

Defect Dynamics in an Oscillatory Reaction-Diffusion Equation

Jonathan A. Sherratt

Department of Mathematics
Heriot-Watt University

Dynamics of Patterns Day, Amsterdam, November 26, 2008

This talk can be downloaded from my web site
www.ma.hw.ac.uk/~jas

This work is in collaboration with:

Matthew Smith

(Microsoft Research
Ltd., Cambridge)



Jens Rademacher

(CWI, Amsterdam)



Outline

- 1 Ecological Motivation
- 2 A Generic Mathematical Model
- 3 Periodic Travelling Wave Stability
- 4 Source-Sink Dynamics
- 5 Conclusions

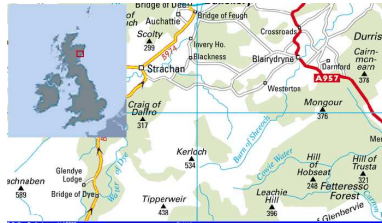
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Habitat Boundaries in Ecology

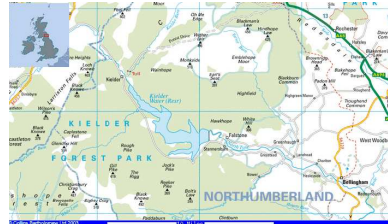
- Ecological habitats are often surrounded by unfavourable environments
- Examples: a wood surrounded by open terrain
moorland surrounded by farmland
marsh surrounded by dry ground
- An appropriate boundary condition is
“population density=0”

Example: Red Grouse on Kerloch Moor



- Red grouse is a cyclic population (period 4-6 years)
- The study site is moorland, with farmland at its Northern edge
- Farmland is very hostile for red grouse

Second Example: Field Voles in Kielder Forest



Field voles in Kielder Forest are also cyclic (period 4 years)

Boundary Condition at the Reservoir Edge

- Voles are an important prey species for owls and kestrels
- The open expanse of Kielder Water will greatly facilitate hunting at its edge



Short eared owl



Common kestrel

Boundary Condition at the Reservoir Edge

- Voles are an important prey species for owls and kestrels
- The open expanse of Kielder Water will greatly facilitate hunting at its edge
- Therefore we expect very high vole loss at the reservoir edge, implying that a suitable boundary condition is “vole density=0”

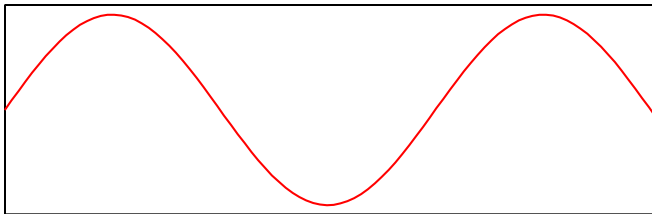
Periodic Travelling Waves in Red Grouse & Field Voles



Spatiotemporal data shows that both red grouse cycles on Kerloch Moor and field vole cycles in Kielder Forest are spatially organised into a periodic travelling wave (wavetrain)



Population Density



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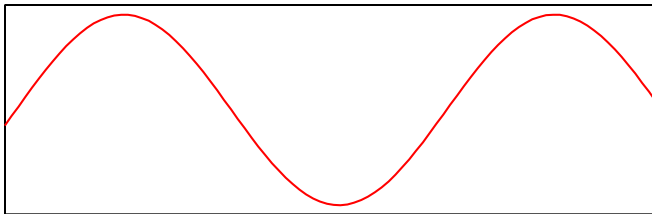
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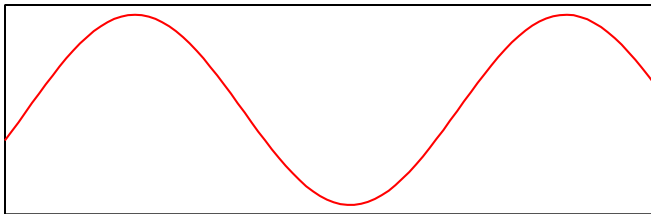
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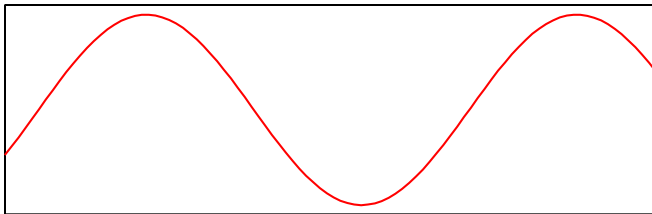
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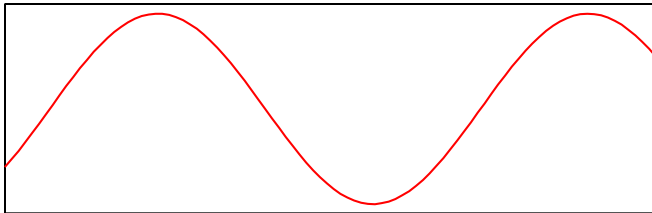
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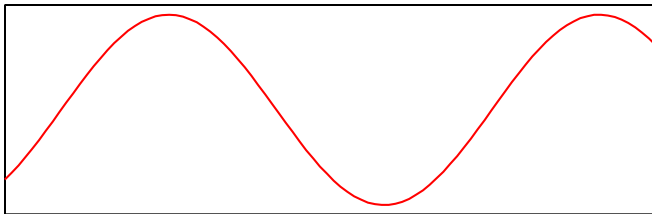
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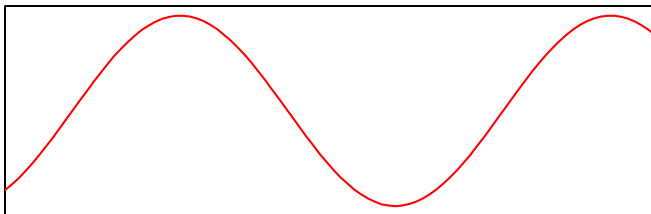
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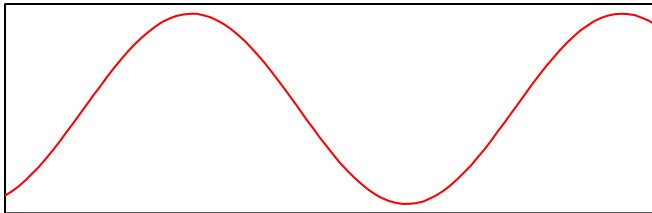
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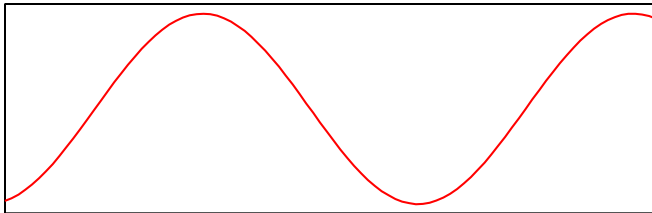
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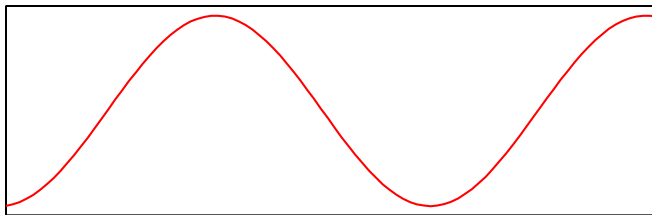
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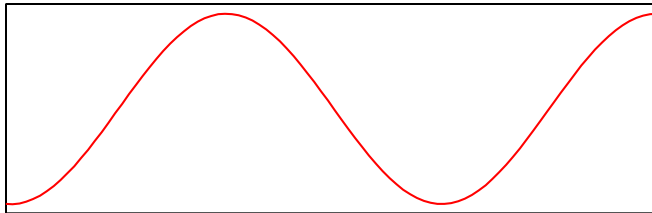
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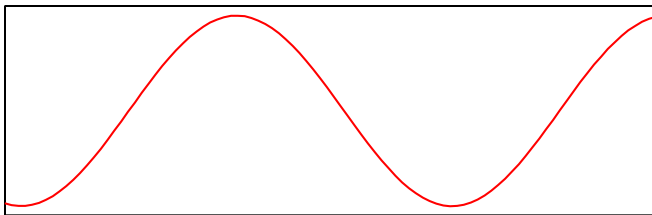
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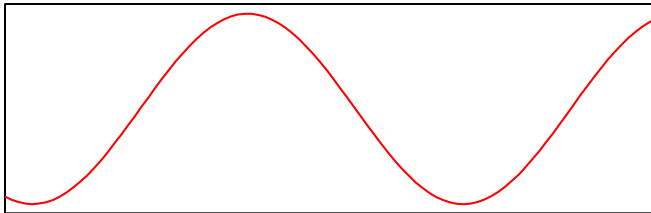
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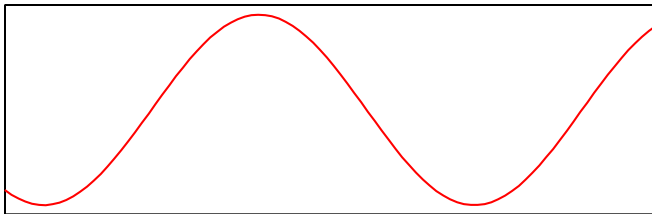
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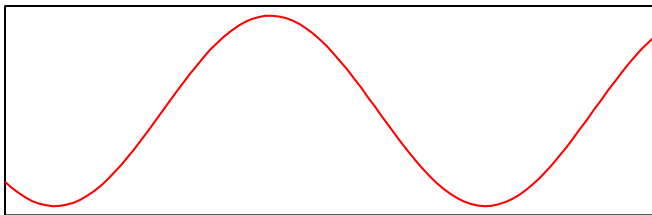
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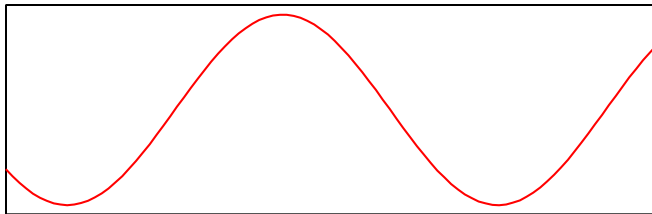
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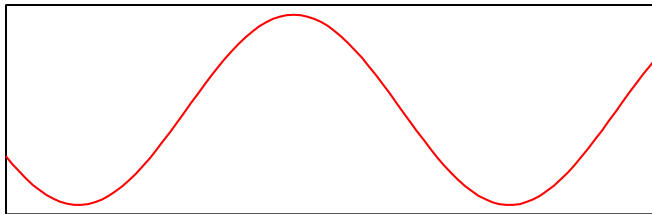
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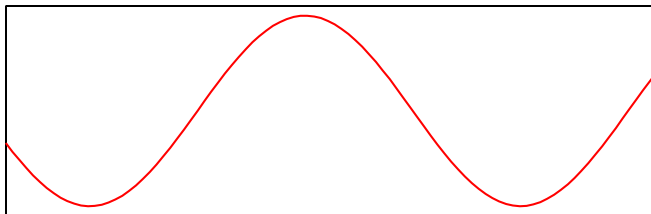
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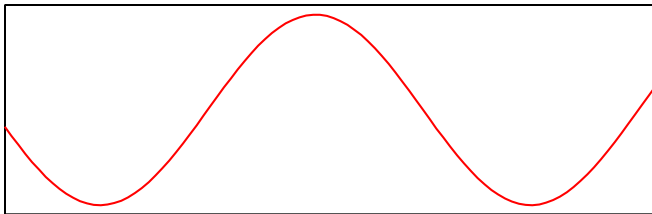
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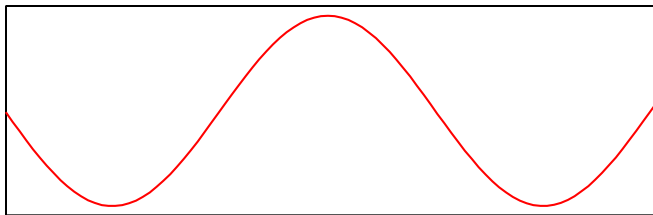
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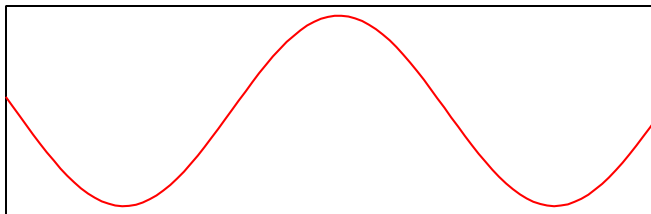
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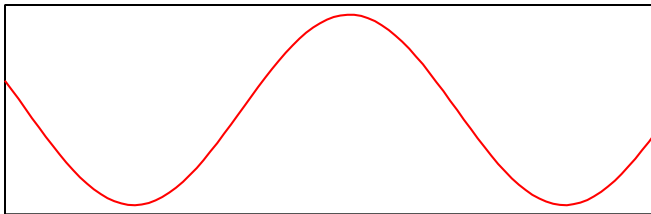
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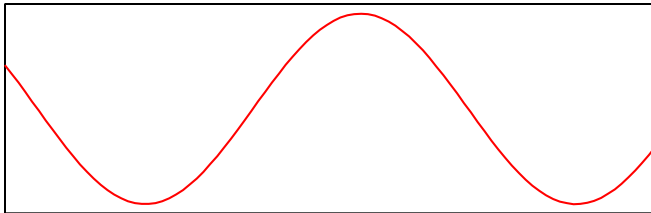
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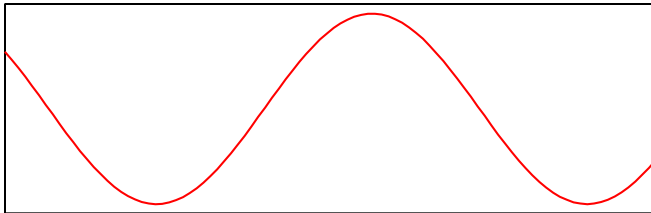
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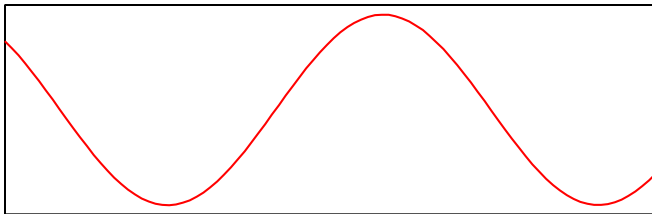
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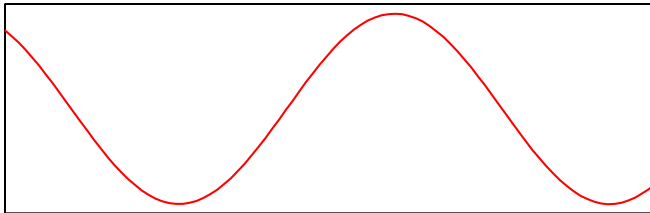
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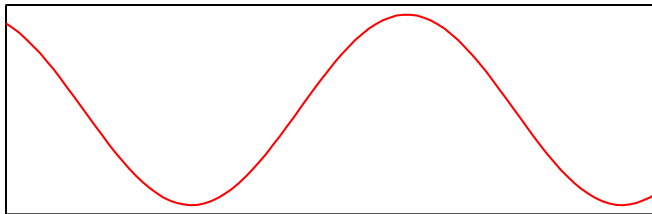
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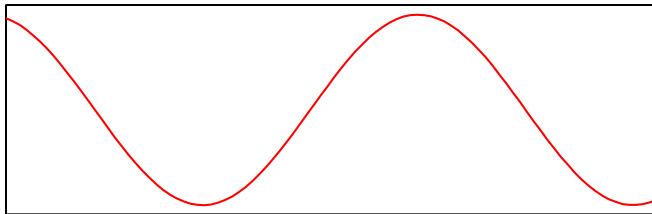
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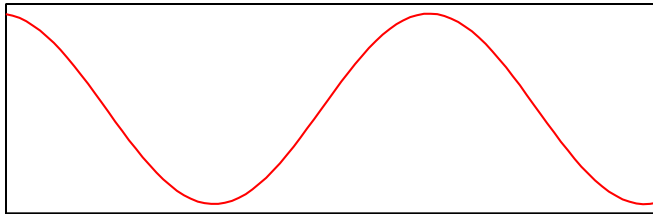
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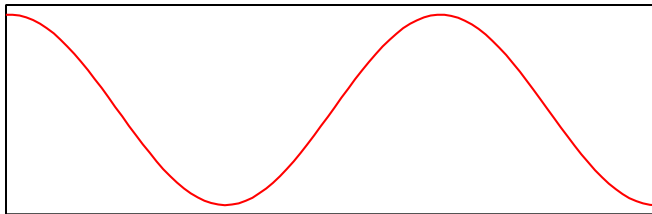
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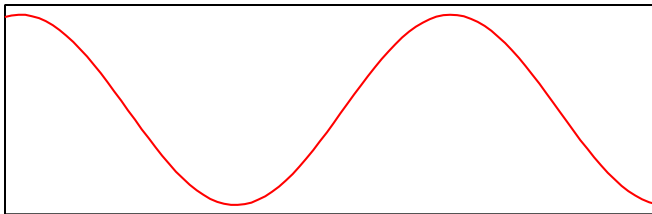
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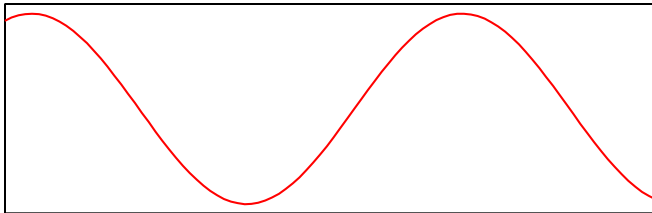
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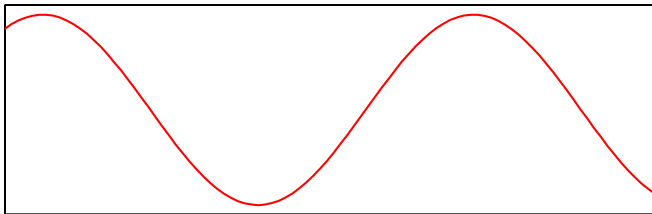
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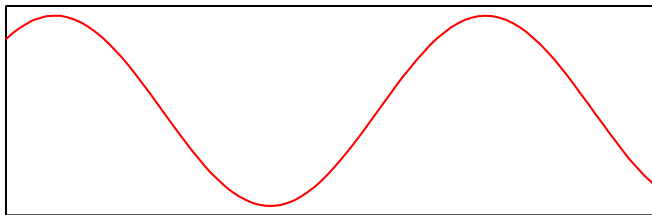
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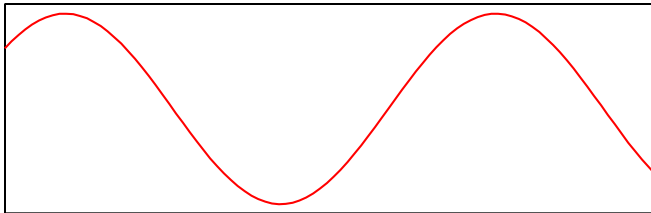
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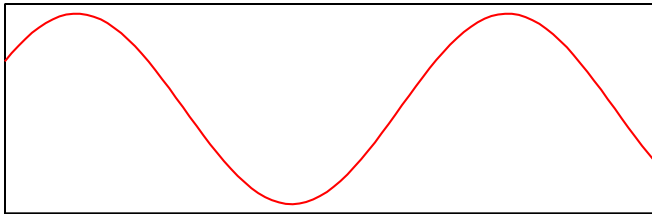
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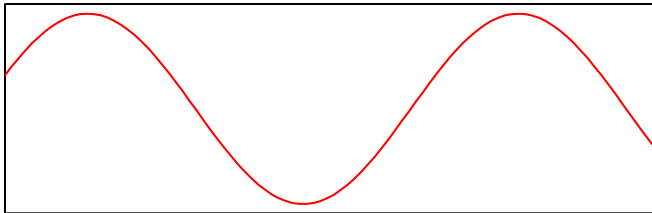
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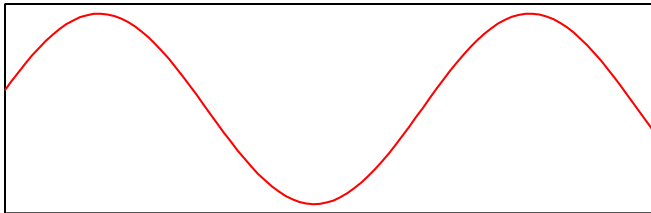
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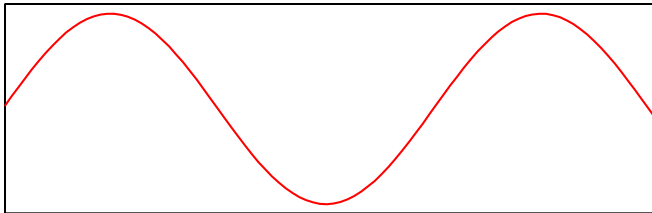
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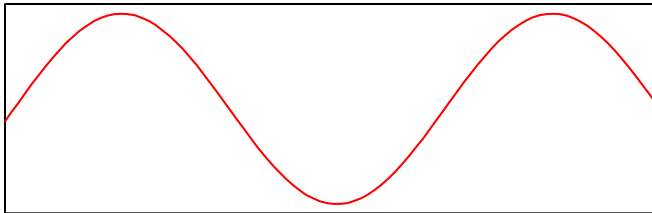
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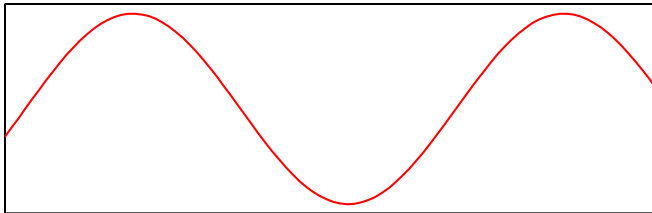
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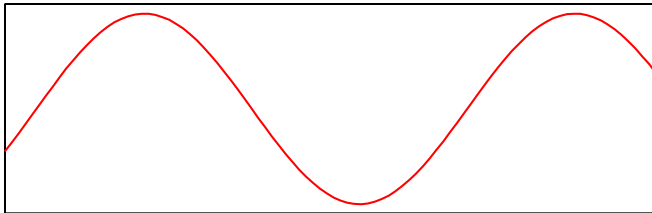
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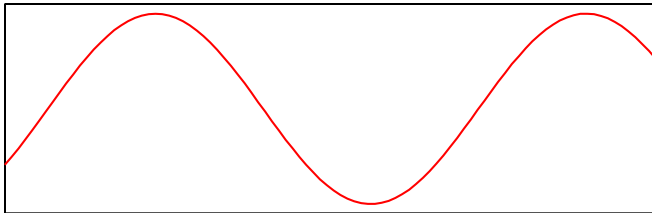
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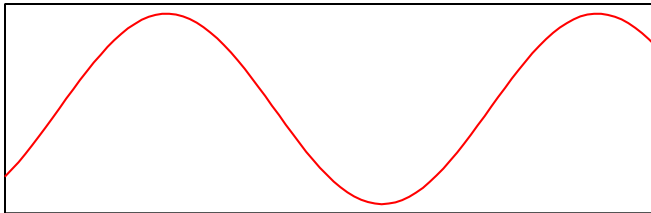
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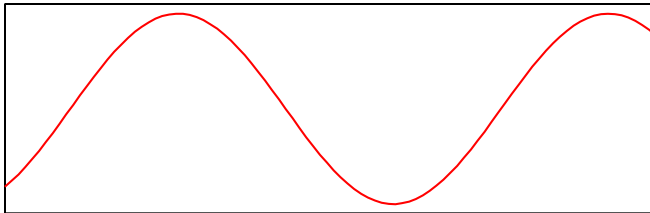
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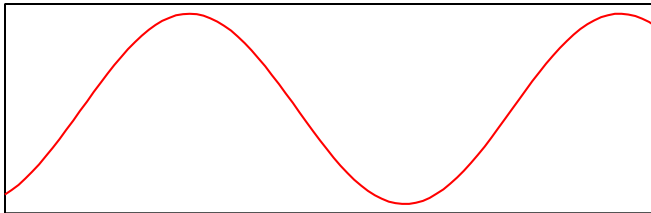
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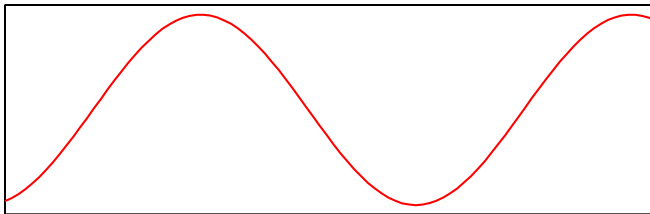
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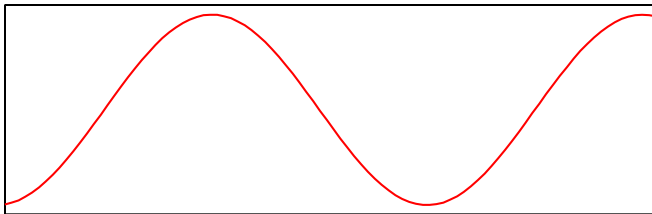
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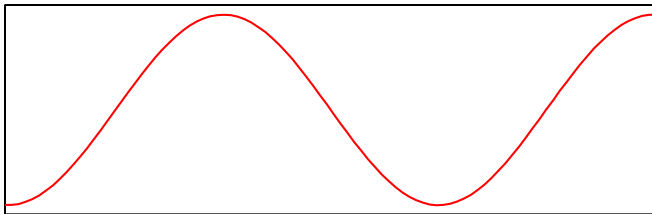
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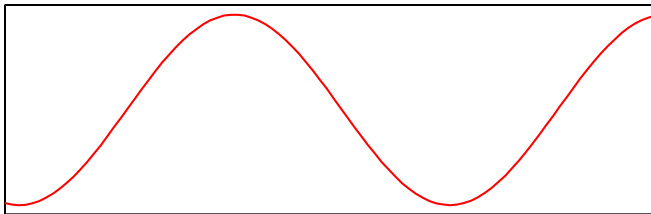
Periodic Travelling Waves in Red Grouse & Field Voles



Spatiotemporal data shows that both red grouse cycles on Kerloch Moor and field vole cycles in Kielder Forest are spatially organised into a periodic travelling wave (wavetrain)



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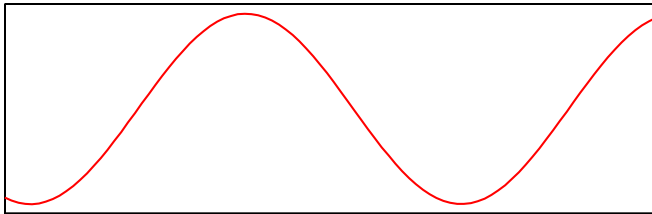
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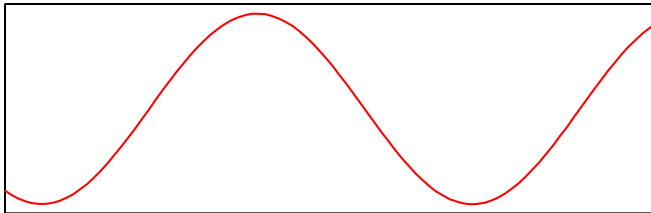
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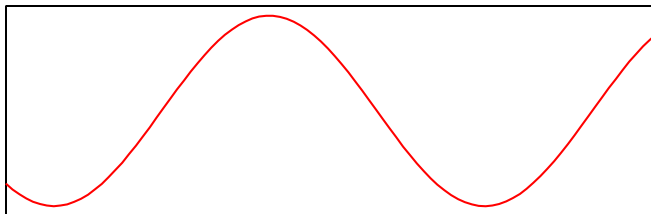
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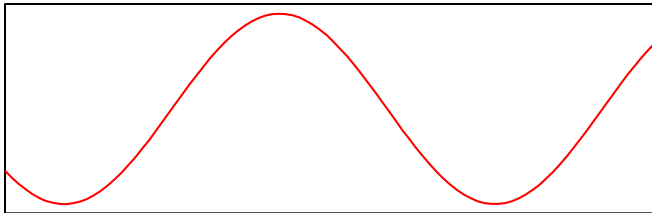
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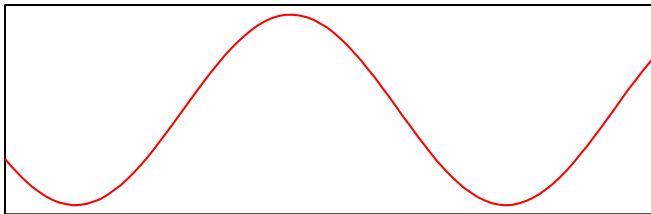
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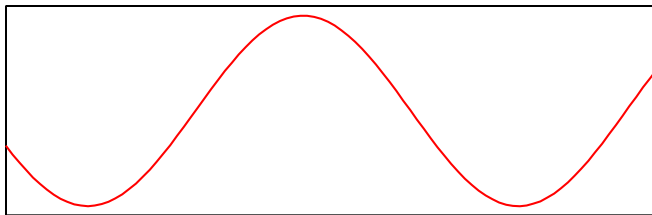
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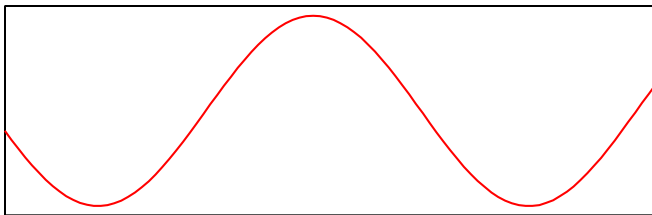
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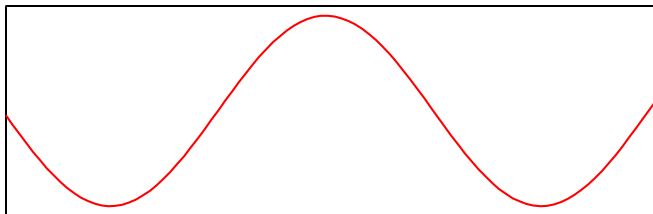
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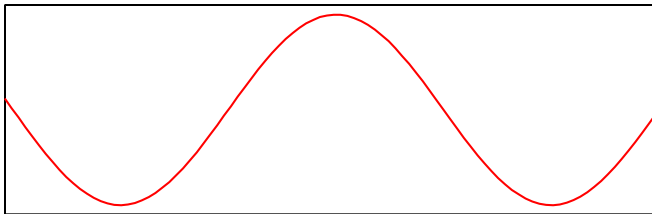
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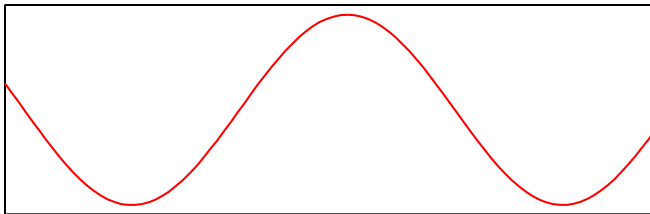
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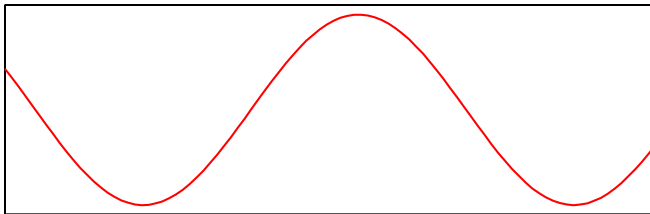
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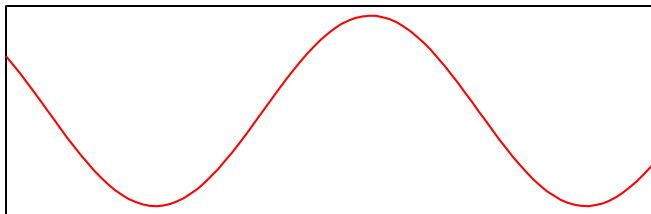
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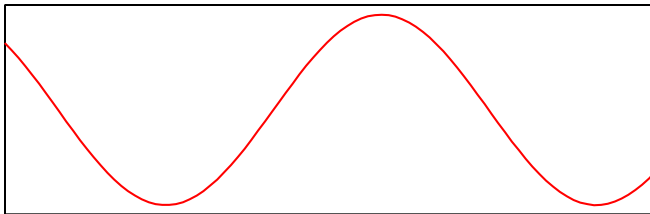
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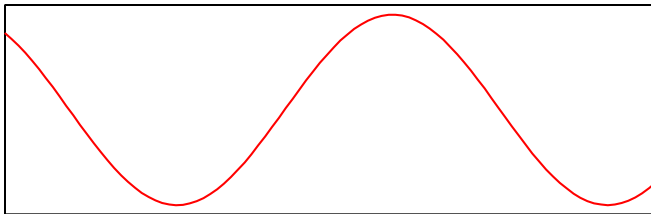
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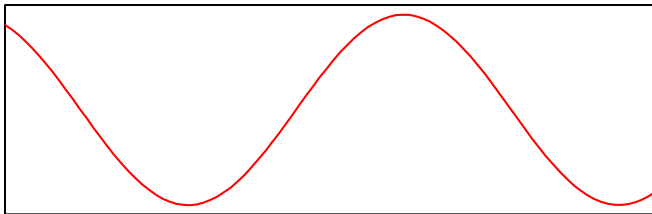
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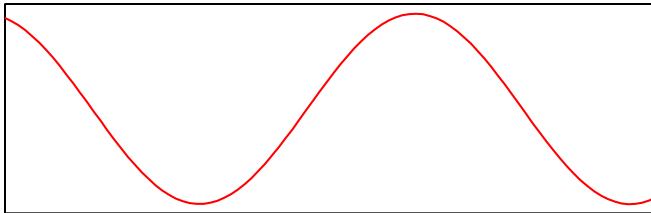
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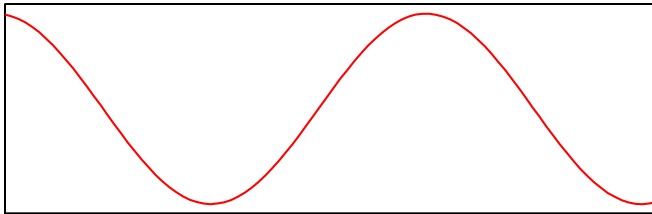
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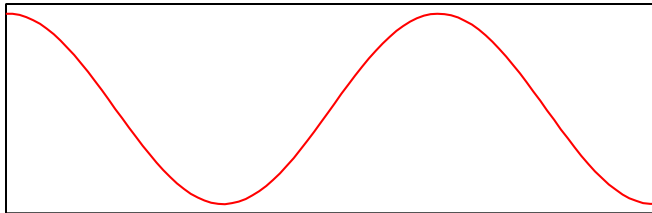
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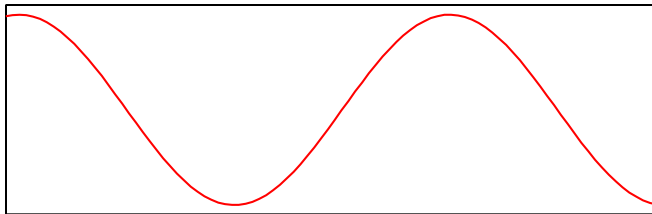
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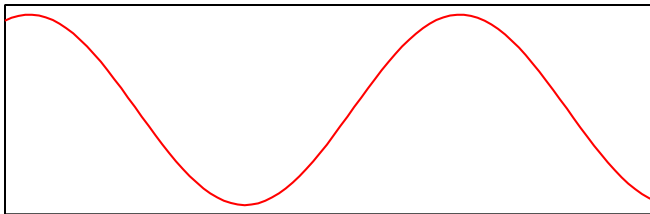
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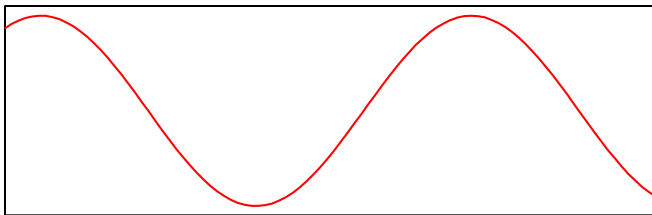
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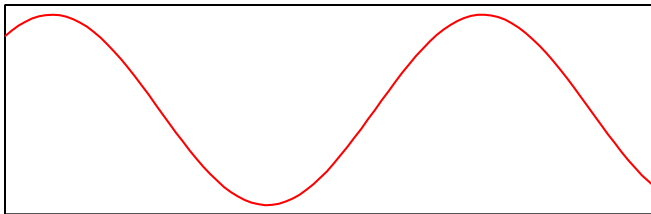
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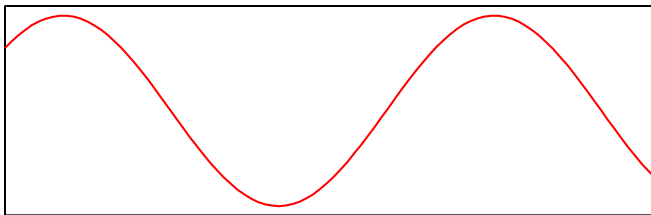
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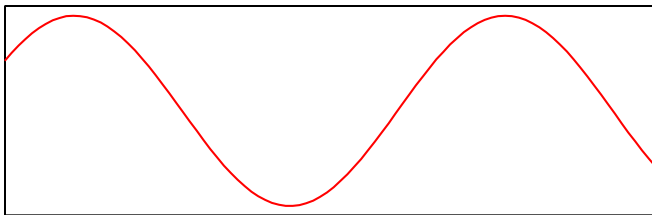
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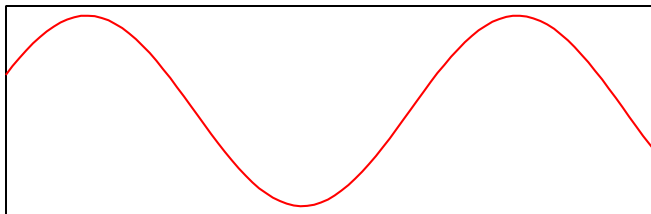
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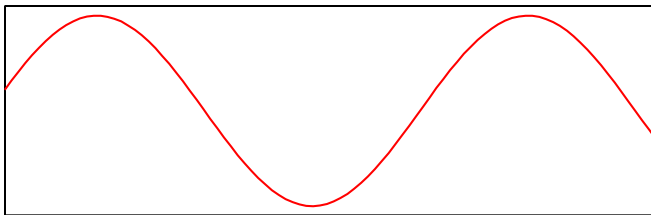
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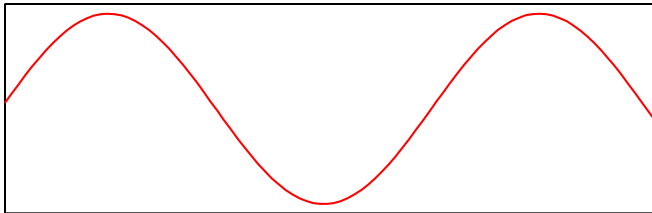
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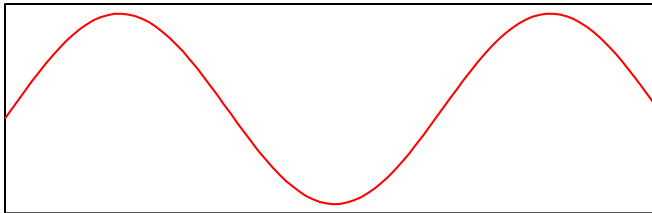
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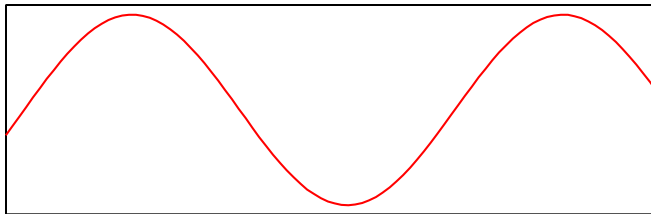
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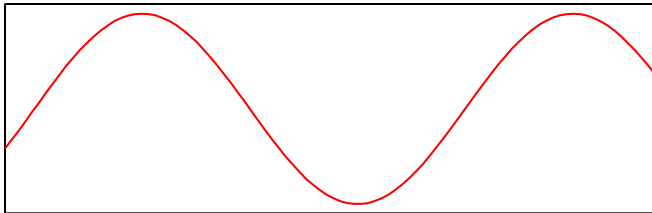
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Population Density



Space

Periodic Travelling Wave Generation Question

Question

Does the Dirichlet condition
at the habitat boundary
play a role in generating
the periodic travelling waves?

Outline

- 1 Ecological Motivation
- 2 A Generic Mathematical Model
- 3 Periodic Travelling Wave Stability
- 4 Source-Sink Dynamics
- 5 Conclusions

Mathematical Model

I consider a generic oscillator model (“ λ – ω equations”)

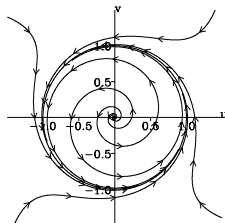
$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \lambda(r)u - \omega(r)v$$

$$\frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} + \omega(r)u + \lambda(r)v$$

$$r = \sqrt{u^2 + v^2}$$

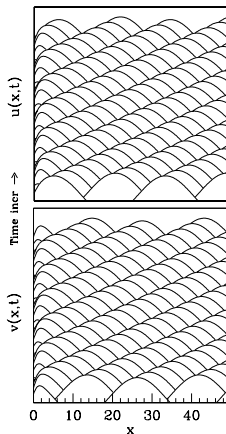
$$\lambda(r) = 1 - r^2$$

$$\omega(r) = \omega_0 + \omega_1 r^2$$



This is the normal form of an oscillatory reaction-diffusion system with scalar diffusion close to a supercritical Hopf bifurcation

Typical Model Solutions



$$\text{Eqns: } \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \lambda(r)u - \omega(r)v$$

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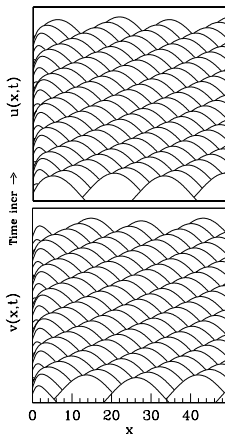
$$\lambda(r) = 1 - r^2$$

$$\omega(r) = \omega_0 + \omega_1 r^2$$

$$\text{Bcs: } u = v = 0 \quad \text{at } x = 0$$

$$u_x = v_x = 0 \quad \text{at } x = 50$$

Typical Model Solutions



Conclusion

Dirichlet boundary conditions
generate a
periodic travelling wave

Question

What is the amplitude,
speed and wavelength of the
periodic travelling wave?

Amplitude and Phase Equations

To study the λ - ω equations, it is helpful to replace u and v by $r = \sqrt{u^2 + v^2}$ and $\theta = \tan^{-1}(v/u)$, giving

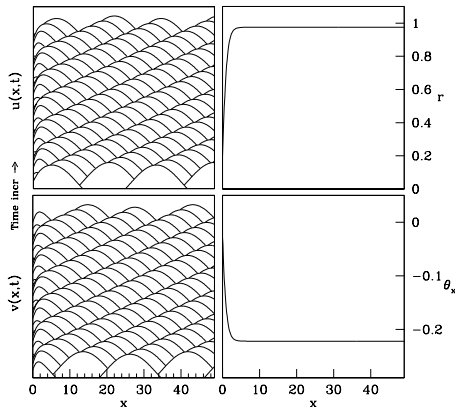
$$\begin{aligned} r_t &= r_{xx} - r\theta_x^2 + r(1 - r^2) \\ \theta_t &= \theta_{xx} + \frac{2r_x\theta_x}{r} + \omega_0 - \omega_1 r^2 \end{aligned}$$

Family of periodic travelling wave solutions ($0 < r^* < 1$):

$$\left\{ \begin{array}{l} r = r^* \\ \theta = [\omega(r^*)t \pm \sqrt{\lambda(r^*)}x] \end{array} \right\} \leftrightarrow \left\{ \begin{array}{l} u = r^* \cos [\omega(r^*)t \pm \sqrt{\lambda(r^*)}x] \\ v = r^* \sin [\omega(r^*)t \pm \sqrt{\lambda(r^*)}x] \end{array} \right\}$$

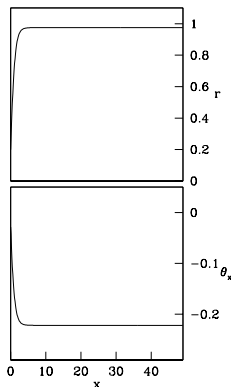
Our question: what r^* is selected by the Dirichlet boundary condition?

Typical Solutions Replotted



Replotting the solutions
in terms of r and θ_x
shows that the
long-term solutions for
 r and θ_x are
independent of time

Equilibrium Equations and the Wavetrain Amplitude



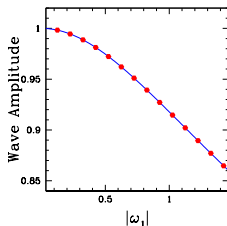
There is an exact solution for
 $r = R(x)$, $\theta_x = \Psi(x)$ on $0 < x < \infty$:

$$R(x) = R^* \tanh\left(x/\sqrt{2}\right) \quad \Psi(x) = \Psi^* \tanh\left(x/\sqrt{2}\right)$$

$$R^* = \left\{ \frac{1}{2} \left[1 + \sqrt{1 + \frac{8}{9} \omega_1^2} \right] \right\}^{-1/2} \Psi^* = -\text{sign}(\omega_1) (1 - R^{*2})^{1/2}$$

Equilibrium Equations and the Wavetrain Amplitude

Wave amplitude
 R^* is in very
 good agreement
 with that found
 in numerical
 simulations.



There is an exact solution for
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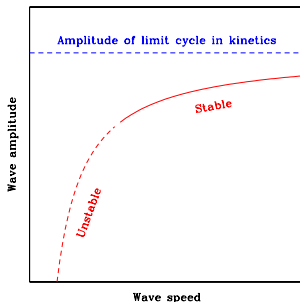
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Stability in the Periodic Travelling Wave Family

In any oscillatory reaction-diffusion system, some members of the periodic travelling wave family are stable as solutions of the partial differential equations, while others are unstable.



For our λ - ω system, the stability condition is

$$r^* > \left(\frac{2 + 2\omega_1^2}{3 + 2\omega_1^2} \right)^{1/2}$$

Stability of the Selected Wave

The stability of the selected wave depends on ω_1 .

$$R^* = \left\{ \frac{1}{2} \left[1 + \sqrt{1 + \frac{8}{9}\omega_1^2} \right] \right\}^{-1/2}$$

This is stable

$$\Leftrightarrow R^* > \left(\frac{2 + 2\omega_1^2}{3 + 2\omega_1^2} \right)^{1/2}$$
$$\Leftrightarrow |\omega_1| < 1.110468 \dots$$

Stability of the Selected Wave

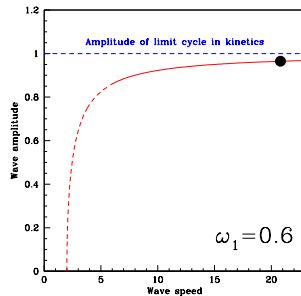
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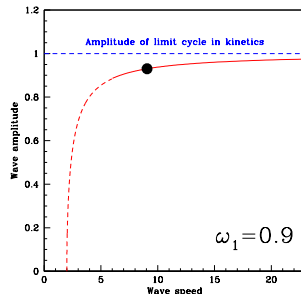
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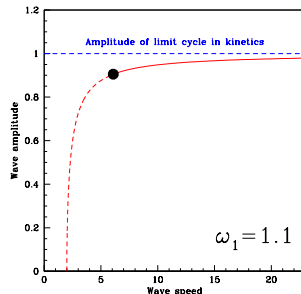
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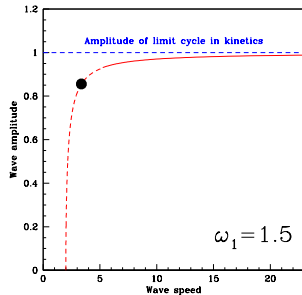
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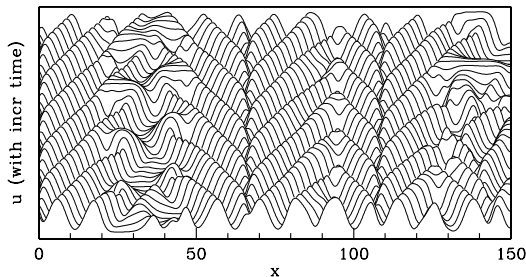
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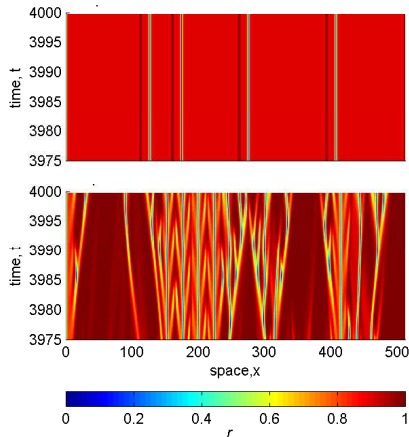
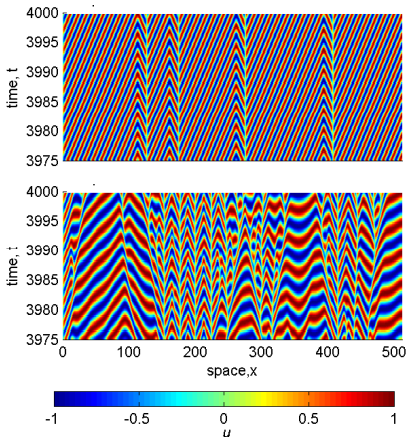


Typical Solution in an Unstable Case



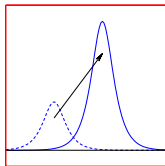
Convective and Absolute Stability

- There are a variety of different solution forms for $|\omega_1| > 1.110468 \dots$ (unstable waves).



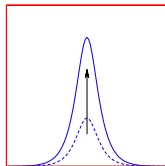
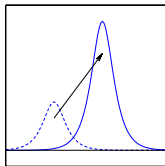
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Convective and Absolute Stability

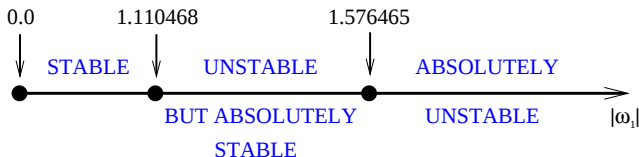
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- Alternatively, a solution can be unstable with perturbations growing without moving. This is “absolute instability”.
- Absolute instability implies instability irrespective of boundary conditions.

Absolute Stability of Wavetrains

- Absolute stability is much harder to calculate than stability.
- For wavetrain solutions of λ - ω reaction-diffusion equations, we have calculated absolute stability by computing the “absolute spectrum” via numerical continuation, adapting the method of Rademacher, Sandstede & Scheel (Physica D 229: 166-183, 2007)

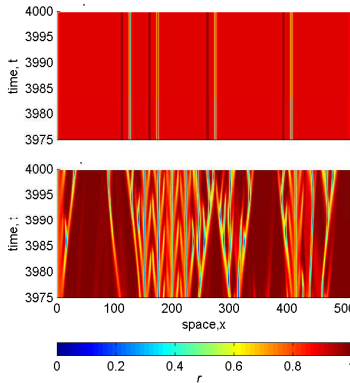
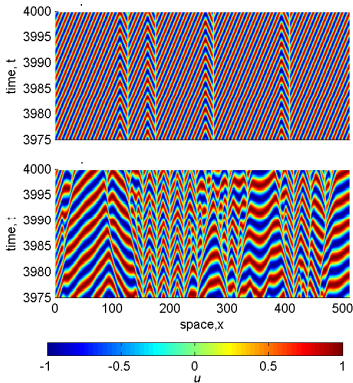
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- Our calculation shows that the stability of the selected wavetrain is:



Generation of Absolutely Stable and Unstable Wavetrains by Dirichlet Boundary Conditions

Numerical simulations show distinct behaviours in the absolutely stable and unstable parameter regimes



Convectively
unstable,
absolutely
stable

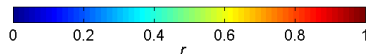
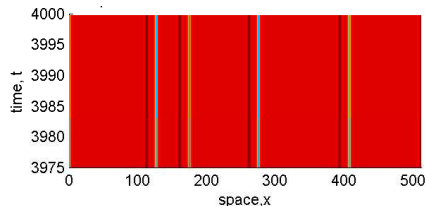
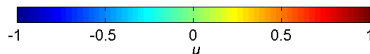
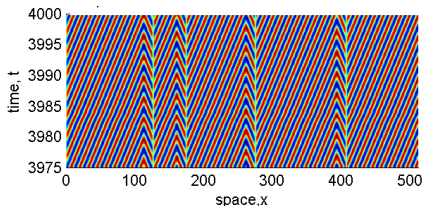
Absolutely
unstable

Outline

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- 2 A Generic Mathematical Model
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Sources, Sinks, and Convective Instability

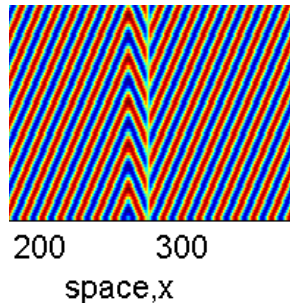
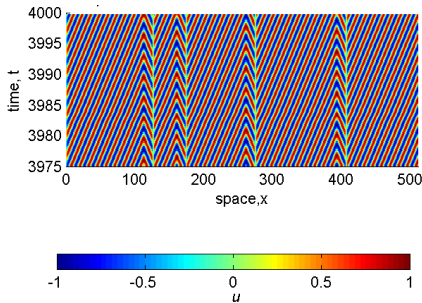
I focus on the convectively unstable but absolutely stable case.



This solution is a pattern of “sources and sinks”.

Sources, Sinks, and Convective Instability

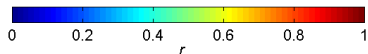
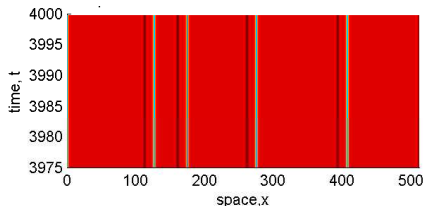
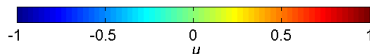
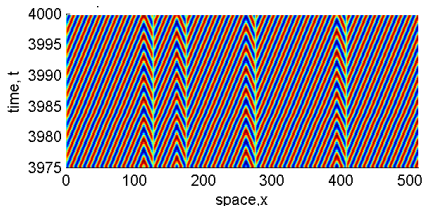
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Sources, Sinks, and Convective Instability

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This solution is a pattern of “sources and sinks”.

The wavetrain between the defects has (approximately) amplitude

$$R^* = \left\{ \frac{1}{2} \left[1 + \sqrt{1 + \frac{8}{9} \omega_1^2} \right] \right\}^{-1/2}.$$

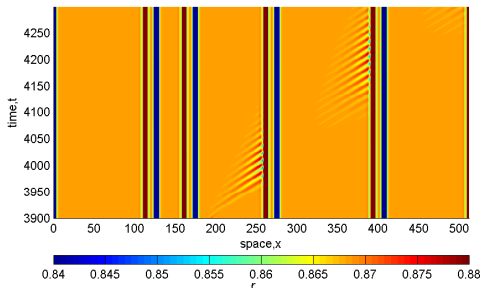
Sources, Sinks, and Convective Instability

Question: How can an unstable wavetrain persist between the sources and sinks?

Sources, Sinks, and Convective Instability

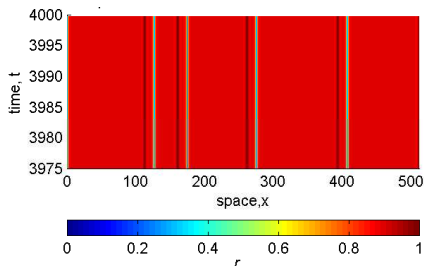
Question: How can an unstable wavetrain persist between the sources and sinks?

Answer: Any growing perturbations moves, and is absorbed when it reaches a sink.



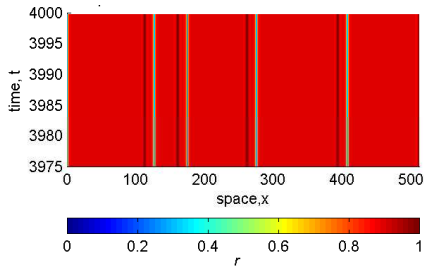
Movement of Sources and Sinks

The sources and sinks appear to be stationary.....

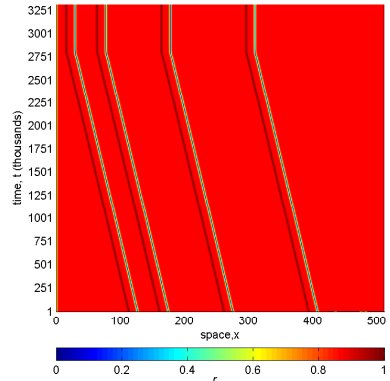


Movement of Sources and Sinks

The sources and sinks appear to be stationary.....



.....but very long simulations show that they move.



Travelling Waves of Amplitude

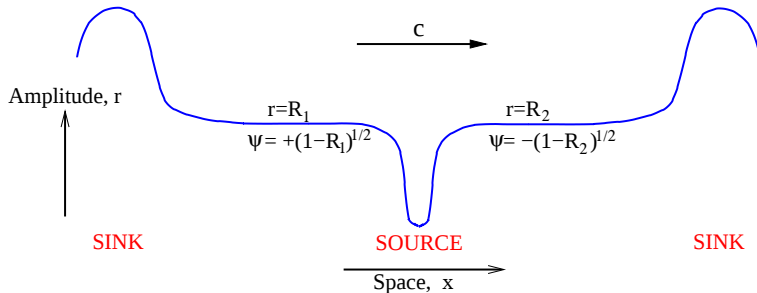
The source-sink patterns are of travelling wave form in amplitude.

Substitute $r(x, t) = \hat{r}(z)$, $\theta_x(x, t) = \hat{\psi}(z)$, $z = x - ct$

$$\begin{aligned}\implies \quad d^2\hat{r}/dz^2 + c d\hat{r}/dz + \hat{r} (1 - \hat{r}^2 - \hat{\psi}^2) &= 0 \\ d\hat{\psi}/dz + c \hat{\psi} + K - \omega_1 \hat{r}^2 + 2\hat{\psi} (d\hat{r}/dz)/\hat{r} &= 0\end{aligned}$$

(K is a constant of integration).

Solution Structure



Between the source and the neighbouring sinks,

$$-c(1 - R_1^2)^{1/2} + \omega_1 R_1^2 = K = +c(1 - R_2^2)^{1/2} + \omega_1 R_2^2$$

$\implies c$ has the same sign as $R_1 - R_2$.

Eigenvalue Structure of Stationary Sources and Sinks

Stationary sources and sinks satisfy

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Linearise about the wavetrain

⇒ stationary sources decay to the wavetrain at rate $\sqrt{2}$
 & stationary sinks decay to the wavetrain at rate $1/\sqrt{2} \pm i\delta/4$

$$(\delta = \sqrt{11 - 12R^{*2}} \in \mathbb{R})$$

⇒ the effect of the moving sinks on the sources dominates
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⇒ when c is small, we can just consider the correction
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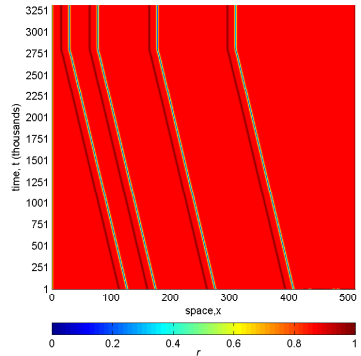
⇒ when c is small, we can just consider the correction
 to a **stationary source**: $r = R^* |\tanh(z/\sqrt{2})|$

Perturbation Theory Calculation

The wave speed is a natural small parameter.....

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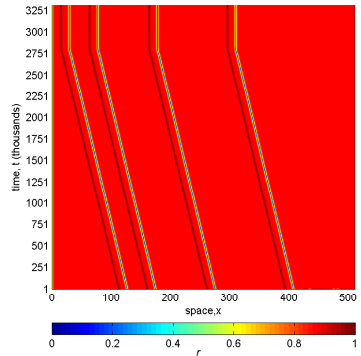


Perturbation Theory Calculation

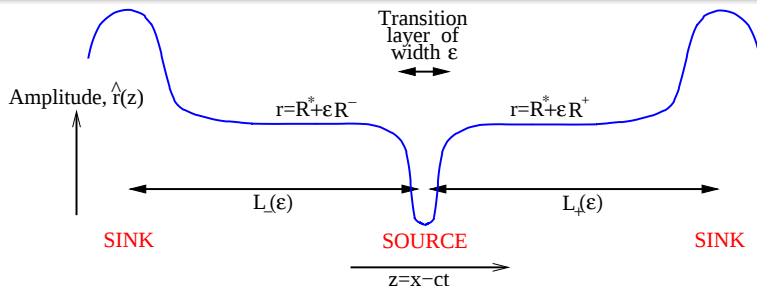
The wave speed is a natural small parameter.....

.....but

$\epsilon = [\frac{1}{2}(R_1 + R_2) - R^*] \cdot (\text{constant})$
is a better choice, where R^* is the amplitude of the stationary source.



Perturbation Theory Calculation



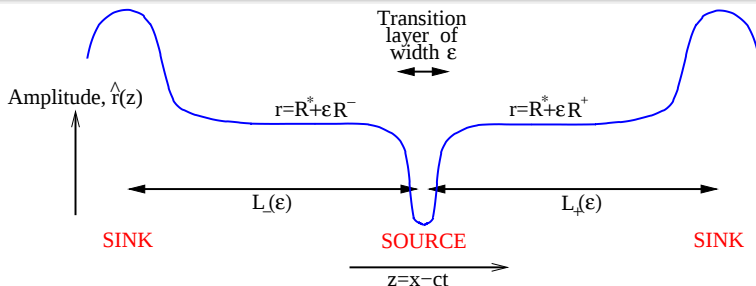
For $\epsilon = 0 : c = 0$

$$K = (9 - \sqrt{81 + 72\omega_1^2}) / (4\omega_1)$$

$$\hat{r} = R^* |\tanh(z/\sqrt{2})|$$

$$\hat{\psi} = -(1 - R^{*2})^{1/2} \tanh(z/\sqrt{2})$$

Perturbation Theory Calculation



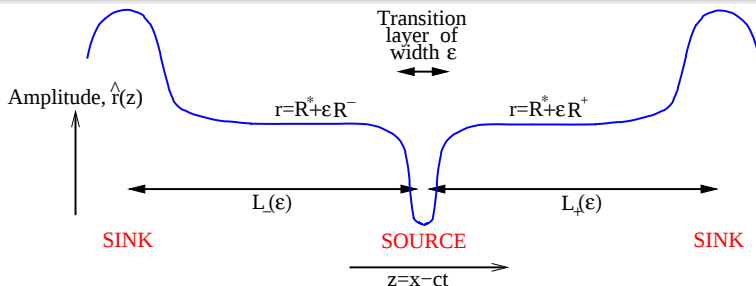
For $\epsilon \neq 0$: $c = \epsilon c_1 + O(\epsilon^2)$

$K = (9 - \sqrt{81 + 72\omega_1^2}) / (4\omega_1) + \epsilon K_1 + O(\epsilon^2)$

$\hat{r} = R^* |\tanh(z/\sqrt{2})| + \epsilon \hat{r}_1(z) + O(\epsilon^2)$

$\hat{\psi} = -(1 - R^{*2})^{1/2} \tanh(z/\sqrt{2}) + \epsilon \hat{\psi}_1(z) + O(\epsilon^2)$

Perturbation Theory Calculation



Results:
$$L_{\pm}(\epsilon) = -\sqrt{2} \log |\epsilon| - \sqrt{2} \log \kappa_{\pm} + o(1)$$

where $\kappa_- \exp\{+i\delta \log \kappa_-\} + \kappa_+ \exp\{+i\delta \log \kappa_+\} = A$

A is a (complex) constant, independent of c_1 , $O(1)$ as $\epsilon \rightarrow 0$

(recall that $\delta = \sqrt{11 - 12R^{*2}} \in \mathbb{R}$)

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A Family of Moving Sources and Sinks

There is a three parameter family of moving sources and sinks:

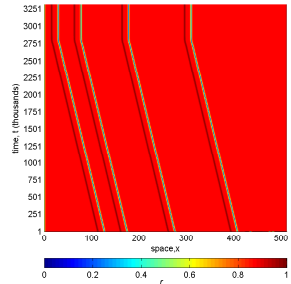
Parameter 1: ϵ , which reflects the difference in wavetrain amplitudes

Parameter 2: c_1 , which reflects the speed of movement

Parameter 3: $\kappa_{\pm}$, which reflects the $O(1)$ contribution to the source-sink separation

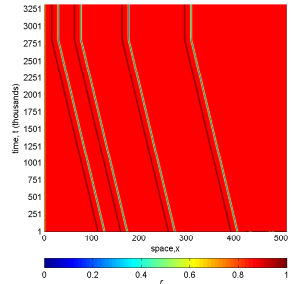
Implications for the PDE Solutions

- Source-sink separations are variable. This corresponds to different values of $\kappa_{\pm}$ associated with different sources.



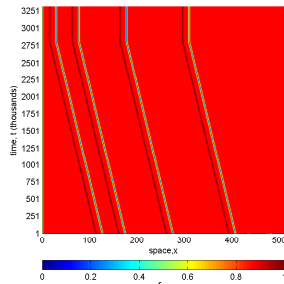
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- The sources and sinks all stop moving at (approximately) the same time. This is expected: all are part of a single travelling wave solution.



Implications for the PDE Solutions

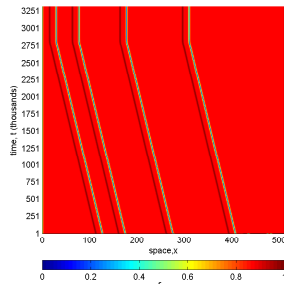
- Source-sink separations are variable. This corresponds to different values of $\kappa_{\pm}$ associated with different sources.
- The sources and sinks all stop moving at (approximately) the same time. This is expected: all are part of a single travelling wave solution.
- There is (approximately) no change in the source-sink separation when the sources and sinks stop moving. This is because the equation for $\kappa_{\pm}$ does not involve the parameter c_1 .



Implications for the PDE Solutions

- What is the distance between the leading sink and the $x = 0$ boundary when the sources and sinks stop moving? A minor adaptation of the calculation shows that the separation $L_{bdy}(\epsilon)$ is

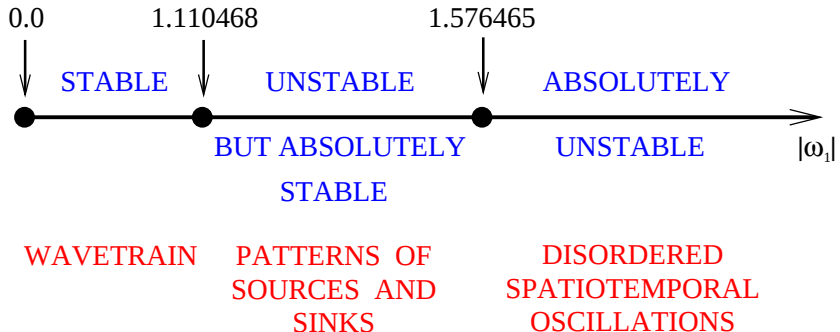
$$-\sqrt{2} \log |\epsilon| - \sqrt{2} \log \kappa_{bdy} + o(1)$$



where $\text{Im} \left[\overline{\sigma_2} \kappa_{bdy} \exp \left\{ +i\delta(\log |\epsilon| + \log \kappa_{bdy}) \right\} \right] = \text{sign}(\epsilon)$

(σ_2 is a (complex) constant; recall $\delta = \sqrt{11 - 12R^*{}^2} \in \mathbb{R}$)

Overall Conclusion



Objectives for Future Work

- A better understanding of how a particular member of the family of moving sources and sinks is selected.
- A better understanding of the disordered solutions in the absolutely unstable parameter regime.

List of Frames

- 1 **Ecological Motivation**
- Habitat Boundaries in Ecology
 - Example: Red Grouse on Kerloch Moor
 - Second Example: Field Voles in Kielder Forest
 - Periodic Travelling Waves in Red Grouse & Field Voles

- 2 **A Generic Mathematical Model**
- Mathematical Model
 - Amplitude and Phase Equations
 - Equilibrium Equations and the Wavetrain Amplitude

- 3 **Periodic Travelling Wave Stability**
- Stability in the Periodic Travelling Wave Family
 - Stability of the Selected Wave
 - Convective and Absolute Stability
 - Absolute Stability of Wavetrains
 - Generation of Absolutely Stable and Unstable Wavetrains

- 4 **Source-Sink Dynamics**
- Sources, Sinks, and Convective Instability
 - Movement of Sources and Sinks
 - Travelling Waves of Amplitude
 - Solution Structure
 - Perturbation Theory Calculation

- 5 **Conclusions**
- A Family of Moving Sources and Sinks
 - Implications for the PDE Solutions
 - Overall Conclusion
 - Objectives for Future Work