Applied Analysis and PDE 6. Scalar conservation laws: Additional remarks

Lehel Banjai (Heriot-Watt University)

December 2, 2014

Outline

Traffic problem

Weak solutions

Equal-Area Principle

Traffic flow

Recall the traffic flow problem:

$$u_t + f(u)_x = 0$$
 where $f(u) = u(1 - u)$.

Uniform flow being stopped at x = 0 and t > 0 by a red light leads to IVP/BVP:

$$u(0,t) = 1,$$
 $u(x,0) = u_{\ell}.$

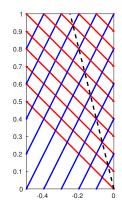
Traffic flow

Recall the traffic flow problem:

$$u_t + f(u)_x = 0$$
 where $f(u) = u(1 - u)$.

Uniform flow being stopped at x = 0 and t > 0 by a red light leads to IVP/BVP:

$$u(0,t) = 1,$$
 $u(x,0) = u_{\ell}.$

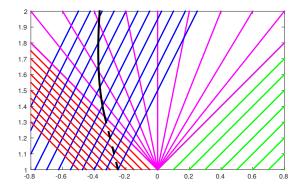


Traffic continued

Now suppose light turns green at $t_0 > 0$ giving initial value problem for $t > t_0$ and $x \in \mathbb{R}$ with

$$u(x, t_0) = \begin{cases} u_{\ell} & \text{if } x < a_0 \\ 1 & \text{if } a_0 < x < 0 \\ 0 & \text{if } x > 0, \end{cases}$$

where a_0 is the position of the shock on previous slide at time t_0 .





Traffic problem

Weak solutions

Equal-Area Principle

Classical solutions

- A more formal approach to the concept of discontinuous solutions leads to *weak solutions*.
- Consider again the conservation law

$$egin{aligned} u_t+f(u)_x&=0, & x\in\mathbb{R},\,t>0,\ u(x,0)&=u_0(x), & x\in\mathbb{R}. \end{aligned}$$

- A smooth solution u satisfying the above equation is called a classical solution.
- We show next how to obtain *weak solutions* of the above equations.

Test functions

Let $v \in C^{\infty}_{comp}(\mathbb{R}, [0, \infty))$ where $C^{\infty}_{comp}(\mathbb{R}, [0, \infty))$ is the set of infinitely smooth functions with compact support, i.e.

supp $v \subset \{(x, t) : t \in [0, T], x \in (a, b), a, b \in \mathbb{R}\}.$

Test functions

Let $v \in C^{\infty}_{comp}(\mathbb{R}, [0, \infty))$ where $C^{\infty}_{comp}(\mathbb{R}, [0, \infty))$ is the set of infinitely smooth functions with compact support, i.e.

$$supp v \subset \{(x, t) : t \in [0, T], x \in (a, b), a, b \in \mathbb{R}\}.$$

Testing (1) with v and integrating by parts gives

$$0 = \int_0^\infty \int_{\mathbb{R}} u_t v + f(u)_x v dx dt$$

= $-\int_{\mathbb{R}} u_0(x) v(x, 0) dx - \int_0^\infty \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt.$

We say that u is a **weak** solution of (1) if

$$\int_0^\infty \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt = -\int_{\mathbb{R}} u_0(x)v(x,0) dx, \qquad \forall v \in C^\infty_{\text{comp}}.$$
(2)

We say that u is a weak solution of (1) if

$$\int_0^\infty \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt = -\int_{\mathbb{R}} u_0(x)v(x,0) dx, \qquad \forall v \in C^\infty_{\text{comp}}.$$
(2)

Any classical solution of (1) also satisfies (2).

We say that u is a **weak** solution of (1) if $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{$

$$\int_{0} \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt = -\int_{\mathbb{R}} u_0(x)v(x,0) dx, \qquad \forall v \in C^{\infty}_{\text{comp}}.$$
(2)

- Any classical solution of (1) also satisfies (2).
- Any solution of (2) that's sufficiently smooth is a classical solution of (1).

We say that u is a **weak** solution of (1) if

$$\int_0^\infty \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt = -\int_{\mathbb{R}} u_0(x)v(x,0) dx, \qquad \forall v \in C^\infty_{\text{comp}}.$$
(2)

- Any classical solution of (1) also satisfies (2).
- Any solution of (2) that's sufficiently smooth is a classical solution of (1).
- However, a weak solution can be much less smooth and in that sense generalises the notion of a solution.

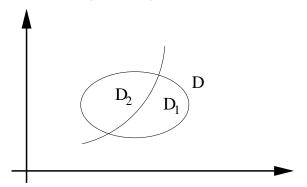
We say that u is a **weak** solution of (1) if

$$\int_0^\infty \int_{\mathbb{R}} (uv_t + f(u)v_x) dx dt = -\int_{\mathbb{R}} u_0(x)v(x,0) dx, \qquad \forall v \in C^\infty_{\text{comp}}.$$
(2)

- Any classical solution of (1) also satisfies (2).
- Any solution of (2) that's sufficiently smooth is a classical solution of (1).
- However, a weak solution can be much less smooth and in that sense generalises the notion of a solution.
- Does the weak solution satisfy the jump condition?

Jump condition

Consider the situation (*x*-*t* space):



with the curve separating D_1 and D_2 given by

$$x = y(t)$$

and hence the exterior normal to D_1 on y(t) by

$$u = rac{(-1,y'(t))}{\sqrt{1+y'(t)^2}}.$$

Jump condition ctd.

We assume that u is smooth except with a jump across the boundary $\Gamma = y(t)$ separating D_1 and D_2 .

Jump condition ctd.

We assume that u is smooth except with a jump across the boundary $\Gamma = y(t)$ separating D_1 and D_2 .

Let v be compactly supported in D, then using the divergence theorem and since u is a solution inside D_1 and D_2 :

$$0 = \int \int_{D} (uv_{t} + f(u)v_{x})dxdt$$

= $\int \int_{D_{1}} (uv_{t} + f(u)v_{x})dxdt + \int \int_{D_{2}} (uv_{t} + f(u)v_{x})dxdt$
= $-\int \int_{D_{1}} (u_{t} + f(u)_{x})v)dxdt - \int \int_{D_{2}} (u_{t} + f(u)_{x})vdxdt$
+ $\int_{\Gamma} v(u_{\ell}y'(t) - f(u_{\ell}))dt - \int_{\Gamma} v(u_{r}y'(t) - f(u_{r}))dt$
= $\int_{\Gamma} v([u]y'(t) - [f(u)])dt.$

Hence

$$0 = [u]y'(t) - [f(u)] \implies s[u] = [f(u)].$$

Outline

Traffic problem

Weak solutions

Equal-Area Principle

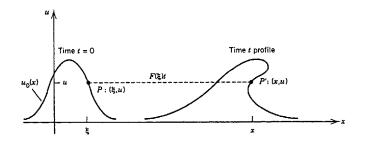
Equal-Area Principle

Equal-area principle gives a simple two-step recipe for constructing a shock path.

Equal-Area Principle

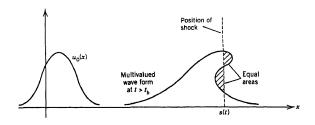
Equal-area principle gives a simple two-step recipe for constructing a shock path.

First follow the characteristics allowing for multivalued solutions (all figures taken from Logan):



Equal-Area Principle ctd.

The location of the shock z = y(t) at time t is the position at which a vertical line cuts off equal area lobes of the multivalued wavelet:

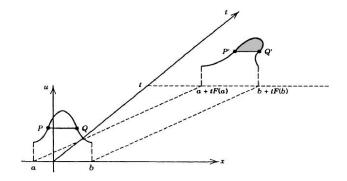


Equal-Area Principle ctd.

Why does this work?

Equal-Area Principle ctd.

- Why does this work?
- Any horizontal line segment PQ at t = 0 has the same length as P'Q' at time t because points on the wave at the same height u move at the same speed c(u) = f'(u) so that the area under a curve segment remains constant:



Exercise

As a trivial example of the principle consider

$$u_t + uu_x = 0,$$
 $u(x, 0) = \begin{cases} 1 & x < 0 \\ 0 & x > 0 \end{cases}$

and compute the solution at t = 1.