

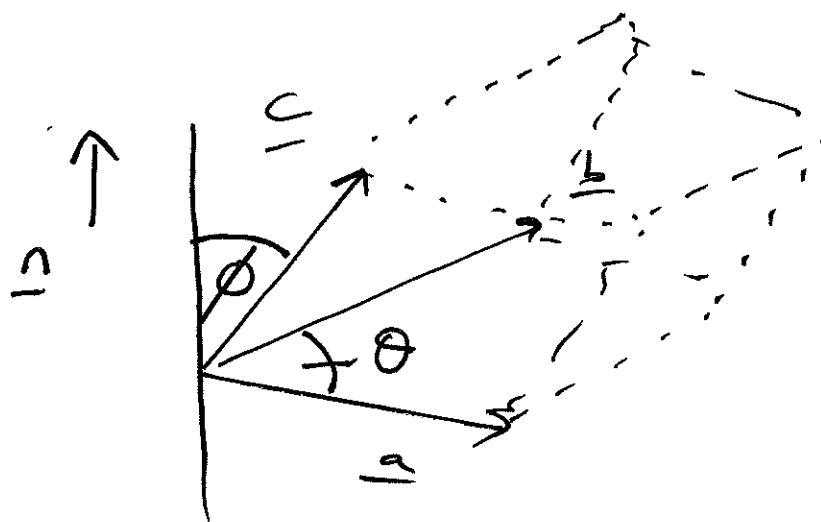
Lecture 25

Defn let $\underline{a} = a_1 \underline{i} + a_2 \underline{j} + a_3 \underline{k}$
 $\underline{b} = b_1 \underline{i} + b_2 \underline{j} + b_3 \underline{k}$
 $\underline{c} = c_1 \underline{i} + c_2 \underline{j} + c_3 \underline{k}$.

The volume of the parallelepiped determined by $\underline{a}, \underline{b}, \underline{c}$ is the absolute value of the det.

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}.$$

Proof



$$\begin{aligned} \text{Volume} &= \text{absolute value of (base area} \times \text{vertical height)} \\ &= \left| \|\underline{a}\| \|\underline{b}\| \cos \theta \cdot \|\underline{c}\| \sin \phi \right| \end{aligned}$$

Observe that

$$\underline{a} \times \underline{b} = \|\underline{a}\| \|\underline{b}\| \sin \theta \underline{n}$$

$$\underline{c} \cdot (\underline{a} \times \underline{b}) = \|\underline{c}\| \|\underline{a}\| \|\underline{b}\| \sin \theta \cos \phi$$

$$\begin{aligned} \therefore \text{Volume of parallelepiped} &= \left| \underline{c} \cdot (\underline{a} \times \underline{b}) \right| \\ &= \left| [\underline{c}, \underline{a}, \underline{b}] \right| \end{aligned}$$

We now use the fact that if you interchange two rows of a det. the det changes by -1 .

$$\begin{aligned} \therefore [\underline{c}, \underline{a}, \underline{b}] &= -[\underline{a}, \underline{c}, \underline{b}] \\ &= [\underline{a}, \underline{b}, \underline{c}] \quad \square \end{aligned}$$

Examples Let

$$\underline{a} = \underline{i} + 2\underline{j} + 3\underline{k}$$

$$\underline{b} = \underline{i} - \underline{j} + 2\underline{k}$$

$$\underline{c} = 2\underline{i} + 3\underline{j} + 4\underline{k}$$

1. Calculate $\|\underline{a}\|$.

$$\|\underline{a}\| = \sqrt{\underline{a} \cdot \underline{a}} = \sqrt{1+4+9} = \sqrt{14} //$$

2. Calculate $\|\underline{b}\|$

$$\|\underline{b}\| = \sqrt{\underline{b} \cdot \underline{b}} = \sqrt{1+1+4} = \sqrt{6} //$$

3. Calculate $\underline{a} \cdot \underline{b}$.

$$\begin{aligned} \underline{a} \cdot \underline{b} &= (\underline{i} + 2\underline{j} + 3\underline{k}) \cdot (\underline{i} - \underline{j} + 2\underline{k}) \\ &= 1 - 2 + 6 = \underline{\underline{5}} \end{aligned}$$

4. Calculate the angle between $\underline{a}$ and $\underline{b}$ to the nearest degree.

$$\cos \theta = \frac{\underline{a} \cdot \underline{b}}{\|\underline{a}\| \|\underline{b}\|} = \frac{5}{\sqrt{14} \sqrt{6}} \approx 0.576$$

$$\therefore \underline{\underline{\theta \approx 57^\circ}}$$

5. Calculate $\underline{a} \times \underline{b}$

$$\underline{a} \times \underline{b} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 1 & 2 & 3 \\ 1 & -1 & 2 \end{vmatrix}$$

$$= \begin{vmatrix} 2 & 3 \\ -1 & 2 \end{vmatrix} \underline{i} - \begin{vmatrix} 1 & 3 \\ 1 & 2 \end{vmatrix} \underline{j} + \begin{vmatrix} 1 & 2 \\ 1 & -1 \end{vmatrix} \underline{k}$$

$$= \underline{7\underline{i} + \underline{j} - 3\underline{k}}$$

Check $(\underline{i} + 2\underline{i} + 3\underline{k}) \cdot (7\underline{i} + \underline{j} - 3\underline{k})$

$$= 7 + 2 - 9 = 0 \checkmark$$

$$(\underline{i} - \underline{j} + 2\underline{k}) \cdot (7\underline{i} + \underline{j} - 3\underline{k}) = 7 - 1 - 6 = 0 \checkmark$$

6. Calculate $[\underline{c}, \underline{a}, \underline{b}]$.

$$[\underline{c}, \underline{a}, \underline{b}] = \underline{c} \cdot (\underline{a} \times \underline{b})$$

$$= (2\underline{i} + 3\underline{j} + 4\underline{k}) \cdot (7\underline{i} + \underline{j} - 3\underline{k})$$

$$= 5 //$$

7. Calculate $\begin{vmatrix} 2 & 3 & 4 \\ 1 & 2 & 3 \\ 1 & -1 & 2 \end{vmatrix}$

$$= 2 \begin{vmatrix} 2 & 3 \\ -1 & 2 \end{vmatrix} - 3 \begin{vmatrix} 1 & 3 \\ 1 & 2 \end{vmatrix} + 4 \begin{vmatrix} 1 & 2 \\ 1 & -1 \end{vmatrix}$$

$$= 2(4+3) - 3(2-3) + 4(-1-2)$$

$$= 14 + 3 - 12 = 5 //$$

[The answers to (6) & (7) should, of course, be the same]

Important

Position vectors (= bound vectors)

The vectors we have studied so far are often called free vectors.

Now choose a fixed point O called the origin. A position vector is a vector rooted at O . Position vectors enable us to describe specific points — that is, give their coordinates in vector form.

The general position vector is denoted by

$$\underline{r} (= x\underline{i} + y\underline{j} + z\underline{k}).$$

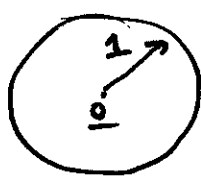
Equations of lines and planes

Curves can be described in two ways

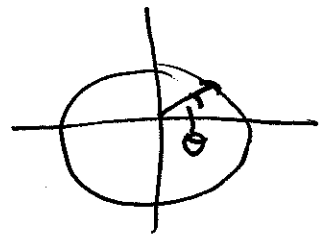
— parametric & non-parametric

[parametric = uses a parameter]

Ex: circle



← time



non-parametric

$$x^2 + y^2 = 1$$

parametric

$$(\cos \theta, \sin \theta)$$

$$0 \leq \theta \leq 2\pi$$

θ is the parameter.

Cartesian coordinates = those given by
 x, y, z
 (Des Cartes)