- Parameters enable us to find an exact position of type systems in the generalised framework of type systems.
- Parameters describe the difference between *developers* and *users* of systems.

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