

Markov semigroups with hypocoercive-type generator in Infinite Dimensions: Ergodicity and Smoothing.

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Abstract

We first consider finite dimensional Markovian dynamics generated by operators of hypocoercive type and for such finite dimensional models we obtain short and long time pointwise estimates for all the derivatives, of any order and in any direction, along the semigroup. We then look at infinite dimensional models (in $(\mathbb{R}^m)^{\mathbb{Z}^d}$) produced by the interaction of infinitely many finite dimensional dissipative dynamics of the type indicated above. For these models we study finite speed of propagation of information, well-posedness of the infinite dimensional semigroup, time behaviour of the derivatives and strong ergodicity.

1 Introduction

In this paper we consider infinite dimensional models of interacting dissipative systems with non-compact state space. In particular we develop a basis for construction and analysis of dissipative semigroups whose generators are given in terms of noncommuting vector fields and for which the equilibrium measures are not a priori known. The ergodicity theory in the case where an invariant measure is not given in advance, in noncompact subelliptic setup is an interesting and challenging problem which was initially studied in [9] and we extend it in new directions in this paper developing further strategy based on generalised gradient bounds. In the following we will first present the main results of the paper and we will then relate them to existing results in the literature.

Hypoelliptic operators of hypocoercive type have received a lot of attention in recent years, see [12, 24] and references therein, as they naturally arise in non-equilibrium statistical mechanics, for example in the context of the heat bath formalism. These are second order operators on \mathbb{R}^m in Hörmander form

$$L = Z_0^2 + B,$$

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where Z_0 and B are first order differential operators. The principal part is spanned by at least one field Z_0 which, together with the term of first order B , generate fields $Z_{j+1} \equiv [B, Z_j]$, $j = 0, \dots, N-1$ spanning the full Lie algebra. Therefore by Hörmander theorem, (see e.g. [13], [6], [23] and references therein), such semigroups have strong smoothing property. Motivated by [24], we will refer to these generators as *hypocoercive* type operators (see Remark 2.2).

At the beginning of the paper, in Section 2, we describe a systematic inductive method which allows to obtain quantitative short and long time estimates for the space-derivatives of the semigroup generated by L . We obtain pointwise bounds on the derivatives of any order and in any space-direction. The techniques of Section 2 were originally developed in [21] and are based on combining the hypocoercive method presented in [12, 24] with the classic Bakry-Emery semigroup approach [2]. Section 2.1 contains an explanation of our technique and of its relations with the aforementioned methods in a simplified setting, so that the involved notation of Section 2.2, which is devoted to proving the time behaviour of the derivatives in full generality, does not obfuscate the idea behind the method we present. While obtaining such estimates is an interesting problem in itself, a motivation for obtaining *pointwise* estimates comes from the fact that in the infinite dimensional situation we are interested in this paper, typically one does not have any reference measure. As a consequence, since we do not have integration by parts trick at our disposal, generally we need to sacrifice estimates in direction of B . To the best of our knowledge, a purely analytical method adapted to obtaining pointwise bounds on the time-behaviour of the derivatives of any order of degenerate Markov semigroups was so far lacking. We now come to present the infinite dimensional problem tackled in the subsequent sections of the paper.

Once we have studied the finite dimensional diffusion in \mathbb{R}^m generated by the operator L , we study systems of infinitely many interacting diffusions of hypocoercive type. This is done by considering the lattice \mathbb{Z}^d and, roughly speaking, "place" an isomorphic copy of our \mathbb{R}^m -diffusion at each point of such a lattice. Finally, we let these dynamics interact, obtaining in this way an infinite dimensional Markovian dynamics in $(\mathbb{R}^m)^{\mathbb{Z}^d}$.

In Section 3 we provide a general construction of Markov semigroups in infinite dimensional setup with an underlying space given as a subset of an infinite product space (including an infinite product of noncompact Lie algebras). We improve there on the results described in [9] for semigroups with all generating fields present in the principal part of the generator. First of all we relax the conditions on the structure of the Lie groups and the principal part. Secondly we get a generalisation of the allowed interaction including a second order perturbation part dependent on fields acting on different coordinates. Additionally to that we prove stronger finite speed of propagation of information estimates providing a tree bound decay when derivatives with respect to many different coordinates act on the semigroup. This in particular allows us to prove smoothness of the semigroups in our general infinite dimensional setup filling the important gap in the literature (one may also expect that our estimates will provide some additional information about equilibrium measure). Additionally this allows to provide some new criteria for ergodicity of the semigroups.

In Section 4 we provide a strategy for proving the existence of invariant measures for a semigroup.

Assuming a Lyapunov type condition for a generator of a finite dimensional semigroup acting on a suitable unbounded function with compact level sets, we formulate conditions on the interaction allowing to apply a weak compactness criterion for the generator of the infinite dimensional non product semigroup constructed in Section 3.

In Section 5 we provide a criterion for uniqueness of invariant measure using first order as well as the higher order estimates.

In general, it is an art how to apply our criterion to particular models. We provide number of explicit examples of applications in [17]. In such a companion paper, we provide concrete illustration of the full flexibility of the theory developed in this paper with a variety of application areas and including examples where the setting we provide here is applied in a non-standard way. This includes a number of examples of infinite dimensional models with smoothing and ergodicity estimates, where precise dependence on parameters can be obtained or where one has long time concentration along some directions only.

1.1 Relation with literature

As we have already remarked, regarding the finite dimensional framework, the techniques of Section 2 result from combining the Bakry-Emery semigroup approach [2] with the hypoelliptic/hypocoercive methods proposed by Hérau and Villani, [12, 24]. As it is well known, the semigroup approach leads to pointwise estimates, but it is mainly designed for elliptic dynamics. The more recent framework proposed in [12, 24] is devised for degenerate diffusions but it requires an a priori knowledge of the invariant measure μ of the semigroup and it indeed produces estimates in the weighted space $L^2(\mu)$. Both of these techniques are entirely analytical. Combining these approaches results in a method that enjoys the perks of both of them: it is suited to the degenerate setup and it produces pointwise estimates. Moreover, it doesn't require any knowledge about the invariant measure and it can be adapted to tackle infinite dimensional problems, as we show in this paper. As far as the finite dimensional setting is concerned, another viable approach to study the time behaviour of the space derivatives of the semigroup is the probabilistic one, via Malliavin calculus, see for example [7] and references therein. However it might be technically involved to extend this technique to the infinite dimensional framework that we are aiming for. In contrast, the method we propose is easy to extend to the infinite dimensional setup.

We now come to explaining how our results for the infinite dimensional dynamics relate to existing ones in the literature. The problem of construction and ergodicity of dissipative dynamics for infinite dimensional interacting particle systems with bounded state space has a long history, see e.g. [18], [10] and references therein. For a construction of Markov semigroups on the space of continuous functions acting on an infinite dimensional underlying space (well suited to study strong ergodicity problems), we refer to [25] in fully elliptic operators, to [9] for the subelliptic setup, and to [20] for Lévy type generators; these constructions will be even more extended in this paper.

An interesting approach via stochastic differential equations can be found in [8] (see also [5], [4] and references therein). We mention also another approach via Dirichlet forms theory, see e.g. [1],

[22] and reference therein, which is well adapted to L_2 theory.

For symmetric semigroups, recent progress has been made in proving the log-Sobolev inequality for infinite dimensional Hörmander type generators \mathcal{L} which are symmetric in the weighted space $L_2(\mu)$, defined with respect to a suitable nonproduct measure μ ([19], [11], [16], [14], [15]). One can therefore expect an extension of the established strategy ([25]) for proving strong pointwise ergodicity for the corresponding Markov semigroups $P_t \equiv e^{t\mathcal{L}}$, (or in case of the compact spaces even in the uniform norm as in [10] and references therein). To obtain a fully fledged theory in this direction which could include for example configuration spaces given by infinite products of general noncompact nilpotent Lie groups other than Heisenberg type groups, one needs to conquer a (finite dimensional) problem of sub-Laplacian bounds (of the corresponding control distance) which for the moment remains still very hard. We remark that in fully elliptic case a strategy based on classical Bakry-Emery arguments involving restricted class of interactions can be achieved (even for nonlocal generators see e.g. [20]). In case of the stochastic strategy of [8], the convexity assumption enters via dissipativity condition in a suitable Hilbert space and does not improve the former one as far as ergodicity is concerned; (although on the other hand it allows to study a number of stochastically natural models). In subelliptic setup involving subgradient this strategy faces serious obstacles, see e.g. comments in [3].

To summarize, the purpose of this paper is twofold: regarding the finite dimensional setup, we improve on the methods presented in [24] by adapting the hypocoercive techniques to problems in which an invariant measure might not be a priori known; in infinite dimension, we provide results about systems of infinitely many interacting diffusions, thereby completing and extending the framework of [9, 20, 25].

2 Short and Long Time Behaviour of n-th Order Derivatives in Finite Dimensions.

Consider a second order differential operator on \mathbb{R}^m , of the form

$$L = Z_0^2 + B, \tag{1}$$

where Z_0 and B are first order differential operators. We will assume the following commutator structure:

Assumption 1 (CR.I). *Assume that for some $N \in \mathbb{N}$, $N \geq 1$, there exist N differential operators*

Z_1, \dots, Z_N such that the following commutator relations hold true:

$$\begin{aligned} [B, Z_j] &= Z_{j+1}, \quad \text{for all } j = 0, \dots, N-1, \\ [B, Z_N] &= \sum_{j=0}^N c_j Z_j, \\ [Z_i, Z_j] &= \sum_{h=0}^N c_{ijh} Z_h, \quad \text{for all } 0 \leq i, j \leq N, \end{aligned} \tag{2}$$

for some constants $c_j \in \mathbb{R}$, $j = 0, \dots, N-1$, $c_N \in [0, \infty)$ and $c_{ijh} \in \mathbb{R}$, with $c_{0jh} \equiv 0$ for $h \geq j-1$.

The main result of this section is Theorem 2.1, regarding the time behaviour of fields of any order along the semigroup. In order to state such a theorem we first need to introduce some notation and to further detail our framework.

We will assume that the collection of differential operators B and Z_0, Z_1, \dots, Z_N span \mathbb{R}^m at each point.¹ For Z_{k_j} , $k_l \in \{0, \dots, N\}$, $l = 1, \dots, n$, and $n \in \mathbb{N}$, we set

$$\mathbf{Z}_{\mathbf{k}, n} \equiv \mathbf{Z}_{k_1, \dots, k_n} := Z_{k_1} \cdot \dots \cdot Z_{k_n}.$$

In the following we will be referring to terms of the form $\mathbf{Z}_{\mathbf{k}, n} f$ and $Z_0 \mathbf{Z}_{\mathbf{k}, n} f \equiv (Z_0 Z_{k_1} \cdot \dots \cdot Z_{k_n} f)$ as terms of length n and terms of length $n+1$ starting with Z_0 , respectively. We will use \mathbf{e}_l , $l = 1, \dots, n$, with $(\mathbf{e}_l)_m = \delta_{lm}$, for the standard basis in \mathbb{R}^n , and have $\mathbf{k} \equiv \sum_{l=1, \dots, n} k_l \mathbf{e}_l$ with non-negative integer coefficients k_l , $l = 1, \dots, n$, and we set

$$|\mathbf{k}|_n := \sum_{l=1}^n k_l.$$

In the following $\|\cdot\|_\infty$ indicates the supremum norm. We will use the notation $P_t := e^{tL}$, $t \geq 0$, for the semigroup generated by the operator L and set $f_t = e^{tL} f$ for any continuous bounded functions f .

For some strictly positive constants $a_{\mathbf{k}, n} \equiv a_{k_1, \dots, k_n}$, $b_{\mathbf{k}, n} \equiv b_{k_1, \dots, k_n}$, $0 \leq k_l \leq N$, $l = 1, \dots, n$, and d , (to be chosen later), we define the following time dependent quadratic forms

$$Q_t^{(0)} f_t = d |f_t|^2$$

¹Strictly speaking, this assumption is not needed in the finite dimensional case. However it will be needed in the infinite dimensional problem. In \mathbb{R}^m , it is simply the case that one will obtain estimates in all the directions that can be obtained from the successive commutators between Z_0 and B , including Z_0 but not B .

and

$$\begin{aligned}\bar{\Gamma}_t^{(1)} f_t &\equiv \sum_{j=0}^N a_j t^{2j+1} |Z_j f_t|^2, \\ \Gamma_t^{(1)} f_t &\equiv \bar{\Gamma}_t^{(1)} f_t + \sum_{j=1}^N b_j t^{2j} (Z_{j-1} f_t)(Z_j f_t),\end{aligned}\tag{3}$$

$$Q_t^{(1)} f_t \equiv \Gamma_t^{(1)} f_t + Q_t^{(0)} f_t.\tag{4}$$

For general $n \geq 2$ we therefore set,

$$\begin{aligned}\bar{\Gamma}_t^{(n)} f_t &\equiv \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\ \Gamma_t^{(n)} f_t &\equiv \bar{\Gamma}_t^{(n)} f_t + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t)(\mathbf{Z}_{\mathbf{k},n} f_t), \\ Q_t^{(n)} f_t &\equiv \Gamma_t^{(n)} f_t + Q_t^{(n-1)} f_t\end{aligned}\tag{5}$$

We prove the following result.

Theorem 2.1. *Suppose the operators $B, Z_j, j = 1, \dots, N$ satisfy Assumption **(CR.I)** and $P_t \equiv e^{tL}$ is a Markov semigroup with generator L given by (1). Then for all $n \in \mathbb{N}$ and for all $0 \leq l \leq n$ there exist strictly positive constants $a_{\mathbf{k},l}, b_{\mathbf{k},l}, \bar{d}_l, d_l$ and $T \in (0, \infty]$ such that*

$$\bar{d}_l \bar{\Gamma}_t^{(l)} f_t \leq \Gamma_t^{(l)} f_t \leq d_l (P_t f^2 - (P_t f)^2), \quad \text{for all } 1 \leq l \leq n \text{ and } 0 < t < T.\tag{6}$$

Moreover if $c_j \equiv 0$ and $c_{0jh} \equiv 0$ for all $j = 1, \dots, N$, then $T = \infty$, and in particular we have

$$\|\mathbf{Z}_{\mathbf{k},n} f_t\|_\infty^2 \leq \frac{C}{t^{2|\mathbf{k}|_n+n}} \|P_t f^2 - (P_t f)^2\|_\infty \leq \frac{C}{t^{2|\mathbf{k}|_n+n}} \inf_{c \in \mathbb{R}} \|f - c\|_\infty^2, \quad \text{for all } t > 0,\tag{7}$$

with some constant $C \in (0, \infty)$ independent of t and f .

Before coming to the proof of Theorem 2.1, we make a couple of remarks in order to give some more intuition about the statement of such a theorem.

Remark 2.1. In words, Theorem 2.1 states the following: under the general commutator relations of Assumption **(CR.I)**, the time behaviour of the first inequality in (7) is valid only for $0 < t < T$ with T small enough, typically $T < 1$, i.e. in all generality we can only obtain a short time estimate. However, if we assume for example that the fields $Z_i, i = 0, \dots, N$ commute and that Z_N commutes with B then the time behaviour (6) is valid for any $t > 0$. In this paper we work under the relatively

general Assumption **(CR.I)**. We would like to emphasize that the technique we use to prove Theorem 2.1 is quite flexible and might give better results depending on the case at hand. In particular one might be able to improve on the time interval in which the estimate is valid when exact knowledge of the constants appearing in Assumption **(CR.I)** is available. This improvement might also be obtained in cases where

$$[B, Z_j] = \alpha_j Z_{j+1}, \quad \text{for all } j = 0, \dots, N-1,$$

for some large positive constants α_j . When the generator contains a dilation operator it is also possible to obtain exponential decay. We have illustrated this fact with an (infinite dimensional) example in [17], see also Theorem 5.1.

Remark 2.2. Notice that the above proposition is coherent with Hörmander's rank nomenclature, as it agrees with the heuristics according to which for any differential operators X and Y , $r(XY) = r(X) + r(Y)$, $r([X, Y]) = r(X) + r(Y)$, where $r(X)$ denotes the rank of the operator X . In particular, Z_0 is an operator of rank 1 and B is an operator of rank 2, so that $r(Z_j) = 2j + 1$, for any $0 \leq j \leq N$ and $r(Z_{k_1} \cdot \dots \cdot Z_{k_n}) = 2 \sum_{j=1}^n k_j + n$.

Because new vector fields are obtained only through commutators with the rank 2 operator B , we will refer to L as to a hypocoercive-type operator, in analogy with the setting considered in [24]. However we would like to stress that despite this clear analogy, the setting in which we are going to work is quite far from the one of the hypocoercivity theory. Indeed, as we have mentioned in the introduction, here we do not assume the existence of a reference (equilibrium) measure and the estimates we obtain are pointwise.

Remark 2.3. Because of the linearity of the operator, all the results of Theorem 2.1 still hold if

$$L = \sum_{i=1}^M Z_{0,i}^2 + B,$$

for some $M > 1$. We do not present the results in such generality only to avoid having cumbersome notations, especially in the proof of Theorem 2.1 and in the infinite dimensional setting.

The proof of Theorem 2.1 is quite lengthy although in principle not complicated. We believe that the lengthy calculations that such a proof requires might obscure the simple idea behind it; especially, they might conceal the flexibility of our approach. In order to clearly explain the strategy of proof, we gather in Section 2.1 below a simple explanation of the principle behind our approach with a sketch of the proof of Theorem 2.1 in the simple case $m = 2$ and $N = n = 1$. The full proof of Theorem 2.1 is instead deferred to Section 2.2.

2.1 Strategy of proof of Theorem 2.1: combining semigroup and hypocoercivity methods

In this section we fix $n = N = 1$ and $m = 2$, i.e. we consider a Markov generator on \mathbb{R}^2 of the form (1) and we assume that B , Z_0 and $Z_1 := [B, Z_0]$ span \mathbb{R}^2 at each point.² We are interested in determining the time behaviour of the fields Z_0 and Z_1 , along the semigroup $f_t := e^{tL}f$, i.e. we want to study the time behaviour of $Z_0 f_t$ and $Z_1 f_t$. Notice that in this simple case the quadratic form $Q_t^{(1)}$ defined in (4) - which, for the purposes of this section, we will just denote by Q_t - reduces to

$$Q_t(f_t) = d|f_t|^2 + a_0 t |Z_0 f_t|^2 + a_1 t^3 |Z_1 f_t|^2 + bt^2 (Z_0 f_t)(Z_1 f_t),$$

where d, a_0, a_1 and b are strictly positive constants to be determined later. To explain why we use such a time-dependent quadratic form, let us start with a simple observation: suppose we consider, instead of Q_t , the function \tilde{Q}_t defined as follows:

$$\tilde{Q}_t(f_t) = d|f_t|^2 + a_0 t |Z_0 f_t|^2 + a_1 t^3 |Z_1 f_t|^2.$$

If we could prove

$$\partial_t(\tilde{Q}_t f_t) < 0 \quad \text{for } t \text{ in some interval say } [0, T], \quad (8)$$

then we would be done as the above would imply

$$\tilde{Q}_t f_t < \tilde{Q}_0 f = d|f|^2 \implies |Z_0 f_t|^2 < \frac{da_0^{-1}}{t} |f|^2 \text{ and } |Z_1 f_t|^2 < \frac{da_1^{-1}}{t^3} |f|^2,$$

for all $t \in [0, T]$. However, as long as we use the time dependent form \tilde{Q}_t , (8) is in general not true. Indeed, roughly speaking, in order to prove (8), one usually needs to prove that

$$\partial_t(\tilde{Q}_t f_t) < -\kappa \left(|Z_0 f_t|^2 + |Z_1 f_t|^2 \right), \quad \text{for some } \kappa > 0.$$

If we use the form \tilde{Q}_t , the negative terms $-\kappa |Z_1 f_t|^2$ will not appear in the expression for $\partial_t(\tilde{Q}_t f_t)$. The mixed term $(Z_0 f_t)(Z_1 f_t)$ is added to the quadratic form precisely to solve this issue. Such a trick has been introduced in [12] and then pushed forward in [24]. However in both cases the quadratic form did not contain the pointwise values of the function f_t and its derivatives, but rather the weighted L^2 norm of such quantities. It is important to stress that, using the quadratic Young's inequality, i.e.

$$\forall x, y \in \mathbb{R}, \mathfrak{d} > 0 \quad |xy| \leq \frac{|x|^2}{2\mathfrak{d}} + \frac{\mathfrak{d}|y|^2}{2}, \quad (9)$$

with \mathfrak{d} a constant times a suitable positive power of t , we can show that there exists a suitable choice of the constant b such that Q_t is still positive. Indeed, choosing $\mathfrak{d} = t/b$, we obtain

$$Q_t(f_t) \geq d|f_t|^2 + t(a_0 - b^2/2) |Z_0 f_t|^2 + t^3(a_1 - 1/2) |Z_1 f_t|^2 \geq 0. \quad (10)$$

²In many applications one finds that only Z_0 and Z_1 are actually needed to fully span \mathbb{R}^2 . See for example [17].

Hence, choosing $a_0 > b^2/2$ and $a_1 > 1/2$ guarantees the positivity of $Q_t f_t$. Unfortunately, even after this modification, it is still the case that the inequality $\partial_t(Q_t f_t) < 0$ is in general not true. We therefore devise another strategy, which makes use of the classic Bakry-Emery semigroup approach: instead of trying to prove that $\partial_t(Q_t f_t) < 0$, we show

$$\partial_s(P_{t-s}Q_s(f_s)) < 0 \quad \text{for } t \text{ in some interval } [0, T]. \quad (11)$$

Integrating the above inequality in $[0, t]$ we obtain

$$\begin{aligned} P_0(Q_t(f_t)) - P_t(Q_0 f) &< 0 \\ \Rightarrow Q_t(f_t) &< d\|f\|_\infty^2 \quad \text{for } t \in [0, T], \end{aligned}$$

which, thanks to (10), implies the sought bounds. Notice that in the above we used the contractivity of the Markov semigroup. In general one will just have $Q_t(f_t) < P_t(f_t^2)$.

A straightforward calculation shows that proving the property (11) reduces to showing

$$(-L + \partial_t)(Q_t(f_t)) < 0.$$

Proving such an inequality is done by repeatedly using the Young's inequality, in the same way shown in (10).

We now turn to the full proof of Theorem 2.1.

2.2 Proof of Theorem 2.1

Throughout the proof of Theorem 2.1 we will often use some elementary facts, which we gather in Lemma 2.1, Lemma 2.2 and Lemma 2.3 below, for the reader's convenience.

Lemma 2.1. *For any $n \in \mathbb{N}$ and $\mathbf{k} \equiv (k_1, \dots, k_n)$ and any smooth function f the following relations hold true:*

$$\begin{aligned} L|\mathbf{Z}_{\mathbf{k},n}f|^2 - 2(L\mathbf{Z}_{\mathbf{k},n}f)(\mathbf{Z}_{\mathbf{k},n}f) &= +2|Z_0\mathbf{Z}_{\mathbf{k},n}f|^2, \\ Z_0^2|\mathbf{Z}_{\mathbf{k},n}f|^2 &= 2(Z_0^2\mathbf{Z}_{\mathbf{k},n}f)(\mathbf{Z}_{\mathbf{k},n}f) + 2|Z_0\mathbf{Z}_{\mathbf{k},n}f|^2, \end{aligned}$$

If $[Z_N, B] = 0$ then

$$[\mathbf{Z}_{\mathbf{k},n}, B] = - \sum_{1 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}+\mathbf{e}_j, n}. \quad (12)$$

The above equality also simply holds if $k_j \neq N$ for all $j = 1, \dots, N$. Finally, if $c_{0jh} = 0$ for all j (i.e. if $[Z_0, Z_j] = 0$ for all j) then $[\mathbf{Z}_{\mathbf{k},n}, L] = [\mathbf{Z}_{\mathbf{k},n}, B]$ for any $n \geq 1$.

Proof of Lemma 2.1. The first relation is a general property of a generator of (sub)diffusion with second order part given by Z_0 and the second is a just a different version of the same. Recalling that for any three operators X, Y and W ,

$$[XY, W] = X[Y, W] + [X, W]Y, \quad (13)$$

from (2), for $k_1 \neq N$, we have

$$[\mathbf{Z}_{\mathbf{k},n}, B] = Z_{k_1}[Z_{k_2} \cdots Z_{k_n}, B] - Z_{k_1+1}Z_{k_2} \cdots Z_{k_n} \equiv Z_{k_1}[Z_{k_2} \cdots Z_{k_n}, B] - \mathbf{Z}_{\mathbf{k}+\mathbf{e}_1,n} \quad (14)$$

Iterating (14) one obtains (12). Regarding the last statement, this can be obtained, when $[Z_0, Z_j] = 0$ for any j , by using (13). \square

Lemma 2.2. *Let X and Y be first order differential operators and $\mathfrak{L} = X^2 + Y$. Assume \mathfrak{L} generates a semigroup such that for any smooth functions h also $h_t = e^{t\mathfrak{L}}h$ is smooth. Then for any differential operators W, V (of any order $l \geq 0$), we have*

$$\begin{aligned} \left(-\mathfrak{L} + \frac{\partial}{\partial t}\right) Wh_t \cdot Vh_t &= -X^2(Wh_t \cdot Vh_t) - Y(Wh_t \cdot Vh_t) + (W\mathfrak{L}h_t)(Vh_t) + (Wh_t)(V\mathfrak{L}h_t) \\ &= -2XWh_t \cdot XVh_t + ([W, \mathfrak{L}]h_t) \cdot Vh_t + Wh_t \cdot ([V, \mathfrak{L}]h_t). \end{aligned}$$

Lemma 2.3. *Suppose*

$$[Z_k, Z_0] = - \sum_{0 \leq l < k-1}^N c_{0kl} Z_l.$$

Then there exist real numbers $\eta_{\mathbf{k},\mathbf{k}',n} \equiv \eta_{\mathbf{k},\mathbf{k}'}, \zeta_{\mathbf{k},\mathbf{k}',n} \equiv \zeta_{\mathbf{k},\mathbf{k}'}$, such that

$$[Z_{\mathbf{k},n}, Z_0^2] = \sum_{\mathbf{k}'} \eta_{\mathbf{k},\mathbf{k}'} Z_0 Z_{\mathbf{k}',n} + \sum_{\mathbf{k}'} \zeta_{\mathbf{k},\mathbf{k}'} Z_{\mathbf{k}',n}$$

with $0 \leq |\mathbf{k}'|_n < |\mathbf{k}|_n - 1 \leq nN$.

The proof of the above Lemma 2.3 can be found after the proof of Theorem 2.1

Proof of Theorem 2.1. We will show that given $n \in \mathbb{N}$, for all $0 \leq l \leq n$ one can choose the coefficients $a_{\mathbf{k},l}, b_{\mathbf{k},l}, d_l \in (0, \infty)$, so that

$$\text{for all } 0 \leq l \leq n, \quad \partial_s \left[P_{t-s} \left(Q_s^{(l)} f_s \right) \right] < 0;$$

hence, integrating on $[0, t]$, for $t \in (0, T]$ (for some $T > 0$ to be determined later), we get

$$Q_t^{(l)} f_t = P_0 \left(Q_t^{(l)} f_t \right) < P_t \left(Q_0^{(l)} f_0 \right) \equiv dP_t f^2$$

Because

$$\partial_s \left[P_{t-s} \left(Q_s^{(n)} f_s \right) \right] = P_{t-s} \left(-L Q_s^{(n)} f_s + \partial_s Q_s^{(n)} f_s \right),$$

and the semigroup P_t preserves positivity, the whole thing boils down to proving that $\forall n \geq 1$ there exist strictly positive constants $\{a_{\mathbf{k},n} : 0 \leq |\mathbf{k}|_n \leq nN\}$, $\{b_{\mathbf{k},n} : 0 \leq |\mathbf{k}|_n \leq nN \text{ with } k_1 \geq 1\}$ and $d_n \in (0, \infty)$ such that

$$\forall t > 0, \quad (-L + \partial_t) \left(Q_t^{(n)} f_t \right) \leq 0. \quad (15)$$

In order to streamline the proof we first consider Assumption **(CR.I)** with $c_j = 0$ and $c_{0jh} = 0$ for all $j = 1, \dots, N$, i.e. we first prove (7). Later we will explain how to remove this restriction (at the cost of obtaining bounds that are valid only for small T) and obtain (6).

• **Proof of (7).** Suppose that Assumption **(CR.I)** holds with $c_j = 0$ and $c_{0jh} = 0$ for all $j = 1, \dots, N$. We will prove (15) by induction on n . The inductive basis, i.e. the proof that for $n = 0$ there exists $d \in (0, \infty)$ such that $\forall t > 0 \quad (-L + \partial_t) Q_t^{(0)} f_t \leq 0$, is straightforward. Indeed

$$(-L + \partial_t) |f_t|^2 = -Z_0^2 |f_t|^2 - B |f_t|^2 + 2f_t L f_t = -2|Z_0 f_t|^2 \leq 0,$$

where we simply used the fact that Z_0^2 is a second order differential operator and B is a first order differential operator.

Now we make an inductive assumption that for any $n \geq 1$ and for all $l = 1, \dots, n-1$ there exist strictly positive constants $\{a_{\mathbf{k},l} : 0 \leq |\mathbf{k}|_l \leq lN\}$, $\{b_{\mathbf{k},l} : 0 \leq |\mathbf{k}|_l \leq lN \text{ with } k_1 \geq 1\}$ and $d_l, \bar{d}_l \in (0, \infty)$, such that

$$\forall t > 0 \quad (-L + \partial_t) \left(Q_t^{(n-1)} f_t \right) \leq 0,$$

and

$$\forall l = 1, \dots, n-1 \quad \bar{d}_l \bar{\Gamma}_t^{(l)} f_t \leq \Gamma_t^{(l)} f_t.$$

Under this inductive assumption we need to prove that there exist strictly positive constants $\{a_{\mathbf{k},n} : 0 \leq |\mathbf{k}|_n \leq nN\}$, $\{b_{\mathbf{k},n} : 0 \leq |\mathbf{k}|_n \leq nN \text{ with } k_1 \geq 1\}$ and $d_n, \bar{d}_n \in (0, \infty)$ such that

$$\forall t > 0 \quad (-L + \partial_t) \left(Q_t^{(n)} f_t \right) \leq 0$$

and

$$\bar{d}_l \bar{\Gamma}_t^{(n)} f_t \leq \Gamma_t^{(n)} f_t.$$

Because we are assuming that $(-L + \partial_t) \left(Q_t^{(n-1)} f_t \right) \leq 0$, for some appropriate choice of the con-

stants, looking at (5), we only need to study the following quantity:

$$\begin{aligned} (-L + \partial_t) \left(\Gamma_t^{(n)} f_t \right) &= (-L + \partial_t) \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\ &+ (-L + \partial_t) \sum_{0 \leq |\mathbf{k}|_n : k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) (\mathbf{Z}_{\mathbf{k},n} f_t). \end{aligned}$$

We stress that throughout this calculation, we intend for all the constants b_{N+1,k_2,\dots,k_n} to be equal to zero. To further expand the expression on the right hand side of the above, we use Lemma 2.1 together with Lemma 2.2, for our generator (1), and we obtain

$$\begin{aligned} (-L + \partial_t) \left(\Gamma_t^{(n)} f_t \right) &= \\ - 2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} |Z_0 \mathbf{Z}_{\mathbf{k},n} f_t|^2 & \quad (16) \end{aligned}$$

$$- 2 \sum_{0 \leq |\mathbf{k}|_n : k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} (Z_0 \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) (Z_0 \mathbf{Z}_{\mathbf{k},n} f_t) \quad (17)$$

$$+ \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} (2|\mathbf{k}|_n + n) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \quad (18)$$

$$+ \sum_{0 \leq |\mathbf{k}|_n : k_1 \geq 1}^{nN} b_{\mathbf{k},n} (2|\mathbf{k}|_n + n - 1) t^{2|\mathbf{k}|_n+n-2} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) (\mathbf{Z}_{\mathbf{k},n} f_t) \quad (19)$$

$$+ 2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n} f_t \cdot [\mathbf{Z}_{\mathbf{k},n}, L] f_t \quad (20)$$

$$+ \sum_{0 \leq |\mathbf{k}|_n : k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \{ ([\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n}, L] f_t) \mathbf{Z}_{\mathbf{k},n} f_t + (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) [\mathbf{Z}_{\mathbf{k},n}, L] f_t \}. \quad (21)$$

We control these terms as follows. Let us set

$$[\text{I}] := (16) + (17), \quad [\text{II}] := (18) + (19), \quad [\text{III}] := (20) + (21)$$

and study these addends separately. Recall now the quadratic Young's inequality (9), which we will repeatedly use. In particular we will choose \mathfrak{d} in (9) to be a constant times a suitable positive power of t . The time dependent factor will be relevant for bounds involving factors with differential

operators of different rank to obtain time dependences of appropriate homogeneity. We have

$$[\text{I}] \leq -2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} |Z_0 \mathbf{Z}_{\mathbf{k},n} f_t|^2 \quad (22)$$

$$+ 2 \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} \left(b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-2} |Z_0 \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t|^2 + t^{2|\mathbf{k}|_n+n} |Z_0 \mathbf{Z}_{\mathbf{k},n} f_t|^2 / b_{\mathbf{k},n} \right). \quad (23)$$

We look separately at the terms with $k_1 = 0$ and at the terms with $k_1 > 0$. In doing so, we need to notice that terms of the form $|Z_0^2 Z_{k_2} \cdots Z_{k_n} f_t|$ (i.e. those with $k_1 = 0$) come from (22) when $k_1 = 0$ but also from the first addend in (23) when $k_1 = 1$. Hence

$$\begin{aligned} [\text{I}] &\leq 2 \sum_{k_2, \dots, k_n=0}^N \left(-a_{0,k_2, \dots, k_n} + b_{1,k_2, \dots, k_n}^2 \right) t^{2|\mathbf{k}-\mathbf{e}_1|_n+n} |Z_0^2 \mathbf{Z}_{k_2, \dots, k_n} f_t|^2 \\ &\quad + 2 \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(-a_{k_1, k_2, \dots, k_n} + b_{k_1+1, k_2, \dots, k_n}^2 + 1 \right) t^{2|\mathbf{k}|_n+n} |Z_0 \mathbf{Z}_{\mathbf{k},n} f_t|^2, \end{aligned}$$

with the understanding that $b_{k_j+1} = 0$ if $k_j = N$. Thus we can make term [I] nonpositive choosing

$$\frac{1}{2} a_{k_1, k_2, \dots, k_n} > b_{k_1+1, k_2, \dots, k_n}^2 + 1, \quad k_1 \geq 0 \quad (24)$$

We can and do assume that similar *strict* inequality is satisfied on induction level $n-1$. We repeat the same kind of procedure for [II], applying first Young's inequality and then looking separately at the two cases $k_1 = 0$ and $k_1 > 0$ to get

$$\begin{aligned} [\text{II}] &\leq \sum_{|\mathbf{k}|_n \geq 0}^{nN} a_{\mathbf{k},n} (2|\mathbf{k}|_n + n) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\ &\quad + \frac{1}{2} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} (2|\mathbf{k}|_n + n - 1) \left(\varepsilon t^{2|\mathbf{k}|_n+n-3} |\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t|^2 + \varepsilon^{-1} t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \right) \\ &\leq (2nN + n) \sum_{|\mathbf{k}|_n \geq 0}^{nN} \left(a_{0,k_2, \dots, k_n} + \frac{\varepsilon}{2} b_{1,k_2, \dots, k_n} \right) t^{2|\mathbf{k}|_n+n-1} |Z_0 \mathbf{Z}_{k_2, \dots, k_n} f_t|^2 \\ &\quad + (2nN + n) \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(a_{k_1, \dots, k_n} + \varepsilon^{-1} b_{k_1+1, k_2, \dots, k_n} + \frac{\varepsilon}{2} b_{k_1, \dots, k_n} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2, \end{aligned}$$

with $\varepsilon < (2nN + n)^{-1}$ to be chosen later. Before turning to [III] notice that, because of our current

simplified assumption, we have $[Z_N, B] = [Z_0, Z_j] = 0$ for all j ; therefore we have $[\mathbf{Z}_{\mathbf{k},n}, L] = [\mathbf{Z}_{\mathbf{k},n}, B]$ (see last statement of Lemma 2.1) and by (12)

$$[\mathbf{Z}_{\mathbf{k},n}, L] = - \sum_{1 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n}.$$

Using this, we have

$$\begin{aligned} [\text{III}] &= -2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n} f_t \cdot \left(\sum_{1 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n} f_t \right) \\ &\quad - \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(\left(\sum_{1 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1+\mathbf{e}_j,n} f_t \right) \mathbf{Z}_{\mathbf{k},n} f_t \right) \\ &\quad - \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t \left(\sum_{1 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n} f_t \right) \right) \\ &\equiv [\text{III}a] + [\text{III}b] + [\text{III}c]. \end{aligned}$$

Each of the sums on the right hand side is bounded using (9) to adjust the power of t according to the rank of the corresponding differential operators as follows:

$$\begin{aligned} [\text{III}a] &\leq \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \left(a_{\mathbf{k},n} t^{-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 + a_{\mathbf{k},n}^{-1} n t \sum_{1 \leq j: k_j \neq N}^n |\mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n} f_t|^2 \right) \\ &\leq \sum_{|\mathbf{k}|_n=0}^{nN} (a_{\mathbf{k},n}^2 + n^2) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \end{aligned}$$

Also,

$$\begin{aligned}
[\text{III}b] &= - \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\
&\quad - \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(\left(\sum_{2 \leq j: k_j \neq N}^n \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1+\mathbf{e}_j,n} f_t \right) \mathbf{Z}_{\mathbf{k},n} f_t \right) \\
&\leq - \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\
&\quad + \frac{1}{2} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left((n-1) \sum_{2 \leq j: k_j \neq N}^n |\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1+\mathbf{e}_j,n} f_t|^2 + |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \right) \\
&= \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(-\frac{1}{2} b_{\mathbf{k},n} + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2. \\
[\text{III}c] &\leq \frac{1}{2} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(b_{\mathbf{k},n} t^{-2} |\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t|^2 + n b_{\mathbf{k},n}^{-1} t^2 \sum_{1 \leq j: k_j \neq N}^n |\mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n} f_t|^2 \right) \\
&= \sum_{0 \leq |\mathbf{k}|_n: 0 \leq k_1 \leq N-1}^{nN} \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 + \frac{n}{2} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} t^{2|\mathbf{k}|_n+n+1} \sum_{1 \leq j: k_j \neq N}^n |\mathbf{Z}_{\mathbf{k}+\mathbf{e}_j,n} f_t|^2 \\
&\leq \sum_{0 \leq |\mathbf{k}|_n: k_1=0}^{nN} \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} t^{2|\mathbf{k}|_n+n-1} |Z_0 \mathbf{Z}_{k_2, \dots, k_n, n} f_t|^2 + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(\frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2.
\end{aligned}$$

We now combine and reorganize the bounds of [III] separating terms with $k_1 = 0$ which need to be offset by level $(n-1)$, (if necessary scaling coefficients of Q_s by a positive sufficiently large constant), and the ones with $k_1 \geq 1$ which can only be offset by negative contribution in [IIIb], as follows.

$$\begin{aligned}
[\text{III}] &\leq \sum_{|\mathbf{k}|_n=0}^{nN} (a_{\mathbf{k},n}^2 + n^2) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\
&\quad + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(-\frac{1}{2} b_{\mathbf{k},n} + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2 \\
&\quad + \sum_{0 \leq |\mathbf{k}|_n: k_1=0}^{nN} \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} t^{2|\mathbf{k}|_n+n-1} |Z_0 \mathbf{Z}_{k_2, \dots, k_n, n} f_t|^2 + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(\frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2.
\end{aligned}$$

Therefore

$$\begin{aligned}
[\text{III}] \leq & \sum_{0 \leq |\mathbf{k}|_n: k_1=0}^{nN} \left(a_{\mathbf{k},n}^2 + n^2 + \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} \right) t^{2|\mathbf{k}|_n+n-1} |Z_0 \mathbf{Z}_{k_2,\dots,k_n,n} f_t|^2 \\
& + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \left(a_{\mathbf{k},n}^2 + n^2 - \frac{1}{2} b_{\mathbf{k},n} + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} + \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2} \right) t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2.
\end{aligned}$$

Combining this with bound of [II] and separating the terms with $k_1 = 0$ (which need to be offset by level $(n-1)$) and the ones with $k_1 \geq 1$ which can only be offset by the negative contribution in [IIIb], we obtain

$$[\text{II}] + [\text{III}] \leq \sum_{0 \leq |\mathbf{k}|_n: k_1=0}^{nN} \mathcal{A}_{k_2,\dots,k_n} t^{2|\mathbf{k}|_n+n-1} |Z_0 \mathbf{Z}_{k_2,\dots,k_n,n} f_t|^2 + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \mathcal{B}_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} |\mathbf{Z}_{\mathbf{k},n} f_t|^2,$$

where $\mathcal{A}_{k_2,\dots,k_n} \equiv (2nN + n) (a_{0,k_2,\dots,k_n} + \frac{\varepsilon}{2} b_{1,k_2,\dots,k_n}) + \left(a_{0,k_2,\dots,k_n}^2 + n^2 + \frac{b_{1,k_2,\dots,k_n}^2}{2} \right)$ and

$$\begin{aligned}
\mathcal{B}_{\mathbf{k},n} & \equiv (2nN + n) \left(a_{k_1,\dots,k_n} + \varepsilon^{-1} b_{k_1+1,k_2,\dots,k_n} + \frac{\varepsilon}{2} b_{k_1,\dots,k_n} \right) \\
& + a_{\mathbf{k},n}^2 + n^2 - \frac{1}{2} b_{\mathbf{k},n} + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} + \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2} \\
& = -\frac{1}{2} (1 - \varepsilon n(2N + 1)) b_{\mathbf{k},n} + (2nN + n) (a_{\mathbf{k},n} + \varepsilon^{-1} b_{\mathbf{k}+\mathbf{e}_1,n}) \\
& + a_{\mathbf{k},n}^2 + n^2 + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} + \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2}.
\end{aligned}$$

We note that the terms involving $\mathcal{A}_{k_2,\dots,k_n}$ can be offset by $Q_t^{(n-1)}$ (possibly at a cost of multiplying by a sufficiently large positive constant). On the other hand choosing $\varepsilon n(2N + 1) < 1$ and the coefficients so that we have

$$\begin{aligned}
\mathcal{B}_{\mathbf{k},n} & \leq -\frac{1}{2} (1 - \varepsilon n(2N + 1)) b_{\mathbf{k},n} + (2nN + n) (a_{\mathbf{k},n} + \varepsilon^{-1} b_{\mathbf{k}+\mathbf{e}_1,n}) \\
& + a_{\mathbf{k},n}^2 + n^2 + \frac{(n-1)}{2} \sum_{2 \leq j: k_j \neq N}^n b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n} + \frac{b_{\mathbf{k}+\mathbf{e}_1,n}^2}{2} + \frac{n^2}{2} < 0,
\end{aligned}$$

this and (24) can be represented as the following condition

$$a_{\mathbf{k},n} \gg b_{\mathbf{k}+\mathbf{e}_1,n}^2, \quad b_{\mathbf{k},n} \gg a_{\mathbf{k},n}, \quad b_{\mathbf{k},n} \gg b_{\mathbf{k}+\mathbf{e}_1,n}, \quad b_{\mathbf{k},n} \gg b_{\mathbf{k}+\mathbf{e}_1-\mathbf{e}_j,n}, \quad j \geq 2, \quad (25)$$

with a convention $x \gg y$ meaning $x \geq Cy^2 + C'$ with some constants $C, C' \in [1, \infty)$ sufficiently large and possibly dependent on n , but not on \mathbf{k} . In this way we get (15).

We are now left with proving the following statement

$$\bar{d}_n \bar{\Gamma}_s^{(n)} f_s \leq \Gamma_s^{(n)} f_s, \quad (26)$$

for some $\bar{d}_n \in (0, \infty)$. To this end, we will use the lower bound implied by the quadratic Young inequality

$$-\frac{|x|^2}{\mathfrak{d}} - \mathfrak{d}|y|^2 \leq xy, \quad \forall x, y \in \mathbb{R}, \mathfrak{d} > 0.$$

We separate the terms with $k_1 = 0$ from the terms with $k_1 > 0$ to we get

$$\begin{aligned} \Gamma_t^{(n)} f_t &= \sum_{k_2, \dots, k_n=0}^N \left[a_{0, k_2, \dots, k_n} t^{2(\sum_{j=2}^n k_j) + n} |Z_0 Z_{k_2} \cdot \dots \cdot Z_{k_n} f_t|^2 \right. \\ &\quad \left. + b_{1, k_2, \dots, k_n} t^{2(\sum_{j=2}^n k_j) + n + 1} (Z_0 Z_{k_2} \cdot \dots \cdot Z_{k_n} f_t) (Z_1 Z_{k_2} \cdot \dots \cdot Z_{k_n} f_t) \right] \\ &\quad + \sum_{k_2, \dots, k_n=0}^N \sum_{k_1=1}^N a_{k_1, \dots, k_n} t^{2|\mathbf{k}|_n + n} |Z_{k_1} \cdot \dots \cdot Z_{k_n} f_t|^2 \\ &\quad + \sum_{k_2, \dots, k_n=0}^N \sum_{k_1=2}^N b_{k_1, \dots, k_n} t^{2|\mathbf{k}|_n + n - 1} (Z_{k_1-1} Z_{k_2} \cdot \dots \cdot Z_{k_n} f_t) (Z_{k_1} Z_{k_2} \cdot \dots \cdot Z_{k_n} f_t). \end{aligned}$$

We now use the inequality (??) on the second and fourth line of the above equations, with $\mathfrak{d} = \frac{t}{b_{1, k_2, \dots, k_n}}$ and $\mathfrak{d} = \frac{t}{b_{k_1, k_2, \dots, k_n}}$, respectively and obtain

$$\begin{aligned}
\Gamma_t^{(n)} f_t &\geq \sum_{k_2, \dots, k_n=0}^N \left[a_{0, k_2, \dots, k_n} t^{2(\sum_{j=2}^n k_j) + n} |Z_0 Z_{k_2} \cdots Z_{k_n} f_t|^2 \right. \\
&\quad \left. + t^{2(\sum_{j=2}^n k_j) + n + 1} \left(-\frac{b_{1, k_2, \dots, k_n}^2 |Z_0 Z_{k_2} \cdots Z_{k_n} f_t|^2}{t} - t |Z_1 Z_{k_2} \cdots Z_{k_n} f_t|^2 \right) \right] \\
&\quad + \sum_{k_2, \dots, k_n=0}^N \sum_{k_1=1}^N a_{k_1, \dots, k_n} t^{2|\mathbf{k}|_n + n} |Z_{k_1} \cdots Z_{k_n} f_t|^2 \\
&\quad + \sum_{k_2, \dots, k_n=0}^N \sum_{k_1=2}^N t^{2|\mathbf{k}|_n + n - 1} \left(-\frac{b_{k_1, \dots, k_n}^2 |Z_{k_1-1} Z_{k_2} \cdots Z_{k_n} f_t|^2}{t} - t |Z_{k_1} Z_{k_2} \cdots Z_{k_n} f_t|^2 \right) \\
&\geq \sum_{k_2, \dots, k_n=0}^N (a_{0, k_2, \dots, k_n} - b_{1, k_2, \dots, k_n}^2) t^{2(\sum_{j=2}^n k_j) + n} |Z_0 Z_{k_2} \cdots Z_{k_n} f_t|^2 \\
&\quad + \sum_{k_2, \dots, k_n=0}^N \sum_{k_1=1}^N (a_{k_1, \dots, k_n} - b_{k_1+1, k_2, \dots, k_n}^2 - 1) t^{2|\mathbf{k}|_n + n} |Z_{k_1} \cdots Z_{k_n} f_t|^2.
\end{aligned}$$

Because of (25), $a_{k_1, \dots, k_n} - C b_{k_1+1, k_2, \dots, k_n}^2 - C' > 0$, with some $C, C' \geq 1$ so one can choose $c_n > 0$ so that the desired bound (26) is satisfied. This ends the proof of the simplified case, i.e the proof of (7).

• **Proof of (6).** We now turn to the proof of (6), i.e. we remove our simplifying assumption. In this case the expression (16)-(21) remains unaltered, as well as the analysis of the terms [I] and [II], as we used our simplifying assumption only to estimate [III]. We therefore concentrate on the terms [III].

Note that if in Assumption **(CR.I)** $c_{0jh} = 0$ for all j but $c_j \neq 0$, then (12) no longer holds. More precisely, if $[Z_0, Z_j] = 0$ for all j then it is still true that $[\mathbf{Z}_{\mathbf{k}, n}, B] = [\mathbf{Z}_{\mathbf{k}, n}, L]$, but in this case (12) needs to be modified to take into account $[Z_N, B] \neq 0$. So, when we expand the expression for [III], we get the following additional terms:

$$\begin{aligned}
[\text{ATI}] &= - \sum_{i=0, \dots, N} c_i \left(2 \sum_{0 \leq |\mathbf{k}|_n}^{nN} \sum_{j=1, \dots, n} \delta_{k_j, N} a_{\mathbf{k}, n} t^{2|\mathbf{k}|_n + n} \mathbf{Z}_{\mathbf{k}, n} f_t \cdot \mathbf{Z}_{\mathbf{k} + (i-N)\mathbf{e}_j, n} \right. \\
&\quad \left. + \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} \sum_{j=1, \dots, n} \delta_{k_j, N} b_{\mathbf{k}, n} t^{2|\mathbf{k}|_n + n - 1} \left((\mathbf{Z}_{\mathbf{k} - \mathbf{e}_1 + (i-N)\mathbf{e}_j, n} f_t)(\mathbf{Z}_{\mathbf{k}, n} f_t) + (\mathbf{Z}_{\mathbf{k} - \mathbf{e}_1, n} f_t)(\mathbf{Z}_{\mathbf{k} + (i-N)\mathbf{e}_j, n} f_t) \right) \right)
\end{aligned}$$

Since by our assumption $c_N \geq 0$, we either get additional negative term (when $i = N$) with coefficient $c_N a_{\mathbf{k}, n} t^{2|\mathbf{k}|_n + n}$ which can be used to beat those coming from the second sum with mixed terms, or

we can apply quadratic Young inequality to get terms as before but with a higher power of t which for sufficiently small time do not change inequality obtained before in the simplified case. Now we discuss the general case, $c_j \neq 0$, $c_{0jh} = 0$ for $h \geq j-1$ and not all of them are equal to zero. In this case it is no longer true that $[\mathbf{Z}_{\mathbf{k},n}, L] = [\mathbf{Z}_{\mathbf{k},n}, B]$, which is why we need to use Lemma 2.3 to study [III]. Using such a lemma we find that, together with the terms in [ATI], we also have the following additional contributions to [III]:

$$\begin{aligned}
[\text{ATII}] &= 2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n} f_t [\mathbf{Z}_{\mathbf{k},n}, Z_0^2] f_t \\
&+ \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} (([\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n}, Z_0^2] f_t) \mathbf{Z}_{\mathbf{k},n} f_t + (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) [\mathbf{Z}_{\mathbf{k},n}, Z_0^2] f_t) \\
&= 2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n} f_t \left(\sum_{|\mathbf{k}'|_n < |\mathbf{k}|_n-1} \eta_{\mathbf{k},\mathbf{k}'} Z_0 Z_{\mathbf{k}',n} f_t \right) \\
&+ 2 \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n} f_t \left(\sum_{|\mathbf{k}'|_n < |\mathbf{k}|_n-1} \zeta_{\mathbf{k},\mathbf{k}'} Z_{\mathbf{k}',n} f_t \right) \\
&+ \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(\sum_{|\mathbf{k}'|_n < |\mathbf{k}-\mathbf{e}_1|_n-1} \eta_{\mathbf{k},\mathbf{k}'} Z_0 Z_{\mathbf{k}',n} f_t \cdot \mathbf{Z}_{\mathbf{k},n} f_t + \sum_{|\mathbf{k}'|_n < |\mathbf{k}-\mathbf{e}_1|_n-1} \zeta_{\mathbf{k},\mathbf{k}'} Z_{\mathbf{k}',n} f_t \cdot \mathbf{Z}_{\mathbf{k},n} f_t \right) \\
&+ \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} \left(\sum_{|\mathbf{k}'|_n < |\mathbf{k}|_n-1} \eta_{\mathbf{k},\mathbf{k}'} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) \cdot Z_0 Z_{\mathbf{k}',n} f_t + \sum_{|\mathbf{k}'|_n < |\mathbf{k}|_n-1} \zeta_{\mathbf{k},\mathbf{k}'} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n} f_t) \cdot Z_{\mathbf{k}',n} f_t \right).
\end{aligned}$$

Because of our restriction on $|\mathbf{k}'|$, all new terms come with a higher power of t and therefore for sufficiently small time they can be offset by the principal terms discussed in the first stage (when all c_j and c_{0kl} were assumed to be zero). The proof is concluded once we observe that in order to prove the lower bound (26), we did not use the simplified form of Assumption **(CR.I)** and hence such a bound still holds in this general case. \square

Proof of Lemma 2.3 . Observe that, with $\{X, Y\} \equiv XY + YX = 2XY - [X, Y]$, we have

$$\begin{aligned}
[Z_{k_j}, Z_0^2] &= \{Z_0, [Z_{k_j}, Z_0]\} = - \sum_{l_j=0}^N c_{0k_j l_j} \{Z_0, Z_{l_j}\} \\
&= -2 \sum_{l_j=0}^N c_{0k_j l_j} Z_0 Z_{l_j} + \sum_{l_j=0}^N \gamma_{k_j l_j} Z_{l_j},
\end{aligned}$$

with

$$\gamma_{k_j l_j} \equiv \sum_{l=0}^N c_{0k_j l} c_{0l l_j}.$$

Using the commutator relation (13) and the above, we get for $0 \leq k_1, \dots, k_n \leq N$

$$\begin{aligned} [Z_{\mathbf{k}, n}, Z_0^2] &= \sum_{j=1}^n Z_{k_1} \cdots Z_{k_{j-1}} [Z_{k_j}, Z_0^2] Z_{k_{j+1}} \cdots Z_{k_n} \\ &= -2 \sum_{j=1}^n \sum_{l_j=0}^N c_{0k_j l_j} Z_{k_1} \cdots Z_{k_{j-1}} Z_0 Z_{l_j} Z_{k_{j+1}} \cdots Z_{k_n} \\ &\quad + \sum_{j=1}^n \sum_{l=0}^N \gamma_{k_j l} Z_{k_1} \cdots Z_{k_{j-1}} Z_l Z_{k_{j+1}} \cdots Z_{k_n}. \end{aligned}$$

We repeat the commutation process involving the operator Z_0 until we bring it to the left. In this way we obtain

$$[Z_{\mathbf{k}, n}, Z_0^2] = \sum_{\mathbf{k}'} \boldsymbol{\eta}_{\mathbf{k}, \mathbf{k}'} Z_0 Z_{\mathbf{k}', n} + \sum_{\mathbf{k}'} \boldsymbol{\zeta}_{\mathbf{k}, \mathbf{k}'} Z_{\mathbf{k}', n}$$

with the following linear operators

$$\sum_{\mathbf{k}'} \boldsymbol{\eta}_{\mathbf{k}, \mathbf{k}'} Z_{\mathbf{k}', n} \equiv -2 \sum_{j=1}^n \sum_{l_j=0}^N c_{0k_j l_j} Z_{k_1} \cdots Z_{k_{j-1}} Z_{l_j} Z_{k_{j+1}} \cdots Z_{k_n}$$

and

$$\begin{aligned} \sum_{\mathbf{k}'} \boldsymbol{\zeta}_{\mathbf{k}, \mathbf{k}'} Z_{\mathbf{k}', n} &\equiv +2 \sum_{j=2}^n \sum_{i=2}^{j-1} \sum_{l_i, l_j=0}^N c_{0k_i l_i} c_{0k_j l_j} Z_{k_1} \cdots Z_{k_{i-1}} Z_{l_i} Z_{k_{i+1}} \cdots Z_{k_{j-1}} Z_{l_j} Z_{k_{j+1}} \cdots Z_{k_n} \\ &\quad + \sum_{j=2}^n \sum_{l_i, l_j=0}^N c_{0k_1 l_1} c_{0k_j l_j} Z_{l_1} Z_{k_2} \cdots Z_{k_{j-1}} Z_{l_j} Z_{k_{j+1}} \cdots Z_{k_n} \\ &\quad + \sum_{j=1}^n \sum_{l_j=0}^N \gamma_{k_j l_j} Z_{k_1} \cdots Z_{k_{j-1}} Z_{l_j} Z_{k_{j+1}} \cdots Z_{k_n}. \end{aligned}$$

Finally we note that because of our assumption on $c_{0,j,h}$, the summation over \mathbf{k}' is restricted by a condition $|\mathbf{k}'| < |\mathbf{k}| - 1$. \square

3 Infinite Dimensional Semigroups

From this section on we focus on infinite dimensional dynamics on $(\mathbb{R}^m)^{\mathbb{Z}^d}$. The present section is organized as follows: in Section 3.1 we present the setting and notation used in this infinite dimensional context. In view of the heavily computational nature of this part of the paper, Section 3.1 is complemented with Subsection 3.1.1, which explains the strategy used throughout this section in a simplified scenario. In Section 3.3 we prove the well posedness of the infinite dimensional dynamics generated by the operator (27) (Theorem 3.2) and in Section 3.4 the smoothing properties of the associated infinite dimensional semigroup (Theorem 3.3). Section 3.2 provides the preliminary estimates needed to prove the results of Section 3.3 and Section 3.4, in particular finite speed of propagation of information type of bounds.

3.1 Setting and notation

The set \mathbb{Z}^d , $d \in \mathbb{N}$ with a distance $dist(x, y) \equiv \sum_{l=1}^d |x_l - y_l|$, will be called a lattice. If a set $\Lambda \subset \mathbb{Z}^d$ is finite, we denote that by $\Lambda \subset\subset \mathbb{Z}^d$. Let $\Omega \equiv (\mathbb{R}^m)^{\mathbb{Z}^d}$. For a set $\Lambda \subset\subset \mathbb{Z}^d$ and $\omega \equiv (\omega_x \in \mathbb{R}^m)_{x \in \mathbb{Z}^d} \in \Omega$ we define its projection $\omega_\Lambda \equiv (\omega_x \in \mathbb{R}^m)_{x \in \Lambda}$ and set $\Omega_\Lambda \equiv (\mathbb{R}^m)^\Lambda$. A smooth function $f : \Omega \rightarrow \mathbb{R}$ is called a cylinder function iff there exists a set $\Lambda \subset\subset \mathbb{Z}^d$ and a smooth function $\phi_\Lambda : \Omega_\Lambda \rightarrow \mathbb{R}$ such that $f(\omega) = \phi_\Lambda(\omega_\Lambda)$. The smallest set for which such representation is possible for a given cylinder function f is denoted by $\Lambda(f)$. We will then say that f is localized in Λ . It is known (see e.g. [10]) that the set of cylinder functions is dense in the set of continuous functions on Ω .

If Z is a differential operator in \mathbb{R}^m , we denote by Z_x an isomorphic copy of the operator Z acting only on the variable ω_x , i.e. Z_x is a copy of Z acting on the copy of \mathbb{R}^m placed at $x \in \mathbb{Z}^d$. In particular we will consider families of first order operators $D_x, Y_{\alpha,x}$, $x \in \mathbb{Z}^d$ and $\alpha \in I$ for some finite index set I , which are isomorphic copies of operators at the origin $x_0 \equiv 0$. In other words, D and $\{Y_\alpha\}_{\alpha \in I}$ are first order operators on \mathbb{R}^m ; D_x and $\{Y_{\alpha,x}\}_{\alpha \in I}$ are, for every $x \in \mathbb{Z}^d$, copies of D and $\{Y_\alpha\}_{\alpha \in I}$, acting on the copy of \mathbb{R}^m placed at $x \in \mathbb{Z}^d$.

We will assume the following commutation relations

Assumption 2 (GCR). *For any $x, y \in \mathbb{Z}^d$ we have:*

- If $x \neq y$, then

$$[Y_{\alpha,x}, Y_{\beta,y}] = [Y_{\alpha,x}, D_y] = 0, \quad \text{for any } \alpha, \beta \in I;$$

- For every $\alpha \in I$, and $x \in \mathbb{Z}^d$

$$\begin{aligned} [Y_{\alpha,x}, D_x] &= \kappa_\alpha Y_{\alpha,x}, & \kappa_\alpha &\geq 0 \\ [Y_{\alpha,x}, Y_{\beta,x}] &= \sum_{\gamma \in I} c_{\alpha\beta\gamma} Y_{\gamma,x}, \end{aligned}$$

with some real constants $c_{\alpha\beta\gamma}$.

We will denote $c \equiv \sup_{\alpha, \beta, \gamma \in I} |c_{\alpha\beta\gamma}|$.

Remark 3.1. We remark that in general, if the constants $c_{\alpha\beta\gamma} \neq 0$, a compatibility condition (coming from Jacobi identity) may force all $\kappa_\alpha = 0$. The case when $\kappa_\alpha > 0$ for all α will be called *stratified case*.

Later it will be convenient to use the following notation for operators of order $n \in \mathbb{N}$:

$$\mathbf{Y}_{\boldsymbol{\iota}, \mathbf{x}}^{(n)} \equiv Y_{\iota_1, x_1} \cdots Y_{\iota_n, x_n}$$

where $\mathbf{x} \equiv (x_1, \dots, x_n)$, $x_i \in \mathbb{Z}^d$, i.e. $\mathbf{x} \subset \mathbb{Z}^d$ is a subset of \mathbb{Z}^d of cardinality n . Also, we denote

$$|\mathbf{Y}_{\mathbf{x}}^{(n)} f|^2 \equiv \sum_{\boldsymbol{\iota}} |\mathbf{Y}_{\boldsymbol{\iota}, \mathbf{x}}^{(n)} f|^2 \equiv \sum_{\iota_1, \dots, \iota_n \in I} |Y_{\iota_1, x_1} \cdots Y_{\iota_n, x_n} f|^2.$$

For some $J \subset I$ (arbitrary but fixed) we set

$$Y_{J, x}^2 \equiv \sum_{\alpha \in J} Y_{\alpha, x}^2$$

and

$$|Y_{J, x} f|^2 \equiv \sum_{\alpha \in J} |Y_{\alpha, x} f|^2.$$

For $x \in \mathbb{Z}^d$, if $\mathbf{q}_x \equiv \{q_{\iota, x}\}_{\iota \in I}$ is a collection of real valued functions (more details about these functions are given below), we set

$$\mathbf{q}_x \cdot Y_x \equiv \sum_{\iota \in I} q_{\iota, x} Y_{\iota, x}.$$

Analogously, for $\mathfrak{S}_{xy} \equiv \{\mathfrak{S}_{\alpha\beta, xy}\}_{\alpha, \beta \in J}$, we introduce

$$\mathfrak{S}_{xy} \cdot Y_x Y_y \equiv \sum_{\alpha, \beta \in J} \mathfrak{S}_{\alpha\beta, xy} \cdot Y_{\alpha, x} Y_{\beta, y}$$

and write

$$\mathfrak{S}_{xy} \cdot (Y_x f)(Y_y g) \equiv \sum_{\alpha, \beta \in J} \mathfrak{S}_{\alpha\beta, xy} \cdot (Y_{\alpha, x} f) \cdot (Y_{\beta, y} g).$$

For every $\gamma \subset \boldsymbol{\iota} \subset I$ and $\mathbf{z} \subset \mathbf{x} \subset \mathbb{Z}^d$ we will also use the notation $\check{\gamma} \equiv \boldsymbol{\iota} \setminus \gamma$ and $\check{\mathbf{z}} \equiv \mathbf{x} \setminus \mathbf{z}$.

Both \mathbf{q}_x and \mathfrak{S}_{xy} will be assumed to be smooth functions of ω which in particular can depend on ω_y , $y \neq x$, but all entries of these "matrices" are real valued cylinder functions, so they only depend on a finite number of coordinates in \mathbb{Z}^d . It is also assumed that $\mathfrak{S}_{xy} < 2\delta_{xy}$ in the sense of quadratic forms. To stress the cardinality of $\mathbf{x} = (x_1, \dots, x_n) \subset \mathbb{Z}^d$ as a subset of \mathbb{Z}^d , we write $|\mathbf{x}| = n$ (same thing for $\boldsymbol{\iota} = (\iota_1, \dots, \iota_\ell) \in I^\ell$, we write $|\boldsymbol{\iota}| = \ell$.) A number of additional technical conditions,

necessary for development of nontrivial infinite dimensional theory, will be provided later. For a finite set $\Lambda \subset \mathbb{Z}^d$ we consider the following Markov generator

$$\mathcal{L}_\Lambda = \sum_{x \in \mathbb{Z}^d} L_x + \sum_{y \in \Lambda} \mathbf{q}_y \cdot Y_y + \sum_{y, y' \in \Lambda} \mathfrak{S}_{yy'} \cdot Y_y Y_{y'} \quad (27)$$

where

$$L_x \equiv Y_{J,x}^2 + B_x - \lambda D_x$$

with some constant $\lambda \geq 0$ and

$$B_x \equiv \sum_{\alpha \in I} b_{\alpha,x} Y_{\alpha,x} \equiv \mathbf{b}_x \cdot Y_x,$$

with $\mathbf{b}_x \equiv \{b_{\alpha,x} \in \mathbb{R}\}_{\alpha \in I}$. We will refer to \mathbf{q}_x and $\mathfrak{S}_{x,y}$ as to *interaction functions*. When such functions satisfy the following two conditions

$$Y_{\alpha,y} \mathbf{q}_x \equiv 0 \quad \text{for } \text{dist}(y, x) \geq R \quad (28)$$

$$\mathfrak{S}_{\gamma\gamma', yy'} \equiv 0 \quad \text{for } \text{dist}(y, y') \geq R \quad (29)$$

for some $R > 0$, we talk about *finite range interaction*.

The semigroup generated by \mathcal{L}_Λ is well defined as an infinite product semigroup, denoted by $\mathcal{P}_t^\Lambda \equiv e^{t\mathcal{L}_\Lambda}$. Will also use the following notation $f_t^\Lambda \equiv \mathcal{P}_t^\Lambda f$. One way of intuitively understanding the dynamics generated by \mathcal{L}_Λ is the following: each of the operators L_x is an hypoelliptic diffusion of the type studied in Section 2 taking place in the copy of \mathbb{R}^m placed at $x \in \mathbb{Z}^d$. If the last two addends in the definition of \mathcal{L}_Λ (27) were identically zero, then the dynamics generated by \mathcal{L}_Λ would simply consist of infinitely many copies of the same hypoelliptic diffusion evolving independently of each other. The last two addends in (27) make such diffusions interact. However, because Λ contains only a finite number of points in \mathbb{Z}^d (and the interaction functions will always assumed to be of finite range), only finitely many of such diffusions interact “directly” under the action of \mathcal{L}_Λ . The main purpose of this section is to show that, in the limit $\Lambda \rightarrow \mathbb{Z}^d$, the semigroup generated on $(\mathbb{R}^m)^{\mathbb{Z}^d}$ by the operator

$$\mathcal{L} = \sum_{x \in \mathbb{Z}^d} L_x + \sum_{y \in \mathbb{Z}^d} \mathbf{q}_y \cdot Y_y + \sum_{y, y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \cdot Y_y Y_{y'} \quad (30)$$

is well posed. In order to achieve this result, some further technical assumptions on the interaction functions will be necessary, see statement of Theorem 3.2; some of these assumptions are purely technical. In order to explain the structure of the remainder of the section and clarify the approach used to construct the infinite dimensional semigroup, we make the following remark, which should hopefully serve as a navigational chart through the technical results of this section.

3.1.1 Structure of Section 3

In this remark we explain the strategy that we are going to use to construct the infinite dimensional semigroup, in its simplest version. In order to do so, we work in a simplified scenario. The details of the general strategy illustrated in this remark need technical modifications in our setting, but the bulk of the approach remains analogous.

- Only for the purpose of this subsection, consider the operator

$$\mathcal{L}_\Lambda = \sum_{x \in \mathbb{Z}^d} L_x + \sum_{y \in \Lambda} \mathbf{q}_y \cdot Y_y = \sum_{x \in \mathbb{Z}^d} L_x + \sum_{y \in \Lambda} \sum_{i \in I} q_{i,y} Y_{i,y}.$$

We want to show

$$\lim_{\Lambda \rightarrow \mathbb{Z}^d} \mathcal{P}_t^\Lambda f(x) = \mathcal{P}_t f(x),$$

for every cylinder function f . Consider two sets $\bar{\Lambda}, \bar{\Lambda}' \subset \mathbb{Z}^d$ such that $\Lambda(f) \subset \bar{\Lambda} \subset \bar{\Lambda}'$ and we then construct an increasing sequence of sets. Here for simplicity we take $\{\Lambda_m\}_{0 \leq m \leq \mathcal{N}}$, such that $\Lambda(f) \subset \Lambda_0 = \bar{\Lambda}$, $\Lambda_{\mathcal{N}} = \bar{\Lambda}'$ and $\Lambda_{m+1} \setminus \Lambda_m = \{h_m\}$, i.e. Λ_{m+1} is obtained from Λ_m by adding the singleton h_m . We denote by \mathcal{L}_{Λ_m} the Markov generator

$$\mathcal{L}_{\Lambda_m} := \sum_{x \in \mathbb{Z}^d} L_x + \sum_{y \in \Lambda_m} \sum_{i \in I} q_{i,y} Y_{i,y}$$

and $\mathcal{P}_t^{\Lambda_m}$ the corresponding semigroup. If we show that the sequence $\{\mathcal{P}_t^{\Lambda_m} f(x)\}$ is a Cauchy sequence then we are done. From the identity

$$\mathcal{P}_t^{\Lambda_{m+1}} f - \mathcal{P}_t^{\Lambda_m} f = \int_0^t ds \frac{d}{ds} \left(\mathcal{P}_{t-s}^{\Lambda_m} \mathcal{P}_s^{\Lambda_{m+1}} f \right) = \int_0^t ds \left[\mathcal{P}_{t-s}^{\Lambda_m} (\mathcal{L}_{\Lambda_{m+1}} - \mathcal{L}_{\Lambda_m}) \mathcal{P}_s^{\Lambda_{m+1}} f \right], \quad (31)$$

we have

$$\begin{aligned} \|\mathcal{P}_t^{\bar{\Lambda}} f - \mathcal{P}_t^{\bar{\Lambda}'} f\|_\infty &\leq \sum_{m=0}^{\mathcal{N}-1} \|\mathcal{P}_t^{\Lambda_{m+1}} f - \mathcal{P}_t^{\Lambda_m} f\|_\infty \\ &\leq \sum_{m=0}^{\mathcal{N}-1} \int_0^t ds \|\mathcal{P}_{t-s}^{\Lambda_m} (\mathcal{L}_{\Lambda_{m+1}} - \mathcal{L}_{\Lambda_m}) \mathcal{P}_s^{\Lambda_{m+1}} f\|_\infty \\ &\leq \sum_{m=0}^{\mathcal{N}-1} \int_0^t ds \sum_{i \in I} \|q_{i,h_m} Y_{i,h_m} f_s^{\Lambda_{m+1}}\|_\infty \end{aligned} \quad (32)$$

The above is a simplified version of the calculation in the proof of Theorem 3.2 - in that setting also second derivatives of $f_s^{\Lambda_{m+1}}$ would appear in the last step, and this is one of the reasons why one cannot choose this simple sequence of increasing sets. In any event, what is important to notice is that in (32) appears the derivative of $f_s^{\Lambda_{m+1}}$ at h_m . This brings us to the next point.

- Recall that in the above we fixed a cylinder function f , supported on $\Lambda(f)$. From the construction in the previous point, $h_m \notin \Lambda(f)$. Hence the need to find estimates on the derivatives of $Y_{i,x} \mathcal{P}_t^\Lambda$ at a point $x \in \mathbb{Z}^d$ which is out of $\Lambda(f)$. This is precisely the kind of estimates that we recover in Theorem 3.1. In order to study the well posedness of the infinite dimensional semigroup we would need, in our case, only second order derivatives. We find the estimates for derivatives of any order as they will be needed in the following.
- Finally, once the infinite dimensional semigroup is obtained we prove, for such a semigroup, smoothing results similar to those shown to hold in Section 2 for the finite dimensional case. Such results will be used to study the ergodicity of the dynamics.

3.2 Strong approximation property

We begin with the following preliminary result.

Proposition 3.1. *Suppose the commutator relations of Assumption (GCR) hold. Moreover, assume the interaction functions are such that*

$$\begin{aligned}
& i) \sup_{\alpha, z} \|q_{\alpha, z}\|_\infty < \infty \\
& ii) \mathfrak{S}_{\gamma\gamma', yy'} \equiv \delta_{y \neq y'} \mathfrak{S}_{\gamma\gamma', yy'}(\omega_y, \omega_{y'}) \\
& iii) \sup_{z \in \mathbb{Z}^d} \sum_{y \in \mathbb{Z}^d} \sum_{\gamma\gamma' \in J} (|\mathfrak{S}_{\gamma'\gamma, yz}| + |\mathfrak{S}_{\gamma\gamma', zy}|) < \infty \\
& iv) \sup_{(\iota, \mathbf{x}) : |\iota| = n} \sum_{y \in \mathbb{Z}^d} \sum_{\gamma, \gamma' \in J} \sum_{l=1}^{n-1} \sum_{\substack{(\beta, \mathbf{z}) \subset (\iota, \mathbf{x}) \\ |\beta| = l}} \sum_{y' \in \tilde{\mathbf{z}}} \left| \mathbf{Y}_{\tilde{\beta}, \tilde{\mathbf{z}}}^{(n-l)} \mathfrak{S}_{\gamma\gamma', yy'} \right| < \infty \\
& v) \sum_{y \in \mathbb{Z}^d} \sum_{\beta \in I} \sum_{k=1}^{n-1} \sup_{(\iota, \mathbf{x})} \sum_{(\gamma, \mathbf{z}) \subset (\iota, \mathbf{x}) : |\gamma| = k} \|\mathbf{Y}_{\tilde{\gamma}, \tilde{\mathbf{z}}}^{(n-k)} q_{\beta, y}\|_\infty < \infty.
\end{aligned}$$

Then for any $\Lambda \subset \mathbb{Z}^d$, for any cylinder function f with $\Lambda(f) \subset \Lambda$ and for any $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{Z}^d$ we have

$$\begin{aligned}
\frac{\partial}{\partial s} \mathcal{P}_{t-s}^\Lambda |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 & \leq \mathcal{P}_{t-s}^\Lambda \left\{ \mathbf{v}_n |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}| = l}} \mathcal{B}_{\mathbf{x}, n}^{(l)}(\mathbf{z}) |\mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda|^2 \right. \\
& \quad \left. + \varepsilon \sum_{l=1}^{n-1} \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x} : |\mathbf{z}| = l} \mathcal{A}_{\mathbf{x}, n}^{(l)}(\mathbf{z}, y) |Y_{J, y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda|^2 + \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}| = l}} \mathcal{B}_{\mathbf{x}, n}^{(l)}(\mathbf{z}, y) |\mathbf{Y}_{(\mathbf{z}, y)}^{(l+1)} f_s^\Lambda|^2 \right\}
\end{aligned} \tag{33}$$

for some constants $\varepsilon \in (0, 1)$, $\mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}), \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y), B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) > 0$ and \mathbf{v}_n , independent of f and t .

Remark 3.2. We clarify that in the last addend of (33), the following notation has been used:

$$\left| \mathbf{Y}_{\mathbf{z},y}^{(l+1)} f \right|^2 := \sum_{\iota_1, \dots, \iota_{l+1}} |Y_{\iota_1, z_1} Y_{\iota_2, z_2}, \dots, Y_{\iota_l, z_l}, Y_{\iota_{l+1}, y} f|^2.$$

We refrain from writing here a full expression of the constants $\mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}), \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y), B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) > 0$ (however such expressions can be found in the proof of Proposition 3.1). What is important for our purposes is that, in case of finite range interaction (see (28)-(29)), such coefficients vanish unless $\text{diam}(\mathbf{x} \setminus \mathbf{z}) \leq R$.

Proof of Proposition 3.1. The proof of this proposition is deferred to Appendix A. \square

Integrating the differential inequality (33) gives

$$\begin{aligned} \left| \mathbf{Y}_{\mathbf{x}}^n f_t^\Lambda \right|^2 &\leq e^{\mathbf{v}_n t} \mathcal{P}_t^\Lambda \left| \mathbf{Y}_{\mathbf{x}}^n f \right|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \int_0^t ds e^{\mathbf{v}_n(t-s)} \mathcal{P}_{t-s}^\Lambda \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\ &+ \varepsilon \sum_{l=1}^{n-1} \sum_{y \in \Lambda} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \int_0^t ds e^{\mathbf{v}_n(t-s)} \mathcal{P}_{t-s}^\Lambda \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\ &+ \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l}} B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \int_0^t ds e^{\mathbf{v}_n(t-s)} \mathcal{P}_{t-s}^\Lambda \left| \mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda \right|^2. \end{aligned}$$

Taking the supremum norm, the above bound can be simplified as follows

$$\begin{aligned} \left\| \mathbf{Y}_{\mathbf{x}}^n f_t^\Lambda \right\|_\infty^2 &\leq e^{\mathbf{v}_n t} \left\| \mathbf{Y}_{\mathbf{x}}^n f \right\|_\infty^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \int_0^t ds e^{\mathbf{v}_n(t-s)} \left\| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right\|_\infty^2 \\ &+ \varepsilon \sum_{l=1}^{n-1} \sum_{y \in \Lambda} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \int_0^t ds e^{\mathbf{v}_n(t-s)} \left\| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right\|_\infty^2 \\ &+ \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l}} B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \int_0^t ds e^{\mathbf{v}_n(t-s)} \left\| \mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda \right\|_\infty^2, \end{aligned} \tag{34}$$

where we have used the contractivity property of the Markov semigroup with respect to supremum norm. The norm in the first term on the right hand side does not depend on time and is zero if $\mathbf{x} \cap \Lambda(f) = \emptyset$; the second sum involves lower order terms and integration with respect to time (and it

may be empty if $n = 1$); the third sum involves integration with respect to time and differentiations at sites which are not in \mathbf{x} and are performed in mild directions (from principal part of the generator with indices from J), but the order can be up to n ; the last is of similar nature as the third, except that all directions are involved.

In case when the interaction is of finite range, one can simplify expression (34) considerably by using Remark 3.2. Indeed in this case we can replace them by their supremum C_0 and restrict the summation over y by a condition $\text{dist}(y, \mathbf{x}) \leq R$. For the rest of the paper we set

$$\|\cdot\| := \|\cdot\|_\infty.$$

Then we get the following result.

Lemma 3.1. *Under the assumptions of Proposition 3.1, for all $\mathbf{x} = (x_1, \dots, x_n) \subset \mathbb{Z}^d$, if (28) and (29) hold, then*

$$\begin{aligned} \|\mathbf{Y}_{\mathbf{x}}^n f_t^\Lambda\|^2 &\leq e^{\mathbf{v}_n t} \|\mathbf{Y}_{\mathbf{x}}^n f\|^2 + C_0 \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l, \text{diam}(\mathbf{x} \setminus \mathbf{z}) \leq R}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|\mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda\|^2 \\ &+ C_0 \sum_{l=1}^{n-1} \sum_{\substack{y \in \Lambda \\ \text{dist}(y, \mathbf{x}) \leq R}} \sum_{\substack{\mathbf{z} \subset \mathbf{x}: \\ |\mathbf{z}|=l, \text{diam}(\mathbf{x} \setminus \mathbf{z}) \leq R}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda\|^2 \\ &+ C_0 \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l, \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|\mathbf{Y}_{(\mathbf{z}, y)}^{(l+1)} f_s^\Lambda\|^2. \end{aligned}$$

The special cases $n = 1, 2$ will be immediately relevant for the construction of the limit of the semigroups P_t^Λ as $\Lambda \rightarrow \mathbb{Z}^d$, so we state such cases explicitly in the next Lemma 3.2.

Lemma 3.2. *Under the assumptions of Lemma 3.1, for $n = 1$, we have*

$$\|Y_x f_t^\Lambda\|^2 \leq e^{\mathbf{v}_1 t} \|Y_x f\|^2 + C_0 \sum_{\substack{y \in \Lambda \\ \text{dist}(y, x) \leq R}} \int_0^t ds e^{\mathbf{v}_1(t-s)} \|Y_y f_s^\Lambda\|^2 \quad (35)$$

For $n = 2$, with some $C_1 \in (0, \infty)$ dependent only on C_0 and $c_{\alpha, \beta, \gamma}$, we have

$$\begin{aligned} \|\mathbf{Y}_{\mathbf{x}}^{(2)} f_t^\Lambda\|^2 &\leq e^{\mathbf{v}_2 t} \|\mathbf{Y}_{\mathbf{x}}^{(2)} f\|^2 + C_0 \sum_{z \in \mathbf{x}} \int_0^t ds e^{\mathbf{v}_2(t-s)} \|Y_z f_s^\Lambda\|^2 \\ &+ C_1 \sum_{\substack{y \in \Lambda \\ \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_2(t-s)} \|Y_y f_s^\Lambda\|^2 \\ &+ 2C_0 \sum_{\substack{z \in \mathbf{x}, y \in \Lambda \\ \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_2(t-s)} \|\mathbf{Y}_{(y, z)}^{(2)} f_s^\Lambda\|^2. \end{aligned}$$

The constants \mathbf{v}_1 and \mathbf{v}_2 in the above are as in the statement of Proposition 3.1.

Using the above lemmata, we prove the following result.

Theorem 3.1 (Finite speed of propagation of information). *Suppose the assumptions of Lemma 3.1 hold. Then for any smooth cylinder function f with $\Lambda(f) \subset \Lambda$ and for any $n \in \mathbb{N}$, there exist constants $B, c, v \in (0, \infty)$, independent of f but possibly dependent on n , such that for all $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{Z}^d$,*

$$\|\mathbf{Y}_{\mathbf{x}}^{(n)} f_t^\Lambda\|^2 \leq B e^{ct - v \cdot d(\mathbf{x}, \Lambda(f))} \sum_{l=1, \dots, n} \|\mathbf{Y}^{(l)} f\|^2 \quad (36)$$

where

$$\|\mathbf{Y}^{(l)} f\|^2 \equiv \sum_{\mathbf{z}: |\mathbf{z}|=l} \|\mathbf{Y}_{\mathbf{z}}^{(l)} f\|^2$$

and $d(\mathbf{x}, \Lambda(f))$ denotes the length of the shortest tree connecting each component of \mathbf{x} and $\Lambda(f)$.

Proof of Theorem 3.1. The case $n = 1$ is well known, see e.g. [9, 10] and references there in. The estimate is essentially based on inductive use of the Gronwall type inequality (35) using the fact that the first term on its right hand side is zero unless $x \in \Lambda(f)$, so if you start from $d(x, \Lambda(f)) \geq NR$ to get a nonzero term you need to make at least N steps producing multiple integral of that order which is responsible for a factor of the form $e^{Ct}(N!)^{-1}$ with $C \leq \mathbf{v}_1 + C_0(2R)^d$ (for more details see [9, 10]).

For $n = 2$, using (36) with $n = 1$, we get

$$\begin{aligned} \|\mathbf{Y}_{\mathbf{x}}^{(2)} f_t^\Lambda\|^2 &\leq e^{\mathbf{v}_2 t} \|\mathbf{Y}_{\mathbf{x}}^{(2)} f\|^2 + B_1 e^{\bar{c}_1 t - \bar{v}_1 d(z, \Lambda(f))} \sum_{y \in \mathbf{x}} \|Y_y f\|^2 \\ &\quad + 2C_0 \sum_{\substack{z \in \mathbf{x}, y \in \Lambda \\ \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_2(t-s)} \|\mathbf{Y}_{(y,z)}^{(2)} f_s^\Lambda\|^2, \end{aligned}$$

for some constants $\bar{c}_1, \bar{v}_1 \in (0, \infty)$. We will use this relation inductively taking into the account that as long as $\mathbf{z} \not\subset \Lambda(f)$, we have $\|\mathbf{Y}_{\mathbf{z}}^{(2)} f\|^2 = 0$. Thus the first term on the right hand side will not give nonzero contribution until we apply our procedure at least $N \equiv d(\mathbf{x}, \Lambda(f))/(2R)$ times, but to reach that we will produce multiple integral of order N giving a factor $(N!)^{-1}$. This implies the following bound

$$\|\mathbf{Y}_{\mathbf{x}}^{(2)} f_t^\Lambda\|^2 \leq B_2 e^{c_2 t - v_2 d(\mathbf{x}, \Lambda(f))} \left(\sum_{\mathbf{z}} \|\mathbf{Y}_{\mathbf{z}}^{(2)} f\|^2 + \sum_y \|Y_y f\|^2 \right).$$

The general case is proven by induction with respect to n . We suppose that

$$\text{for all } 1 \leq k \leq n-1 \text{ and } \mathbf{z}: |\mathbf{z}| = k, \quad \|\mathbf{Y}_{\mathbf{z}}^{(k)} f_t^\Lambda\|^2 \leq B_k \sum_{\mathbf{z} \in \mathbf{z}} e^{c_k t - v_k d(z, \Lambda(f))} \sum_{l=1, \dots, n} \|\mathbf{Y}^{(l)} f\|^2.$$

Then, using Lemma 3.1, we get

$$\begin{aligned}
\|\mathbf{Y}_{\mathbf{x}}^{(n)} f_t^\Lambda\|^2 &\leq e^{\mathbf{v}_n t} \|\mathbf{Y}_{\mathbf{x}}^{(n)} f\|^2 + C_0 \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|\mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda\|^2 \\
&+ C_0 \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l, \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda\|^2 \\
&+ C_0 \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l, \text{dist}(y, \mathbf{x}) \leq R}} \int_0^t ds e^{\mathbf{v}_n(t-s)} \|\mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda\|^2.
\end{aligned}$$

□

3.3 Existence of the infinite dimensional semigroup

In this section we prove, through an approximation procedure, that the infinite dimensional semigroup is well posed. We work under the assumption that the interaction functions are bounded, together with their derivatives of any order. Furthermore, we assume that the interaction is short range and we denote by $R > 0$ the range of interaction. This is the meaning of the assumptions in the following theorem.

Theorem 3.2. *Suppose Assumption (GCR) is satisfied and, for every $x \in \mathbb{Z}^d$, the fields $\{Y_{J,x}, B_x\}$ form a Hörmander system. Suppose that the following conditions are satisfied*

$$\begin{aligned}
\sup_{\alpha, z} \|q_{\alpha, z}\|_\infty &< \infty, \quad \sup_{\gamma, \mathbf{z}, \beta, y, k} \|\mathbf{Y}_{\gamma, \mathbf{z}}^{(k)} q_{\beta, y}\|_\infty < \infty \\
\mathfrak{S}_{\gamma\gamma', yy'} &\equiv \delta_{y \neq y'} \mathfrak{S}_{\gamma\gamma', yy'}(\omega_y, \omega_{y'}), \quad \sup_{\alpha, \mathbf{z}, \gamma, \gamma', y, y', k} \|\mathbf{Y}_{\alpha, \mathbf{z}}^{(k)} \mathfrak{S}_{\gamma\gamma', yy'}\|_\infty < \infty
\end{aligned}$$

and (28)-(29) hold. Then, for any continuous compactly supported cylinder function f , the following limit exists

$$\mathcal{P}_t f \equiv \lim_{\Lambda \rightarrow \mathbb{Z}^d} \mathcal{P}_t^{(\Lambda)} f$$

and its extension defines a strongly continuous Markov semigroup on $\mathcal{C}(\Omega)$. Moreover, $\mathcal{P}_t(C(\Omega)) \subset C^\infty(\Omega)$.

In addition, for any continuous compactly supported function f and all $\mathbf{x} \in \mathbb{Z}^d$ with $|\mathbf{x}| = n$, we have

$$\mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t f = \lim_{\Lambda \rightarrow \mathbb{Z}^d} \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda)} f.$$

Proof. We consider a lexicographic order $(\{x_k \in \mathbb{Z}^d, \preceq\}_{k \in \mathbb{N}})$ on the lattice so that

$$x_k \preceq x_{k+1} \iff d(x_k, 0) \leq d(x_{k+1}, 0)$$

with $d(x, y) \equiv \max_{l=1, \dots, d} |x_l - y_l|$, and such that $\Lambda_j \equiv \{x_i : i \leq j\}$ is a connected set. For a smooth cylinder function f with bounded derivatives and $\Lambda(f) \subset \Lambda_j$, we have

$$\left| \mathcal{P}_t^{(\Lambda_{j+1})} f - \mathcal{P}_t^{(\Lambda_j)} f \right| = \left| \int_0^t ds (\mathcal{P}_{t-s}^{(\Lambda_j)} (\mathcal{L}_{\Lambda_{j+1}} - \mathcal{L}_{\Lambda_j}) \mathcal{P}_s^{(\Lambda_{j+1})} f) \right|$$

Using the definition of the generators and our finite speed of propagation of information estimate (Theorem 3.1), we get

$$\begin{aligned} \left| \mathcal{P}_t^{(\Lambda_{j+1})} f - \mathcal{P}_t^{(\Lambda_j)} f \right| &\leq \int_0^t ds \left(\|q_{x_j}\| \cdot \|\mathbf{Y}_{x_j}^{(1)} \mathcal{P}_s^{(\Lambda_{j+1})} f\| \right. \\ &\quad \left. + \int_0^t ds \left(\sum_{y \in \Lambda_{j+1}} (\|\mathfrak{S}_{yx_j}\| \cdot \|\mathbf{Y}_{yx_j}^{(2)} \mathcal{P}_s^{(\Lambda_{j+1})} f\| + \|\mathfrak{S}_{x_j y}\| \cdot \|\mathbf{Y}_{x_j y}^{(2)} \mathcal{P}_s^{(\Lambda_{j+1})} f\|) \right) \right) \\ &\leq t e^{Ct - v \cdot d(x_j, \Lambda(f))} \sup_x \|\mathbf{q}_x\| \cdot \|\mathbf{Y}^{(1)} f\| \\ &\quad + 2t e^{Ct - v \cdot d(x_j, \Lambda(f))} e^{2vR} |2R|^d \sup_{xy} \|\mathfrak{S}_{xy}\| \cdot \|\mathbf{Y}^{(2)} f\|, \end{aligned}$$

with $\|\mathbf{q}_x\| \equiv \sum_{\alpha} \|\mathbf{q}_{\alpha, z}\|_{\infty}$ and $\|\mathfrak{S}_{xy}\| \equiv \sum_{\gamma\gamma'} \|\mathfrak{S}_{\gamma\gamma', xy}\|_{\infty}$. Hence for any Λ_k and Λ_m , $k \leq m$, we have

$$\|\mathcal{P}_t^{(\Lambda_m)} f - \mathcal{P}_t^{(\Lambda_k)} f\| \leq \sum_{k \leq j \leq m} |\mathcal{P}_t^{(\Lambda_{j+1})} f - \mathcal{P}_t^{(\Lambda_j)} f| \leq A_t e^{-\frac{v}{2} d(x_k, \Lambda(f))} (\|\mathbf{Y}^{(2)} f\| + \|\mathbf{Y}^{(1)} f\|),$$

with a constant

$$A_t \equiv 2t e^{Ct} B \max \left(\sup_x \|\mathbf{q}_x\|, e^{2vR} |2R|^d \sup_{xy} \|\mathfrak{S}_{xy}\| \right),$$

where $B \equiv \sum_j e^{-\frac{v}{2} d(x_j, \Lambda(f))}$. Hence, for any $t > 0$, the sequence $\mathcal{P}_t^{(\Lambda_j)} f$, $j \in \mathbb{N}$, is Cauchy in the space of continuous functions equipped with the uniform norm and there exists a (positivity and unit preserving), densely defined linear operator \mathcal{P}_t such that

$$\|\mathcal{P}_t f - \mathcal{P}_t^{(\Lambda_k)} f\| \leq A_t e^{-\frac{v}{2} d(\Lambda_k^c, \Lambda(f))} (\|\mathbf{Y}^{(2)} f\| + \|\mathbf{Y}^{(1)} f\|).$$

By the density of smooth cylinder functions and contractivity of \mathcal{P}_t , it can be extended to all $C(\Omega)$. Using the last estimate one can also show the semigroup property for \mathcal{P}_t . The fact that $\mathcal{P}_t(C(\Omega)) \subseteq C^\infty(\Omega)$ follows by Hörmander's theorem.

Next we consider sequences of derivatives. For $\mathbf{x} \in \Lambda_j$ and $n = |\mathbf{x}|$, arguing as above and using the definition of the generators, for a smooth cylinder function f with bounded derivatives and $\Lambda(f) \subset \Lambda_j$, we have

$$\left| \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda_j)} f - \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda_{j-1})} f \right| = \left| \int_0^t ds \left(\mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_{t-s}^{(\Lambda_j)} \left(\mathbf{q}_{x_j} \cdot \mathbf{Y}_{x_j}^{(1)} + \sum_{y \in \Lambda_{j+1}} (\mathfrak{S}_{yx_j} \cdot \mathbf{Y}_{yx_j}^{(2)} + \mathfrak{S}_{x_j y} \cdot \mathbf{Y}_{x_j y}^{(2)}) \right) \mathcal{P}_s^{(\Lambda_j)} f \right) \right|.$$

Applying Theorem 3.1 to $\mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_{t-s}^{(\Lambda_j)} F$ with

$$F \equiv \left(\mathbf{q}_{x_j} \cdot \mathbf{Y}_{x_j}^{(1)} + \sum_{y \in \Lambda_{j+1}} (\mathfrak{S}_{yx_j} \cdot \mathbf{Y}_{yx_j}^{(2)} + \mathfrak{S}_{x_j y} \cdot \mathbf{Y}_{x_j y}^{(2)}) \right) \mathcal{P}_s^{(\Lambda_j)} f,$$

we get the following estimate

$$\left\| \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_{t-s}^{(\Lambda_{j-1})} F \right\|^2 \leq B e^{C(t-s)} \sum_{l=1}^n \sum_{\mathbf{z} \in \tilde{\Lambda}_j: |\mathbf{z}|=l} \left\| \mathbf{Y}_{\mathbf{z}}^{(l)} F \right\|^2,$$

with $\tilde{\Lambda}_j \equiv \{x \in \mathbb{Z}^d : d(x, \Lambda_j) \leq R\}$. We note that for the cylinder function f , the function F is also a smooth cylinder function with $\Lambda(F) \equiv \tilde{\Lambda}_j$. Thus the sum over $\mathbf{z} \in \tilde{\Lambda}_j$ such that $|\mathbf{z}| = l$ contains less than $\frac{1}{l!}(|\Lambda_j| + 2R)^l$ terms. Each of the terms can be bounded as follows

$$\begin{aligned} \left| \mathbf{Y}_{\mathbf{z}}^{(l)} F \right|^2 &\leq D_1 \sum_{k=1}^l \sum_{|\mathbf{z}'|=k} \left\| \mathbf{Y}_{\mathbf{z}'x_j}^{(k+1)} \mathcal{P}_s^{(\Lambda_j)} f \right\|^2 \\ &\quad + D_2 \sum_{d(y, x_j) \leq R} \sum_{k=1}^l \sum_{|\mathbf{z}'|=k} \left(\left\| \mathbf{Y}_{\mathbf{z}'yx_j}^{(k+2)} \mathcal{P}_s^{(\Lambda_j)} f \right\|^2 + \left\| \mathbf{Y}_{\mathbf{z}'x_j y}^{(k+2)} \mathcal{P}_s^{(\Lambda_j)} f \right\|^2 \right), \end{aligned}$$

with

$$\begin{aligned} D_1 &\equiv \max_{l=1, \dots, n} \sup_{\{x_j \in \mathbb{Z}^d, |\mathbf{z}|=l\}} \sum_{k=1}^l \sum_{|\mathbf{z}'|=k} \left\| \mathbf{Y}_{\mathbf{z} \setminus \mathbf{z}'}^{(l-k)} \mathbf{q}_{x_j} \right\|^2, \\ D_2 &\equiv \max_{l=1, \dots, n} \sup_{\{x_j \in \mathbb{Z}^d, |\mathbf{z}|=l\}} \sum_{d(y, x_j) \leq R} \sum_{k=1}^l \sum_{|\mathbf{z}'|=k} \left(\max \left\| \mathbf{Y}_{\mathbf{z} \setminus \mathbf{z}'}^{(l-k)} \mathfrak{S}_{yx_j} \right\|^2, \left\| \mathbf{Y}_{\mathbf{z} \setminus \mathbf{z}'}^{(l-k)} \mathfrak{S}_{x_j y} \right\|^2 \right). \end{aligned}$$

Since each tree connecting points in $\mathbf{z}'x_j$, $\mathbf{z}'yx_j$ and $\mathbf{z}'x_jy$ with $\Lambda(f)$ is of length at least $d(x_j, \Lambda(f))$, applying Theorem 3.1 we obtain

$$\left\| \mathbf{Y}_{\mathbf{z}}^{(l)} F \right\|^2 \leq D e^{(Cs - vd(x_j, \Lambda(f)))} \sum_{k=1, \dots, l+2} \sum_{|\mathbf{z}'|=k} \left\| \mathbf{Y}_{\mathbf{z}'}^{(k)} f \right\|^2,$$

with some constant $D \in (0, \infty)$ independent of s , x_j and the function f . Combining our estimates we arrive at

$$\left| \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda_j)} f - \mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda_{j-1})} f \right| \leq D' e^{\frac{1}{2}(Ct - vd(x_j, \Lambda(f)))} \left(\sum_{k=1, \dots, n+2} \sum_{|\mathbf{z}'|=k} \left\| \mathbf{Y}_{\mathbf{z}'}^{(k)} f \right\|^2 \right)^{\frac{1}{2}},$$

with some constant $D' \in (0, \infty)$ independent of t , x_j and the function f . Using a similar telescopic expansion as in the proof of existence of the limit for the semigroup, this implies that the sequence $\mathbf{Y}_{\mathbf{x}}^{(n)} \mathcal{P}_t^{(\Lambda_j)} f$, $j \in \mathbb{N}$, is Cauchy in the supremum norm for every $n \in \mathbb{N}$ and \mathbf{x} , $|\mathbf{x}| = n$. This ends the proof of the theorem. \square

3.4 Smoothing properties of infinite dimensional semigroups

In this section we extend Theorem 2.1 to infinite dimensions, proving smoothing estimates in the setup when the fields at each site of \mathbb{Z}^d satisfy the commutation relations of Assumption **(CR.I)**. Now our generator has the form

$$\mathcal{L} \equiv \mathbf{L} + \mathbf{L}_{\text{int}}$$

with

$$\mathbf{L} \equiv \sum_{x \in \mathbb{Z}^d} L_x$$

where

$$L_x \equiv Z_{J,x}^2 + B_x - \lambda D_x$$

and

$$\mathbf{L}_{\text{int}} \equiv \sum_{x \in \mathbb{Z}^d} \mathbf{q}_x \cdot Z_x + \sum_{y, y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \cdot Z_{J,y} Z_{J,y'},$$

recalling that $J \subset I$. For notational simplicity we only describe one component type system, with $\mathfrak{S}_{klyy'} \equiv \mathfrak{S}_{00yy'} \equiv \mathfrak{S}_{yy'}$ and $Z_{J,y} \equiv Z_{0,y}$, but provide sufficient detail to make clear how to recover the more general case with many components. For $n \in \mathbb{N}$, we introduce the form $\mathbf{\Gamma}_t^{(n)}$ as follows. For $n = 1$, we consider the following quadratic form

$$\mathbf{\Gamma}_t^{(1)}(f_t) \equiv \sum_{x \in \mathbb{Z}^d} \mathbf{\Gamma}_{t,x}^{(1)}(f_t),$$

with $\Gamma_{t,x}^{(1)}(f)$ being an isomorphic copy of the form (3) defined in Section 2

$$\Gamma_{t,x}^{(1)}(f_t) \equiv \sum_{i=0,\dots,N} (a_i t^{2i+1} |Z_{i,x} f_t|^2 + b_i t^{2i} Z_{i-1,x} f_t \cdot Z_{i,x} f_t),$$

with the convention that $Z_{-1} \equiv Z_0$ (so de facto there is no spurious term in the second sum on the right hand side). We moreover set

$$\mathbf{Q}_t^{(1)}(f) \equiv \Gamma_t^{(1)}(f) + df^2.$$

For $n > 1$, we define

$$\Gamma_t^{(n)}(f_t) \equiv \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \Gamma_{t,\mathbf{x}}^{(n)} f_t$$

with $\Gamma_{t,\mathbf{x}}^{(n)}(g) \equiv \Gamma_{t,\mathbf{x}}^{(n)}(g, g)$, where

$$\Gamma_{t,\mathbf{x}}^n(g, h) \equiv \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} g \cdot \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} h + \sum_{0 \leq |\mathbf{k}|_n : k_1 \geq 1}^{nN} b_{\mathbf{k},n} t^{2|\mathbf{k}|_n+n-1} (\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n,\mathbf{x}} g) (\mathbf{Z}_{\mathbf{k},n,\mathbf{x}} h);$$

here and later $\mathbf{Z}_{\mathbf{k},n,\mathbf{x}} \equiv Z_{k_1,x_1} \dots Z_{k_n,x_n}$, for $\mathbf{x} \equiv (x_1, \dots, x_n) \in \mathbb{Z}^{nd}$, and $\mathbf{k} \equiv (k_1, \dots, k_n) \in \{1, \dots, N\} \times \{0, \dots, N\}^{n-1}$. We also define

$$\mathbf{Q}_t^{(n)}(g) \equiv \Gamma_t^{(n)}(g) + \varsigma_n \mathbf{Q}_t^{(n-1)}(g),$$

with some $\varsigma_n > 0$ to be chosen later. The main result of this section is the following.

Theorem 3.3 (Infinite Dimensional Smoothing Estimates). *Suppose that for every $x, y \in \mathbb{Z}^d$*

$$Z_{i,x} q_{jy} = 0 \quad \text{if } j > i, \quad (37)$$

$$\sum_{j=1,\dots,N} c_{ijk} q_{jx} = 0 \quad \text{if } k > i, \quad (38)$$

$$c_{i0k} = 0 \quad \text{if } k > i, \quad (39)$$

$$\sum_{k=1,\dots,N} c_{i0k} c_{k0l} = 0 \quad \text{if } l > i, \quad (40)$$

and recall that the commutator relations of Assumption **(CR.I)** are assumed to hold at each site. Then, there exist coefficients $a_i, b_i, d, \varepsilon \in (0, \infty)$ and $t_0 \in (0, 1)$, such that if

$$\sup_{k_j, z_j, i, y} \|Z_{k_j, z_j} q_{iy}\| < \varepsilon,$$

then for any $t \in (0, t_0)$ one has

$$\sum_{l=1,\dots,n} \Gamma_t^{(l)}(f_t) \leq d(\mathcal{P}_t(f^2) - (\mathcal{P}_t f)^2).$$

Observe that, if Assumption **(CR.I)** holds, (39) is redundant as $c_{i0k} = -c_{0ik} = 0$ for $k > i - 1$. Also, the assumptions in the statement of this theorem are all purely technical and are there in order to enable us to extend the technique introduced in Section 2 for the finite dimensional setting to the present infinite dimensional environment.

Proof. We begin with an estimate for the case $n = 1$. For $f_t \equiv \mathcal{P}_t f \equiv e^{t\mathcal{L}} f$, we have

$$\begin{aligned}
\partial_s \mathcal{P}_{t-s} \mathbf{Q}_s^{(1)}(f_s) &= \mathcal{P}_{t-s}(\partial_s - \mathcal{L}) \mathbf{Q}_s^{(1)}(f_s) \\
&- 2 \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} (a_i s^{2i+1} \mathcal{E}_{\mathcal{L}}(Z_{i,x} f_s) + b_{i+1} s^{2i} \mathcal{E}_{\mathcal{L}}(Z_{i-1,x} f_s, Z_{i,x} f_s)) - 2d \mathcal{E}_{\mathcal{L}}(f_s) \\
&+ \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} (2a_i s^{2i+1} (Z_{i,x} f_s \cdot [Z_{i,x}, \mathcal{L}] f_s) + b_i s^{2i} ([Z_{i-1,x}, \mathcal{L}] f_s \cdot Z_{i,x} f_s + Z_{i-1,x} f_s \cdot [Z_{i,x}, \mathcal{L}] f_s)) \\
&+ \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} ((2i+1) a_i s^{2i} |Z_{i,x} f_s|^2 + 2i b_i s^{2i-1} Z_{i-1,x} f_s \cdot Z_{i,x} f_s) \\
&\equiv (\mathbf{I}),
\end{aligned}$$

where $\mathcal{E}_{\mathcal{L}}(V, W) \equiv \frac{1}{2}(\mathcal{L}(VW) - V\mathcal{L}W - (\mathcal{L}V)W)$ and $\mathcal{E}_{\mathcal{L}}(V) \equiv \mathcal{E}_{\mathcal{L}}(V, V)$ and $Z_{-1} \equiv 0$. The right-hand side can be written as

$$(\mathbf{I}) = (\mathbf{II}) + (\mathbf{III}),$$

with

$$\begin{aligned}
(\mathbf{II}) &= -2 \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} (a_i s^{2i+1} \mathcal{E}_{L_x}(Z_{i,x} f_s) + b_i s^{2i} \mathcal{E}_{L_x}(Z_{i-1,x} f_s, Z_{i,x} f_s)) - 2d \mathcal{E}_{L_x}(f_s) \\
&+ \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} (2a_i s^{2i+1} (Z_{i,x} f_s \cdot [Z_{i,x}, L_x] f_s) + 2b_i s^{2i} ([Z_{i-1,x}, L_x] f_s \cdot Z_{i,x} f_s + Z_{i-1,x} f_s \cdot [Z_{i,x}, L_x] f_s)) \\
&+ \sum_{x \in \mathbb{Z}^d} \sum_{i=0, \dots, N} \mathcal{P}_{t-s} ((2i+1) a_i s^{2i} |Z_{i,x} f_s|^2 + 2i b_i s^{2i-1} Z_{i-1,x} f_s \cdot Z_{i,x} f_s),
\end{aligned}$$

and

$$(\mathbf{III}) = -2 \sum_{x,y \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} (a_i s^{2i+1} \mathcal{E}_{L_y} (Z_{i,x} f_s) + b_i s^{2i} \mathcal{E}_{L_y} (Z_{i-1,x} f_s, Z_{i,x} f_s)) \quad (41)$$

$$- 2 \sum_{y,y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \cdot \sum_{x,y \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} a_i s^{2i+1} (Z_{0,y} Z_{i,x} f_s) \cdot (Z_{0,y'} Z_{i,x} f_s) \quad (42)$$

$$- 2 \sum_{y,y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \cdot \sum_{x,y \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} b_i s^{2i} (Z_{0,y} Z_{i-1,x} f_s) \cdot (Z_{0,y'} Z_{i,x} f_s) \quad (43)$$

$$+ \sum_{x,y \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} (2a_i s^{2i+1} (Z_{i,x} f_s \cdot [Z_{i,x}, \mathbf{q}_y \cdot \mathbf{Z}_y] f_s)) \quad (44)$$

$$+ \sum_{x,y \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} (2b_i s^{2i} ([Z_{i-1,x}, \mathbf{q}_y \cdot \mathbf{Z}_y] f_s \cdot Z_{i,x} f_s + Z_{i-1,x} f_s \cdot [Z_{i,x}, \mathbf{q}_y \cdot \mathbf{Z}_y] f_s)) \quad (45)$$

$$+ \sum_{y,y' \in \mathbb{Z}^d} \sum_{x \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} (2a_i s^{2i+1} (Z_{i,x} f_s \cdot [Z_{i,x}, \mathfrak{S}_{yy'} \cdot Z_{0,y} Z_{0,y'}] f_s)) \quad (46)$$

$$+ \sum_{x \in \mathbb{Z}^d} \sum_{y,y' \in \mathbb{Z}^d} \sum_{i=0,\dots,N} \mathcal{P}_{t-s} (2b_i s^{2i} ([Z_{i-1,x}, \mathfrak{S}_{yy'} \cdot Z_{0,y} Z_{0,y'}] f_s \cdot Z_{i,x} f_s \quad (47)$$

$$+ Z_{i-1,x} f_s \cdot [Z_{i,x}, \mathfrak{S}_{yy'} \cdot Z_{0,y} Z_{0,y'}] f_s)). \quad (48)$$

We have studied **(II)** (called the ‘free part’ later on) before. From our assumptions about the free part, (41) is strictly negative and can be made so that it dominates contributions from (42)-(43). The contributions from (44)-(48) can not be dominated by the free part without additional assumptions about the interaction which we will discuss in the following. First of all we remark that

$$[Z_{i,x}, \mathbf{q}_y \cdot \mathbf{Z}_y] = \sum_{j=1,\dots,N} (Z_{i,x} q_{jy}) Z_{j,y} + \delta_{xy} \sum_{j,k=1,\dots,N} c_{ijk} q_{jx} Z_{k,x}.$$

Assumptions (37) and (38) enable us to dominate the terms involving these commutators by the free part for small times. The newly generated terms will come accompanied by a sufficiently high power of s so they will be irrelevant for small times. Next we note that

$$\begin{aligned} [Z_{i,x}, \mathfrak{S}_{yy'} \cdot Z_{0,y} Z_{0,y'}] &= (Z_{i,x} \mathfrak{S}_{yy'}) \cdot Z_{0,y} Z_{0,y'} \\ &+ \delta_{xy} \sum_{k=1,\dots,N} c_{i0k} \mathfrak{S}_{xy'} Z_{0,y'} Z_{k,x} \\ &+ \delta_{xy} \delta_{xy'} \sum_{k,l=1,\dots,N} c_{i0k} c_{k0l} \mathfrak{S}_{yx} Z_{l,x} \\ &+ \delta_{xy'} \sum_{k=1,\dots,N} c_{i0k} \mathfrak{S}_{yx} Z_{0,y} Z_{k,x}. \end{aligned}$$

For the corresponding terms to be dominated by the free part it is sufficient that (39) and (40) hold, because in this case the terms will be accompanied by a sufficiently large power of s . (One can in fact see that (39) implies (40).) Thus, under the conditions (37) -(39), for sufficiently small time we have

$$\partial_s \mathcal{P}_{t-s} \mathbf{Q}_s^{(1)}(f_s) \leq 0.$$

Hence, we arrive to the following smoothing estimates for infinite dimensional system, when $n = 1$

$$\Gamma_t^{(1)}(f_t) \leq d(\mathcal{P}_t f^2 - (\mathcal{P}_t f)^2).$$

Now we proceed by induction. We have

$$(\partial_s - \mathcal{L})\Gamma_{s,\mathbf{x}}^{(n)}(f_s) = \left(\partial_s \Gamma_{s,\mathbf{x}}^{(n)} \right)(f_s) - \left[\mathbf{L}, \Gamma_{s,\mathbf{x}}^{(n)} \right](f_s) - \left[\mathbf{L}_{\text{int}}, \Gamma_{s,\mathbf{x}}^{(n)} \right](f_s)$$

where

$$\left[\mathbf{L}, \Gamma_{s,\mathbf{x}}^{(n)} \right](g, h) \equiv \mathbf{L} \left(\Gamma_{s,\mathbf{x}}^{(n)}(g, h) \right) - \Gamma_{s,\mathbf{x}}^{(n)}(\mathbf{L}g, h) - \Gamma_{s,\mathbf{x}}^{(n)}(g, \mathbf{L}h)$$

and similarly for the second commutator involving \mathbf{L}_{int} .

Analogously to the proof of Theorem 2.1, let us start with assuming for simplicity that $Z_{0,y}$ fields commute with all the other $Z_{\alpha,x}$ fields; in this case the terms which will appear on the n^{th} level will be as follows

$$- 2 \sum_{y \in \mathbb{Z}^d} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n} \mathcal{E}_{L_y}(\mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s) \quad (49)$$

$$- 2 \sum_{y \in \mathbb{Z}^d} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n-1} \mathcal{E}_{L_y}(\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n,\mathbf{x}} f_s, \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s) \quad (50)$$

$$- 2 \sum_{y,y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \cdot \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n} Z_{0,y} \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s \cdot Z_{0,y'} \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s \quad (51)$$

$$- 2 \sum_{y,y' \in \mathbb{Z}^d} \mathfrak{S}_{yy'} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n-1} \cdot Z_{0,y} \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n,\mathbf{x}} f_s \cdot Z_{0,y'} \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s \quad (52)$$

$$+ 2 \sum_{y \in \mathbb{Z}^d} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{|\mathbf{k}|_n=0}^{nN} a_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n} \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s \cdot [\mathbf{Z}_{\mathbf{k},n,\mathbf{x}}, \mathbf{q}_y \cdot \mathbf{Z}_y] f_s \quad (53)$$

$$+ 2 \sum_{y \in \mathbb{Z}^d} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} \sum_{0 \leq |\mathbf{k}|_n: k_1 \geq 1}^{nN} b_{\mathbf{k},n} s^{2|\mathbf{k}|_n+n-1} [\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n,\mathbf{x}} \mathbf{q}_y \cdot \mathbf{Z}_y] f_s \cdot \mathbf{Z}_{\mathbf{k},n,\mathbf{x}} f_s \quad (54)$$

$$+ \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1,n,\mathbf{x}} f_s \cdot [\mathbf{Z}_{\mathbf{k},n,\mathbf{x}}, \mathbf{q}_y \cdot \mathbf{Z}_y] f_s. \quad (55)$$

Under the conditions for which the original finite dimensional case is negative, (49)-(50) are also negative and, if $\mathfrak{S}_{yy'}$ is assumed sufficiently small, they can dominate contributions from (51) and (52). As discussed before one has the following expressions for the commutators in (53) and (55)

$$[\mathbf{Z}_{\mathbf{k},n,\mathbf{x}}, \mathbf{q}_y \cdot \mathbf{Z}_y] = \sum_{i=1}^n \left(\sum_{l=1}^{n-1} \sum_{\substack{\widehat{\mathbf{z}} \subset \mathbf{z}, \widehat{\mathbf{k}} \subset \mathbf{k}: \\ |\mathbf{x} \setminus \widehat{\mathbf{z}}| = l}} \left(\mathbf{Z}_{\mathbf{k} \setminus \widehat{\mathbf{k}}, n-l, \mathbf{x} \setminus \widehat{\mathbf{z}}} q_{iy} \right) \cdot \mathbf{Z}_{\widehat{\mathbf{k}}, l, \widehat{\mathbf{z}}} Z_{i,y} + q_{iy} \cdot [\mathbf{Z}_{\mathbf{k},n,\mathbf{x}}, Z_{i,y}] \right)$$

and

$$[\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1, n, \mathbf{x}}, \mathbf{q}_y \cdot \mathbf{Z}_y] = \sum_{i=1}^n \left(\sum_{l=1}^{n-1} \sum_{\substack{\widehat{\mathbf{z}} \subset \mathbf{z}, \widehat{\mathbf{k}} \subset \mathbf{k}-\mathbf{e}_1 \\ |\mathbf{x} \setminus \widehat{\mathbf{z}}| = l}} \left(\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1 \setminus \widehat{\mathbf{k}}, n-l, \mathbf{x} \setminus \widehat{\mathbf{z}}} q_{iy} \right) \cdot \mathbf{Z}_{\widehat{\mathbf{k}}, l, \widehat{\mathbf{z}}} Z_{i,y} + q_{iy} \cdot [\mathbf{Z}_{\mathbf{k}-\mathbf{e}_1, n, \mathbf{x}}, Z_{i,y}] \right),$$

with a rule that $\mathbf{Z}_{\mathbf{k} \setminus \widehat{\mathbf{k}}, n-l, \mathbf{x} \setminus \widehat{\mathbf{z}}} \mathbf{q}_y, \mathbf{Z}_{\mathbf{k}-\mathbf{e}_1 \setminus \widehat{\mathbf{k}}, n-l, \mathbf{x} \setminus \widehat{\mathbf{z}}} \mathbf{q}_y \neq 0$ only in the case when $\text{dist}(x_i, y) \leq R$ for each $x_i \in \mathbf{x} \setminus \widehat{\mathbf{z}}, i = 1, \dots, l$. In both cases we produce the terms of order at most n , but the terms with $l < n - 1$ will be accompanied by higher power of time s and can be compensated for sufficiently small time by terms in $\mathbf{Q}_s^{(n-1)}$ by a choice of sufficiently large ς_n . When $l = n - 1$ and $i = 0$ the corresponding terms can be compensated by terms coming from the derivative of $\mathbf{Q}_s^{(n-1)}$ for small times provided ς_n is sufficiently large. Otherwise for $l = n - 1$ and $i \neq 0$, the corresponding terms can be dominated by terms coming from the derivative of the free part (i.e. the part coming from the commutator with \mathbf{L}) provided $\sup_{k_j, z_j, i, y} \|Z_{k_j, z_j} q_{iy}\|$ is sufficiently small.

As in the finite dimensional case of Theorem 2.1, if we no longer assume that the $Z_{0,y}$ fields commute with all the other $Z_{\alpha,x}$, then we will obtain extra terms. Such terms can be controlled, like in the proof of Theorem 2.1, thanks to our assumptions on the commutators. We do not repeat the whole calculation here, as it is completely analogous to the one done in finite dimensions. \square

4 Existence of Invariant States for the Infinite Dimensional Semigroups

In this section we consider the operators \mathcal{L} which are obtained as the limits of \mathcal{L}_Λ as $\Lambda \uparrow \mathbb{Z}^d$. We will provide a strategy for the associated semigroups \mathcal{P}_t which a priori may depend on the initial configuration. To start with, consider the operator L given in Section 2, on \mathbb{R}^m equipped with a metric \mathbf{d} . For any $x \in \mathbb{Z}^d$, we consider the semi-distance $\mathbf{d}_x(\omega) = \mathbf{d}(\omega_x)$, $(\mathbb{R}^m)^{\mathbb{Z}^d} \ni \omega = \{\omega_y \in \mathbb{R}^m\}_{y \in \mathbb{Z}^d}$, and set $\rho_x(\omega) \equiv \phi(\mathbf{d}_x(\omega))$, for some smooth increasing ϕ with bounded derivative. Given summable weights $(\epsilon_x \in (0, \infty))_{x \in \mathbb{Z}^d}$, $\sum_{x \in \mathbb{Z}^d} \epsilon_x < \infty$, we define the set

$$\Omega = \left\{ \omega \in (\mathbb{R}^m)^{\mathbb{Z}^d} : \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) < \infty \right\}.$$

The following assumption plays a key role in the proof of our results.

Assumption 3. *There exists a smooth function $\rho : \mathbb{R}^m \rightarrow \mathbb{R}$, which satisfies $\rho(u) \rightarrow \infty$ as $\mathbf{d}(u) \rightarrow \infty$, whose level sets $\{\rho < L\}$, $L > 0$ are compact, and satisfies the Lyapunov-type condition*

$$L\rho < C_1 - C_2\rho, \quad (56)$$

for some constants $C_1 \geq 0$ and $C_2 > 0$.

Examples of generators for which $\rho = \phi(d)$ satisfies (56) will be given elsewhere [17]. The moral behind Theorem 4.1 below is the following: roughly speaking, if we are able to exhibit a Lyapunov function ρ for the finite dimensional dynamics, then $\sum_{x \in \mathbb{Z}^d} \rho_x$ (where ρ_x is a "copy" of ρ acting at $x \in \mathbb{Z}^d$) is a candidate Lyapunov function for the infinite dimensional generator; this is, provided some assumptions involving the interaction functions are satisfied, see (58) and (59). With this in mind, we have the following result on existence of invariant measures.

Theorem 4.1. *Suppose that ρ satisfies Assumption 3 and let \mathcal{P}_t be the semigroup generated by*

$$\mathcal{L} = \sum_{x \in \mathbb{Z}^d} L_x - \sum_{x \in \mathbb{Z}^d} \mathbf{q}_x \cdot Z_x - \sum_{\substack{yy' \in \mathbb{Z}^d \\ y \neq y'}} \mathfrak{S}_{yy'} \cdot Z_{0,y} Z_{0,y'}. \quad (57)$$

If ρ is such that

$$- \sum_{y \in \mathbb{Z}^d} \mathbf{q}_x \cdot Z_x \rho_x \leq C_3 + \sum_{y \in \mathbb{Z}^d} \eta_{x,y} \rho_y \quad (58)$$

for some $C_3 > 0$, with $\eta_{x,y} \in (0, \infty)$, $S \equiv \sup_{x \in \mathbb{Z}^d} \sum_{y \in \mathbb{Z}^d} \eta_{x,y} < \infty$, satisfying

$$\sum_{x \in \mathbb{Z}^d} \epsilon_x \eta_{x,y} \leq C_4 \epsilon_y \quad (59)$$

with some positive constant $C_4 < C_2$, then there exists a subsequence $(t_k)_{k \in \mathbb{N}} \subset \mathbb{R}$ and a probability measure μ_ω such that $\mu_\omega(\Omega) = 1$ and

$$\mathcal{P}_{t_k} f(\omega) \rightarrow \mu_\omega(f), \quad (60)$$

as $k \rightarrow \infty$, for all bounded smooth cylinder functions f and all $\omega \in \Omega$.

Remark 4.1. *One can see that, if $\eta_{x,y} \equiv 0$ for $|x - y| \geq R$, for some $R \in (0, \infty)$, condition (59) is satisfied for polynomially as well as exponentially decaying weights.*

Proof. The proof of Theorem 4.1 consists of the following steps. We start by constructing a Lyapunov function for the operator \mathcal{L} using suitable function ρ . We then use this function to deduce that the corresponding semigroup converges weakly to a probability measure, pointwise with respect to the initial configuration $\omega \in \Omega$. Finally, we show that the limit measure is independent of the initial configuration.

We consider $\sum_{x \in \mathbb{Z}^d} \rho_x$, with ρ_x as above. Since $Z_{lr,y} \rho_x = 0$ whenever $x \neq y$, using (58), we obtain

$$\mathcal{L} \rho_x = L_x \rho_x - \sum_{x \in \Lambda} \mathbf{q}_x \cdot Z_x \rho_x \leq C_1 - C_2 \rho_x - \sum_{x \in \Lambda} \mathbf{q}_x \cdot Z_x \rho_x \quad (61)$$

Thus if

$$- \sum_{x \in \mathbb{Z}^d} \mathbf{q}_x \cdot Z_x \rho_x \leq C_3 + \sum_{y \in \mathbb{Z}^d} \eta_{x,y} \rho_y$$

with some $\eta_{x,y} \in (0, \infty)$, $S \equiv \sup_{x \in \mathbb{Z}^d} \sum_{y \in \mathbb{Z}^d} \eta_{x,y} < \infty$, then, with $\bar{C} \equiv C_1 + C_3$, we have

$$\frac{d}{dt} \mathcal{P}_t \rho_x = \mathcal{P}_t \mathcal{L} \rho_x \leq \bar{C} - C_2 \mathcal{P}_t \rho_x + \sum_{y \in \mathbb{Z}^d} \eta_{x,y} \mathcal{P}_t \rho_y$$

Hence

$$\mathcal{P}_t \rho_x(\omega) \leq \bar{C} + e^{-C_2 t} \rho_x(\omega) + \sum_{y \in \mathbb{Z}^d} \eta_{x,y} \int_0^t ds e^{-C_2(t-s)} \mathcal{P}_s \rho_y$$

and for any summable weights $\epsilon_x \in (0, \infty)$ we have

$$\mathcal{P}_t \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) \leq \bar{C} S + e^{-C_2 t} \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) + \sum_{x \in \mathbb{Z}^d} \epsilon_x \sum_{y \in \mathbb{Z}^d} \eta_{x,y} \int_0^t ds e^{-C_2(t-s)} \mathcal{P}_s \rho_y$$

If we have

$$\sum_{x \in \mathbb{Z}^d} \epsilon_x \eta_{x,y} \leq C_4 \epsilon_y$$

with some constant $C_4 \in (0, \infty)$, then for

$$F_t \equiv \mathcal{P}_t \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega)$$

we get the following relation

$$F_t \leq \bar{C} S + e^{-C_2 t} F_0 + C_4 \int_0^t ds e^{-C_2(t-s)} F_s.$$

This implies that

$$\sup_{0 \leq s \leq t} F_s \leq (1 - \bar{\kappa})^{-1} (\bar{C} S + F_0) \quad (62)$$

which is finite and uniformly bounded in t , provided that $\bar{\kappa} \equiv \frac{C_4}{C_2} \in (0, 1)$ and $\sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) < \infty$, i.e. we have

$$\sup_{t \geq 0} \left(\mathcal{P}_t \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x \right) (\omega) \leq (1 - \bar{\kappa})^{-1} \left(\bar{C}S + \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) \right) \quad (63)$$

(Strictly speaking one applies first all the above arguments to a smooth cutoff $\rho_x^A \leq A < \infty$ of ρ_x and after applying the formal Gronwall arguments, we pass to the limit $A \rightarrow \infty$. This is more lengthy to write, but there is no technical difficulty in that.)

The existence of such uniform bound (63) implies ([9], Section 3.2) the weak convergence of a subsequence of $(\mathcal{P}_t)_{t \geq 0}$ for an initial configuration $\omega \in \Omega$, i.e. the existence of a sequence $(t_k)_{k \in \mathbb{N}} \subset \mathbb{R}$ and a measure μ_ω such that for all bounded and smooth cylinder functions f

$$\mathcal{P}_{t_k} f(\omega) \rightarrow \mu_\omega(f),$$

as $k \rightarrow \infty$, for all $\omega \in \Omega$. Consider the set

$$\Omega_L = \left\{ \tilde{\omega} \in (\mathbb{R}^m)^{\mathbb{Z}^d} : \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\tilde{\omega}) < L \right\}.$$

Using Markov's inequality we obtain, for all $\omega \in \Omega$,

$$\mu_\omega(\Omega_L) \geq 1 - \frac{1}{L} \sup_{t \geq 0} \left(\mathcal{P}_t \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x \right) (\omega) \geq 1 - \frac{1}{L} \left((1 - \bar{\kappa})^{-1} \left(\bar{C}S + \sum_{x \in \mathbb{Z}^d} \epsilon_x \rho_x(\omega) \right) \right),$$

and thus taking the limit as $L \rightarrow \infty$, we conclude that $\mu_\omega(\Omega) = 1$. □

5 Ergodic Properties of the Infinite Dimensional Semigroups

First of all we note that in the general case for which the semigroup was constructed in Section 3, and the Lie algebra is stratified (see Remark 3.1) for each $x \in \mathbb{Z}^d$ with the corresponding dilation generator D_x , one can show the following result.

Theorem 5.1. *Consider*

$$\mathcal{L} \equiv \sum_{x \in \mathbb{Z}^d} L_x - \sum_{x \in \Lambda} \mathbf{q}_x \cdot Y_x - \sum_{\substack{yy' \in \mathbb{Z}^d \\ y \neq y'}} \mathfrak{S}_{yy'} \cdot Y_{0,y} Y_{0,y'} - \lambda \sum_{x \in \mathbb{Z}^d} D_x$$

with $\lambda > 0$, $P_t = e^{t\mathcal{L}}$ and

$$L_x \equiv \mathbf{Z}_{J,x}^2 + B_x,$$

where $J \subset I$. For every $n \in \mathbb{N}$ there exists $\lambda_n \in (0, \infty)$ such that for any $\lambda \geq \lambda_n$ one has

$$\sum_{\mathbf{x} \in \mathbb{Z}^{nd}} |\mathbf{Y}_{\mathbf{x}} f_t|^2 \leq e^{-m_n t} \sum_{\mathbf{x} \in \mathbb{Z}^{nd}} |\mathbf{Y}_{\mathbf{x}} f|^2$$

with some $m_n \in (0, \infty)$. Hence for any $\omega, \omega' \in \Omega_\delta \equiv \{\tilde{\omega} : \sum_{x \in \mathbb{Z}^d} \frac{|\tilde{\omega}_x|}{(1+d(x,0))^{d+\delta}} < \infty\}$, defined with some $\delta \in (0, \infty)$, we get

$$|P_t f(\omega) - P_t f(\omega')| \leq C e^{-mt} \sum_{\mathbf{x} \in \mathbb{Z}^d} |Y_{\mathbf{x}} f|$$

with some $m \in (0, \infty)$ independent of a smooth cylinder function f and some constant C dependent on $\Lambda(f)$.

For the full gradient bound estimate see e.g. [17]. The ergodicity statement follows via similar strategy as in [9]. We consider the lexicographic order on the lattice introduced in the proof of Theorem 3.2 and an interpolating sequence of points

$$(\omega^{(j)})_{x_k} \equiv \begin{cases} \omega_{x_k}, & \text{if } k \leq j \\ \omega'_{x_k}, & \text{if } k > j. \end{cases}$$

With this interpolation we consider the following telescopic expansion

$$P_t f(\omega) - P_t f(\omega') = \sum_k \left(P_t f(\omega^{(k+1)}) - P_t f(\omega^{(k)}) \right)$$

and notice that for a piecewise differentiable unit speed path $\gamma_\tau^{(k)}$ such that $\gamma_{\tau=0}^{(k)} = \omega_{x_k}^{(k)}$ and $\gamma_{\tau=1}^{(k)} = \omega_{x_k}^{(k+1)}$ with tangent vectors given by \mathbf{Y} (such a path exists by Chow's Theorem, see e.g. [6]), we have

$$\left| P_t f(\omega^{(k+1)}) - P_t f(\omega^{(k)}) \right| = \left| \int_0^1 d\tau \dot{\gamma}_\tau^{(k)} \cdot \nabla_{\mathbf{Y}_{x_k}} P_t f(\gamma_\tau^{(k)}) \right| \leq d(\omega_{x_k}, \omega'_{x_k}) \|\nabla_{\mathbf{Y}_{x_k}} P_t f\|.$$

The sum of such terms over $\{k : d(x_k, 0) \geq Ct\}$, with suitable constant $C \in (0, \infty)$, can be bounded using finite speed of propagation of information by a factor converging exponentially quickly to zero with respect to t . The remaining contribution can be estimated as follows.

$$\sum_{k: d(x_k, 0) \leq Ct} \left| P_t f(\omega^{(k+1)}) - P_t f(\omega^{(k)}) \right| \leq C^d t^d \max_{d(x, 0) \leq Ct} (|\omega_x|, |\omega'_x|) \cdot |\mathbf{Y} P_t f|$$

Thus for ω, ω' in the set Ω_δ , to get the uniqueness of the limit (and possibly also uniqueness of invariant measure supported by this set) it is sufficient to show

$$|\mathbf{Y} P_t f| \leq C' t^{-d-2\delta}$$

with some finite constant C' . A similar idea to prove uniqueness of the limit $\lim_{t \rightarrow \infty} P_t f$ can be used in the situation when additional restrictions on the commutation relations are imposed.

Theorem 5.2. Suppose that Assumption (CR.I) is satisfied with $c_j = 0$ and $c_{0jk} = 0$, $j, k = 1, \dots, N$. Suppose that

$$\begin{aligned} Z_{i,x} \mathbf{q}_{jy} &= 0 & \text{if } j > i \\ \sum_{j=1, \dots, N} c_{ijk} \mathbf{q}_{jx} &= 0 & \text{if } k > i \end{aligned}$$

Suppose additionally that

$$Z_{i,x} \mathbf{q}_{jy} = 0 \quad \text{if } j \neq i$$

and

$$Z_{i,x} \mathfrak{S}_{kk', yy'} = 0$$

Then, there exists coefficients $a_i, b_i, d_0, \varepsilon \in (0, \infty)$, such that if

$$\sup_{k_j, z_j, i, y} \|\mathbf{Z}_{k_j, z_j} \mathbf{q}_{iy}\| < \varepsilon,$$

then for any $t \in (0, \infty)$ one has

$$\sum_{l=1, \dots, n} \mathbf{\Gamma}_t^{(l)}(f_t) \leq d_0(P_t(f^2) - (P_t f)^2)$$

Hence, in case $[d + 2\delta] \leq N$, for any bounded cylinder function f , if

$$\|(B, Z_0, Z_{j_{\max}})P_t f\| \leq C t^{-d-2\delta},$$

for some constant $C \in (0, 1)$ and $j_{\max} \equiv \min([d + 2\delta], N)$, then the limit $\lim_{t \rightarrow \infty} P_t f(\omega)$ is unique for $\omega \in \Omega_\delta$.

We notice that the decay in the directions of Z_j with $j > [d + 2\delta]$ is automatically sufficiently fast. Thus for the question of uniqueness it is sufficient to concentrate on estimates in direction B and Z_j , $j \leq [d + 2\delta]$. Finally we mention that in the same situation one can take advantage of higher order estimates as follows.

Theorem 5.3. Under the conditions of Theorem 5.2, assume the higher order bounds including $\mathbf{Y} \equiv (B, \mathbf{Z})$ are true globally in time. If for some configuration $\tilde{\omega} \in \Omega_\delta$ one has for any bounded cylinder function f ,

$$|\mathbf{Y}^{(n)} P_t f(\tilde{\omega})| \leq C_n t^{-d-2\delta},$$

for some constants $C_n \in (0, 1)$ and $n \leq n_{\max} \equiv [d + 2\delta]$, with $\mathbf{Y} \equiv (B, \mathbf{Z})$, then the limit $\lim_{t \rightarrow \infty} P_t f(\omega)$ is unique for all $\omega \in \Omega_\delta$.

This result follows in the similar fashion as before re-expanding $\nabla_{\mathbf{Y}_{x_k}} P_t f(\gamma_\tau^{(k)})$ sufficiently many times.

Appendix A

This Appendix is devoted to the proof of Proposition 3.1.

Proof of Proposition 3.1. For $t \geq s \geq 0$, we have:

$$\begin{aligned} \frac{\partial}{\partial s} \mathcal{P}_{t-s}^\Lambda |\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda|^2 &= \mathcal{P}_{t-s}^\Lambda \left\{ \left(-\mathcal{L}_\Lambda + \frac{\partial}{\partial s} \right) |\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda|^2 \right\} \\ &= \mathcal{P}_{t-s}^\Lambda \left\{ -\mathcal{L}_\Lambda |\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda|^2 + 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) (\mathcal{L}_\Lambda \mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) + 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) [\mathbf{Y}_{\ell, \mathbf{x}}^n, \mathcal{L}_\Lambda] f_s^\Lambda \right\}. \end{aligned} \quad (64)$$

First we note that

$$\begin{aligned} -\mathcal{L}_\Lambda |\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda|^2 + 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) \mathcal{L}_\Lambda \mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda &= -2 \sum_{z \in \mathbb{Z}^d} |Y_{J, z} \mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda|^2 \\ &\quad - 2 \sum_{z, z' \in \Lambda} \mathfrak{S}_{zz'} \cdot (Y_z \mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) \cdot (Y_{z'} \mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda); \end{aligned} \quad (65)$$

the last addend in (64) can instead be decomposed as follows:

$$\begin{aligned} &2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) [\mathbf{Y}_{\ell, \mathbf{x}}^n, \mathcal{L}_\Lambda] f_s^\Lambda \\ &= \sum_{z \in \mathbb{Z}^d} 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) [\mathbf{Y}_{\ell, \mathbf{x}}^n, L_z] f_s^\Lambda \end{aligned} \quad (\mathbf{T}_1)$$

$$+ 2 \sum_{z \in \Lambda} \sum_{\beta \in I} \mathbf{q}_{\beta, z} (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) [\mathbf{Y}_{\ell, \mathbf{x}}^n, Y_{\beta, z}] f_s^\Lambda \quad (\mathbf{T}_2)$$

$$+ \sum_{z \in \Lambda} \sum_{\beta \in I} 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) [\mathbf{Y}_{\ell, \mathbf{x}}^n, \mathbf{q}_{\beta, z}] Y_{\beta, z} f_s^\Lambda \quad (\mathbf{T}_3)$$

$$+ \sum_{z, z' \in \Lambda} \sum_{\gamma, \gamma' \in J} 2 \mathfrak{S}_{\gamma\gamma', zz'} (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) ([\mathbf{Y}_{\ell, \mathbf{x}}^n, Y_{\gamma, z}] Y_{\gamma', z'} + Y_{\gamma, z} [\mathbf{Y}_{\ell, \mathbf{x}}^n, Y_{\gamma', z'}]) f_s^\Lambda \quad (\mathbf{T}_4)$$

$$+ \sum_{z, z' \in \Lambda} \sum_{\gamma, \gamma' \in J} 2 (\mathbf{Y}_{\ell, \mathbf{x}}^n f_s^\Lambda) ([\mathbf{Y}_{\ell, \mathbf{x}}^n, \mathfrak{S}_{\gamma\gamma', zz'}]) Y_{\gamma, z} Y_{\gamma', z'} f_s^\Lambda. \quad (\mathbf{T}_5)$$

To estimate each of the above terms we use lengthy but elementary arguments of which we list the result in Lemma 5.1 to Lemma 5.5 below, and briefly sketch an idea of the proof.

The estimates of (T_1) and (T_2) in the first two lemmas below are based on our locality assumption, i.e. the fact that $\mathbf{Y}_{\ell, \mathbf{x}}^{(n)}$ and $L_z, Y_{\beta, z}$ commute unless $z \in \mathbf{x}$, and the structure of L_z , together with the quadratic Young's inequality (9). We recall the notation $c \equiv \sup_{\alpha, \gamma, \beta} |c_{\alpha\gamma\beta}|$, where $c_{\alpha\gamma\beta}$ are as in Assumption (GCR).

Lemma 5.1 (Estimate of (\mathbf{T}_1)). *Under the assumptions of Proposition 3.1, for any $\varepsilon \in (0, \infty)$ we have*

$$2 \sum_{\iota} \left| \left(\mathbf{Y}_{\iota, \mathbf{x}}^{(n)} f_s^\Lambda \right) \left[\mathbf{Y}_{\iota, \mathbf{x}}^{(n)}, \sum_{z \in \mathbb{Z}^d} L_z \right] f_s^\Lambda \right| \leq (-\lambda n \kappa + A_n) |\mathbf{Y}_{\mathbf{x}}^{(n)} f_s^\Lambda|^2 + \varepsilon \sum_{j=1}^n |Y_{J, x_j} Y_{\mathbf{x}}^{(n)} f_s^\Lambda|^2,$$

where $\kappa \equiv \inf_{\alpha \in I} \kappa_\alpha$, $b \equiv \sup_{\alpha \in I, x \in \mathbb{Z}^d} |b_{\alpha, x}|$ and $A_n \equiv 2nbc|I| + n\varepsilon^{-1}|I| + \frac{1}{2}n^2c^2|I|^2(|I| + 1)$.

Lemma 5.2 (Estimate of (\mathbf{T}_2)). *Under the assumptions of Proposition 3.1,*

$$\sum_{\iota} \left| 2 \sum_{z \in \Lambda} \sum_{\beta \in I} \mathbf{q}_{\beta, z} \left(\mathbf{Y}_{\iota, \mathbf{x}}^{(n)} f_s^\Lambda \right) \left[\mathbf{Y}_{\iota, \mathbf{x}}^{(n)}, Y_{\beta, z} \right] f_s^\Lambda \right| \leq 2n\bar{q}c|I| |\mathbf{Y}_{\mathbf{x}}^{(n)} f_s^\Lambda|^2$$

with $\bar{q} \equiv \sup_{\alpha, z} \|\mathbf{q}_{\alpha, z}\|_\infty$.

The key to the next estimate is contained in the following commutator expression. For any sufficiently smooth function g , we have

$$[\mathbf{Y}_{\iota, \mathbf{x}}^{(n)}, g] = \sum_{l=0}^n \sum_{\gamma \subset \iota: |\gamma|=l} \sum_{\mathbf{z} \subset \mathbf{x}: |\mathbf{z}|=l} \varphi_n(l) \left(\mathbf{Y}_{\check{\gamma}, \check{\mathbf{z}}}^{(n-l)} g \right) \mathbf{Y}_{\gamma, \mathbf{z}}^{(l)},$$

where

$$\varphi_n(l) = \begin{cases} 1 & \text{if } l \leq n/2 \\ -1 & \text{otherwise,} \end{cases}$$

and with the convention that $\mathbf{Y}_{\check{\gamma}, \check{\mathbf{z}}}^{(0)} \equiv id$ and the elements of $\gamma, \check{\gamma}$ are ordered in the same way as in ι and those of $\check{\mathbf{z}}, \mathbf{z}$ in the same way as in \mathbf{x} .

Lemma 5.3 (Estimate of (\mathbf{T}_3)). *Under the assumptions of Proposition 3.1, for any $\varepsilon \in (0, 1)$, we have*

$$\begin{aligned} \sum_{\iota} \left| \sum_{y \in \Lambda} \sum_{\beta} 2 \left(\mathbf{Y}_{\iota, \mathbf{x}}^{(n)} f_s^\Lambda \right) \left[\mathbf{Y}_{\iota, \mathbf{x}}^{(n)}, \mathbf{q}_{\beta, y} \right] Y_{\beta, y} f_s^\Lambda \right| &\leq \varepsilon^{-1} B_n |\mathbf{Y}_{\mathbf{x}}^{(n)} f_s^\Lambda|^2 \\ &+ \varepsilon \sum_{k=0}^n \sum_{\mathbf{z} \subset \mathbf{x}, y \in \mathbb{Z}^d} B_{\mathbf{x}, k}(\mathbf{z}, y) |\mathbf{Y}_{(\mathbf{z}, y)}^{(k+1)} f_s^\Lambda|^2 \end{aligned}$$

with

$$B_n \equiv \sum_{y \in \mathbb{Z}^d} \sum_{\beta \in I} \sum_{k=1}^n \sup_{(\iota, \mathbf{x})} \sum_{(\gamma, \mathbf{z}) \subset (\iota, \mathbf{x}): |\gamma|=k} \|\mathbf{Y}_{\check{\gamma}, \check{\mathbf{z}}}^{(n-k)} \mathbf{q}_{\beta, y}\|_\infty$$

and

$$B_{\mathbf{x},k}(\mathbf{z}, y) \equiv \delta_{\{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=k\}} \sup_{\beta, \tilde{\gamma}} \|\mathbf{Y}_{\tilde{\gamma}, \tilde{\mathbf{z}}}^{(n-k)} \mathbf{q}_{\beta, y}\|_{\infty}.$$

We remark that when we consider an interaction with finite range $R \in \mathbb{N}$, i.e. when $\mathbf{q}_{\beta, y}$ is a cylinder function dependent only on coordinates ω_z with $\text{dist}(z, y) < R$, we have

$$\mathbf{Y}_{\tilde{\gamma}, \tilde{\mathbf{z}}}^{(n-k)} \mathbf{q}_{\beta, y} = 0, \quad \text{dist}(\tilde{\mathbf{z}}, y) \geq R.$$

The next estimate uses our locality assumption together with the quadratic Young's inequality.

Lemma 5.4 (Estimate of (\mathbf{T}_4)). *Under the assumptions of Proposition 3.1, for any $\varepsilon \in (0, 1)$*

$$\begin{aligned} & \sum_{\iota} \left| \sum_{yy' \in \Lambda} \sum_{\gamma\gamma' \in J} 2\mathfrak{S}_{\gamma\gamma', yy'}(\mathbf{Y}_{\iota, \mathbf{x}}^n f_s^\Lambda) \left([\mathbf{Y}_{\iota, \mathbf{x}}^n, Y_{\gamma, y}] Y_{\gamma', y'} + Y_{\gamma, y} [\mathbf{Y}_{\iota, \mathbf{x}}^n, Y_{\gamma', y'}] \right) f_s^\Lambda \right| \\ & \leq C_n \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 + \varepsilon \sum_{y \in \Lambda} \left| Y_{J, y} \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 \end{aligned}$$

with positive constants

$$C_n \leq \varepsilon^{-1} n^3 c |I| \sup_{z \in \mathbb{Z}^d} \sum_{y \in \mathbb{Z}^d} \sum_{\gamma\gamma' \in J} (|\mathfrak{S}_{\gamma\gamma', yz}| + |\mathfrak{S}_{\gamma\gamma', zy}|) + \frac{1}{2} n^2 \bar{C}_n (|I|^2 + 1),$$

where $\bar{C}_n = 2c \sup_{\gamma \in I, y, z \in \mathbb{Z}^d} \sum_{\gamma' \in J} |\mathfrak{S}_{\gamma\gamma', yz}|$.

The last estimate is similar to that of (\mathbf{T}_3) .

Lemma 5.5 (Estimate of (\mathbf{T}_5)). *Under the assumptions of Proposition 3.1, for any $n \geq 1$, for every $l = 1, \dots, n$, for any $\mathbf{x} = (x_1, \dots, x_n) \subset \mathbb{Z}^d$ and for every $\mathbf{z} \subset \mathbf{x}$ there exist positive constants $\mathcal{D}_{\mathbf{x}, n}^{(l)}(\mathbf{z}, y) \in (0, \infty)$, satisfying*

$$\sup_{|\mathbf{x}|=n, \mathbf{z} \subset \mathbf{x}} \sum_{y \in \mathbb{Z}^d} \mathcal{D}_{\mathbf{x}, n}^{(l)}(\mathbf{z}, y) < \infty$$

such that for any $\varepsilon \in (0, 1)$ the following bound is true

$$\begin{aligned} & \sum_{\iota} \left| 2 \left(\mathbf{Y}_{\iota, \mathbf{x}}^{(n)} f_s^\Lambda \right) \sum_{yy' \in \Lambda} \sum_{\gamma\gamma' \in J} \left([\mathbf{Y}_{\iota, \mathbf{x}}^{(n)}, \mathfrak{S}_{\gamma\gamma', yy'}] \right) Y_{\gamma, y} Y_{\gamma', y'} f_s^\Lambda \right| \\ & \leq \varepsilon \sum_{l=1}^n \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{D}_{\mathbf{x}, n}^{(l)}(\mathbf{z}, y) \left| Y_{J, y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 + \sum_{l=1}^n \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{D}_{\mathbf{x}, n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \end{aligned}$$

for some $\mathcal{D}_{\mathbf{x}, n}^{(l)}(\mathbf{z}) \in (0, \infty)$, $l = 1, \dots, n$, $\mathbf{z} \subset \mathbf{x}$.

We remark that because of our strong assumption of locality of $\mathfrak{S}_{\gamma\gamma',yy'}$, we have

$$\mathbf{Y}_{\check{\beta},\check{\mathbf{z}}}^{(n-l)} \mathfrak{S}_{\gamma\gamma',yy'} = 0, \quad \text{if} \quad \check{\mathbf{z}} \subseteq \{yy'\}.$$

Now we combine all estimates of Lemma 5.1 to Lemma 5.5, i.e. all the estimates of (\mathbf{T}_1) - (\mathbf{T}_5) :

$$\begin{aligned} & \left| 2 \left(\mathbf{Y}_{\iota,\mathbf{x}}^n f_s^\Lambda \right) \left[\mathbf{Y}_{\iota,\mathbf{x}}^n, \mathcal{L}_\Lambda \right] f_s^\Lambda \right| \\ & \leq (-\lambda n \kappa + A_n) \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 + \varepsilon \sum_{j=1}^n \left| Y_{J,x_j} Y_{\mathbf{x}}^n f_s^\Lambda \right|^2 \\ & \quad + 2n\bar{q}c|I| \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 \\ & \quad + \varepsilon^{-1} B_n \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 + \varepsilon \sum_{k=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=k}} B_{\mathbf{x},k}(\mathbf{z}, y) \left| \mathbf{Y}_{(\mathbf{z},y)}^{(k+1)} f_s^\Lambda \right|^2 \\ & \quad + C_n \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 + \varepsilon n^2 \bar{C}_n \sum_{y \in \Lambda} \left| Y_{J,y} \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 \\ & \quad + \varepsilon \sum_{l=1}^n \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{D}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 + \sum_{l=1}^n \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} D_{\mathbf{x},n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2. \end{aligned} \quad (66)$$

This can be rewritten as follows:

$$\begin{aligned} \left| 2 \left(\mathbf{Y}_{\iota,\mathbf{x}}^n f_s^\Lambda \right) \left[\mathbf{Y}_{\iota,\mathbf{x}}^n, \mathcal{L}_\Lambda \right] f_s^\Lambda \right| & \leq \varepsilon \sum_{l=1}^n \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\ & \quad + (-\lambda n \kappa + A_n) \left| \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda \right|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\ & \quad + \varepsilon \sum_{k=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=k}} B_{\mathbf{x},k}(\mathbf{z}, y) \left| \mathbf{Y}_{(\mathbf{z},y)}^{(k+1)} f_s^\Lambda \right|^2, \end{aligned}$$

where $\mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y)$ and $\mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z})$ are positive constants depending on the constants appearing in (66).

Putting this together with (64) and (65), we obtain

$$\begin{aligned}
\frac{\partial}{\partial s} \mathcal{P}_{t-s}^\Lambda |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 &\leq \mathcal{P}_{t-s}^\Lambda \left\{ -2 \sum_{z \in \mathbb{Z}^d} |Y_{J,z} \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 - 2 \sum_{z, z' \in \Lambda} \mathfrak{S}_{zz'} \cdot \sum_{\iota} (Y_z \mathbf{Y}_{\iota, \mathbf{x}}^n f_s^\Lambda) \cdot (Y_{z'} \mathbf{Y}_{\iota, \mathbf{x}}^n f_s^\Lambda) \right\} \\
&+ \mathcal{P}_{t-s}^\Lambda \left\{ \varepsilon \sum_{l=1}^n \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \right. \\
&\quad + (-\lambda n \kappa + \mathbf{A}_n) |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\
&\quad \left. + \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \\ |\mathbf{z}|=l}} B_{\mathbf{x},k}^{(l)}(\mathbf{z}, y) |\mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda|^2 \right\}.
\end{aligned}$$

Assuming that for some $\delta \in (0, 1)$ we have $\mathfrak{S}_{zz'} \leq \delta \text{Id}$ in the sense of quadratic forms, we can simplify the above as follows.

$$\begin{aligned}
\frac{\partial}{\partial s} \mathcal{P}_{t-s}^\Lambda |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 &\leq \mathcal{P}_{t-s}^\Lambda \left\{ -2(1-\delta) \sum_{z \in \mathbb{Z}^d} |Y_{J,z} \mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 \right\} \\
&+ \mathcal{P}_{t-s}^\Lambda \left\{ \varepsilon \sum_{l=1}^n \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \right. \\
&\quad + (-\lambda n \kappa + A_n) |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \\
&\quad \left. + \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \\ |\mathbf{z}|=l}} B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) |\mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda|^2 \right\}
\end{aligned}$$

Choosing ε so that $\varepsilon \sup_{\mathbf{x}, y, l} \mathcal{A}_{\mathbf{x},n}^{(n)}(\mathbf{z}, y) < 2(1-\delta)$, we get the following bound

$$\begin{aligned}
\frac{\partial}{\partial s} \mathcal{P}_{t-s}^\Lambda |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 &\leq \mathcal{P}_{t-s}^\Lambda \left\{ (-\lambda n \kappa + A_n) |\mathbf{Y}_{\mathbf{x}}^n f_s^\Lambda|^2 + \sum_{l=1}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x} \\ |\mathbf{z}|=l}} \mathcal{B}_{\mathbf{x},n}^{(l)}(\mathbf{z}) \left| \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 \right. \\
&\quad \left. + \varepsilon \sum_{l=1}^{n-1} \sum_{y \in \Lambda} \sum_{\mathbf{z} \subset \mathbf{x}; |\mathbf{z}|=l} \mathcal{A}_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) \left| Y_{J,y} \mathbf{Y}_{\mathbf{z}}^{(l)} f_s^\Lambda \right|^2 + \varepsilon \sum_{l=0}^{n-1} \sum_{\substack{\mathbf{z} \subset \mathbf{x}, y \in \Lambda \\ |\mathbf{z}|=l}} B_{\mathbf{x},n}^{(l)}(\mathbf{z}, y) |\mathbf{Y}_{(\mathbf{z},y)}^{(l+1)} f_s^\Lambda|^2 \right\}
\end{aligned}$$

Setting

$$\mathbf{v}_n \equiv (-\lambda n\kappa + A_n), \quad (67)$$

we obtain the statement of Proposition 3.1. \square

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