

# F28HS Hardware-Software Interface: Systems Programming

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<sup>0</sup>No proprietary software has been used in producing these slides



# Outline

- 1 Lecture 1: Introduction to Systems Programming
- 2 Lecture 2: Systems Programming with the Raspberry Pi
- 3 Lecture 3: Memory Hierarchy
  - Memory Hierarchy
    - Principles of Caches
- 4 Lecture 4: Programming external devices
  - Basics of device-level programming
- 5 Lecture 5: Exceptional Control Flow
- 6 Lecture 6: Computer Architecture
  - Processor Architectures Overview
    - Pipelining
- 7 Lecture 7: Code Security: Buffer Overflow Attacks
- 8 Lecture 8: Interrupt Handling
- 9 **Lecture 9: Miscellaneous Topics**
- 10 Lecture 10: Revision

# Lecture 9.

## Miscellaneous Topics

# Bare-metal programming

- **Bare-metal programming** means “programming directly on the hardware”, i.e. on a system that doesn’t run an operating system.
- This is the most common scenario for embedded systems programming.
- In this course we used Raspbian on the RPi2 mainly for **convenience** (tool support etc)
- Embedded systems in industry usage are often too small to run any OS
- For time-critical operations you don’t want an OS because in order to meet **real-time** constraints.

# What's different?

A lot:

- You have to control the boot process yourself
- You have to manage all aspects of the hardware directly:
  - ▶ memory (no virtual memory!)
  - ▶ external devices
- You need to produce stand-alone executables, i.e. no dynamically linked libraries
- You typically need to cross-compile your code

# What are the advantages?

- You have direct control over the hardware:
  - ▶ For our LED etc examples, you **don't need** `mmap` to access the devices, rather you directly write to the hardware registers.
  - ▶ You can access aspects of the hardware that might not be accessible otherwise.
- Better suited for real-time constraints: no OS overhead, predictable performance
- Very small code size of the entire application
- Typically lower energy consumption

# How does the application code differ?

Looking at our example code from the course

- No `mmap` is needed to access the GPIO pins
- You can't use external libraries: everything must be part of the application
- This means that in general you need to write your own device drivers for external devices such as a monitor
- The code typically needs to be cross-compiled, i.e. the machine that you are **compiling on** is different from the machine that you are **compiling for**.

And of course there are a lot of differences in terms of usability.

## Further Reading & Deeper Hacking

- “*Embedded Linux*”, by Jürgen Quade (Textbook on embedded systems programming, using a bare-metal approach)
- [Baking Pi](#), by Alex Chadwick (a course on bare-metal programming on the Raspberry Pi at Cambridge University (only for RPi1))
- [Valvers: Bare Metal Programming in C](#)



# Rust: an alternative systems programming language

*Rust is a systems programming language that runs blazingly fast, prevents segfaults, and guarantees thread safety.*

# Rust Features

- zero-cost abstractions
- move semantics
- guaranteed memory safety
- threads without data races
- trait-based generics
- pattern matching
- type inference
- minimal runtime
- efficient C bindings

# Internet of Things

- The amount of processors used in all kinds of settings is increasing rapidly.
- Examples are “smart homes” with configurable/programmable devices such as smart TVs etc
- These typically use small, embedded devices
- These devices want to exchange data, e.g. to monitor the environment and react to changes
- Therefore, these systems are inter-connected, building an **Internet of Things**
- These systems increasingly use a full operating system underneath
- Thus, a **RPI 2 running Raspbian is a good case study**

# OS choices for the Internet of Things

- Raspbian, while useful as an interactive OS, comes with a lot of unnecessary packages if it should be used on one of these networked, embedded devices.
- Smaller, configurable Linux versions are often a better choice, e.g. Arch Linux (also available for RPi2).
- These reduce the resource consumption of the system, and improve maintainability.
- Several new<sup>1</sup> OS's target this market: for example **MinocaOS**

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<sup>1</sup>There are also several old OS's that fit this characterisation: see **Minix** and **RISC OS**.

# Main features of MinocaOS

- **MinocaOS** is a completely new OS, matching standard interfaces such as POSIX.
- MinocaOS is advertised as: *Modular, Lean, Flexible*
- MinocaOS supports RPi1 and RPi2/3 in 2 different images that can be downloaded
- There is no 64-bit support available yet<sup>2</sup>
- MinocaOS is also provided as a Qemu-based virtual machine, for experimentation on a laptop
- MinocaOS has a very small resource footprint, and works well even on older RPi1's
- MinocaOS has good hardware support and fairly good tool support

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<sup>2</sup>See the slides at the end for a link on how to build your own 64-bit kernel on an RPi3

# MinocaOS

Some notable features of MinocaOS are:

- Most command-line tools are based on GNU versions: `bash`, `ls`, `cat`, `chmod`, `nano` (use `--help` to get info)
- It uses package management similar to Debian-based systems (`opkg` as package manager; packages have extension `.ipkg`)
- The list of available packages and repos can be edited in `/var/opkg-lists/`
- **No** graphical user interface at the moment (not necessary for IoT context)

A [Guided Tour](#) is available on the MinocaOS web page.

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# UBOS: easy configuration

- **UBOS** is a Linux distribution for easy management of several web services on an Rpi.
- Very flexible, being based on **Arch Linux**
- Features (as advertised):
  - ▶ With UBOS, web applications can be installed, and fully configured with a single command.
  - ▶ UBOS fully automates app management at virtual hosts
  - ▶ UBOS pre-installs and pre-configures networking and other infrastructure.
  - ▶ Systems that have two Ethernet interfaces can be turned into a home router/gateway with a single command.
  - ▶ UBOS can backup or restore all, or any subset of installed applications on a device
  - ▶ UBOS uses a rolling-release development model
  - ▶ UBOS itself is all free/libre and open software.



# Compiling an 64-bit kernel for RPi3

A detailed discussion on how to build a 64-bit kernel on a Raspberry Pi 3 is given in the [Raspberry Pi Geek 04/2017](#).  
A pre-pared 64-bit image for the RasPi 3 is [here](#)