

Modelling Cell Adhesion in Cancer

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Collaborators

Kevin Painter



Nicola Armstrong

Outline

- 1 Introduction and Basic Modelling
- 2 Model Solutions and Extensions
- 3 Application I: Somite Formation – Background
- 4 Application I: Somite Formation – New Modelling
- 5 Application II: Cancer Invasion

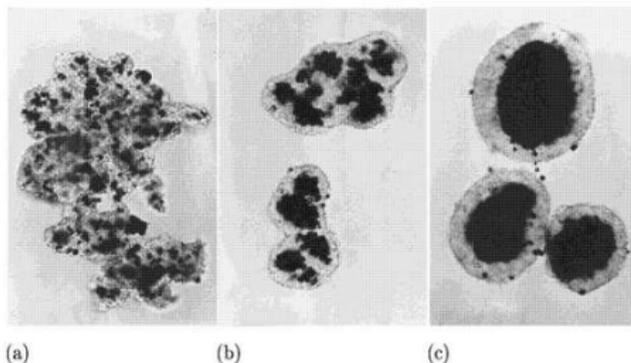
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What is Cell-Cell Adhesion?

- Cells bind to each other through cell adhesion molecules
- This is important in a range of developmental and pathological contexts
 - Embryonic cells adhere selectively, enabling them to sort into tissues and organs
 - Altered adhesion properties are thought to be important in tumour invasion

Aggregation and Cell Sorting



- (a) After 5 hours
- (b) After 19 hours
- (c) After 2 days

Armstrong, P.B. 1971. Wilhelm
Roux' Archiv 168, 125-141

Derivation of the Model I

- We assume no cell birth/death, with movement due to random motion and adhesion

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- Diffusive flux $J_d = -D\partial n / \partial x$
- Adhesive flux $J_a = \phi n F / R$
 F = force due to breaking and forming adhesive bonds
 ϕ = a constant related to viscosity
 R = the sensing radius of the cells

Derivation of the Model II

- The force on cells at x exerted by cells a distance x_0 away depends on
 - 1 cell density at $x + x_0$
 - 2 distance $|x_0|$
 - 3 sign of x_0 (\Rightarrow direction of force)

$$f(x, x_0) = \alpha \cdot g(n(x + x_0, t)) \cdot \omega(x_0)$$

Derivation of the Model II

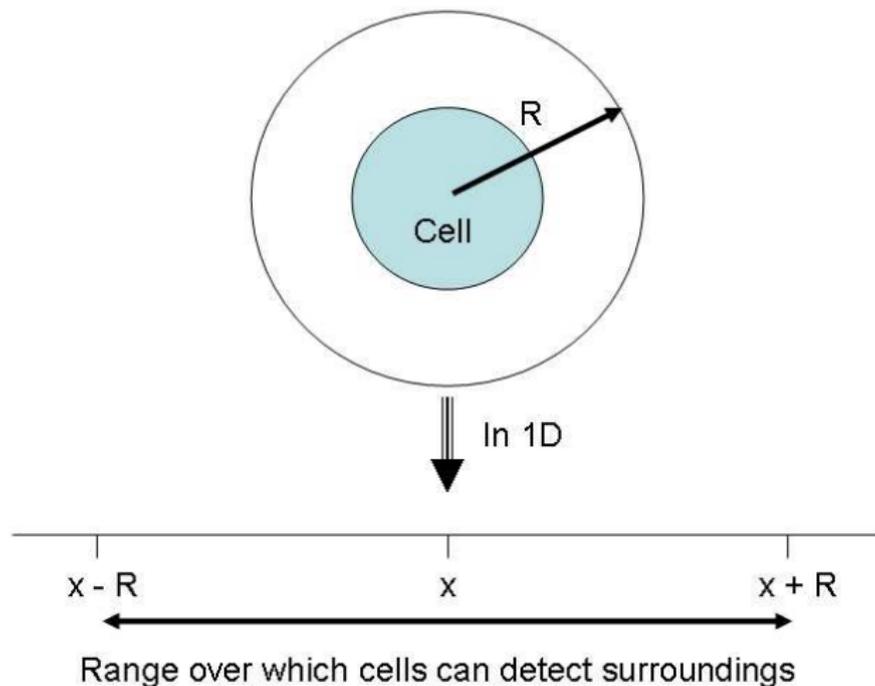
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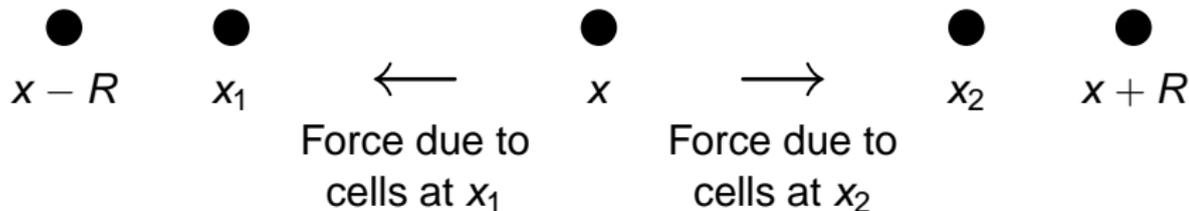
- Total force = sum of all forces acting on cells at x

$$F(x) = \int_{-R}^{+R} f(x, x_0) dx_0$$

Model Details: The Sensing Radius, R



Model Details: The Function $\omega(x_0)$



$\omega(x_0)$ is an odd function. For simplicity we take

$$\omega(x_0) = \begin{cases} -1 & \text{if } -R < x_0 < 0 \\ +1 & \text{if } 0 < x_0 < +R \end{cases}$$

Mathematical Model for One Cell Population

Nondimensionalising the model gives

$$\frac{\partial n}{\partial t} = \frac{\partial^2 n}{\partial x^2} - \frac{\partial}{\partial x} [nK(n)]$$

$$\text{where } K(n) = \alpha \int_{-1}^{+1} g(n(x + x_0, t)) \omega(x_0) dx_0$$

- Initially we assume $g(n) = n$

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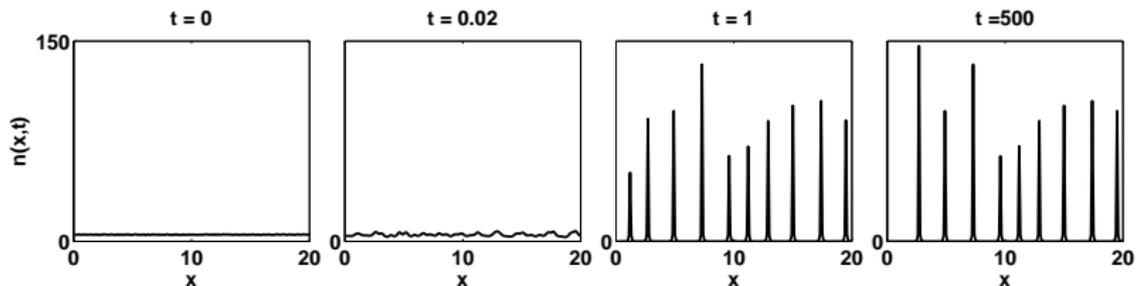
$$\text{where } K(n) = \alpha \int_{-1}^{+1} g(n(x + x_0, t)) \omega(x_0) dx_0$$

- Initially we assume $g(n) = n$
- We expect aggregation of disassociated cells
- Stability analysis and PDE approximation suggest that such aggregation does occur
- The adhesion parameter α is critical in determining model behaviour

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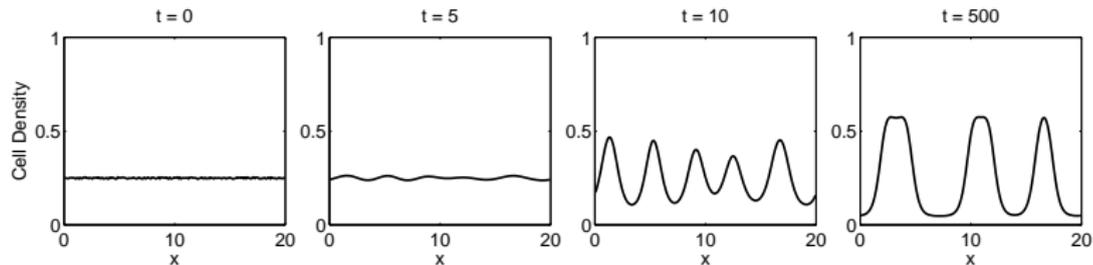
A Numerical Solution of the Basic Model



Model Improvement: Nonlinear $g(n)$

- The solutions of the basic model suffer from steep aggregations with progressive coarsening
- In reality, there will be a density limit beyond which cells will no longer aggregate
- We can account for this via a nonlinear $g(n)$; we take $g(n) = n(2n_{max} - n)$.
- We require $g(\cdot)$ to be an increasing function, so that n_{max} corresponds to close-packed cells

A Numerical Solution of the Improved Model



Extending the Model to Interacting Cell Populations I

- To consider cell sorting, we extend the model to two interacting cell populations
- The extended model includes self-population adhesion and cross-population adhesion

Extending the Model to Interacting Cell Populations II

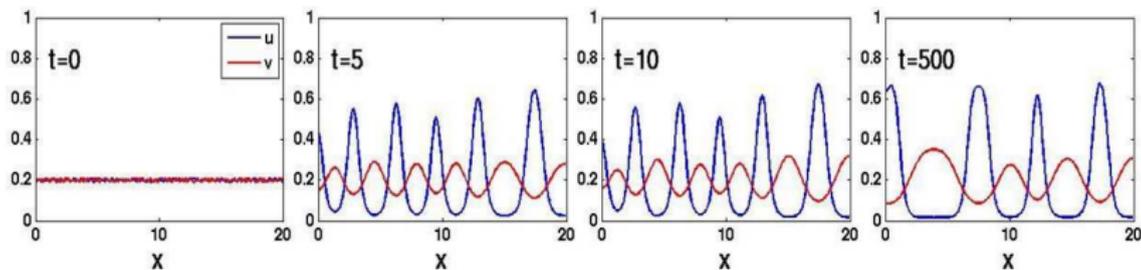
$$\frac{\partial n}{\partial t} = \frac{\partial^2 n}{\partial x^2} - \frac{\partial}{\partial x} [nK_n(n, m)] \quad \frac{\partial m}{\partial t} = \frac{\partial^2 m}{\partial x^2} - \frac{\partial}{\partial x} [mK_m(n, m)]$$

$$K_n = S_n \int_{-1}^{+1} g_{nn}(n(x+x_0, t), m(x+x_0, t)) \omega(x_0) dx_0 \\ + C \int_{-1}^{+1} g_{nm}(n(x+x_0, t), m(x+x_0, t)) \omega(x_0) dx_0$$

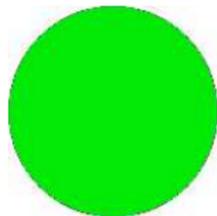
$$K_m = S_m \int_{-1}^{+1} g_{mm}(n(x+x_0, t), m(x+x_0, t)) \omega(x_0) dx_0 \\ + C \int_{-1}^{+1} g_{mn}(n(x+x_0, t), m(x+x_0, t)) \omega(x_0) dx_0$$

with $g_{nn} = g_{mn} = n(1 - n - m)$ and $g_{mm} = g_{nm} = m(1 - n - m)$

A Numerical Simulation of Cell Sorting in 1-D



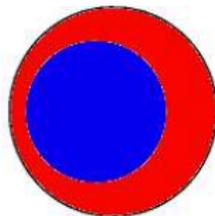
Experimental Cell Sorting Results



A

Mixing

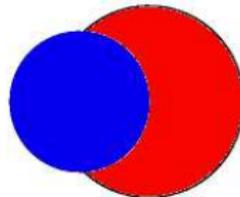
$$C > (S_n + S_m)/2$$



B

Engulfment

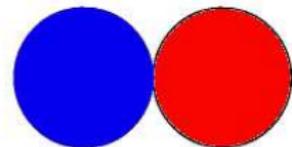
$$S_n > C > S_m$$



C

Partial
engulfment

$$C < S_n \text{ and } C < S_m$$



D

Complete
sorting

$$C = 0$$

Movie of Cell Sorting in 2-D: Case A

[Click here to
play the movie](#)

Movie of Cell Sorting in 2-D: Case B

[Click here to
play the movie](#)

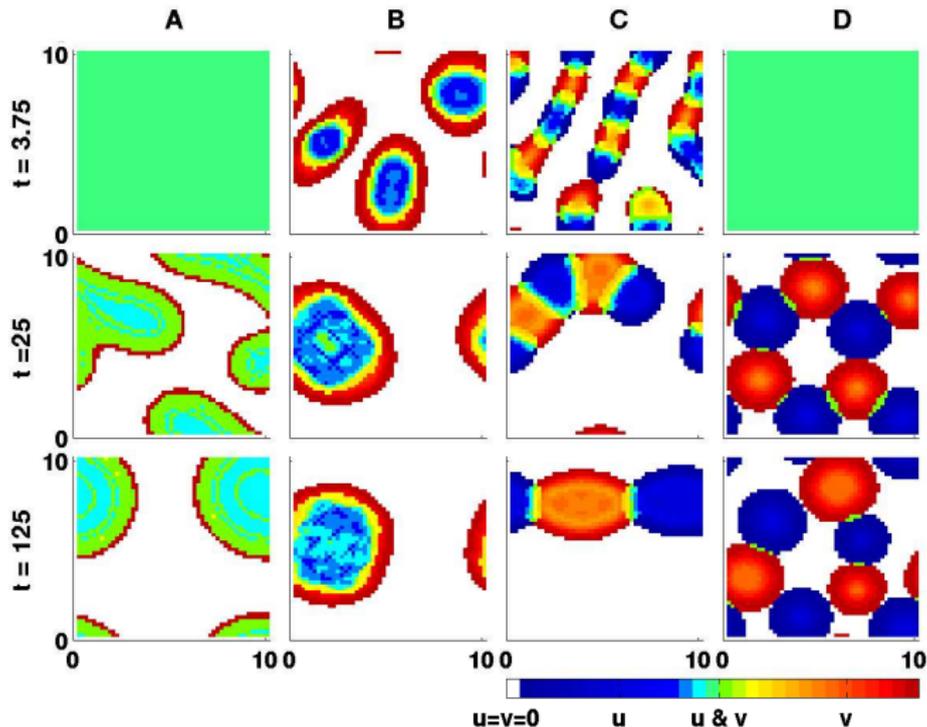
Movie of Cell Sorting in 2-D: Case C

Click here to
play the movie

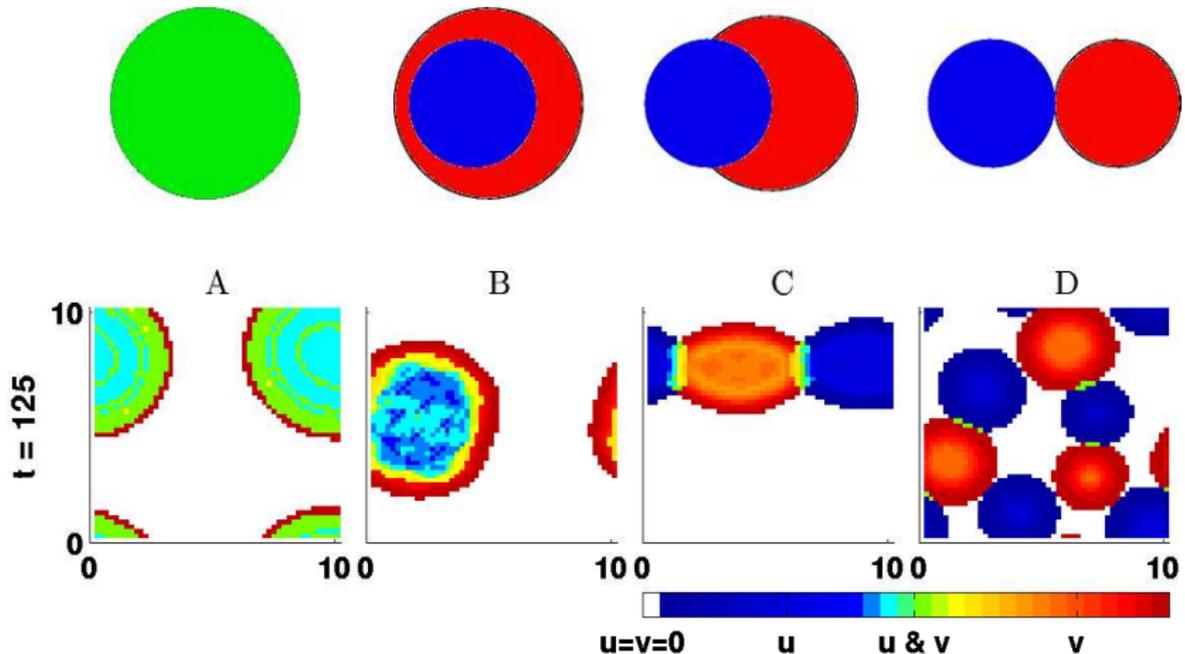
Movie of Cell Sorting in 2-D: Case D

Click here to
play the movie

Model Solutions: Cases A–D



Summary of Results on Cell Sorting in 2-D

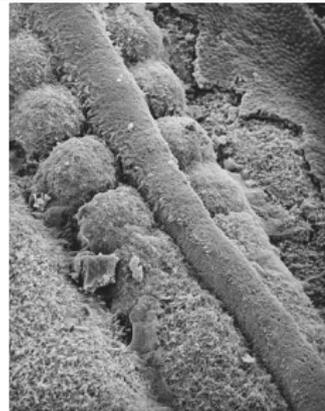
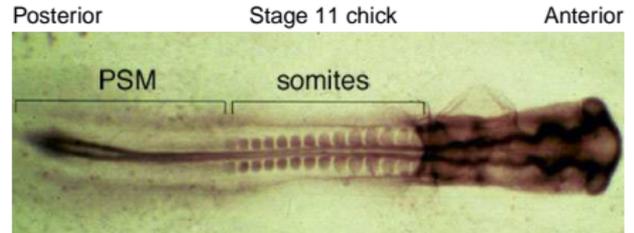


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Introduction to Somite Formation

Somites are an initial stage of segmentation along the head–tail axis of vertebrates.

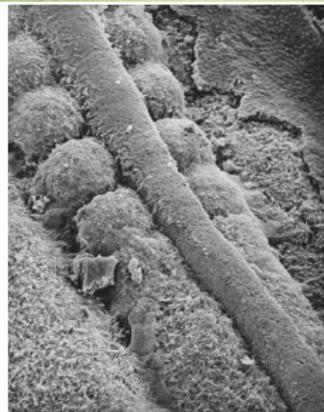
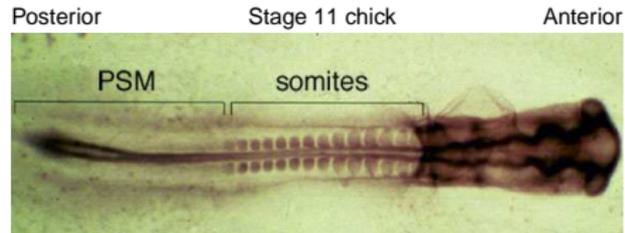


Introduction to Somite Formation

Somites are an initial stage of segmentation along the head–tail axis of vertebrates.

They form in a regular anterior–posterior sequence, via:

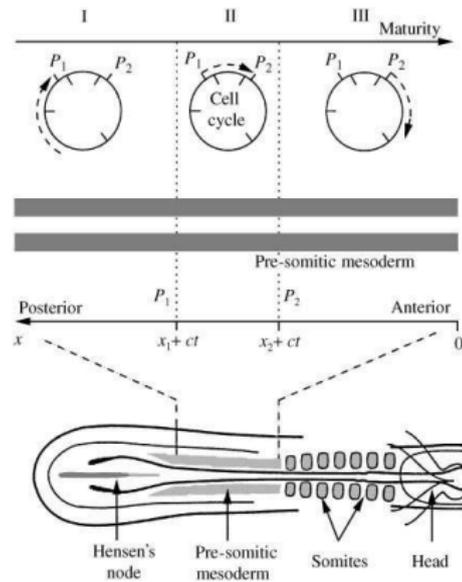
- 1 Pre-pattern forms in PSM
- 2 Cells coalesce into somites
- 3 Each somite differentiates into anterior and posterior halves, and later into dorsal and ventral parts



The Cell Cycle Model of Somite Formation

In 1998, Stern et al (Development 104S:231, 1998) proposed the conceptual “cell cycle model”.

The model proposes that when cells reach a point P_2 in the cell cycle, they release a signal. In response to this signal, cells between P_2 and an earlier point P_1 in the cell cycle increase their adhesion and then coalesce into a somite.



Mathematical Formulation of the Cell Cycle Model

Collier et al (J Theor Biol 207:305, 2000)
proposed a mathematical
formulation of the cell cycle
model.

The model variables are:

$v(x, t)$ conc of the
signalling
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$u(x, t)$ conc of a
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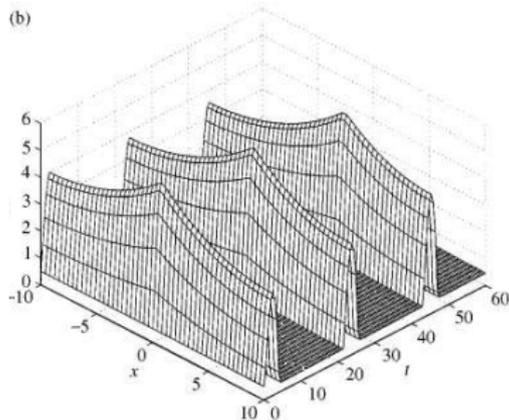
$$\frac{\partial u}{\partial t} = \frac{(u + \mu v)^2}{\gamma + \kappa u^2} \Gamma_u(x, t) - \frac{u}{\kappa}$$

$$\frac{\partial v}{\partial t} = \frac{\Gamma_v(x, t)}{\epsilon + u} - v + D \frac{\partial^2 v}{\partial x^2}$$

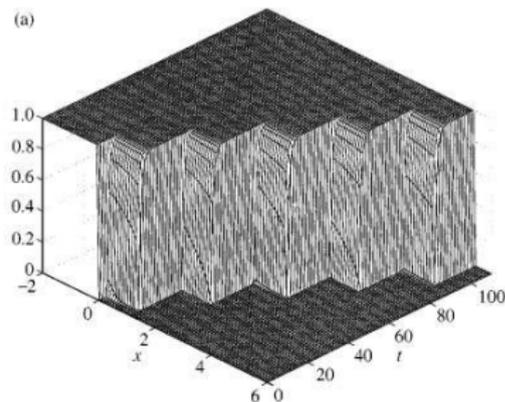
$$\Gamma_u(x, t) = H(ct - x + x_1)$$

$$\Gamma_v(x, t) = H(ct - x + x_2)$$

Typical Solution of the Collier et al Model



Signalling molecule $v(x, t)$



Precursor to adhesion molecule $u(x, t)$

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Adding Adhesive Cells to the Collier et al Model

We add a third equation, for the cell density $n(\mathbf{x}, t)$

$$\frac{\partial n(\mathbf{x}, t)}{\partial t} = \frac{\partial}{\partial \mathbf{x}} \left[D_n \frac{\partial n(\mathbf{x}, t)}{\partial \mathbf{x}} + \alpha u(\mathbf{x}, t) n(\mathbf{x}, t) \cdot \int_{-r}^r u(\mathbf{x} + \mathbf{x}_0, t) n(\mathbf{x} + \mathbf{x}_0, t) (2 - n(\mathbf{x} + \mathbf{x}_0, t)) \omega(\mathbf{x}_0) d\mathbf{x}_0 \right]$$

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- Cell adhesion depends on the concentration of the adhesion molecule precursor, u

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- The parameter α determines the strength of cell-cell adhesion

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- Cell adhesion depends on the concentration of the adhesion molecule precursor, u
- The parameter α determines the strength of cell-cell adhesion
- Note that there is no feedback from the cell equation to the chemical equations

Parameter Constraints for the Extended Model

The extended model predicts somite formation provided that:

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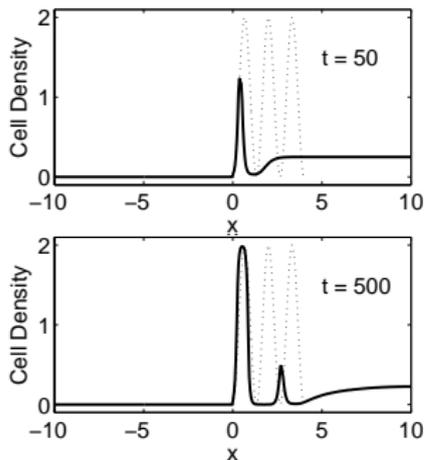
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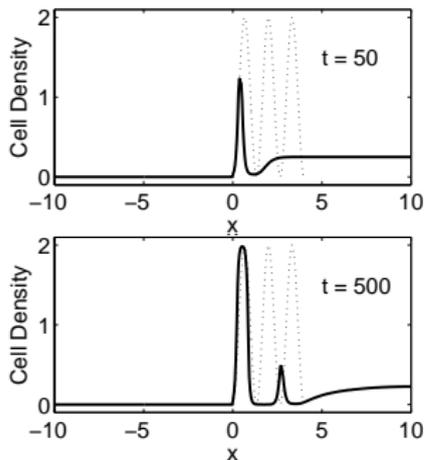
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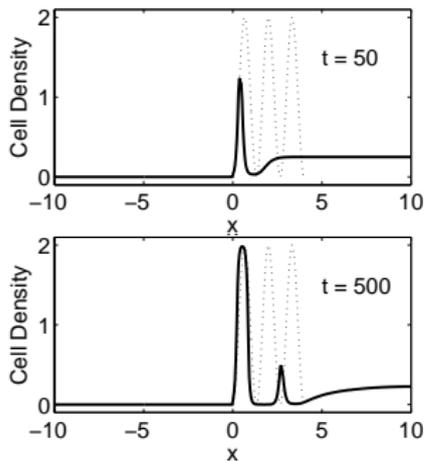
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- The imposed speed c is neither too low nor too high.



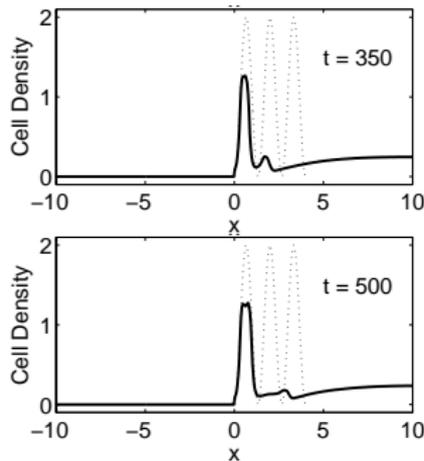
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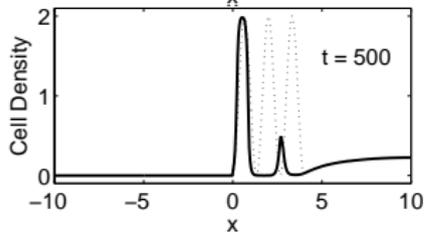
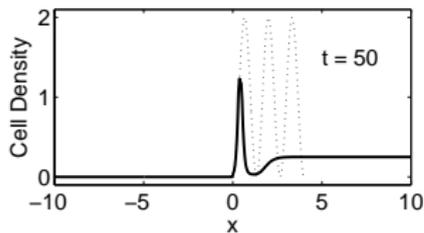
2. The imposed speed c is neither too low nor too high.
 c too low \Rightarrow coarsening



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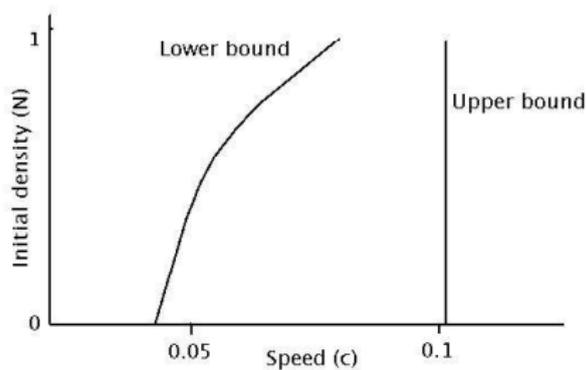
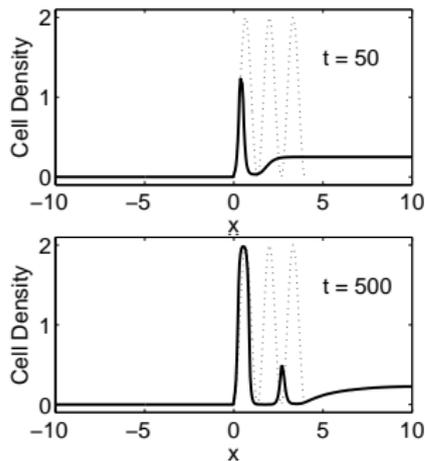


c too high \Rightarrow somites do not have time to form

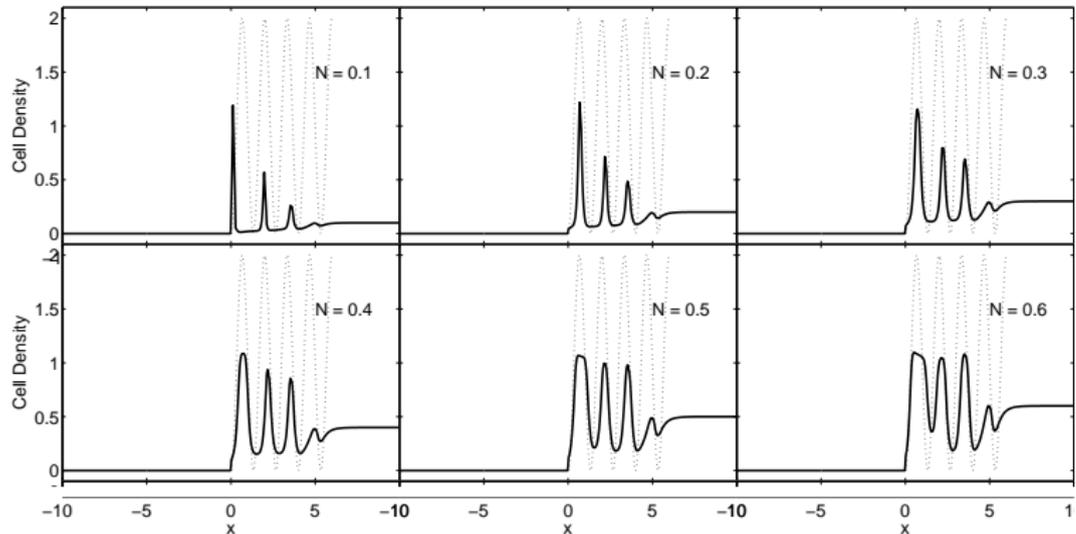
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Somite Formation in the Extended Model



Further Model Extension: Two Cell Populations

We investigate differentiation of somites into anterior and posterior halves by considering two cell populations $n_1(x, t)$, $n_2(x, t)$.

$$\frac{\partial n_1(x, t)}{\partial t} = D \frac{\partial^2 n_1(x, t)}{\partial x^2} + \frac{\partial}{\partial x} [u(x, t)n_1(x, t) (\alpha_1 K_1(u, n_1, n_2) + \beta K_2(u, n_1, n_2))]$$

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$$K_1(u, n_1, n_2) = \int_{-r}^r u(x+x_0, t) n_1(x+x_0, t) \cdot (2 - n_1(x+x_0, t) - n_2(x+x_0, t)) \omega(x_0) dx_0$$

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Further Model Extension: Two Cell Populations

We investigate differentiation of somites into anterior and posterior halves by considering two cell populations $n_1(x, t)$, $n_2(x, t)$.

Provided that cross-adhesion is weak ($0 < \beta < \alpha_1, \alpha_2$), the model does predict anterior/posterior differentiation.

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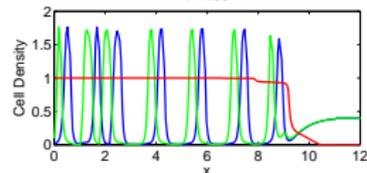
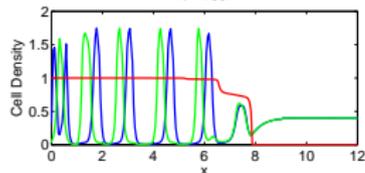
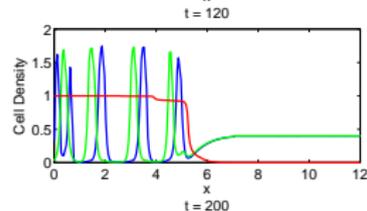
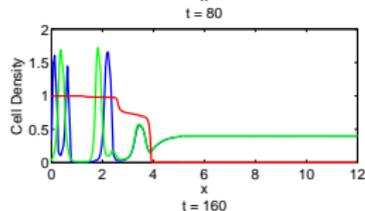
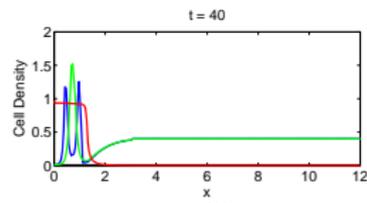
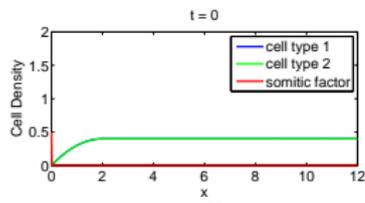
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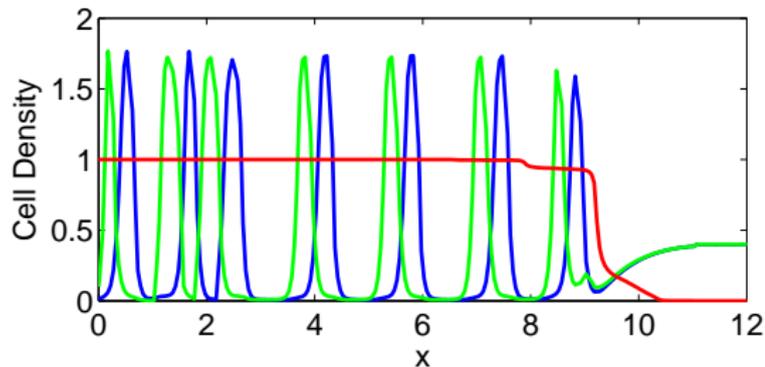
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Conclusions of Somite Application

Conceptual cell
cycle model
(Stern et al)



Mathematical
cell cycle model
(Collier et al)



Predictions on the diffusion and decay
rates of the signalling molecule, and
on the outcome of new heat shock expts

Our extended
mathematical
model

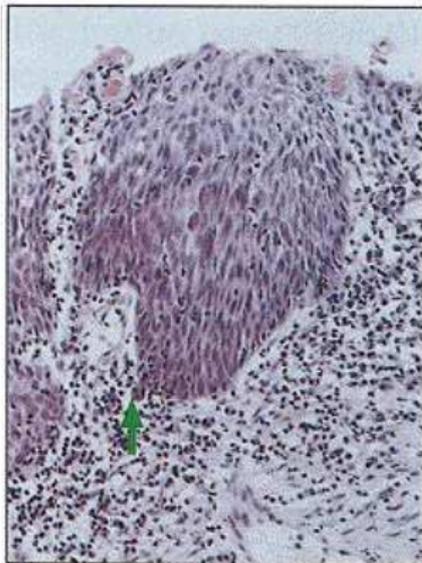


Predictions on the
values of α , c and N

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Introduction to Cancer Invasion

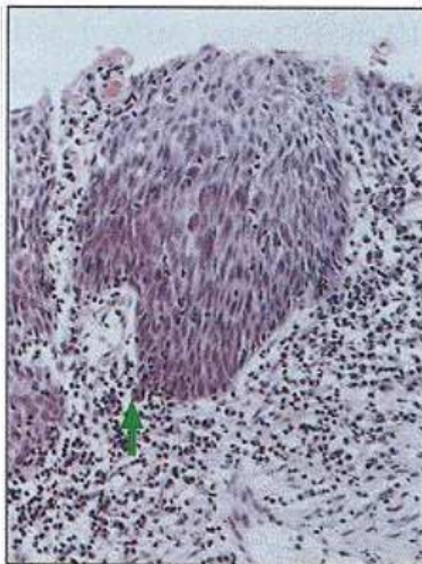


Carcinoma of the uterine cervix

Cells in a solid tumour invade surrounding tissue due to changes in:

- migration
- protease/anti-protease production
- adhesion

Introduction to Cancer Invasion



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- migration
- protease/anti-protease production
- **adhesion**: decreased cell-cell adhesion and increased cell-matrix adhesion

Modelling Adhesion in Cancer

Variables: $n(x, t)$ tumour cell density, $m(x, t)$ matrix density

$$\frac{\partial n}{\partial t} = \frac{\partial^2 n}{\partial x^2} - \frac{\partial}{\partial x} [n \cdot (K_{nn} + K_{nm})] + n(1 - n)$$

$$K_{nn} = \alpha \int_{-1}^1 n(x + x_0, t) \cdot (2 - n(x + x_0, t) - m(x + x_0, t)) \cdot \omega(x_0) dx_0$$

$$K_{nm} = \beta \int_{-1}^1 m(x + x_0, t) \cdot (2 - n(x + x_0, t) - m(x + x_0, t)) \cdot \omega(x_0) dx_0$$

$$\frac{\partial m}{\partial t} = -\lambda \cdot n \cdot m^2$$

Model
ingredients:

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$$\frac{\partial m}{\partial t} = -\lambda \cdot n \cdot m^2$$

Model ingredients:

- random motility
- cell–cell adhesion
- **cell-matrix adhesion**

Modelling Adhesion in Cancer

Variables: $n(x, t)$ tumour cell density, $m(x, t)$ matrix density

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$$\frac{\partial m}{\partial t} = -\lambda \cdot n \cdot m^2$$

Model ingredients:

- random motility
- cell–cell adhesion
- cell-matrix adhesion
- cell proliferation

Modelling Adhesion in Cancer

Variables: $n(x, t)$ tumour cell density, $m(x, t)$ matrix density

$$\frac{\partial n}{\partial t} = \frac{\partial^2 n}{\partial x^2} - \frac{\partial}{\partial x} [n \cdot (K_{nn} + K_{nm})] + n(1 - n)$$

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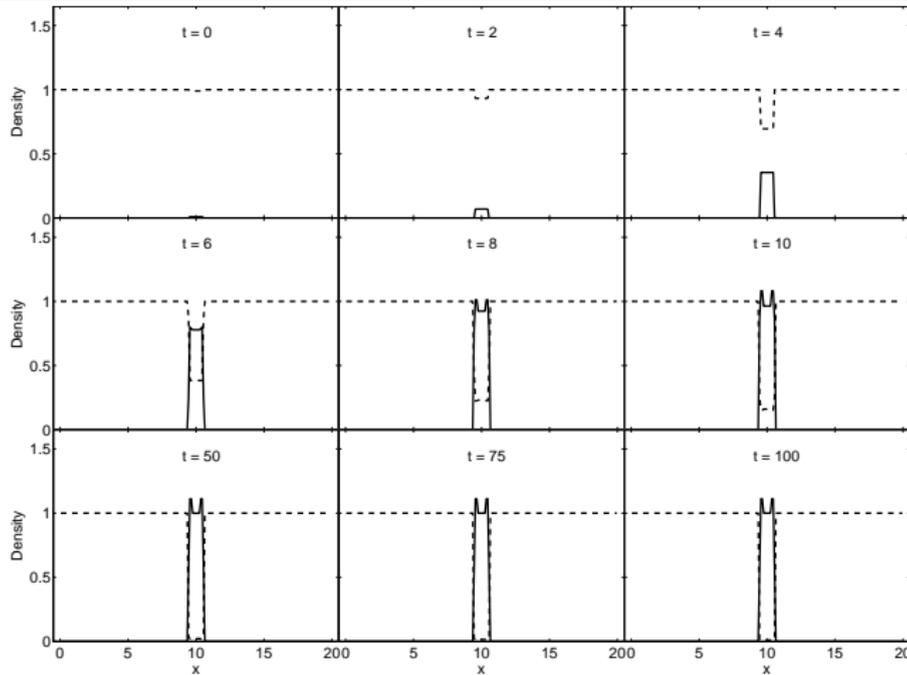
Model ingredients:

- random motility
- cell–cell adhesion
- cell-matrix adhesion
- cell proliferation
- **matrix degradation**

Model Solution: Non-Invasive Tumour

For α relatively large and β relatively small, the model predicts a non-invasive tumour

Model Solution: Non-Invasive Tumour

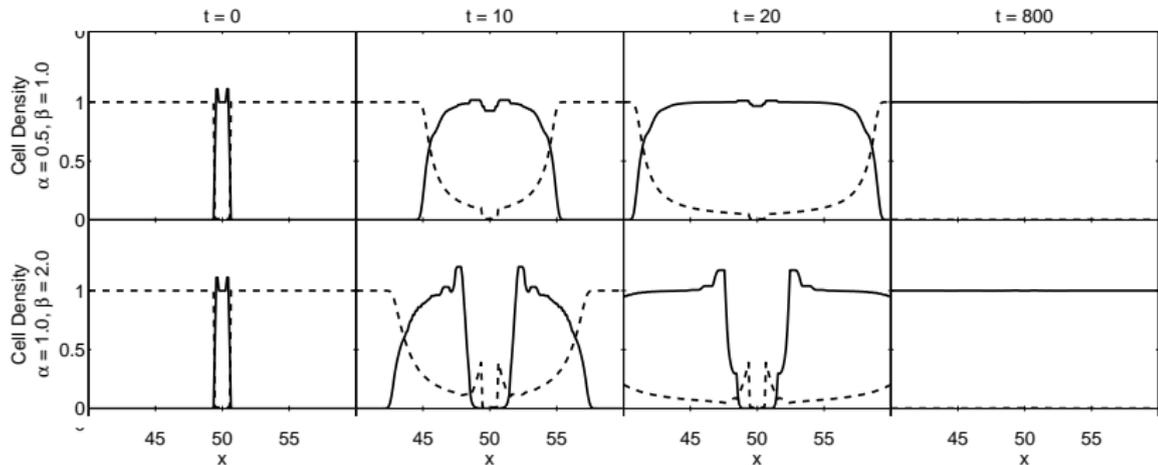


Model Solution: Invasive Tumour

Starting from the non-invasive tumour ($\alpha = \beta = 1$), invasion can be initiated either by decreasing cell-cell adhesion (α) or by increasing cell-matrix adhesion (β)

Model Solution: Invasive Tumour

Starting from the non-invasive tumour ($\alpha = \beta = 1$), invasion can be initiated either by decreasing cell-cell adhesion (α) or by increasing cell-matrix adhesion (β)



Future Work on Cancer Application

- Numerical solutions in two space dimensions
- Addition of normal tissue cells and multiple matrix types
- Addition of other aspects of the invasive phenotype

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 - Model Details
 - Mathematical Model for One Cell Population

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 - Extending the Model to Interacting Cell Populations
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 - Mathematical Formulation of the Cell Cycle Model
 - Typical Solution of the Collier et al Model

- 4 Application I: Somite Formation – New Modelling
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 - Somite Formation in the Extended Model
 - Further Model Extension: Two Cell Populations
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- 5 Application II: Cancer Invasion
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