

Data Structures and Algorithms

Weighted Graphs & Algorithms

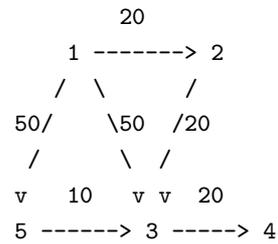
Goodrich & Tamassia Sections 13.5 & 13.6

- Weighted Graphs
- Shortest Path Problems
- A Greedy Algorithm

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Weighted Graphs

Sometimes want to associate some value with the edges in graph.



So.. label all the edges with a number. That number (called the weight) could represent:

- Distances between two locations (cities; computers on network)
- Time taken to get from one node to another (stations; states in schedule or plan).
- Cost of traversing the edge (train fares; cost of wires)

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Weighted graphs can be directed or undirected, cyclic or acyclic etc as unweighted graphs.

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Weighted Graph ADT

- Easy to modify the graph ADT(s) representations to accommodate weights
- Also need to add operations to modify/inspect weights.

For example we can modify adjacency matrix representation so entries in array are now numbers (int or float) rather than true/false.

You can travel from a node to itself at zero cost, and if there is no connection between two nodes then the “weight” is ‘null’ (sometimes called ‘infinity’): typically a large number in simple implementations

	1	2	3	4	5
1	0	20	50	null	50
2	null	0	20	null	null
3	null	null	0	20	null
4	null	null	null	0	null
5	null	null	10	null	0

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Weighted Edge Class

Introduce a `WeightedEdge` subclass, derived from the `Edge` class.

For genericity the weight is an `Object` it can take different classes of weights, e.g. `Integer`, `MyInteger`, `MyFloat`

```
public class WeightedEdge extends Edge
{
    // data member
    Object weight;

    // constructor
    public WeightedEdge(int theVertex1,
                        int theVertex2,
                        Object theWeight)
    {
        super(theVertex1, theVertex2);
        weight = theWeight;
    }
}
```

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Weighted Graph Class

Introduce a `WeightedGraph` subclass, derived from Sahni's `Graph` class.

```
public class AdjacencyWDigraph extends Graph
{
    int n;           // number of vertices
    int e;           // number of edges
    Object [][] a;  // adjacency array

    // constructors
    public AdjacencyWDigraph(int theVertices)
    {
        // validate theVertices
        if (theVertices < 0
            throw new IllegalArgumentException
                ("number of vertices must be >= 0");
        n = theVertices;
        a = new Object [n + 1] [n + 1];
        // default values are e = 0 and a[i][j] = null
    }
}
```

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```
/*put edge e into the digraph;
if the edge is already
there, update its weight to e.weight */
public void putEdge(Object theEdge)
{
    WeightedEdge edge = (WeightedEdge) theEdge;
    int v1 = edge.vertex1;
    int v2 = edge.vertex2;
    if (v1 < 1 || v2 < 1 || v1 > n || v2 > n | v1 ==
        throw new IllegalArgumentException
            ("(" + v1 + "," + v2 +
             ") is not a permissible edge");

    if (a[v1][v2] == null) // new edge
        e++;
    a[v1][v2] = edge.weight;
}
```

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Shortest Path Problems

Many problems can be solved using weighted graphs. For example finding the 'shortest path' between two nodes, e.g.,:

- shortest distance between two cities by road links.
- fastest train journey
- cheapest plane journey
- lowest cost plan

'length' of path is just sum of weights on relevant edges. e.g.,:

N.B. the shortest path may visit more nodes!

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A Shortest Path Algorithm

There are several possible shortest path problems, we consider the *single source, all destinations* version.

If all the weights are the same, then *breadth first search* finds shortest path first:

Explores paths of length N before paths of length N+1

But for arbitrary weights we need a slightly more complex algorithm developed by E.Dijkstra. My intuition is “how far can you go for your money”.

More formally, the key is

From the vertices to which a shortest path has not been generated, select the one that results in the least path length

Shortest Path Algorithm

	Path Length
20	
1 -----> 2	0
/ \ /	
50/ \50 /20	20
/ \ /	
v 10 v v 20	40
5 -----> 3 -----> 4	50
	60

See Weiss Section 9.3.2 for another example.

Recording Paths and Path Lengths

Observe that

- the 2nd path is a 1-edge extension of the 1st;
- the 3rd path is a 1-edge extension of the 2nd;
- the 4th path is a 1-edge extension of the 1st;
- the 5th path is a 1-edge extension of the 3rd;

So we can represent a path by recording the immediate predecessor for each vertex as a data member `path`.

Similarly the length of the shortest path to each vertex found so far can be recorded as a data member `dist`.

We also need to record whether we've seen this visitor before `known`

```
class Vertex
{
    public boolean known;
        // Disttype is probably int or Double
    public DistType dist;
        // preceding vertex on path
    public Vertex path;
    ... // Other fields and methods
}
```

The last thing we require is a function `Weight getWeight(Vertex v, Vertex w)` that returns the weight on the edge between `v` and `w`.

Shortest Path Pseudocode

Based on Weiss Chapter 9

```
dijkstraShortestPath(Vertex s)
{
  for each vertex v {
    v.dist = INFINITY
    v.known = false
  }
  s.dist = 0
  newReachables = {s}
  while newReachables is not empty {
    delete from newReachables the v with
      smallest dist
    v.known = true
    for each vertex w adjacent to v
      if (!w.known) {
        add w to newReachables
        if (v.dist + getWeight(v,w) < w.dist)
          w.dist = v.dist + getWeight(v,w)
          w.path = v
      }
    }
  }
}
```

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Walkthrough: Initialisation

```

      1      2
      0      INF
      U      20      U
      null -----> null
      / \      /
50/      \50 /20
      /      \ /
v   10   v v 20
5 -----> 3 -----> 4
INF      INF      INF
U        U        U
null     null     null

newReachables = 1
```

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Walkthrough: First Iteration

Chose vertex 1

```

      1      2
      0      20
      K      20      U
      null -----> 1
      / \      /
50/      \50 /20
      /      \ /
v   10   v v 20
5 -----> 3 -----> 4
50      50      INF
U        U        U
1        1        null
```

newReachables = 2, 3, 5

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Walkthrough: Second Iteration

Chose vertex 2

```

      1      2
      0      20
      K      20      K
      null -----> 1
      / \      /
50/      \50 /20
      /      \ /
v   10   v v 20
5 -----> 3 -----> 4
50      40      INF
U        U        U
1        2        null
```

newReachables = 3, 5

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Walkthrough: Final Graph

```

    1          2
    0          20
    K    20    K
null -----> 1
 /  \      /
50/   \50 /20
 /     \ /
v  10   v v  20
5 -----> 3 -----> 4
50          40      INF
K           K       60
1           2       3

newReachables = {}

```

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Tip: Performing walkthroughs of complex algorithms operating on a simple set of data aids understanding.

Exercise: Complete the walkthrough for the graph above, and check your results with the final graph above.

Exercise: Weiss Exercise 9.5

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jgrapht Implementation

```

public final class DijkstraShortestPath<V, E>
{
    //~ Constructors -----

    /*Create & execute a new DijkstraShortestPath alg.
    *instance. An instance is only good for a single
    *search; after construction, it can be accessed
    *to retrieve information about the path found
    */
    public DijkstraShortestPath(Graph<V, E> graph,
        V startVertex,
        V endVertex)
        ...
    //~ Methods -----

    /* Return the edges making up the path found.
    */
    public List<E> getPathEdgeList()
    { return edgeList; }
}

```

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```

    /* Return the length of the path found,
    * or Double.POSITIVE_INFINITY if no path exists
    */
    public double getPathLength()
    { return pathLength; }
    ...
}

```

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Priority Queue Refresher

Used to retrieve items in a priority order. Uses include:

- Sorting
- Task scheduling

Can be implemented as a list or tree.

Example where small numbers have priority:

- Insert 10, 30, 20, 5
- Dequeue:
- Dequeue:
- Insert 15, 40
- Dequeue:
- Dequeue:

Exercise: Rework this exercise assuming large numbers have high priority.

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Graph Traversal Reflection

The graph traversal is determined by **how the next vertex to visit is selected**

- **shortest path:** chose next vertex from a **priority queue** (priority is shortest length).
- **depth-first search** chose next vertex from a **stack**
- **breadth-first search** chose next vertex from a **queue**
- **random walk** chose the next vertex randomly from a **set**

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Summary

- Weighted graphs useful for many problems - each edge has an associated number representing weight/cost/length.
- Easy to implement as $N \times N$ array of weights, or by adding a weight to edge objects.
- Example problem: single-source, all-destinations shortest path
- Example algorithm: Dijkstra's greedy solution.

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