

## PARTIAL DIFFERENTIAL EQUATIONS (PDEs)

First a little bit of notation: let  $u(x, t)$  be a <sup>scalar</sup> function of two variables, for example

$$u(x, t) = x^2 t + tx - x$$

then  $\frac{\partial u}{\partial x} = u_x = \partial_x u$  are all equivalent notations for the partial derivative with respect to  $x$ . In the example

$$u_x = 2xt + t - 1$$

$$u_t = x^2 + x$$

Analogously,  $u_{xx} = \frac{\partial^2 u}{\partial x^2} = \partial_{xx} u$  is the second derivative w.r. to  $x$ ; in the example

$$u_{xx} = 2t, \quad u_{tt} = 0, \quad u_{xt} = 0$$

$$\text{where } u_{xt} = \partial_{xt} u = \frac{\partial^2 u}{\partial x \partial t}$$

An ODE is a differential equation involving functions of one variable.

A PDE is a differential equation for functions of two (or more) variables, involving partial derivatives.

For example, let  $u = u(x, t)$ , then

$$\textcircled{u_{tt} - u_{xt} + x u_x = 0} \quad (*)$$

is a PDE and it is a second order PDE because the higher <sup>order</sup> derivative that appears in  $(*)$  is a second derivative.

$$\text{Ex: } u_{xx} - u_x + 2u_t + 7u = 0$$

is a second order PDE with constant coefficients (because the coefficients in front of  $u$  and its derivatives do not depend on either  $x$  or  $t$ ).

• Classification of second order PDEs with constant coefficients  
(for functions of two variables)

The most general PDE of this type is

$$a \frac{\partial^2 u}{\partial x^2} + h \frac{\partial^2 u}{\partial x \partial t} + b \frac{\partial^2 u}{\partial t^2} + 2f \frac{\partial u}{\partial x} + 2g \frac{\partial u}{\partial t} + cu = 0 \quad (cc)$$

where  $a, b, c, h, f, g$  are all constants.

We say that equation (cc) is

ELLIPTIC if  $ab - \frac{h^2}{4} > 0$

PARABOLIC if  $ab - \frac{h^2}{4} = 0$

HYPERBOLIC if  $ab - \frac{h^2}{4} < 0$

EXAMPLES : i)  $3u_{xx} - u_{xt} + u = 0$

$$a = 3 \quad b = 0 \quad h = -1 \Rightarrow ab - \frac{h^2}{4} = -\frac{1}{4} < 0 \Rightarrow \text{hyperbolic}$$

ii) for  $u = u(x, y)$  :  $u_{xx} + \sqrt{3}u - e^2 u_{yy} + u_{yy} = 0$

$$a = 1 \quad b = 1 \quad h = 0 \Rightarrow ab - \frac{h^2}{4} = 1 > 0 \Rightarrow \text{elliptic}$$

• REM (for those who want to know): given a function  $f(x, y)$  it is not always true that

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} \quad \text{Though, Schwartz's Theorem}$$

says that if  $f$  is a continuous function s.t.

its first and second derivatives are continuous functions

then  $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ , i.e. the order of differentiation

does not matter. In the cases that we will talk

about the function  $f$  will always be very regular,

so you won't have to worry about this.



The most famous PDES

- $\boxed{\partial_t u = D \partial_{xx} u}$  is the HEAT EQN. or DIFFUSION EQN.

where  $u = u(x, t)$  and  $D > 0$  is a constant,  
called DIFFUSIVITY CONSTANT.

- $\boxed{\partial_{tt} u = c^2 \partial_{xx} u}$  is the WAVE EQN or the equation

of the VIBRATING STRING, where  $u = u(x, t)$  and  $c^2 > 0$   
is a constant, called WAVE SPEED.

- $\boxed{u_{xx} + u_{yy} = 0}$  is LAPLACE'S EQN, where

$u = u(x, y)$ .

REM: for the first two equations we use the notation

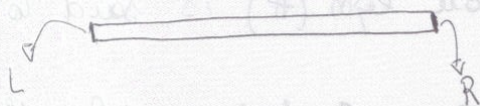
$u = u(x, t)$ , i.e.  $u$  is a function of space  $x$  and time  $t$ .

In the last eqn, instead,  $u$  is a function of two space  
variables,  $x$  and  $y$ . We will talk a little about the

meaning and physical interpretation of these equations;  
that should hopefully make things more clear.

Before getting into this matter let us answer a question:  
Why do we need functions of two variables?

EXAMPLE: consider a metallic bar, which is everywhere perfectly  
isolated from the exterior  
except at point  $R$ .



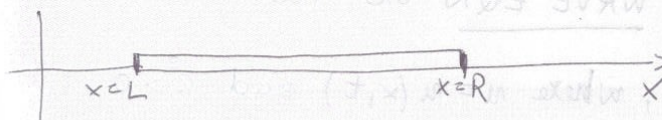
If we bring a hot body in contact with the bar at the point  $R$   
the bar starts heating up. Though it is common knowledge  
that ~~the part of the bar close to R~~ the part of the bar close to  $R$



will warm up before the part of the bar close to the point  $L$ .  
Hence the Temperature  $T$  depends on Time and space, i.e.  
it depends on when and where we measure it.

Indeed  $T = T(x, t)$  and we have for example

$T(R, 0) = 100^\circ$  ,  $T(L, 0) = 10^\circ$  . After enough  
time, we will see that


$$T(R, t) = T(L, t)$$

### HEAT EQUATION (or DIFFUSION EQN)

Setting for the moment  $D=1$ , the heat eqn looks like

(#)  $u_t = u_{xx}$  where  $u = u(x, t)$  -

$u(x, t)$  here represents the density of a quantity that  
diffuses (= "propagates") across a certain body and then  
it either reaches an equilibrium state or dissipates.  
This is typically what happens with heat conduction:  
if we put a hot body in contact with a cold one, heat  
diffuses (= spreads) through the cold body. When we  
remove the hot body, if the cold body was insulated then  
heat distributes homogeneously across the cold body  
until a state of equilibrium is reached. If the cold body  
was not insulated then heat dissipates into the  
environment. For this reason eqn (#) is said to  
be a dissipative equation.

~~So  $u(x, t)$  can be thought of as~~ So (#) models the  
phenomenon of heat conduction and similar phenomena;  
indeed it is also used in population dynamics to  
describe migratory phenomena -

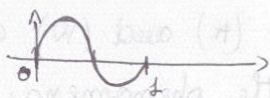


# WAVE EQUATION (or VIBRATING STRING EQN)

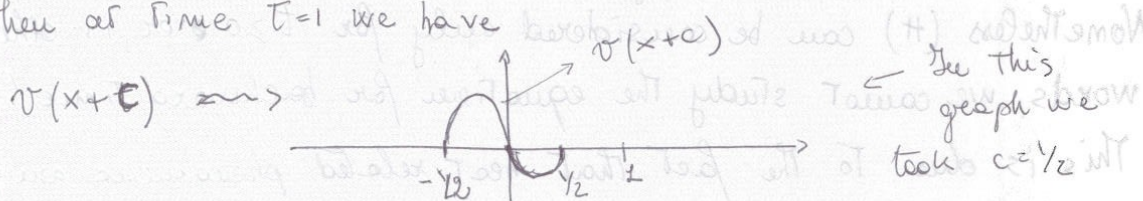
(w)  $u_{tt} = c^2 u_{xx}$

We will see that the general solution of (w) is of the form  $u(x,t) = v(x+ct) + f(x-ct)$  where  $v$  and  $f$  are two arbitrary functions to be determined through initial conditions.

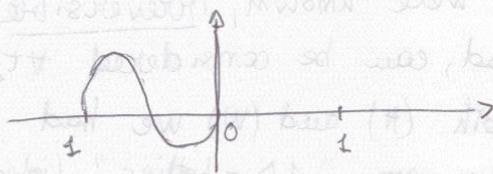
Suppose  $0 < x < 1$  and  $v(x) =$



Then at time  $t=1$  we have

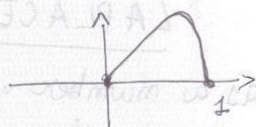


and at time  $t=2$

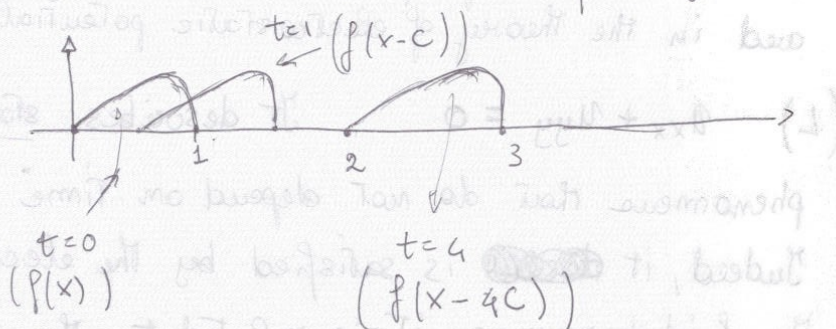


This is to say that  $v(x+ct)$  is a wave travelling towards the left with speed  $c$ .

In the same way, suppose  $f(x) =$



then  $f(x-ct) =$



Then  $f(x-ct)$  is a wave travelling towards right with speed  $c$ .



In conclusion, this is why (W) is called the wave eqn; indeed its solution is the superimposition of two ~~waves~~ waves travelling with speed  $c$  in opposite directions.

It also models the vibration of a string; in this context  $u(x,t)$  can be interpreted to be the vertical displacement of the string with respect to the  $x$ -axis.

- Equations (H) and (W) are called evolution equations because the phenomena they describe evolve in time.

Nonetheless (H) can be considered only for  $t \geq 0$  or, in other words, we cannot study the equation for backward time!

This is due to the fact that heat related phenomena are, as it is well known, irreversible!

(W), instead, can be considered  $\forall t$ .

Also in both (H) and (W) we had  $x \in \mathbb{R}$ , so the bodies we consider are "1D-bodies" (idealization)

For Laplace's eqn things are different.

### LAPLACE'S EQUATION

It has a number of applications, especially in fluid dynamics and in the theory of electrostatic potentials.

(L)  $u_{xx} + u_{yy} = 0$  It describes static phenomena, i.e. phenomena that do not depend on time.

Indeed, it ~~is~~ is satisfied by the electrostatic potential.

In fluid dynamics it is related to the description of incompressible and irrotational fluids -

The bodies involved are in this case "2D-bodies" as  $x$  and  $y$  are both space-variables. Solutions of (L) are called HARMONIC functions.