# Algebraic subgroups of acylindrically hyperbolic groups

Bryan Jacobson Vanderbilt University

Equations and formal languages in algebra Les Diablerets 9 March 2016

B. Jacobson Algebraic subgroups of acylindrically hyperbolic groups

# Equations

Notation:

For each  $w(x) \in G * \langle x \rangle$  and each  $g \in G$ , let w(g) denote the image of w(x) under the homomorphism  $G * \langle x \rangle \to G$  given by taking  $id : G \to G$  and sending  $x \mapsto g$ .

イロト イ押ト イヨト イヨトー

# Equations

Notation:

For each  $w(x) \in G * \langle x \rangle$  and each  $g \in G$ , let w(g) denote the image of w(x) under the homomorphism  $G * \langle x \rangle \to G$  given by taking  $id : G \to G$  and sending  $x \mapsto g$ .

#### Definition

Write w(x) = 1 to represent an *equation* in the single variable x with coefficients in *G* whose *solution set* is

 $\{g \in G \,|\, w(g) = 1\}.$ 



Examples:



イロン イロン イヨン イヨン

æ



Examples:

Let  $G = F_2$  with generators *a* and *b*.

 If w(x) = [x, a], then the equation w(x) = 1 has solution set equal to ⟨a⟩.

イロト イポト イヨト イヨト



### Examples:

Let  $G = F_2$  with generators *a* and *b*.

- If w(x) = [x, a], then the equation w(x) = 1 has solution set equal to (a).
- If w(x) = a, then the equation w(x) = 1 has solution set equal to Ø.

イロト イポト イヨト イヨト



### Examples:

Let  $G = F_2$  with generators *a* and *b*.

- If w(x) = [x, a], then the equation w(x) = 1 has solution set equal to (a).
- If w(x) = a, then the equation w(x) = 1 has solution set equal to Ø.
- If w(x) is 1, then the equation w(x) = 1 has solution set equal to F<sub>2</sub>.

イロト イポト イヨト イヨト



### Examples:

Let  $G = F_2$  with generators *a* and *b*.

- If w(x) = [x, a], then the equation w(x) = 1 has solution set equal to (a).
- If w(x) = a, then the equation w(x) = 1 has solution set equal to Ø.
- If w(x) is 1, then the equation w(x) = 1 has solution set equal to F<sub>2</sub>.

イロト イポト イヨト イヨト

# The Zariski topology on G

### Definition

The *Zariski topology* on *G* is defined by taking the collection of solution sets to individual equations to be a sub-basis for the closed sets of the topology.

# The Zariski topology on G

### Definition

The *Zariski topology* on G is defined by taking the collection of solution sets to individual equations to be a sub-basis for the closed sets of the topology. That is, each Zariski-closed set of G is of the form

### $\cap_{i\in I}S_i$

where for each  $i \in I$ , the set  $S_i$  is a finite union of solution sets corresponding to (single-variable) equations with coefficients in G.

# The Zariski topology on G

### Definition

The *Zariski topology* on G is defined by taking the collection of solution sets to individual equations to be a sub-basis for the closed sets of the topology. That is, each Zariski-closed set of G is of the form

### $\cap_{i\in I}S_i$

where for each  $i \in I$ , the set  $S_i$  is a finite union of solution sets corresponding to (single-variable) equations with coefficients in G.

• Zariski-closed sets are closed in every *T*<sub>0</sub> group topology, and, in the case of countable groups, the Zariski-closed sets are the only such sets (Markov, 1944).

# Algebraic subgroups of G

#### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

# Algebraic subgroups of G

#### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

Examples:

• The whole group G

# Algebraic subgroups of G

### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

### Examples:

- The whole group G
- Any finite subgroup of G

A B A B A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A
A

→ E → < E →</p>

# Algebraic subgroups of G

#### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

### Examples:

- The whole group G
- Any finite subgroup of G
- We saw that the subgroup  $\langle a \rangle$  in  $F_2 = \langle a, b \rangle$  was algebraic.

# Algebraic subgroups of G

### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

### Examples:

- The whole group G
- Any finite subgroup of G
- We saw that the subgroup  $\langle a \rangle$  in  $F_2 = \langle a, b \rangle$  was algebraic.
- Centralizers of subsets of G
- Exercise: If *G* is a torsion-free abelian group, then the only algebraic subgroups of *G* are *G* and {1}.

# Algebraic subgroups of G

### Definition

A Zariski-closed subgroup (or more generally, a subset) of *G* is called *algebraic*.

### Examples:

- The whole group G
- Any finite subgroup of G
- We saw that the subgroup  $\langle a \rangle$  in  $F_2 = \langle a, b \rangle$  was algebraic.
- Centralizers of subsets of G
- Exercise: If *G* is a torsion-free abelian group, then the only algebraic subgroups of *G* are *G* and  $\{1\}$ . (Hint: WLOG, each equation is of the form  $gx^n = 1$ , where  $g \in G$ ,  $n \in \mathbb{Z}$ .)

# Algebraic subgroups of G

**Goal:** structural result for algebraic subgroups in the case where G is an acylindrically hyperbolic group

**Next:** definition of acylindrically hyperbolic group, some examples

### Acylindrical actions

Let *G* be group acting by isometries on a metric space (S, d).

イロト イポト イヨト イヨト

ъ

# Acylindrical actions

Let G be group acting by isometries on a metric space (S, d).

#### Definition

The action of *G* on *S* is called *acylindrical* if  $\forall \varepsilon > 0$  $\exists R, N > 0$  such that  $\forall x, y \in S$ 

 $d(x,y) \geq R \Longrightarrow |\{g \in G \mid d(x,gx) \leq \varepsilon \text{ and } d(y,gy) \leq \varepsilon\}| \leq N.$ 

◆□▶ ◆□▶ ◆三▶ ◆三▶ ● ● ●

## Acylindrical actions

Let *G* be group acting by isometries on a metric space (S, d).

#### Definition

The action of *G* on *S* is called *acylindrical* if  $\forall \varepsilon > 0$  $\exists R, N > 0$  such that  $\forall x, y \in S$ 

 $d(x,y) \geq R \Longrightarrow |\{g \in G \mid d(x,gx) \leq \varepsilon \text{ and } d(y,gy) \leq \varepsilon\}| \leq N.$ 



イロト イヨト イヨト

## Acylindrical actions

Let *G* be group acting by isometries on a metric space (S, d).

#### Definition

The action of *G* on *S* is called *acylindrical* if  $\forall \varepsilon > 0$  $\exists R, N > 0$  such that  $\forall x, y \in S$ 

 $d(x,y) \geq R \Longrightarrow |\{g \in G \mid d(x,gx) \leq \varepsilon \text{ and } d(y,gy) \leq \varepsilon\}| \leq N.$ 



イロト イヨト イヨト

# Acylindrically hyperbolic groups

#### Definition

If *S* is a hyperbolic space, then the action of *G* on *S* is called *elementary* if the limit set of *G* on the Gromov boundary  $\partial S$  contains at most 2 points.

# Acylindrically hyperbolic groups

#### Definition

If *S* is a hyperbolic space, then the action of *G* on *S* is called **elementary** if the limit set of *G* on the Gromov boundary  $\partial S$  contains at most 2 points.

#### Definition

A group *G* is called *acylindrically hyperbolic* if it admits a non-elementary acylindrical action on a hyperbolic space.

# Acylindrically hyperbolic groups

### Examples:

- non-elementary hyperbolic and relatively hyperbolic groups
- infinite mapping class groups of punctured closed surfaces (Mazur-Minsky, Bowdich)
- $Out(F_n)$  for  $n \ge 2$  (Bestvina-Feign, Dahmani-Guirardel-Osin)
- directly indecomposable non-cyclic right angled Artin groups (Sisto, Caprace-Sageev, Osin)
- most 3-manifold groups (Minasyan-Osin)
- groups of deficiency  $\geq 2$  (Osin)

イロト イ押ト イヨト イヨトー

# Acylindrically hyperbolic groups

#### Definition

Given an acylindrically hyperbolic group G, a subgroup  $H \le G$  is called **non-elementary** if for some acylindrical action of G on a hyperbolic space S, the action of H on S is non-elementary.

### Main Result

### Theorem (J., 2015)

Suppose that *G* is an acylindrically hyperbolic group and that  $H \leq G$  is non-elementary. Then *H* is algebraic if and only if *H* is a virtual centralizer of some finite subgroup of *G*.

ヘロン 人間 とくほ とくほ とう

### Main Result

### Theorem (J., 2015)

Suppose that *G* is an acylindrically hyperbolic group and that  $H \leq G$  is non-elementary. Then *H* is algebraic if and only if *H* is a virtual centralizer of some finite subgroup of *G*.

Stronger version of the forward implication:

#### Theorem (J., 2015)

Suppose that *G* is an acylindrically hyperbolic group and *H* is a non-elementary subgroup of *G*. Then the Zariski closure of *H* contains  $C_G(E_G(H))$  where  $E_G(H)$  is the unique maximal finite subgroup of *G* normalized by *H*.

イロト イポト イヨト イヨト

### Main Result

### Theorem (J., 2015)

Suppose that *G* is an acylindrically hyperbolic group and that  $H \leq G$  is non-elementary. Then *H* is algebraic if and only if *H* is a virtual centralizer of some finite subgroup of *G*.

Stronger version of the forward implication:

#### Theorem (J., 2015)

Suppose that *G* is an acylindrically hyperbolic group and *H* is a non-elementary subgroup of *G*. Then the Zariski closure of *H* contains  $C_G(E_G(H))$  where  $E_G(H)$  is the unique maximal finite subgroup of *G* normalized by *H*.

 $(E_G(H)$  exists by Hull (2013) or Antolin-Minasyan-Sisto (2013).)

# Classification of acylindrical actions on hyperbolic spaces

### Theorem (Osin, 2013)

If *G* acts acylyndrically on a hyperbolic space, then exactly one of the following holds:

- The action of G is non-elementary.
- G has bounded orbits.
- G is virtually cyclic and contains a loxodromic element.

ヘロト 人間 ト ヘヨト ヘヨト



### Corollary (Free products)

Let *A* and *B* be nontrivial groups, and let *H* be an algebraic subgroup of *A* \* *B*. Then at least one of the following holds:

- (a) *H* is either infinite cyclic or isomorphic to  $D_{\infty}$ , the infinite dihedral group.
- (b) *H* is conjugate to a subgroup of either *A* or *B*.

(c) H = A \* B.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

# Corollaries

### Corollary (Torsion-free relatively hyperbolic groups)

Let *G* be a torsion-free relatively hyperbolic group with peripheral subgroups  $\{H_{\lambda}\}_{\lambda \in \Lambda}$ , and let  $H \leq G$  be an algebraic subgroup. Then at least one of the following holds:

- (a) H = G.
- (b) H is cyclic.
- (c) *H* is conjugate to a subgroup of some  $H_{\lambda}$ .

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 ののの

# Corollaries

### Corollary (Torsion-free relatively hyperbolic groups)

Let *G* be a torsion-free relatively hyperbolic group with peripheral subgroups  $\{H_{\lambda}\}_{\lambda \in \Lambda}$ , and let  $H \leq G$  be an algebraic subgroup. Then at least one of the following holds:

- (a) H = G.
- (b) H is cyclic.
- (c) *H* is conjugate to a subgroup of some  $H_{\lambda}$ .

Furthermore, if (c) holds for an abelian  $H_{\lambda}$ , then either  $H = \{1\}$  or H is conjugate to  $H_{\lambda}$ .

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 ののの

## Corollaries

Corollary (Ascending chains of algebraic subgroups)

Let *G* be an acylindrically hyperbolic group and let  $H_1 \leq H_2 \leq H_3 \leq \ldots$  be an ascending chain of algebraic subgroups of *G*. Then either

(a) for each acylindrical action of *G* on a hyperbolic space *S*, the subgroup  $\bigcup_{i \in \mathbb{N}} H_i$  acts on *S* with bounded orbits (in particular, each  $H_i$  is elliptic), or

(b) the chain stabilizes.

# Corollaries

#### Corollary (Ascending chains of algebraic subgroups)

Let *G* be an acylindrically hyperbolic group and let  $H_1 \leq H_2 \leq H_3 \leq \ldots$  be an ascending chain of algebraic subgroups of *G*. Then either

- (a) for each acylindrical action of *G* on a hyperbolic space *S*, the subgroup  $\cup_{i \in \mathbb{N}} H_i$  acts on *S* with bounded orbits (in particular, each  $H_i$  is elliptic), or
- (b) the chain stabilizes.

Note: in general, it is actually possible for an acylindrically hyperbolic group to have an ascending chain of (elliptic) algebraic subgroups which does not stabilize.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

# Ascending chain example

Consider a group with presentation  $\langle X|R\rangle$  that contains an infinite ascending chain of subgroups

$$K_1 \leq K_2 \leq \ldots (K_i \neq K_{i+1}).$$

・ロン・西方・ ・ ヨン・

# Ascending chain example

Consider a group with presentation  $\langle X|R\rangle$  that contains an infinite ascending chain of subgroups

$$K_1 \leq K_2 \leq \ldots (K_i \neq K_{i+1}).$$

Let

$$H = \langle X, a, t_1, t_2, \dots | R, [X, a] = 1, [K_1, t_1] = 1, [K_2, t_2] = 1, \dots \rangle$$

Then  $G = H * \mathbb{Z}$  is acylindrically hyperbolic.

# Ascending chain example

Consider a group with presentation  $\langle X|R\rangle$  that contains an infinite ascending chain of subgroups

$$K_1 \leq K_2 \leq \ldots (K_i \neq K_{i+1}).$$

Let

$$H = \langle X, a, t_1, t_2, \dots | R, [X, a] = 1, [K_1, t_1] = 1, [K_2, t_2] = 1, \dots \rangle$$

Then  $G = H * \mathbb{Z}$  is acylindrically hyperbolic. Furthermore,

$$K_i = \{x \in H * \mathbb{Z} \mid [x, t_i] = 1\} \cap \{x \in H * \mathbb{Z} \mid [x, a] = 1\}$$

so that  $K_1 \le K_2 \le ...$  is an ascending chain of algebraic subgroups of *G* that does not stabilize.

# Thank you!

B. Jacobson Algebraic subgroups of acylindrically hyperbolic groups

イロト イロト イヨト イヨト

æ