

Multilevel mathematical models for cell migration in dense fibrous environments



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Take-home message and plan

- Stay away from the carpenter syndrome

“To a man with a hammer, everything looks like a nail”

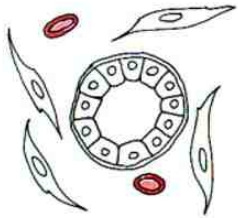
- Look at the biomedical problem with no mathematical bias

Plan of the talk

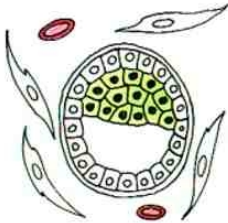
- Take a phenomenon (migration in fibrous environments)
- Present several modelling frameworks to study the problem

Tumour compartmentalization and invasion

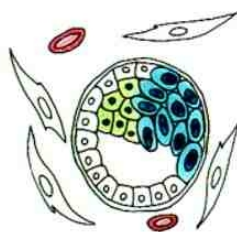
Normal
duct



Hyperplasia



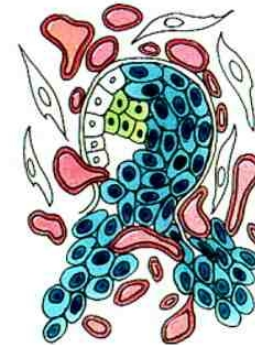
Dysplasia/
CIS



Angiogenic
CIS



Invasive
carcinoma



Breast

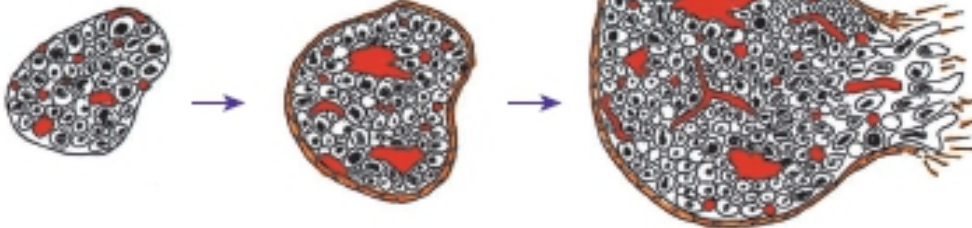
Ovary

Pancreas

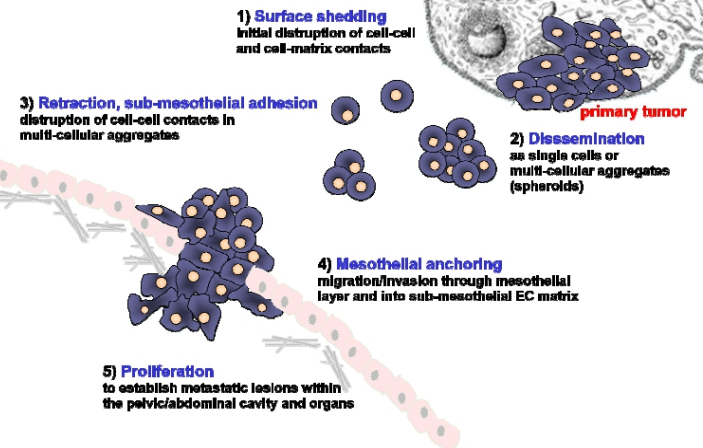
Angiogenic
Dysplasia/CIS

Small Tumor

Large Tumor/
Invasive Carcinoma



Ovarian cancer dissemination





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Cell motion





American Journal of Physics vol 45, pages 3-11, 1977.

Editor's note: This is a reprint of a (slightly edited) paper of the same title that appeared in the book *Physics and Our World: A Symposium in Honor of Victor F. Weiskopf*, published by the American Journal of Physics (1976). The personal tone of the original talk has been preserved in the paper, which was itself a slightly edited transcript of a tape. The figures reproduce transparencies used in the talk. The demonstration involved a tall rectangular transparent vessel of corn syrup, projected by an overhead projector turned on its side. Some essential hand waving could not be reproduced.

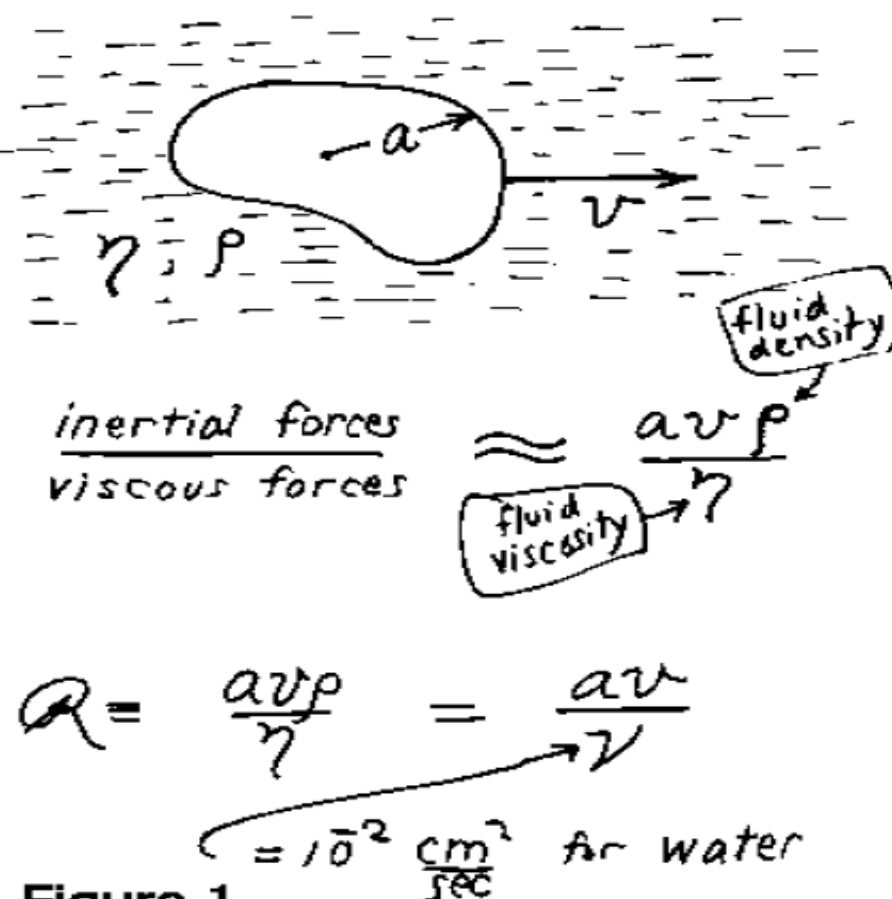


Figure 1

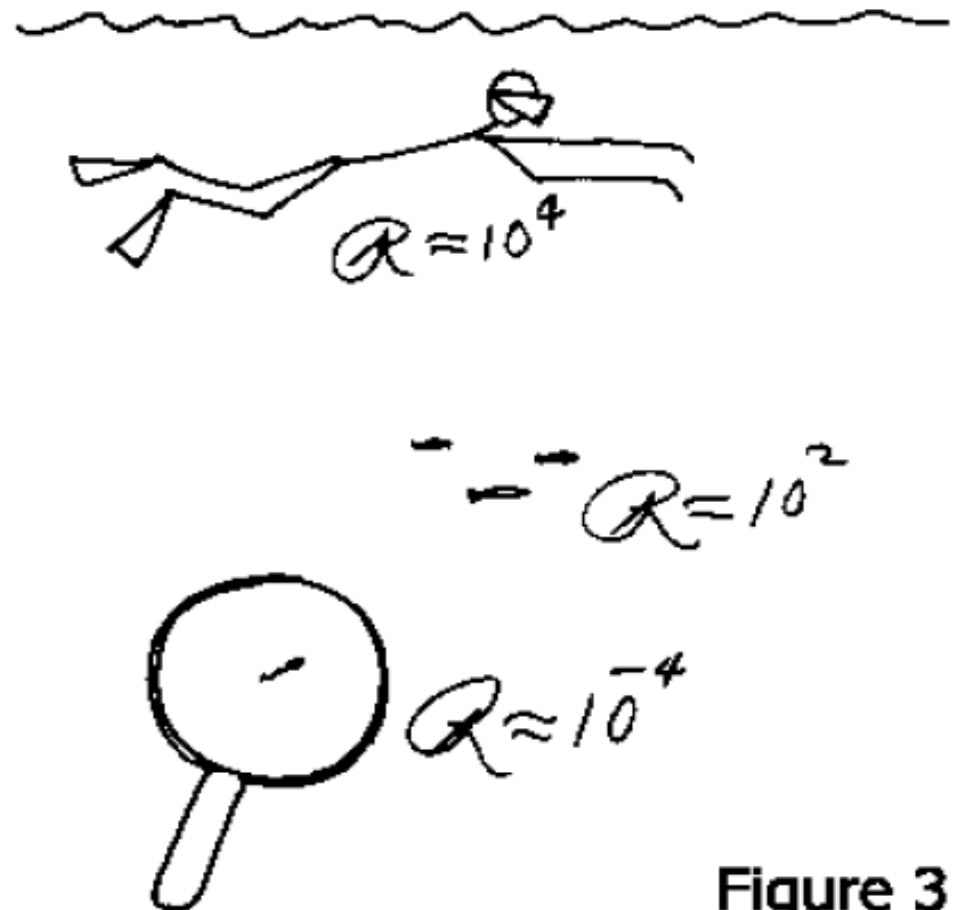


Figure 3



$$\text{Re} = \frac{VL\rho}{\eta}$$

Velocity (typical order of magnitude) V

Diameter (typical size) L

Mass density of the fluid ρ

Viscosity of the fluid η

For water at room temperature $\rho/\eta = 10^6 (\text{m}^2\text{s}^{-1})^{-1}$.

Orders of magnitude for swimmers:

Men, dolphins, sharks: $L=1\text{m}$, $V=1-10 \text{ ms}^{-1}$ $\text{Re}=10^6-10^7$

Bacteria: $L=1\times 10^{-6}\text{m}$, $V=1-10\times 10^{-6} \text{ ms}^{-1}$ $\text{Re}=10^{-6}-10^{-5}$



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Life at Low Reynolds Number

E.M. Purcell

Lyman Laboratory, Harvard University, Cambridge, Mass 02138

June 1976

$$Re = \frac{VL}{\nu}$$



Kinematic viscosity

Water = $10^{-6} \text{ m}^2/\text{s}$

Nutella = $0.1 \text{ m}^2/\text{s}$

	Length	Speed	Reynolds
Men	1.6-1.8 m	1 m/s	10^6 - 10^7
Fish	0.1-1 m	0.01-10 m/s	10^2 - 10^7
Micro-organisms	0.1-1 mm	1 mm/s	1
Sperm cell	10 μm	1-4 mm/min	10^{-3} - 10^{-4}
Bacteria	1 μm	10 $\mu\text{m/s}$	10^{-5} - 10^{-6}

Given $F=6\pi\rho\nu LV$  In a new fluid $V_{\text{visc}} = \frac{\nu_{\text{water}} V_{\text{water}}}{\nu_{\text{visc}}}$

$$Re_{\text{visc}} = \frac{\nu_{\text{visc}}^2}{\nu_{\text{water}}^2} Re_{\text{water}}$$

 Swimming in Nutella corresponds to $Re_{\text{visc}} = 10^{-4}$



Navier - Stokes :

$$-\nabla p + \eta \nabla^2 \vec{v} = \cancel{\rho \frac{\partial \vec{v}}{\partial t}} + \cancel{\rho (\vec{v} \cdot \nabla) \vec{v}}$$

If $Q \ll 1$:

Time doesn't matter. The pattern of motion is the same, whether slow or fast, whether forward or backward in time.

The Scallop Theorem



Figure 6



Scallop theorem

in a flow regime obeying **Stokes equations**, whatever forward motion will be produced by closing the valves, it will be exactly canceled by a backward motion upon reopening them

Micro-motility as a struggle against the scallop theorem



www.youtube.com/watch?v=51-6QCJTAjU



High Reynolds: www.youtube.com/watch?v=4h079P7qRSw



Low Reynolds: www.youtube.com/watch?v=2kkfHj3LHeE



Low Reynolds (spiral): www.youtube.com/watch?v=s_5ygWhcxKk



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Life at Low Reynolds Number

E.M. Purcell

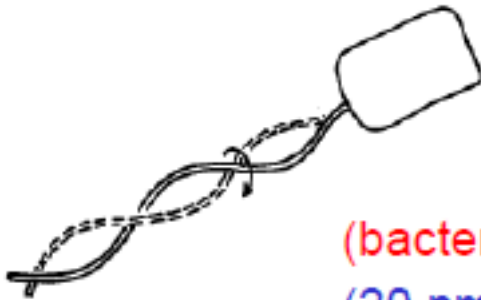
Lyman Laboratory, Harvard University, Cambridge, Mass 02138

June 1976



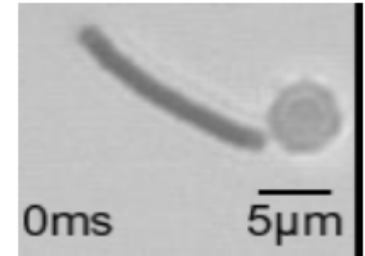
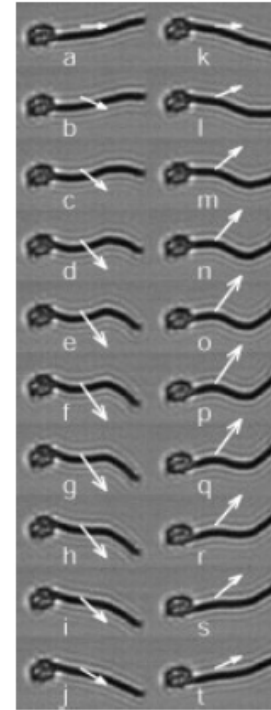
(eukaryotic flagella, cilia)

(bending of 9+2 μ -tubule bundles)



(bacterial flagella)

(20 nm rotary motor)



red blood cell + flexible magnetic filament

J. Bibette, H. Stone et al.: Nature (2005)

www.rowland.harvard.edu/labs/bacteria/movies/



Nematode: <https://www.youtube.com/watch?v=hHSbdbQHk9M>



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Types of motions



3-sphere swimmer

www.youtube.com/watch?v=B7F7CvHrEHs

Najafi, Golestanian, *Phys. Rev. E* **69**, 062901 (2004)



Race

www.youtube.com/watch?v=aN6I9mJVuas



Final aim

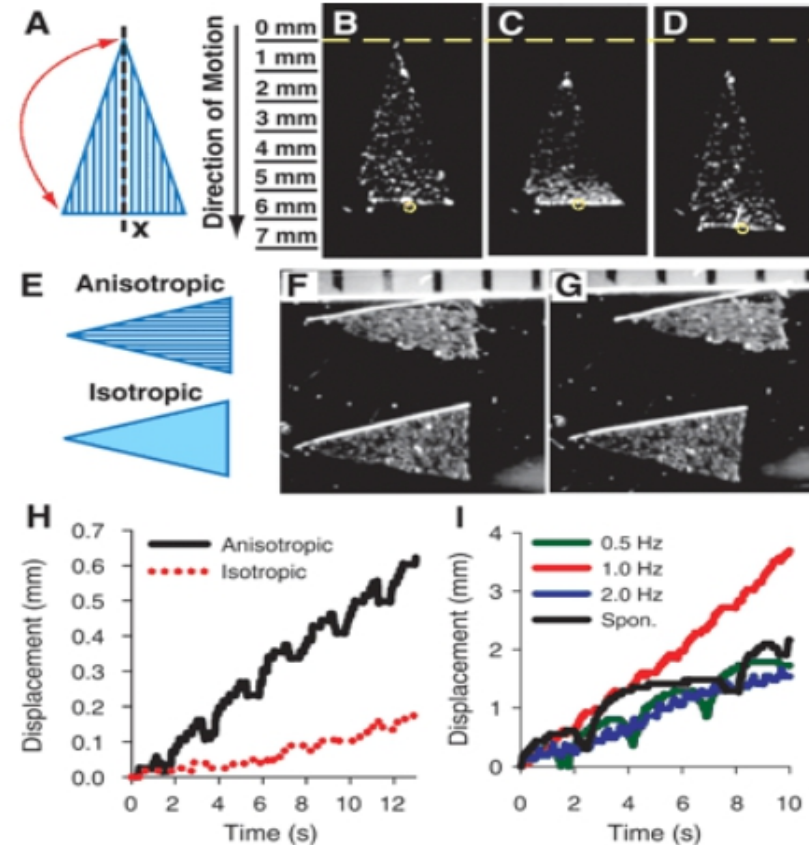
www.youtube.com/watch?v=VRMEtCCDR_E



Moving films

www.youtube.com/watch?v=qcebMTFmzUY

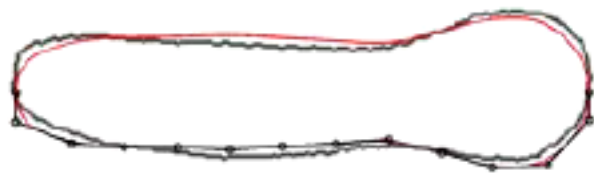
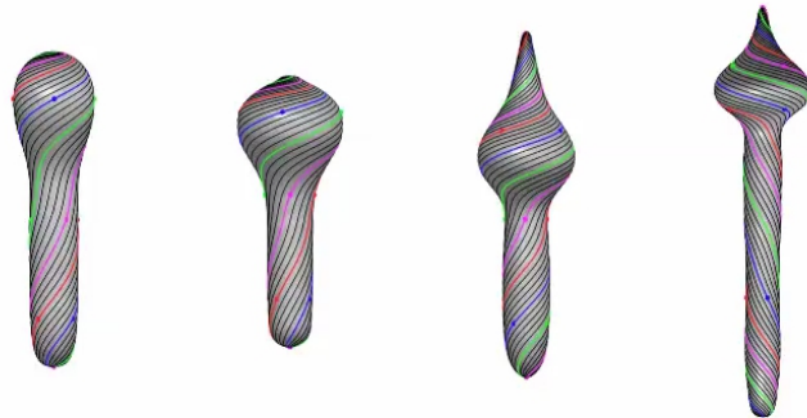
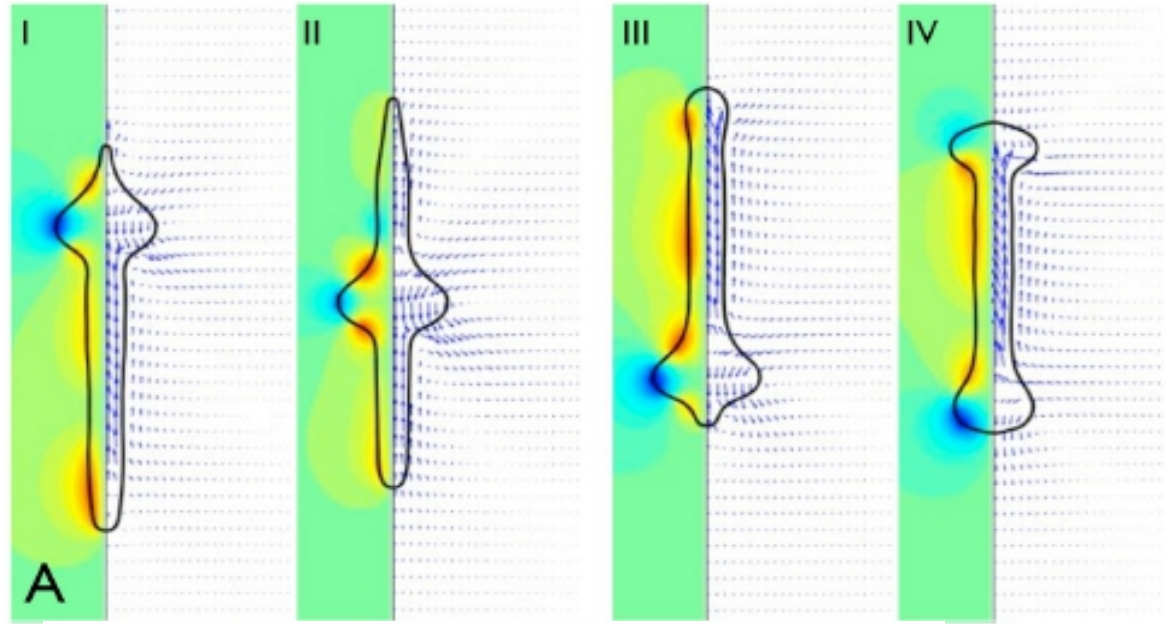
www.youtube.com/watch?v=v0vMp0T6kvI



polymer film + muscle cells

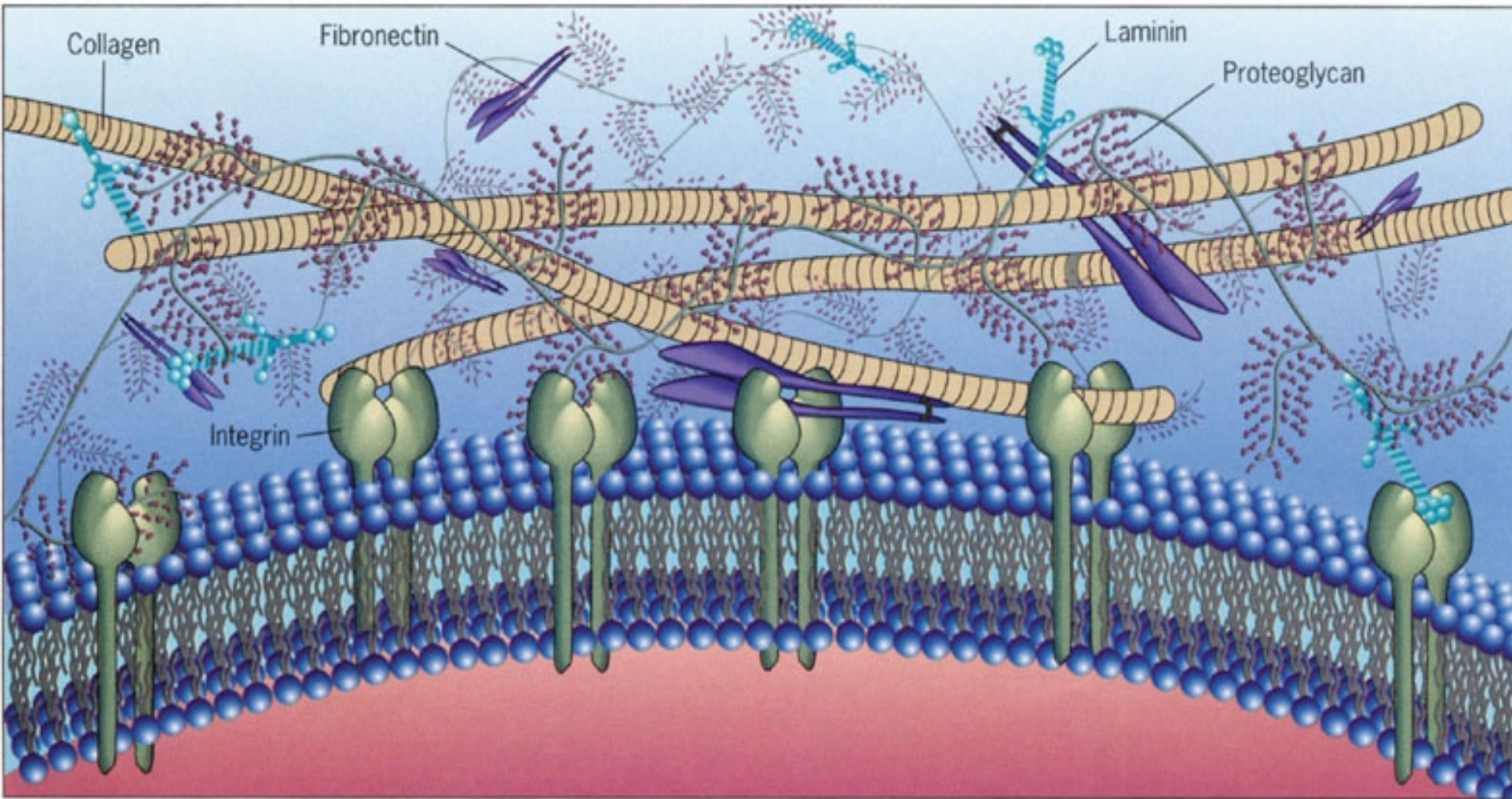
G. Whitesides et al., *Science* (2007)

Euglenoid motion



Arroyo, Milan, Heltai, De Simone,
PNAS **109**, 1784-1789 (2012)

Extra-cellular matrix



Extra-cellular matrix

Heart

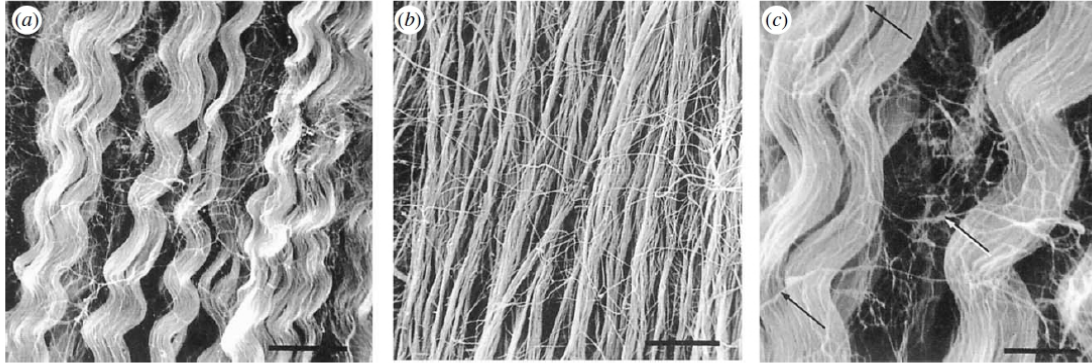
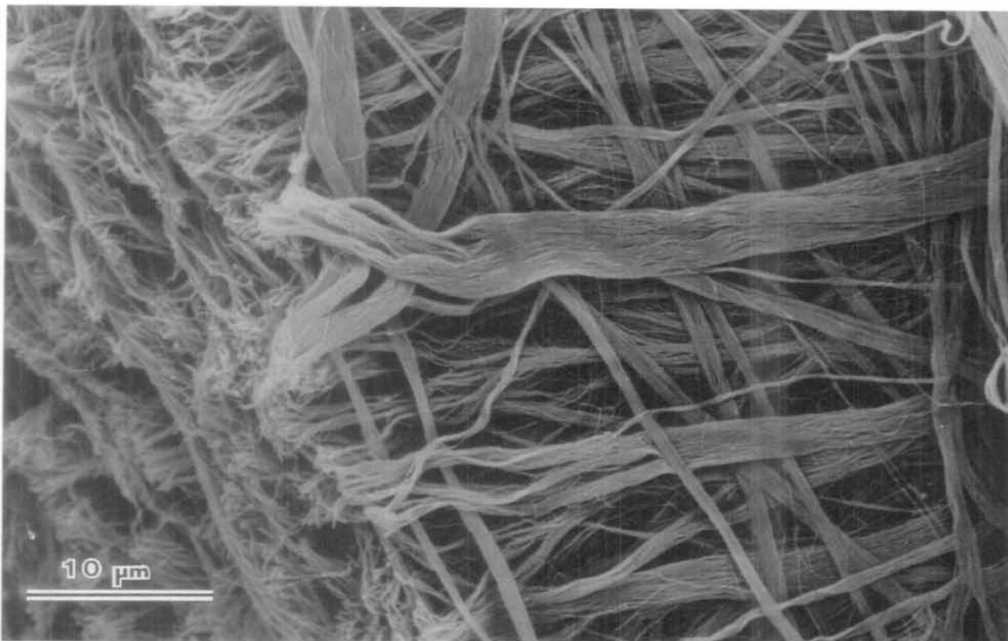
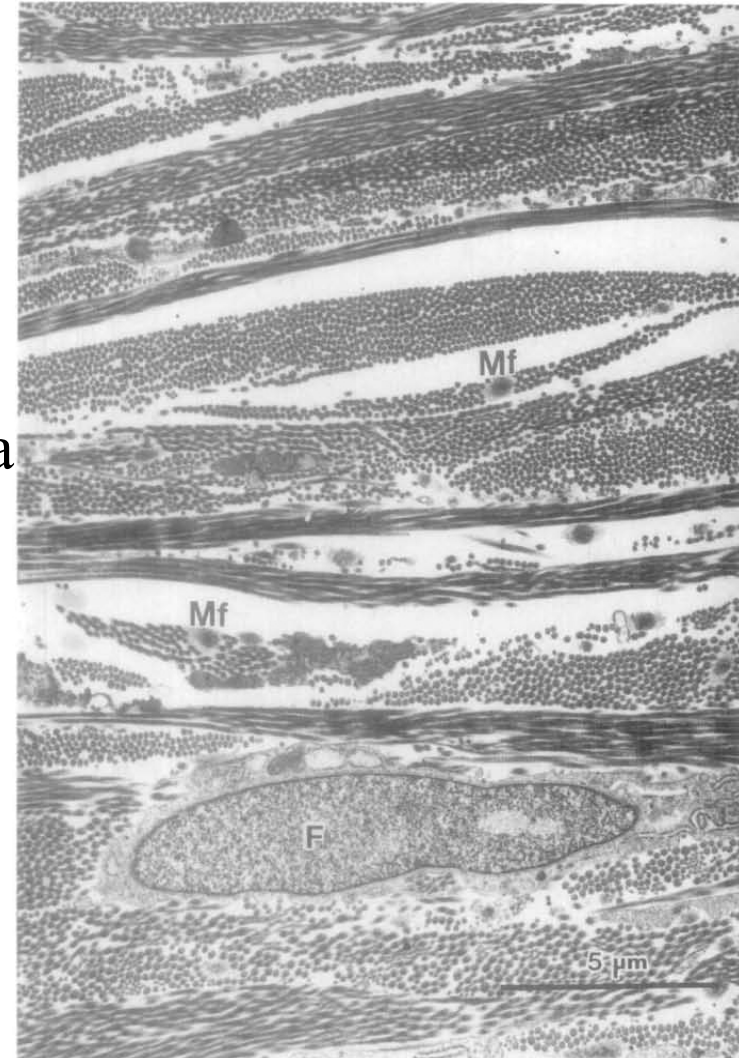


Figure 11. Electron micrograph of the arrangement of collagenous fibrils of the lamina radialis of an aortic valve leaflet at different magnifications. Arrows indicate non-directional fibrils surrounding helical arranged collagenous fibrils. (a,b) Scale bars, 8 μm and (c) 3 μm (adapted from Fastenrath 1995, p. 43).



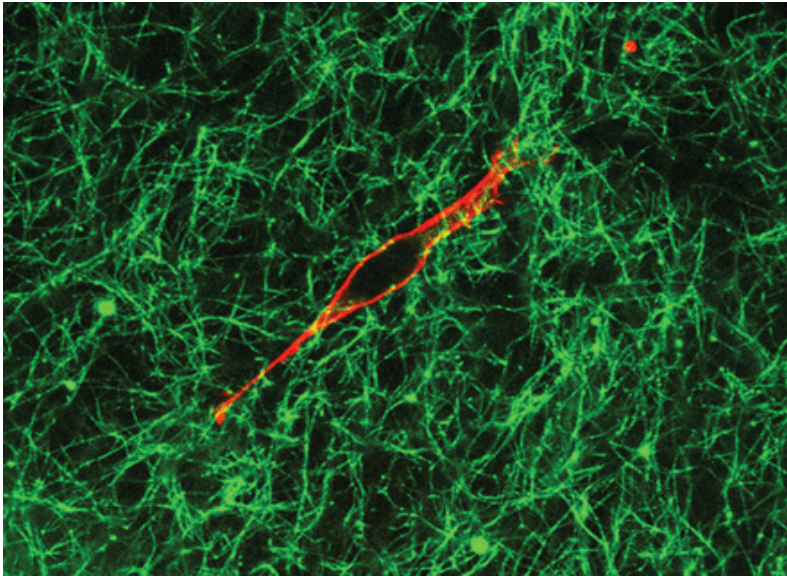
Sclera





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Cell motion in dense ECM



(P. Friedl, K. Wolf)



HT1080 migration in rat tail collagen (1.7 mg/ml)
in presence of MMP inhibitor



Neutrophil migration in rat tail collagen (1.7 mg/ml)
in presence of IL-8

Cell motion in dense ECM

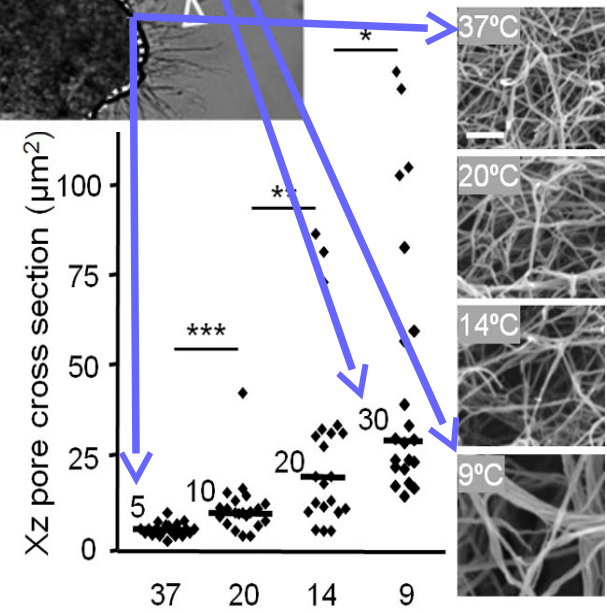
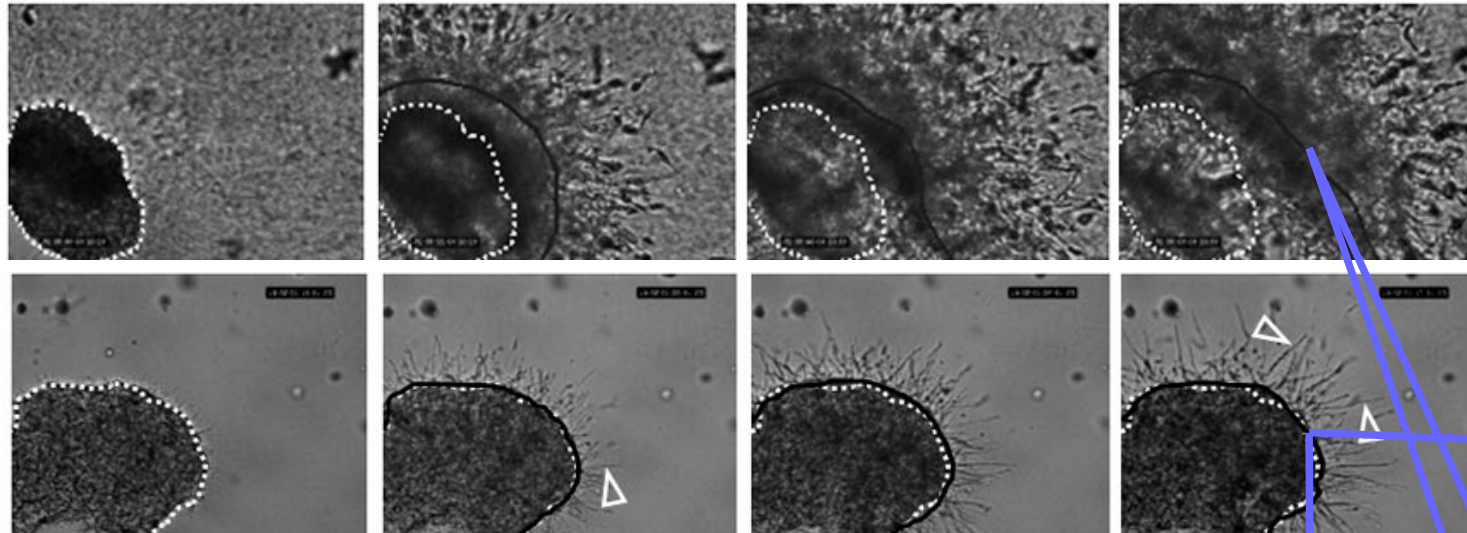
Rat tail

0h

6h

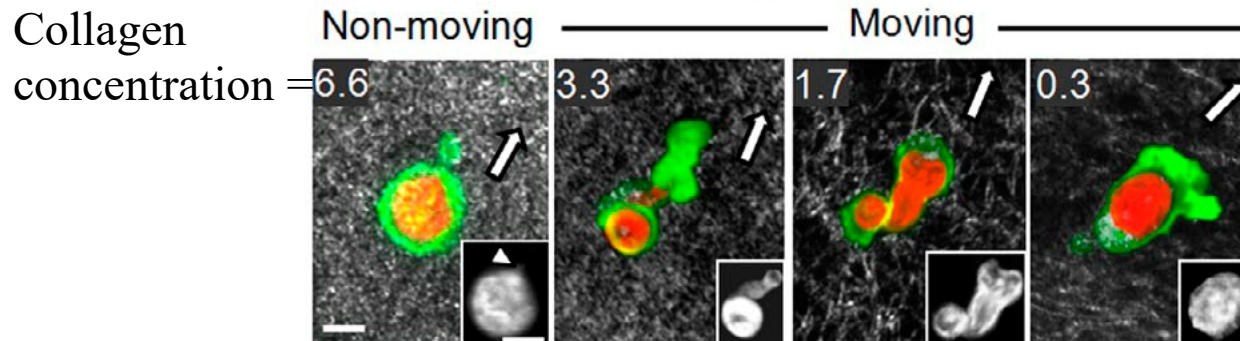
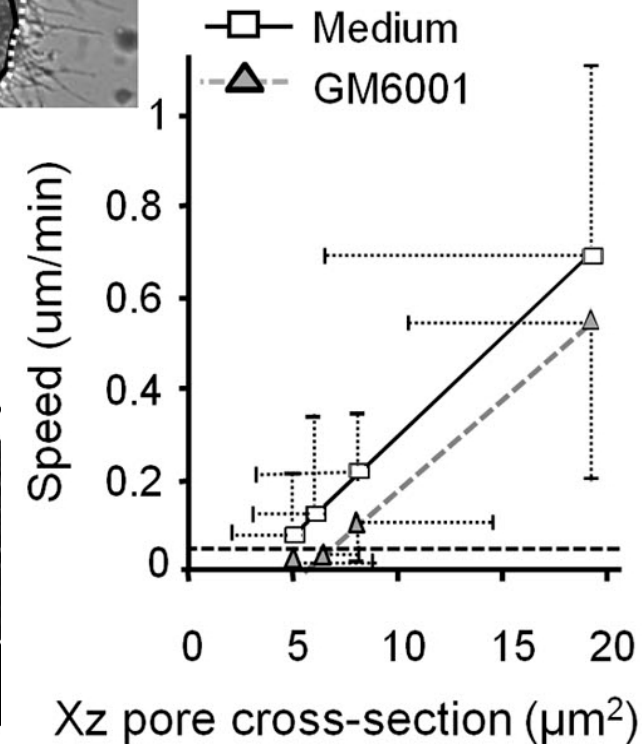
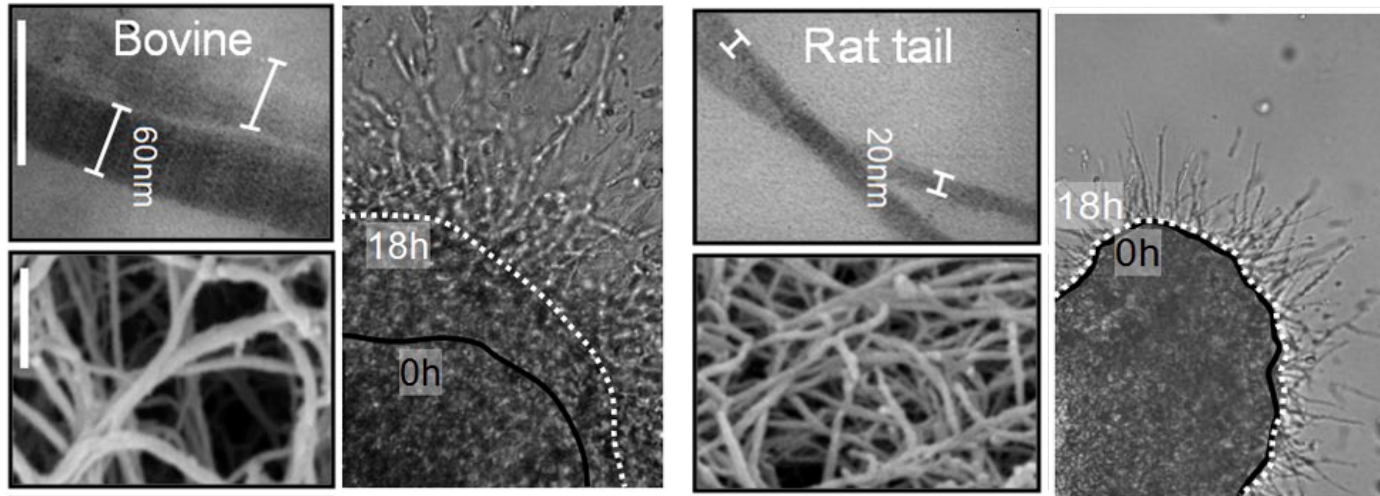
12h

18h



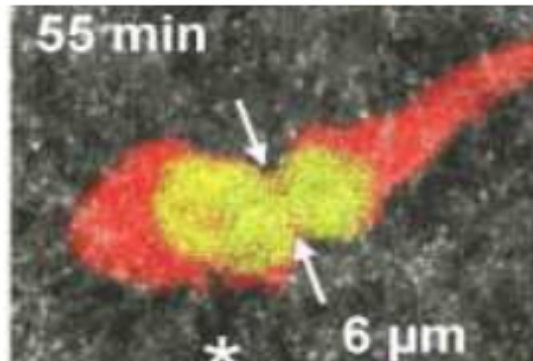
Wolf, te Lindert, Krause, Alexander, te Riet,
Wills, Hoffman, Figdor, Weiss, Friedl
J. Cell Biol. **201**, 1069-1084 (2013)

Cell motion in dense ECM

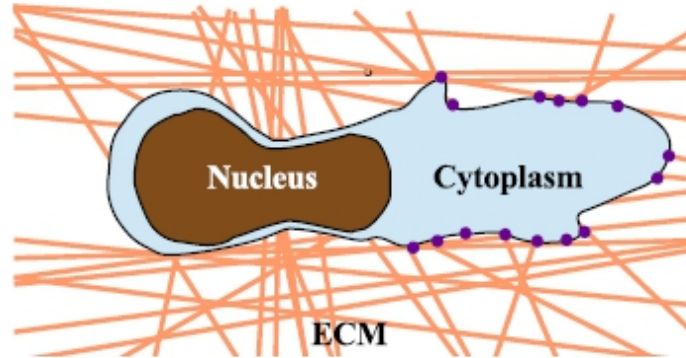


Taking into account of the nucleus

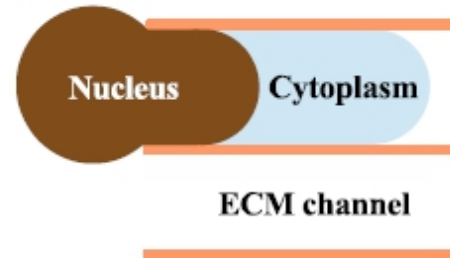
BIOLOGICAL
EXPERIMENT



BIOLOGICAL
REPRESENTATION

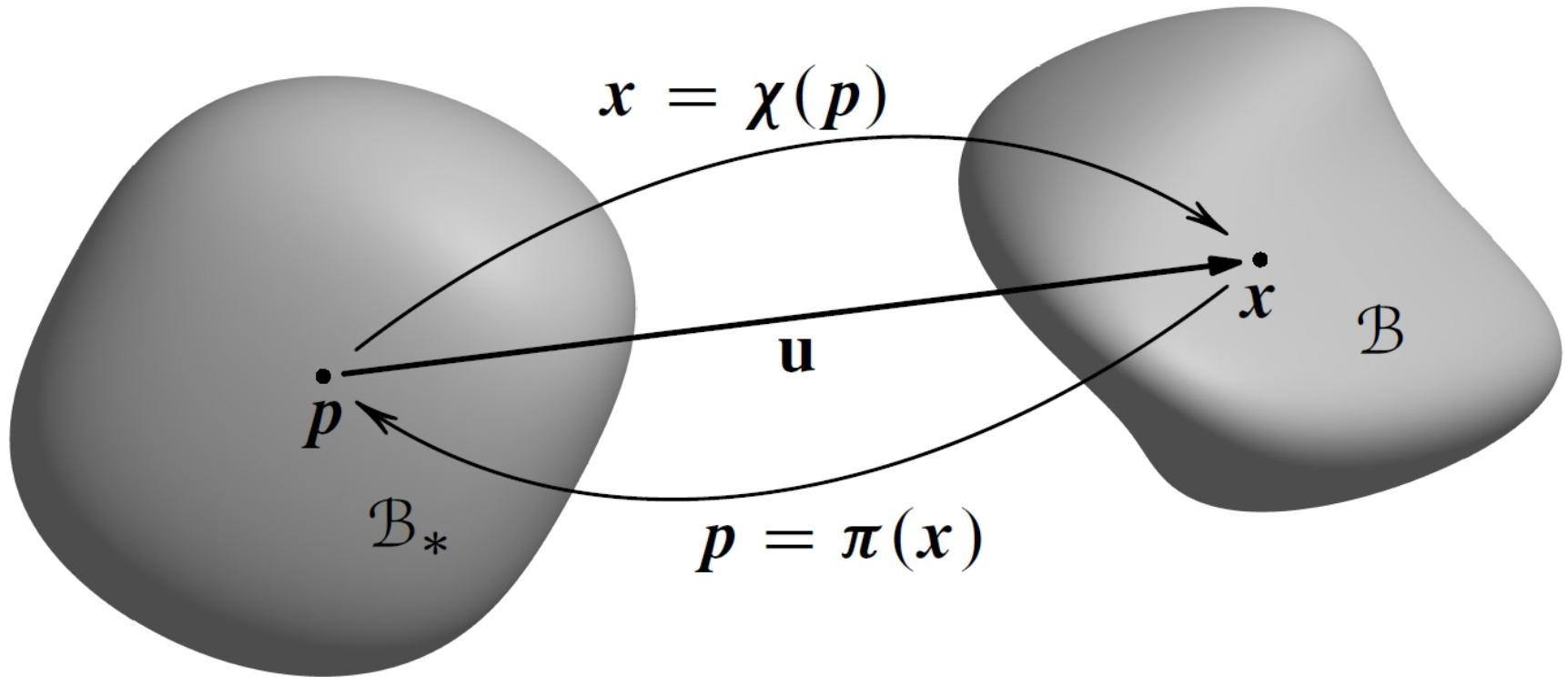


MATHEMATICAL
REPRESENTATION

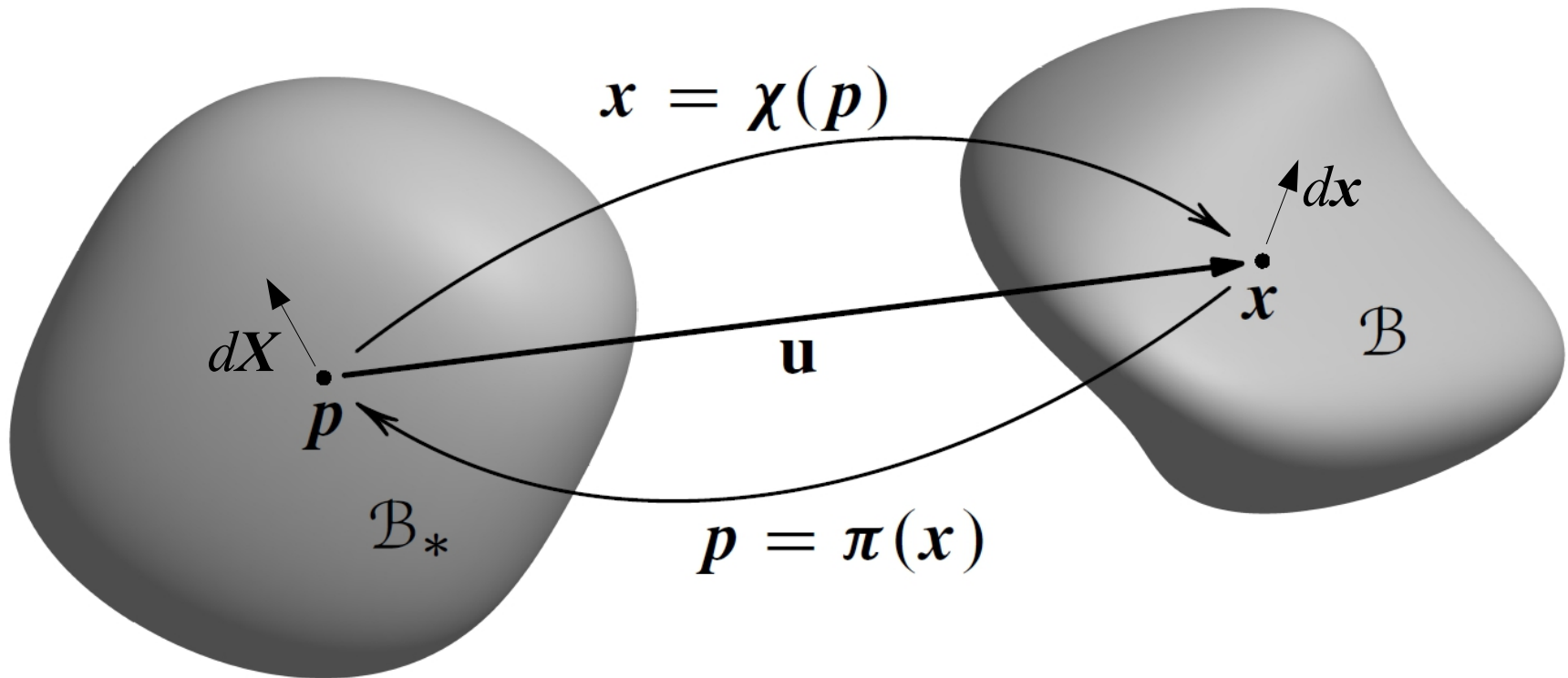


Work done by traction > Energy required to squeeze the nucleus

Continuum mechanics in a nutshell



Continuum mechanics in a nutshell

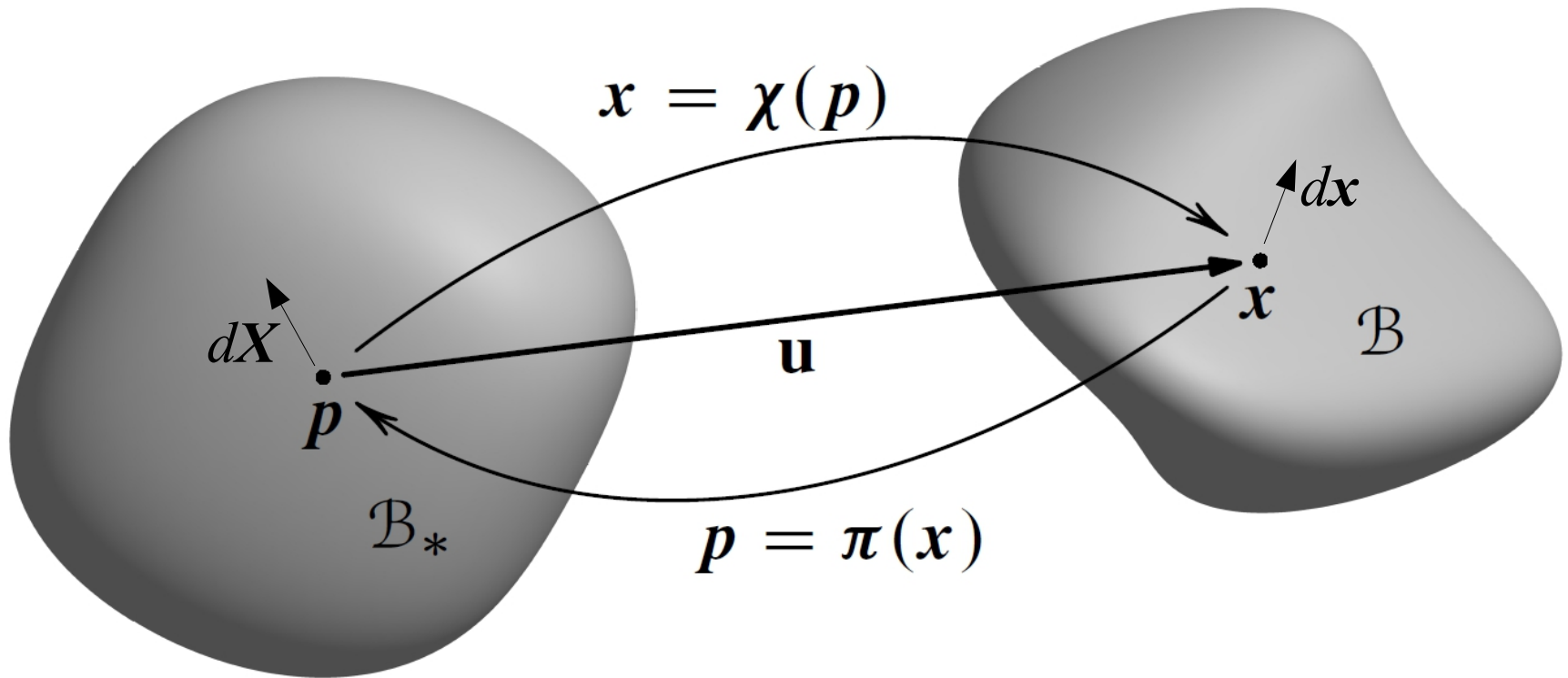


$$d\mathbf{x} = \mathbf{F} d\mathbf{X}$$

$$F_{iK} = \frac{\partial \chi_i}{\partial X_K}$$

Deformation gradient

Continuum mechanics in a nutshell



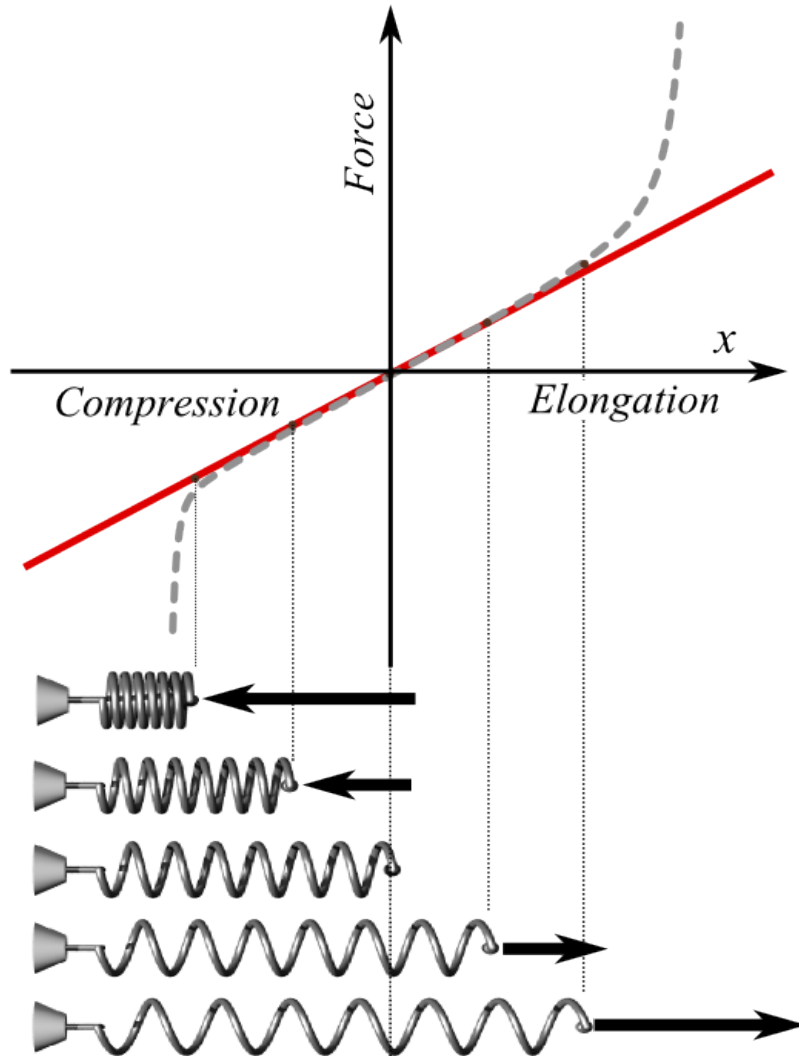
$$d\mathbf{x} = \mathbf{F} d\mathbf{X}$$

Cauchy-Green deformation tensor

$$|d\mathbf{X}|^2 = d\mathbf{x} \cdot \mathbf{B}^{-1} d\mathbf{x}$$

$$\mathbf{B} = \mathbf{F}\mathbf{F}^T$$

Continuum mechanics in a nutshell



The force field is conservative



The work is independent on the path



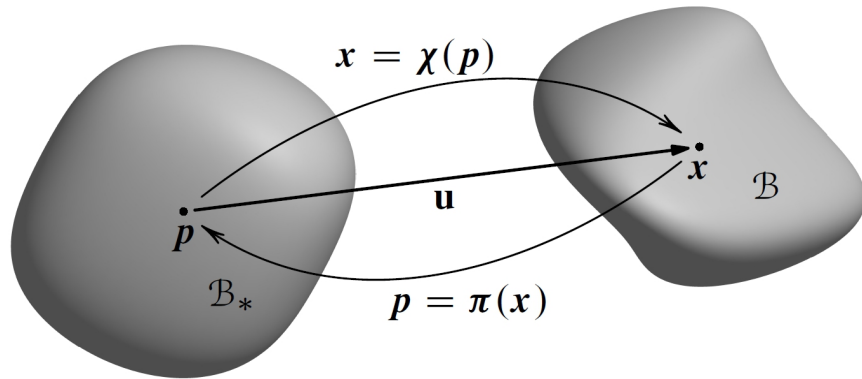
There exists a potential energy

$$U(\mathbf{x})$$

related to the elastic force $\mathbf{f}$ by

$$\mathbf{f} = -\nabla U$$

Continuum mechanics in a nutshell



The force field is conservative



The work is independent on the path



There exists a potential energy

$$W(\mathbf{F}) = \rho_* \sigma(\mathbf{F})$$

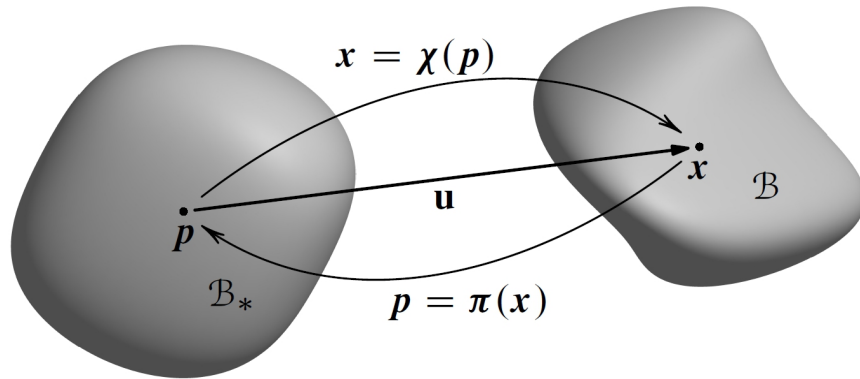
related to the Piola stress tensor $\mathbf{S}$ by

$$\mathbf{S} = \frac{\partial W}{\partial \mathbf{F}}$$

and related to the Cauchy stress tensor $\mathbf{T}$ by

$$\mathbf{T}(\mathbf{F}) = \rho \frac{\partial \sigma}{\partial \mathbf{F}} \mathbf{F}^T$$

Continuum mechanics in a nutshell



The force field is conservative



The work is independent on the path



There exists a potential energy

$$W(\mathbf{F}) = \rho_* \sigma(\mathbf{F})$$

Frame indifference + isotropy $\Rightarrow \sigma = \bar{\sigma}(\mathbf{I}_B, \mathbf{II}_B, \mathbf{III}_B)$

e.g., neo-Hookean material

$$W(\mathbf{I}_B) = \frac{\mu}{2}(\mathbf{I}_B - 3)$$

$$\mathbf{T} = -p\mathbf{I} + \mu\mathbf{B}$$

Continuum mechanics in a nutshell

neo-Hookean material

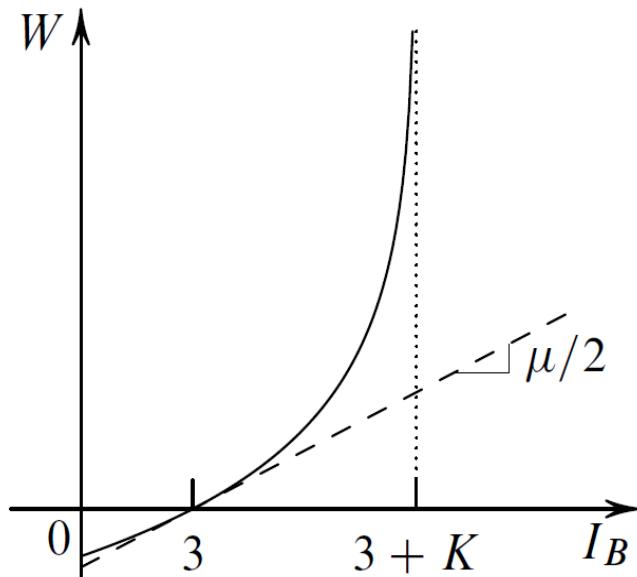
$$W(I_B) = \frac{\mu}{2}(I_B - 3)$$

$$\mathbf{T} = -p\mathbf{I} + \mu\mathbf{B}$$

Gent material

$$W(I_B) = -\frac{\mu}{2}K \ln \left(1 - \frac{I_B - 3}{K} \right)$$

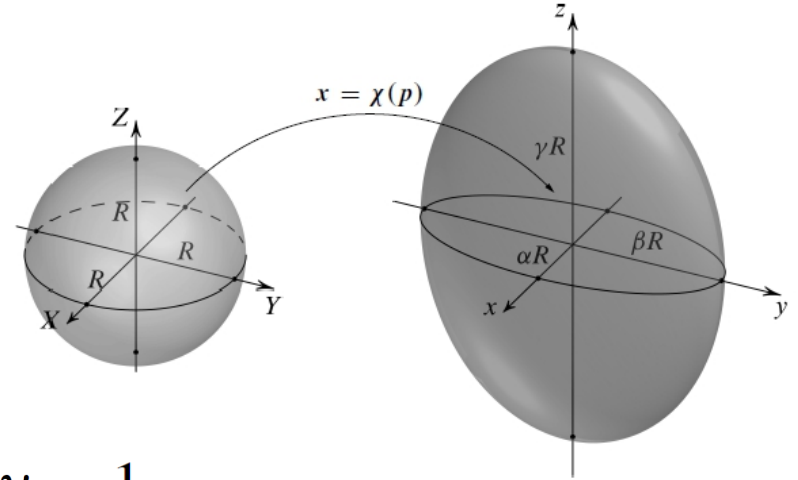
$$\mathbf{T} = -p\mathbf{I} + \frac{\mu}{1 - \frac{I_B - 3}{K}}\mathbf{B}$$



— Gent
- - - Neo-Hookeano

Pure extension

$$\begin{cases} x = \alpha X \\ y = \beta Y \\ z = \gamma Z \end{cases} \quad \mathbf{F} = \begin{bmatrix} \alpha & 0 & 0 \\ 0 & \beta & 0 \\ 0 & 0 & \gamma \end{bmatrix}$$



Incompressibility $\implies J = \det \mathbf{F} = \alpha\beta\gamma = 1$

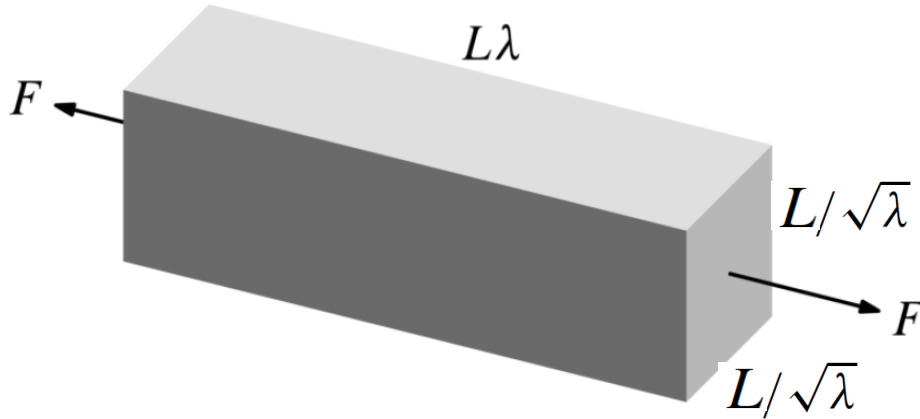
$$\mathbf{B} = \mathbf{F}\mathbf{F}^T = \begin{bmatrix} \alpha^2 & 0 & 0 \\ 0 & \beta^2 & 0 \\ 0 & 0 & \gamma^2 \end{bmatrix}$$

$$\mathbf{T} = -p\mathbf{I} + h_1\mathbf{B} + h_{-1}\mathbf{B}^{-1}$$

$$h_{\pm 1} = h_{\pm 1}(I_B, I_{B^{-1}})$$

neo-Hookean material $h_1 = \mu \quad h_{-1} = 0$

Uniaxial extension



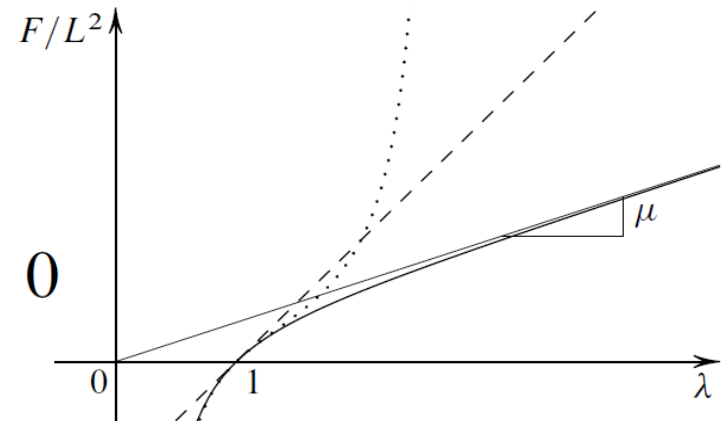
$$\mathbf{F} = \begin{bmatrix} \lambda & 0 & 0 \\ 0 & 1/\sqrt{\lambda} & 0 \\ 0 & 0 & 1/\sqrt{\lambda} \end{bmatrix}$$

$$\mathbf{T} = -p\mathbf{I} + h_1\mathbf{B} + h_{-1}\mathbf{B}^{-1}$$

$$\begin{cases} T_{11} = -p + h_1\lambda^2 + h_{-1}\lambda^{-2} = \frac{F}{L^2}\lambda \\ T_{22} = T_{33} = -p + h_1/\lambda + h_{-1}\lambda = 0 \end{cases}$$

neo-Hookean material $h_1 = \mu$ $h_{-1} = 0$

$$\frac{F}{L^2} = \mu \left(\lambda - \frac{1}{\lambda^2} \right)$$

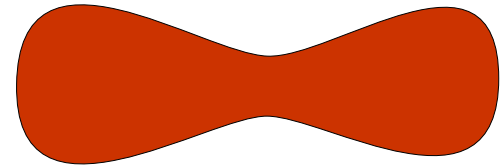
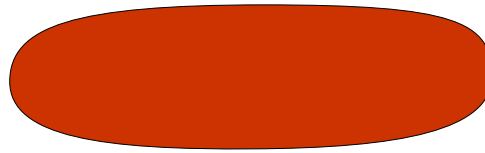
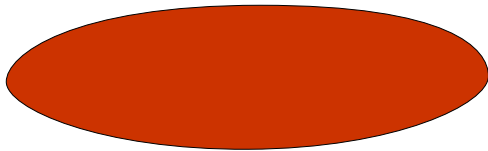


----- Hooke
———— Neo-Hookeano
..... Gomma vulcanizzata

Computing the energy required

Work done by traction $>$ Energy required to squeeze the nucleus

- Given the deformation $\mathbf{F}$

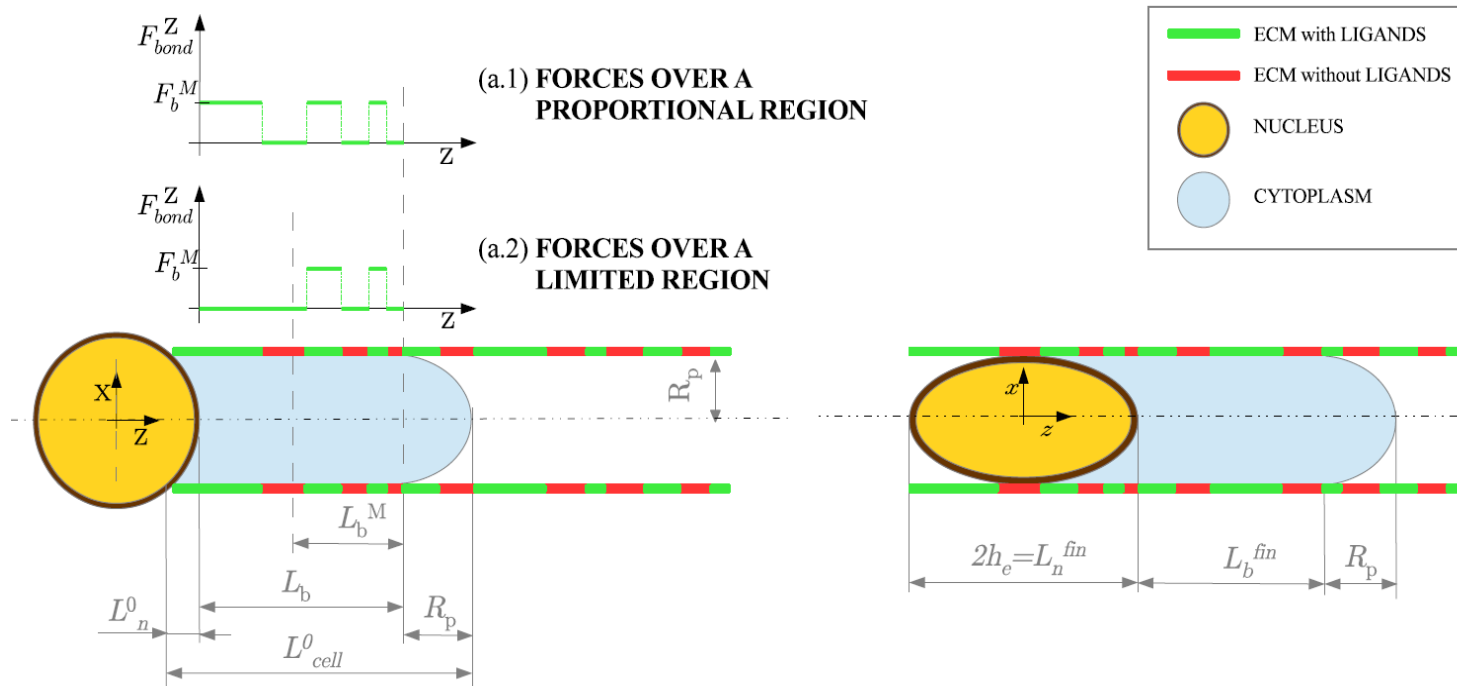


- Given the constitutive equation W

- Compute $\mathbf{B}$ and then, for instance, $W(I_{\mathbf{B}}) = \frac{\mu}{2}(I_B - 3)$

Computing the work done by traction

Work done by traction > Energy required to squeeze the nucleus



$$\mathbf{F}_{adhesion} = \int_S \rho_b(\mathbf{X}) \alpha_{ECM}(\mathbf{X}) \mathbf{F}_{bond}(\mathbf{X}) dS$$

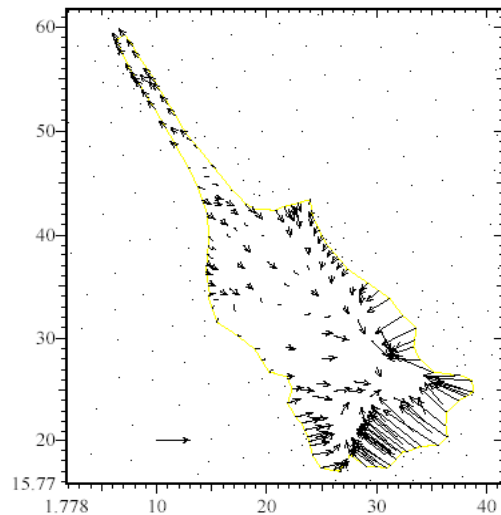
$$\mathcal{W}_{adhesion} = F_{adhesion}^Z \Delta L$$

Cell traction

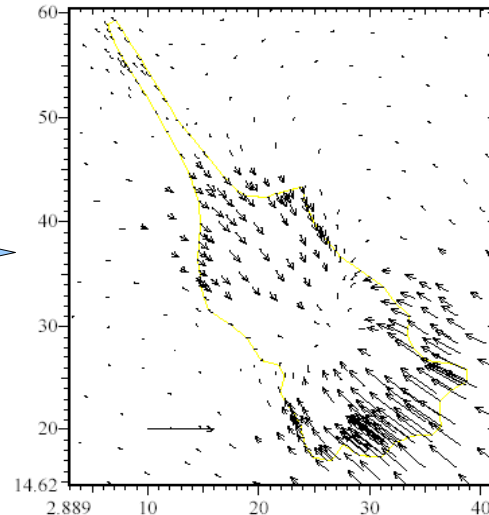
The classical (direct) problem in elasticity:

Given the stress $\mathbf{f}$, find the deformation $\mathbf{u}$ of the substratum such that

$$\left. \begin{aligned} A\mathbf{u} &= \mathbf{f}, & \mathbf{u}|_{\partial\Omega} &= 0, \\ A\mathbf{u} &= -\mu\Delta\mathbf{u} - (\mu + \lambda)\nabla(\nabla \cdot \mathbf{u}) \end{aligned} \right\} \mathcal{S}: \mathbf{f} \rightarrow \mathbf{u}$$



Direct

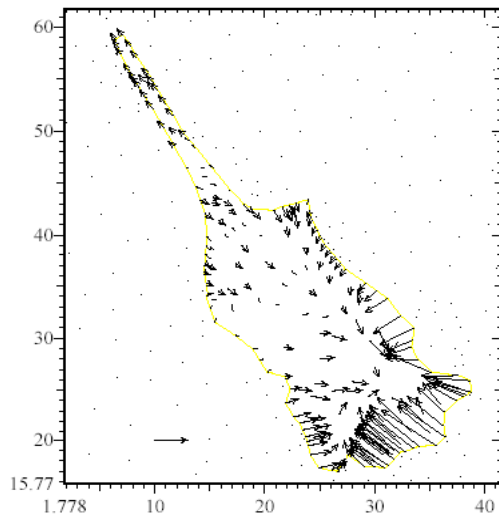


Cell traction

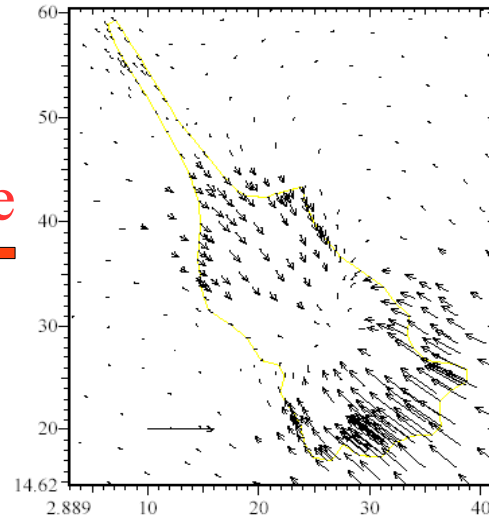
The classical (direct) problem in elasticity:

Given the stress $\mathbf{f}$, find the deformation $\mathbf{u}$ of the substratum such that

$$\left. \begin{aligned} A\mathbf{u} &= \mathbf{f}, & \mathbf{u}|_{\partial\Omega} &= 0, \\ A\mathbf{u} &= -\mu\Delta\mathbf{u} - (\mu + \lambda)\nabla(\nabla \cdot \mathbf{u}) \end{aligned} \right\} \mathcal{S}^{-1}: \mathbf{u} \rightarrow \mathbf{f}$$



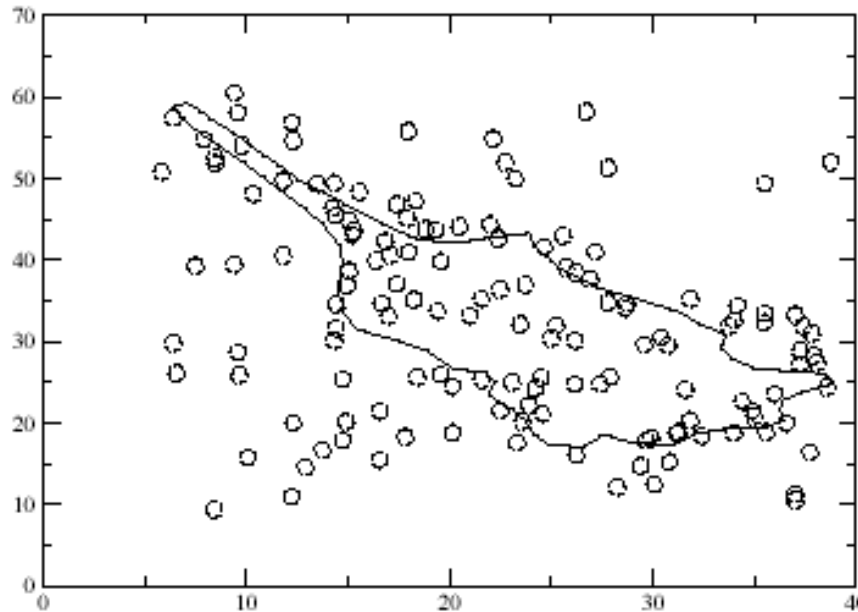
Inverse



Cell traction

deformation

Ω is the whole domain,
 Ω_0 is the subdomain where $\mathbf{u}$ is measured,
 Ω_c is the area covered by the cell.



(A. Cavalcanti)

Where are the forces exerted in Ω_c ?

What is their magnitude?

D. Ambrosi
J. Math. Biol. **58**, 163 (2009)



The inverse problem

Set of forces acting on Ω_c with null resultant and momentum

The penalty functional $\mathcal{J} : F \rightarrow \mathbb{R}^+$ is defined as:

$$\mathcal{J}(g) = \frac{1}{2} \| \mathcal{O} S g - u_0 \|_X^2 + \frac{\varepsilon}{2} \| g \|_F^2$$

Take the smallest
force possible

Compute the deformation
for a given virtual force

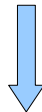
Measured deformation

Evaluate the computed deformation
in the measurement points

The inverse problem

The penalty functional $\mathcal{J} : F \rightarrow \mathbb{R}^+$ is defined as:

$$\mathcal{J}(\mathbf{g}) = \frac{1}{2} \|\mathcal{O}\mathcal{S}\mathbf{g} - u_0\|_{\chi}^2 + \frac{\varepsilon}{2} \|\mathbf{g}\|_F^2.$$

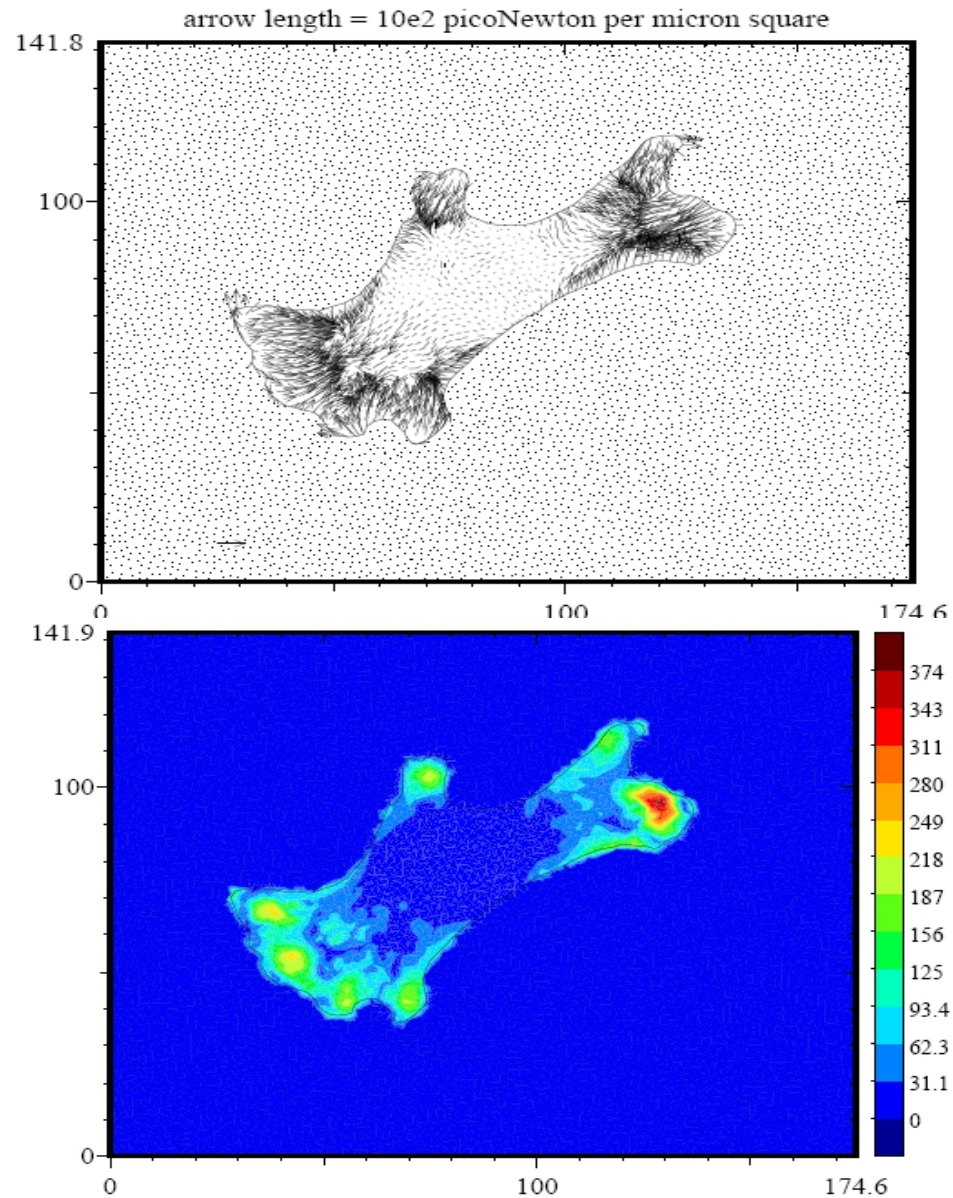
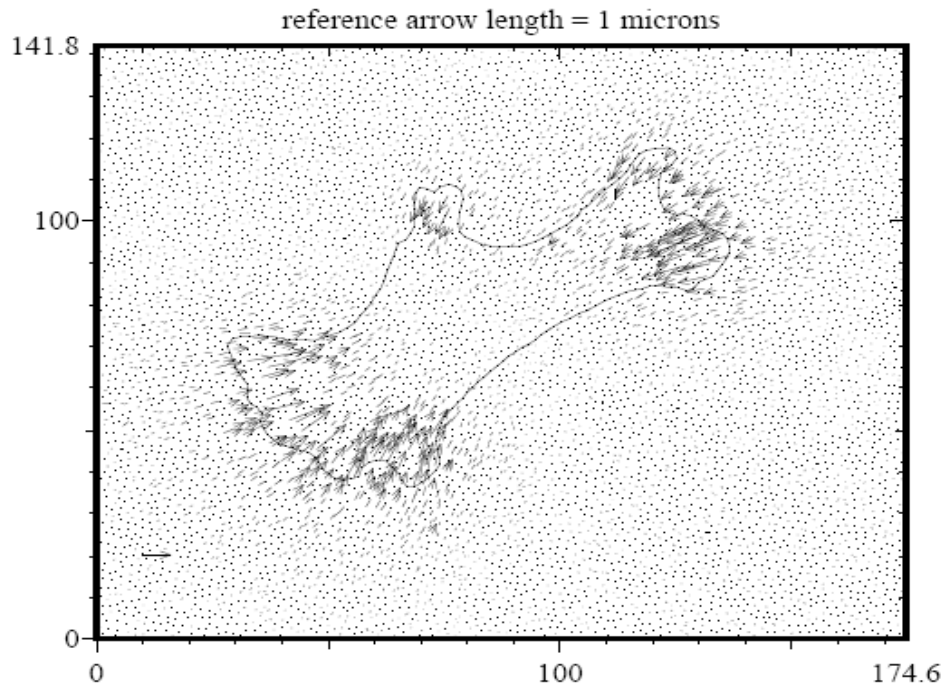


Two coupled sets of elliptic partial differential equations to be solved in Ω ,

$$\begin{aligned} -\hat{\mu}\Delta\mathbf{u} - (\hat{\mu} + \hat{\lambda})\nabla(\nabla \cdot \mathbf{u}) &= -\frac{\chi_c}{\varepsilon}\mathbf{p}, & \mathbf{u}|_{\partial\Omega} &= 0, \\ -\hat{\mu}\Delta\mathbf{p} - (\hat{\mu} + \hat{\lambda})\nabla(\nabla \cdot \mathbf{p}) &= \chi_o\mathbf{u} - \mathbf{u}_0, & \mathbf{p}|_{\partial\Omega} &= 0. \end{aligned}$$

where χ_c and χ_o are the characteristic functions related to Ω_c and Ω_0 , respectively.

Traction force microscopy



Cell traction

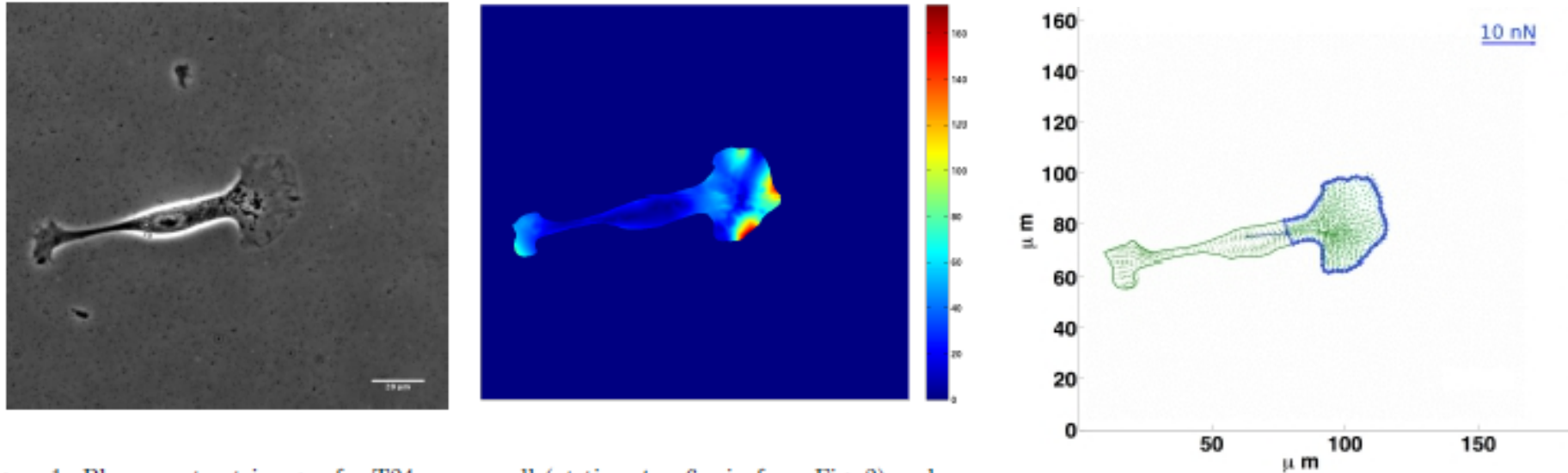
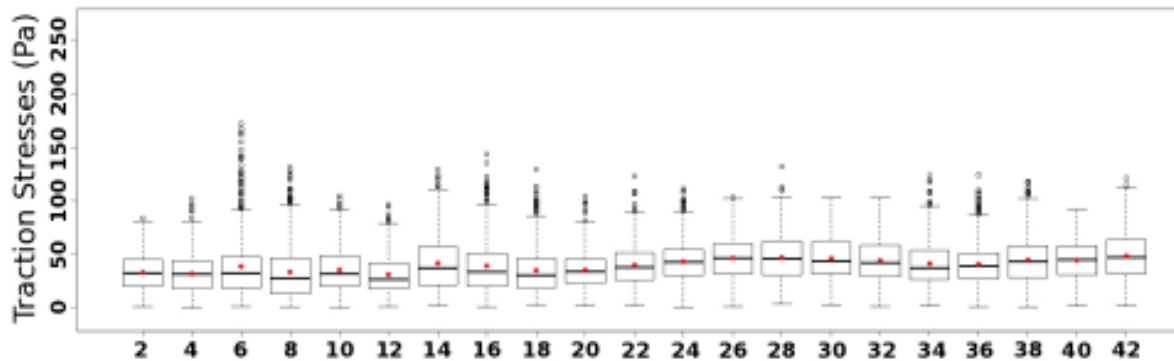
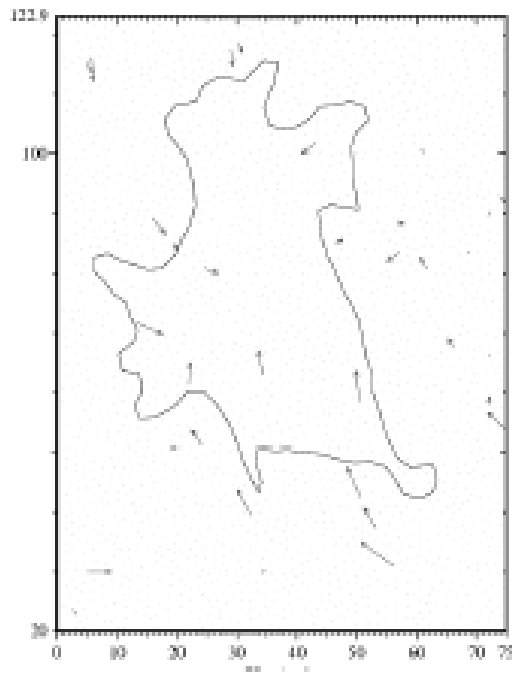
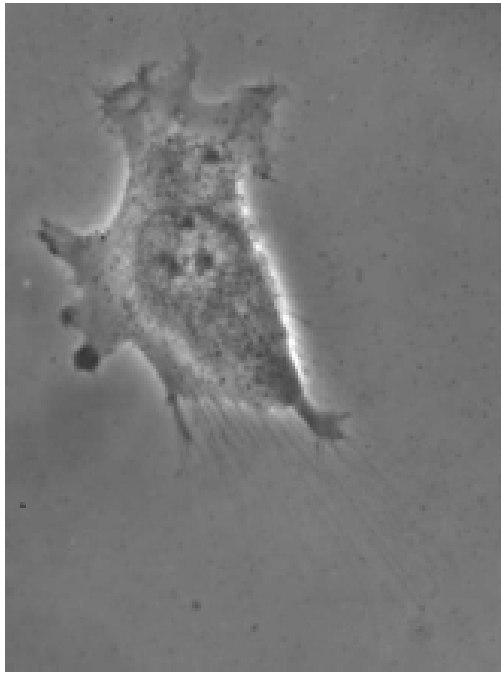


Figure 1: Phase-contrast image of a T24 cancer cell (at time $t = 6$ min from Fig. 2) and corresponding traction field of a T24 cell represented as a color map. The color scale for stresses reads in Pascal (Pa).



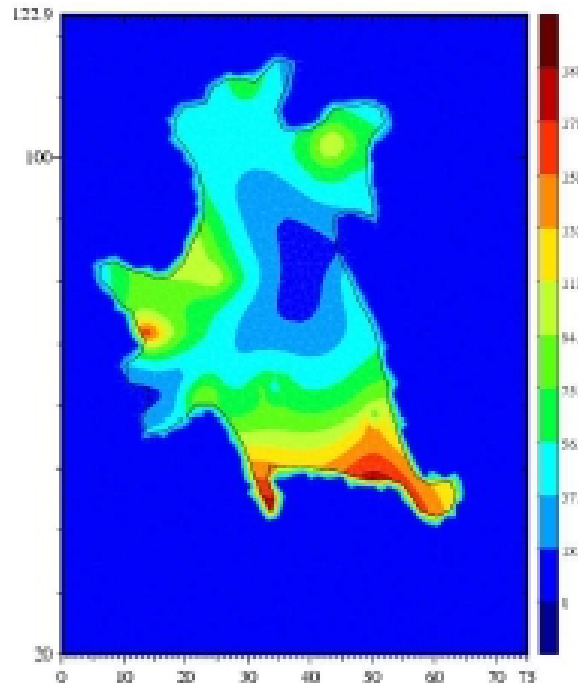
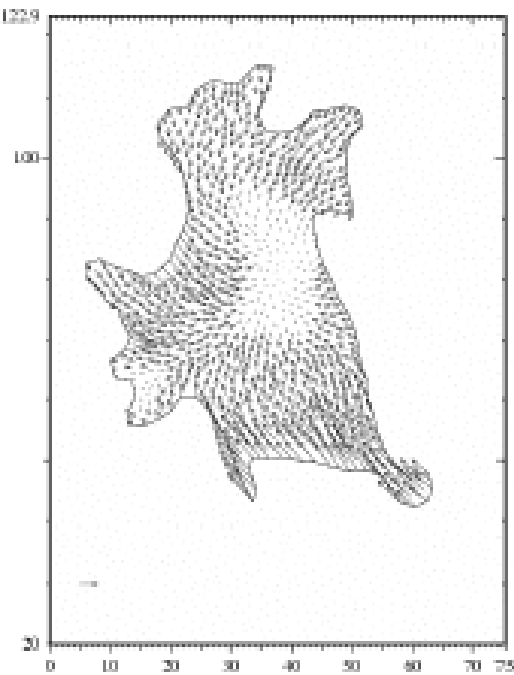
V. Peschetola et al.
Comp. Methods Biomech. Biomed.
Engng. **14**, 159-160 (2011).



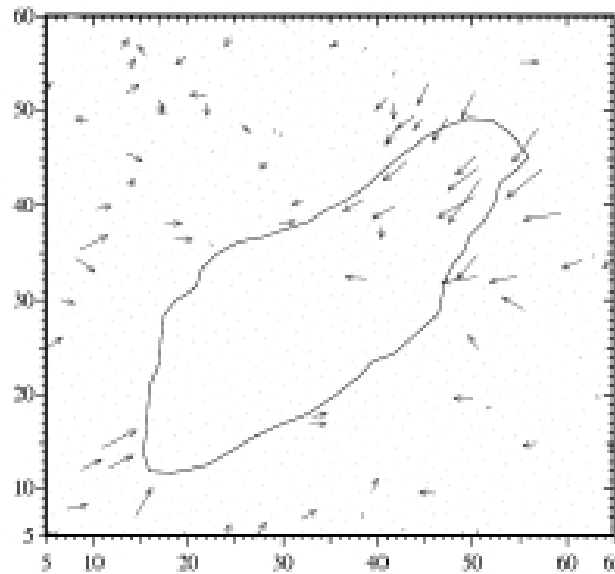
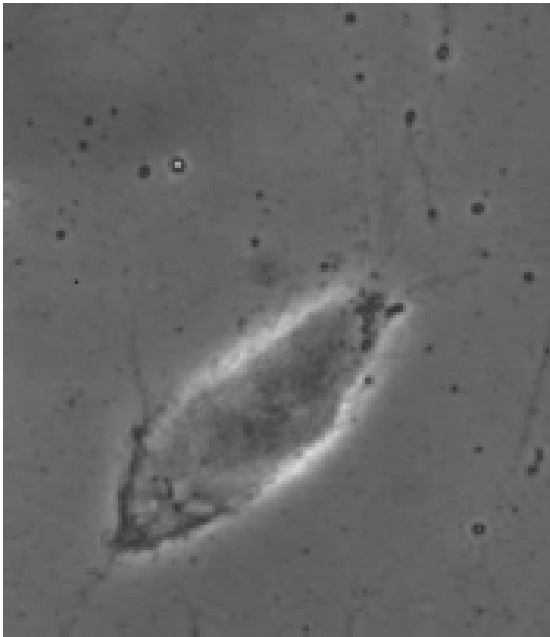
Traction on a stiff gel

Ambrosi, Peschetola, Verdier
SIAM J. Appl. Math, (2006)

T24 cancer cells



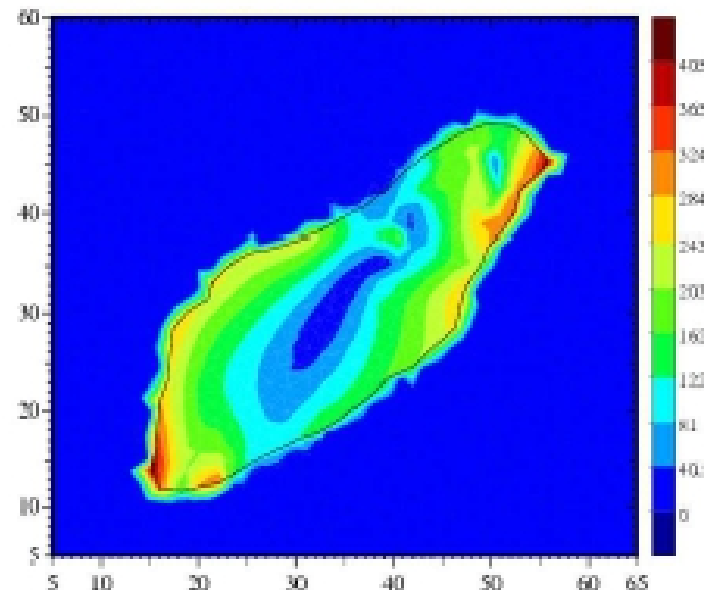
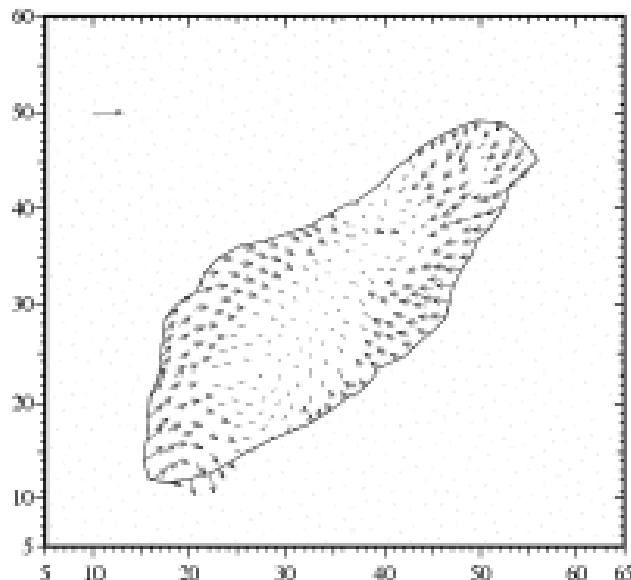
Traction on softer gel



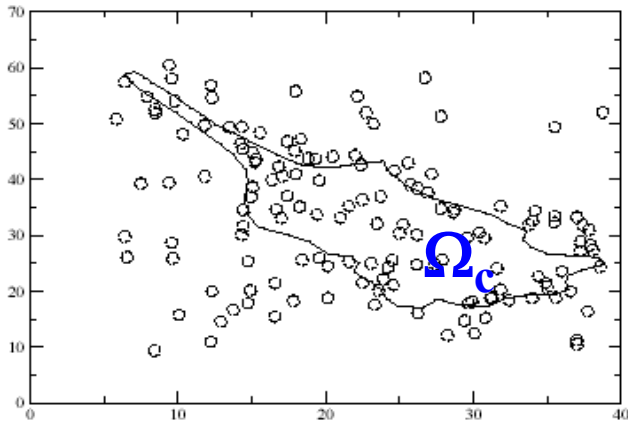
T24 cancer cells

Conclusions

- minor traction ability than fibroblasts
- larger forces on stiffer gels



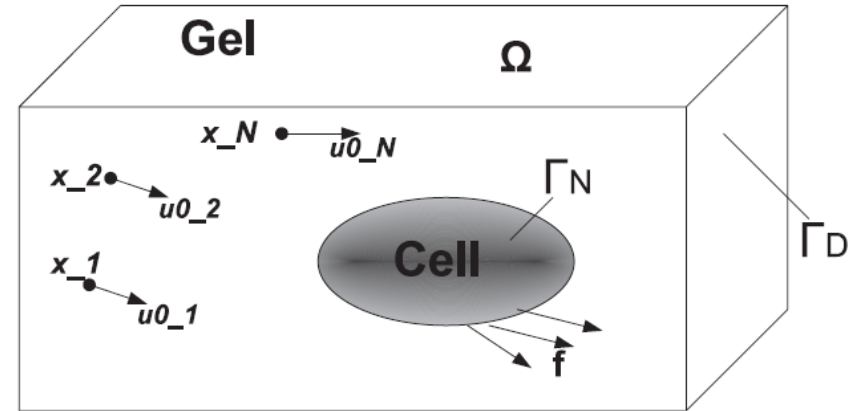
Traction in 3D



2D

Differences

- Measurements everywhere
(even below the cell or
“inside” the cell domain Ω_c)
- Forces below the cell or
“inside” the cell domain Ω_c)



3D

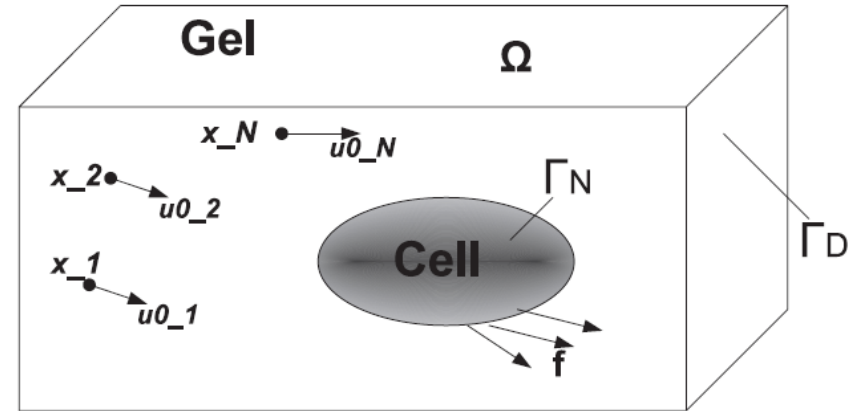
- Measurements outside the cell
 - Forces exerted on the cell
boundary

$$\mathcal{S}: \mathbf{f} \longrightarrow \mathbf{u} \longleftrightarrow \begin{cases} -\nabla \cdot \mathbb{C}[\nabla \mathbf{u}] = 0, & \text{in } \Omega, \\ \mathbb{C}[\nabla \mathbf{u}] \mathbf{n} = \mathbf{f}, & \text{on } \Gamma_N, \\ \mathbf{u} = 0, & \text{on } \Gamma_D. \end{cases}$$

Traction in 3D

Penalty function for the
minimization problem

$$\mathcal{J}(\mathbf{f}) = \frac{1}{2} \|\mathcal{O}\mathcal{S}\mathbf{f} - u_0\|^2 + \frac{\varepsilon}{2} \|\mathbf{f}\|^2$$

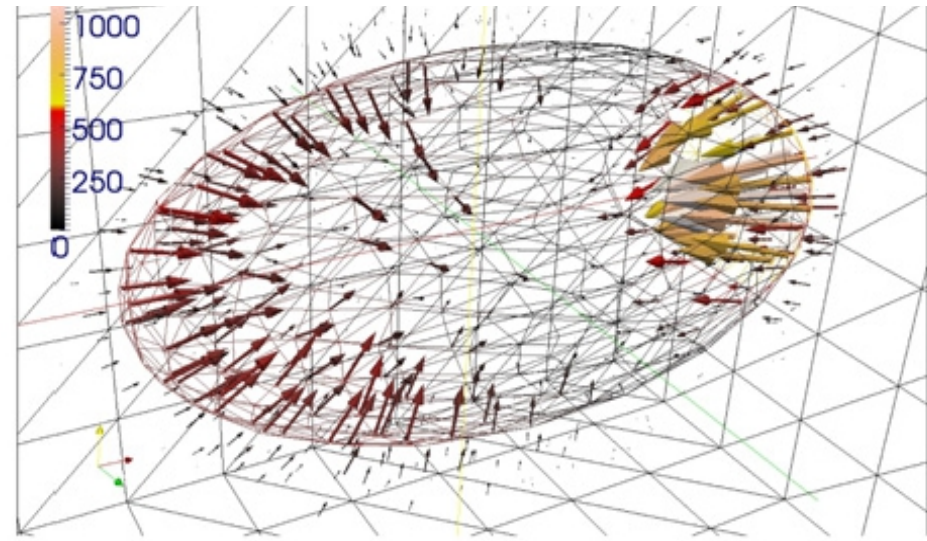
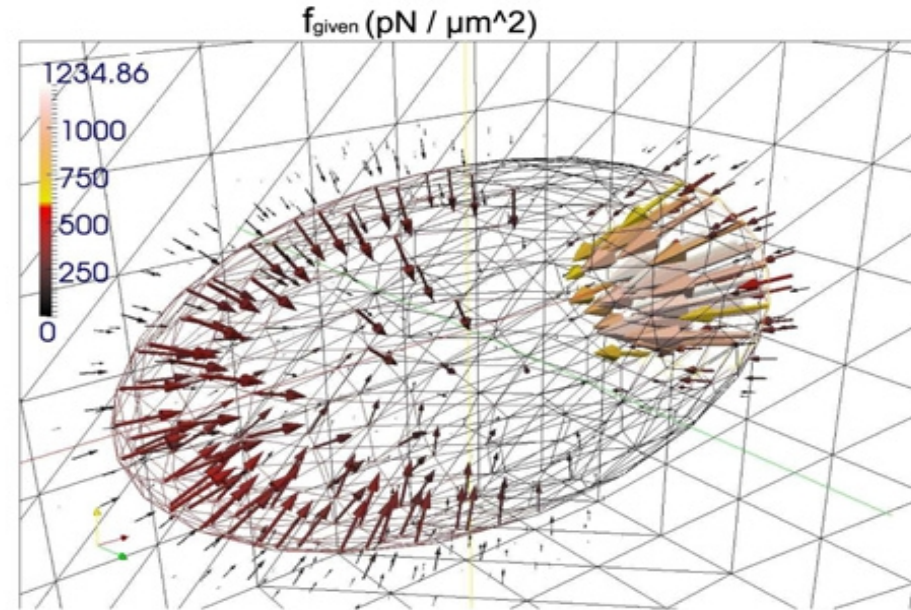
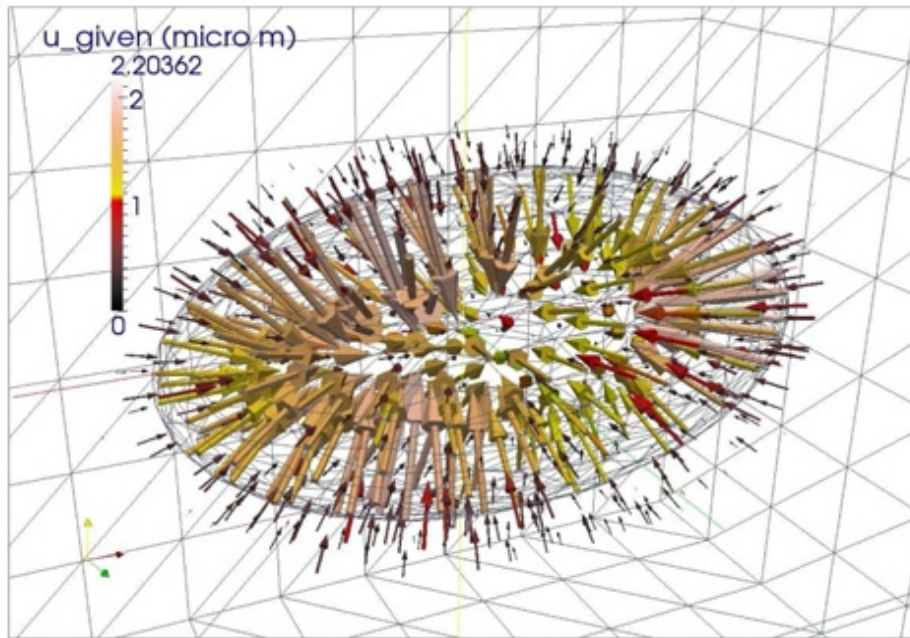
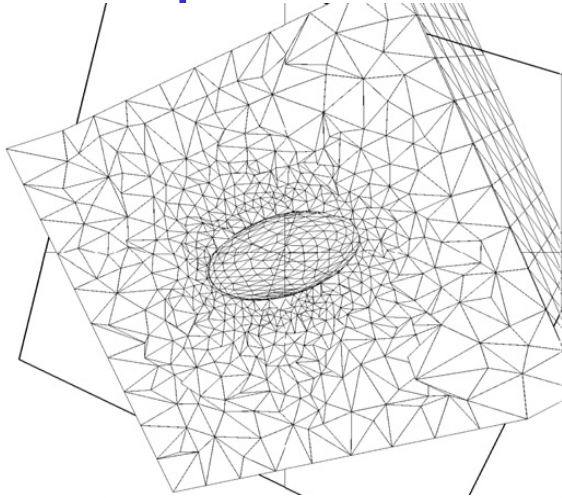


G. Vitale, D. Ambrosi, L.P.,
J. Math. Anal. Appl. **395**, 788-801 (2012)
Inverse Problems **28**, 095013 (2012)

Self-adjoint problem

$$\begin{cases} \int_{\Omega} (\mu \nabla \mathbf{u} \cdot \nabla \mathbf{v} + \lambda (\nabla \cdot \mathbf{u})(\nabla \cdot \mathbf{v})) + \frac{1}{\varepsilon} \left(\int_{\Gamma_N} \mathbf{p} \cdot \mathbf{v} - \frac{1}{|\Gamma_N|} \int_{\Gamma_N} \mathbf{p} \cdot \int_{\Gamma_N} \mathbf{v} \right) = 0, \\ \int_{\Omega} (\mu \nabla \mathbf{p} \cdot \nabla \mathbf{q} + \lambda (\nabla \cdot \mathbf{p})(\nabla \cdot \mathbf{q})) + \sum_{j=1}^N \delta_{x_j} \mathbf{u} \cdot \delta_{x_j} \mathbf{q} = \sum_{j=1}^N u_{0_j} \cdot \delta_{x_j} \mathbf{q}, \end{cases}$$

Traction in 3D

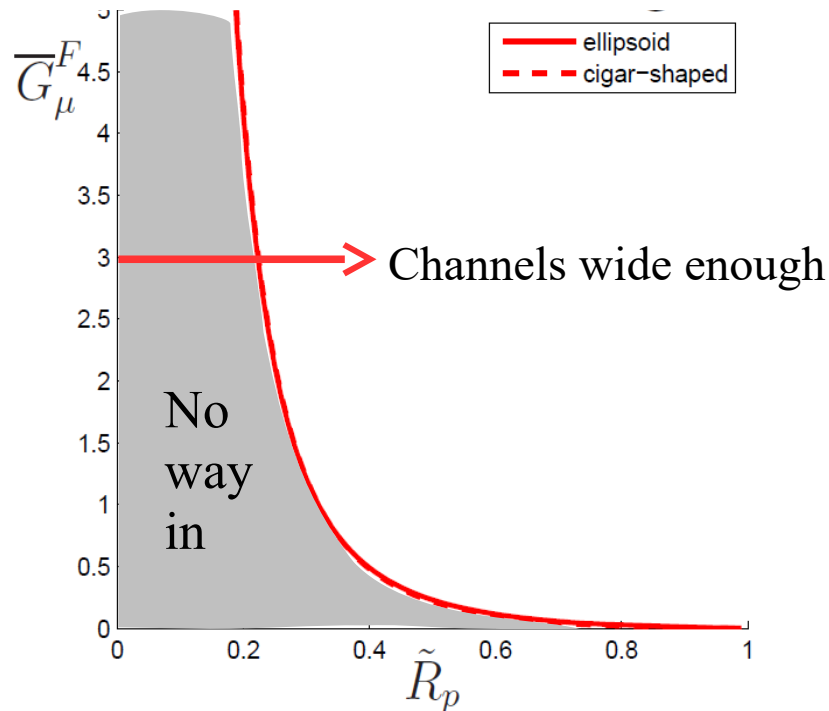


Criterion for invasion

Work done by traction > Energy required to squeeze the nucleus

Elastic nucleus	Ellipsoid	$G_{\mu}^F \geq \frac{2}{3} \frac{2\tilde{R}_p^2 + \frac{1}{\tilde{R}_p^4} - 3}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{ellips}}$
	Cigar	$G_{\mu}^F \geq \frac{2}{3} \frac{\mathcal{I}(\tilde{R}_p)}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{cigar}}$

$$G_{\mu}^F = \frac{\text{Traction} \quad \rho_b \alpha_{ECM} F_b^M}{\text{Nucleus stiffness} \quad \mu}$$



$$\tilde{R}_p = R_p / R_n$$

Criterion for invasion

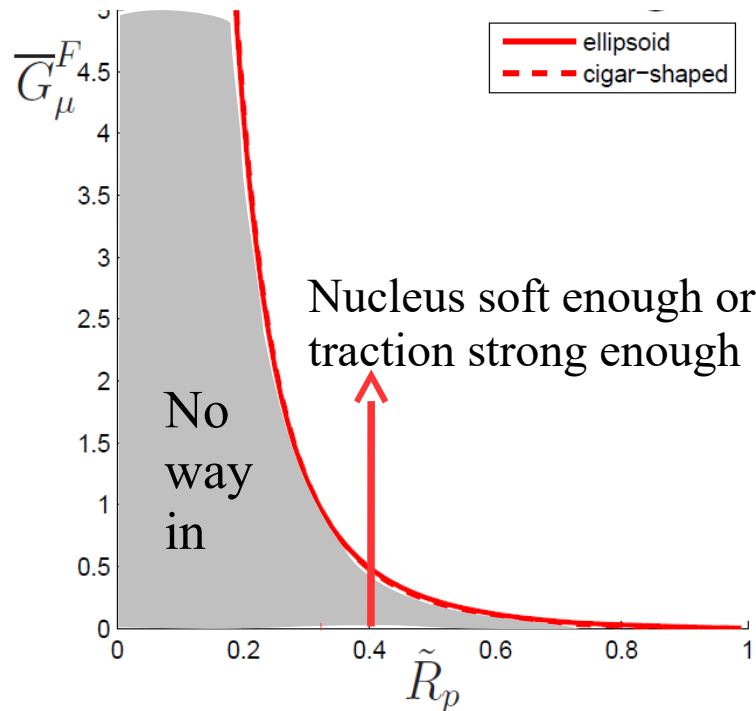
Work done by traction > Energy required to squeeze the nucleus

Elastic nucleus	Ellipsoid	$G_{\mu}^F \geq \frac{2}{3} \frac{2\tilde{R}_p^2 + \frac{1}{\tilde{R}_p^4} - 3}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{ellips}}$
	Cigar	$G_{\mu}^F \geq \frac{2}{3} \frac{\mathcal{I}(\tilde{R}_p)}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{cigar}}$

$$G_{\mu}^F = \frac{\text{Traction} \cdot \text{Nucleus stiffness}}{\mu}$$

Traction
Nucleus stiffness

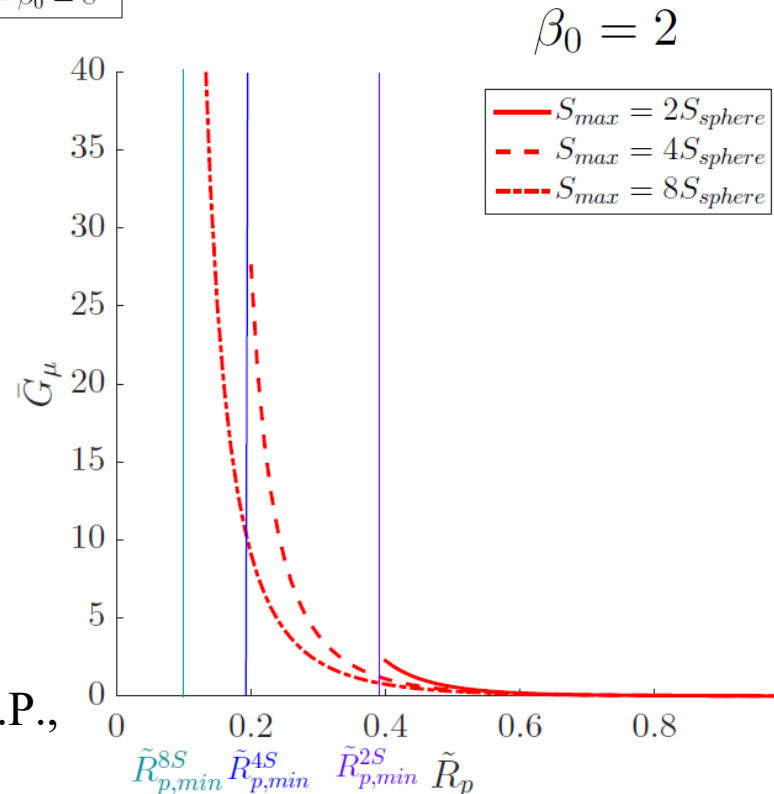
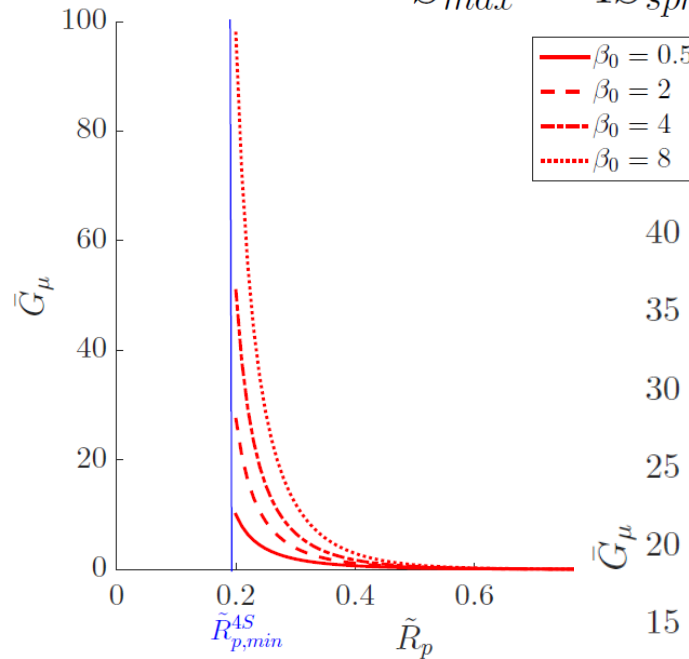
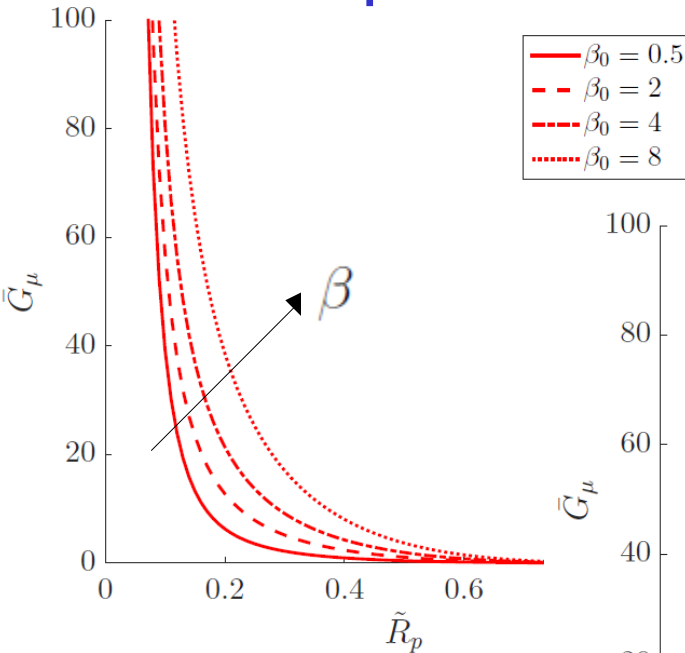
$$\tilde{R}_p = R_p / R_n$$



Effect of nucleus envelope stretchability

$$\lambda(\Delta S) = \lambda_0 \left(\frac{\Delta S}{S_{max} - S} \right)$$

$$S_{max} = 4S_{sphere}$$



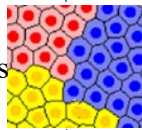
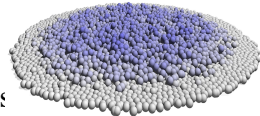
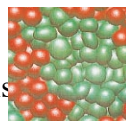
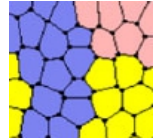
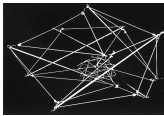
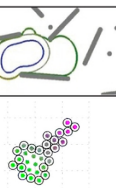
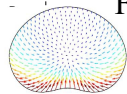
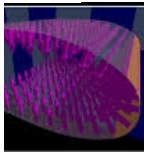
$$\tilde{R}_p = R_p / R_n$$

Membrane

$$\beta := \frac{\lambda R_n}{\mu}$$

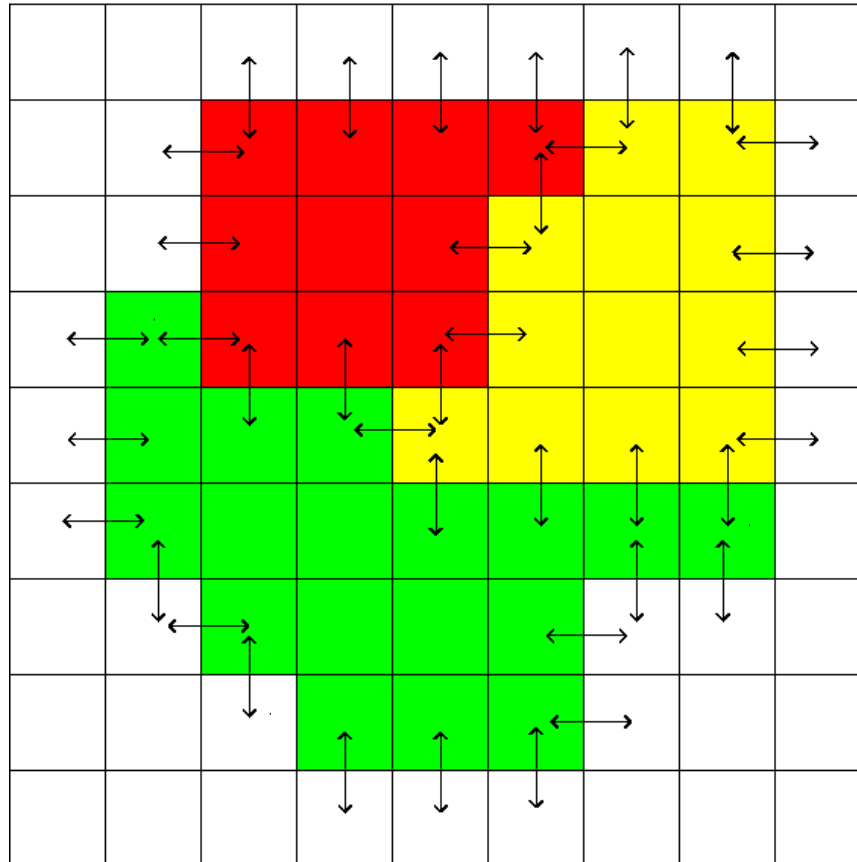
Nucleus

C. Giverso, A. Arduino & L.P.,
Bull. Math. Biol. (2017)

	Models based on a regular grid		Grid-free models	
	Rule based	Energy based	Force based	Energy based
Cell center	Lattice-gas cellular automata 		Cell center Voronoi models 	Self-propelled Voronoi models
Cell center and radius			Individual cell-based models 	
Cell center and dimensions of ellipsoidal shape			Ellipsoidal cell-based models 	
Vertices of polygonal cells			Force based vertex models 	Energy based vertex models
Many points per cell body		Cellular Potts models 	Tensegrity models  Sub-cellular element models 	
Continuous membrane and cytoplasm			Finite element methods  Boundary element methods 	
Kinetic model for cytoplasm			Filament based model of the lamellipodium 	

The cellular Potts model

A cell is
represented by
several nodes

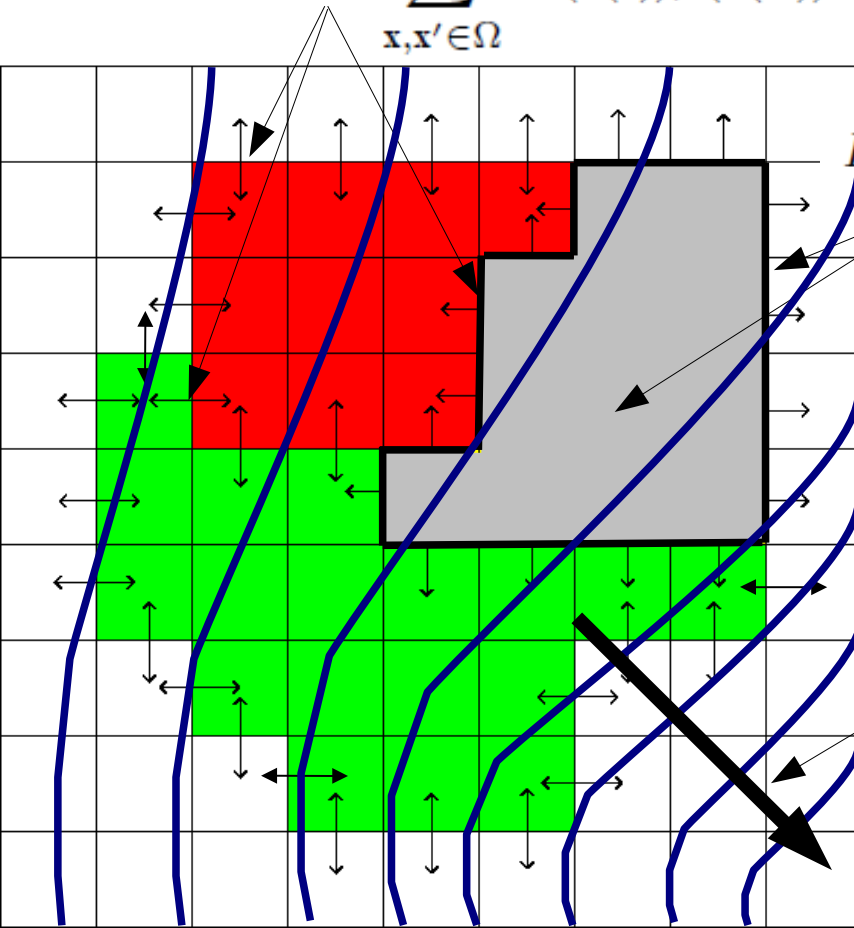


- Based on a generalized energy H
- Evolution stochastically tries to minimize the system energy

The cellular Potts model

$$H(t) = H_{adhesion}(t) + H_{attribute}(t) + H_{force}(t).$$

$$H_{adhesion}(t) = \sum_{\mathbf{x}, \mathbf{x}' \in \Omega} J_{\tau(\sigma(\mathbf{x})), \tau(\sigma(\mathbf{x}'))}(t) [1 - \delta_{\sigma(\mathbf{x}), \sigma(\mathbf{x}')} (t)],$$

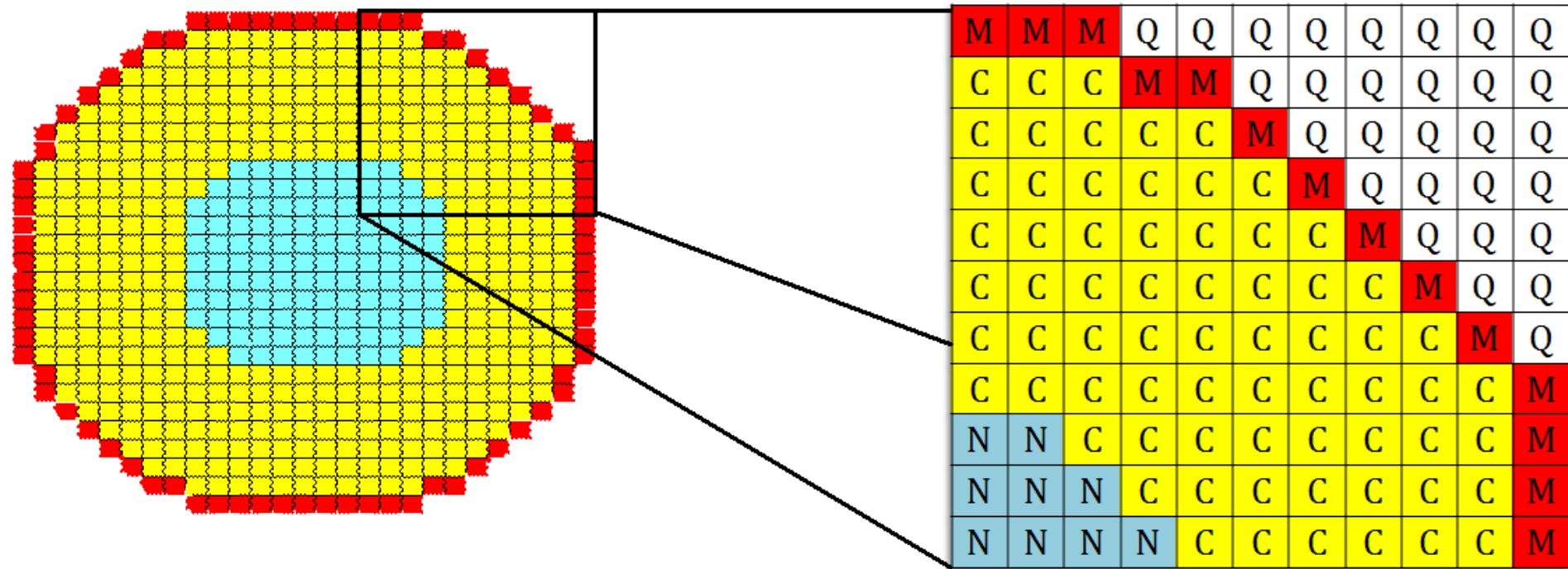


$$H_{attribute}(t) = \sum_{\eta, \sigma, i-\text{attribute}} \lambda_{\eta, \sigma}^i(t) \left| \frac{a_{\eta, \sigma}^i(t) - A_{\eta, \sigma}^i(t)}{a_{\eta, \sigma}^i(t)} \right|^p.$$

$$H_{force}^{chemical}(t) = - \sum_{\sigma} \sum_{\mathbf{x} \in \sigma} \mu_{\sigma}(t) c(\mathbf{x}, t),$$

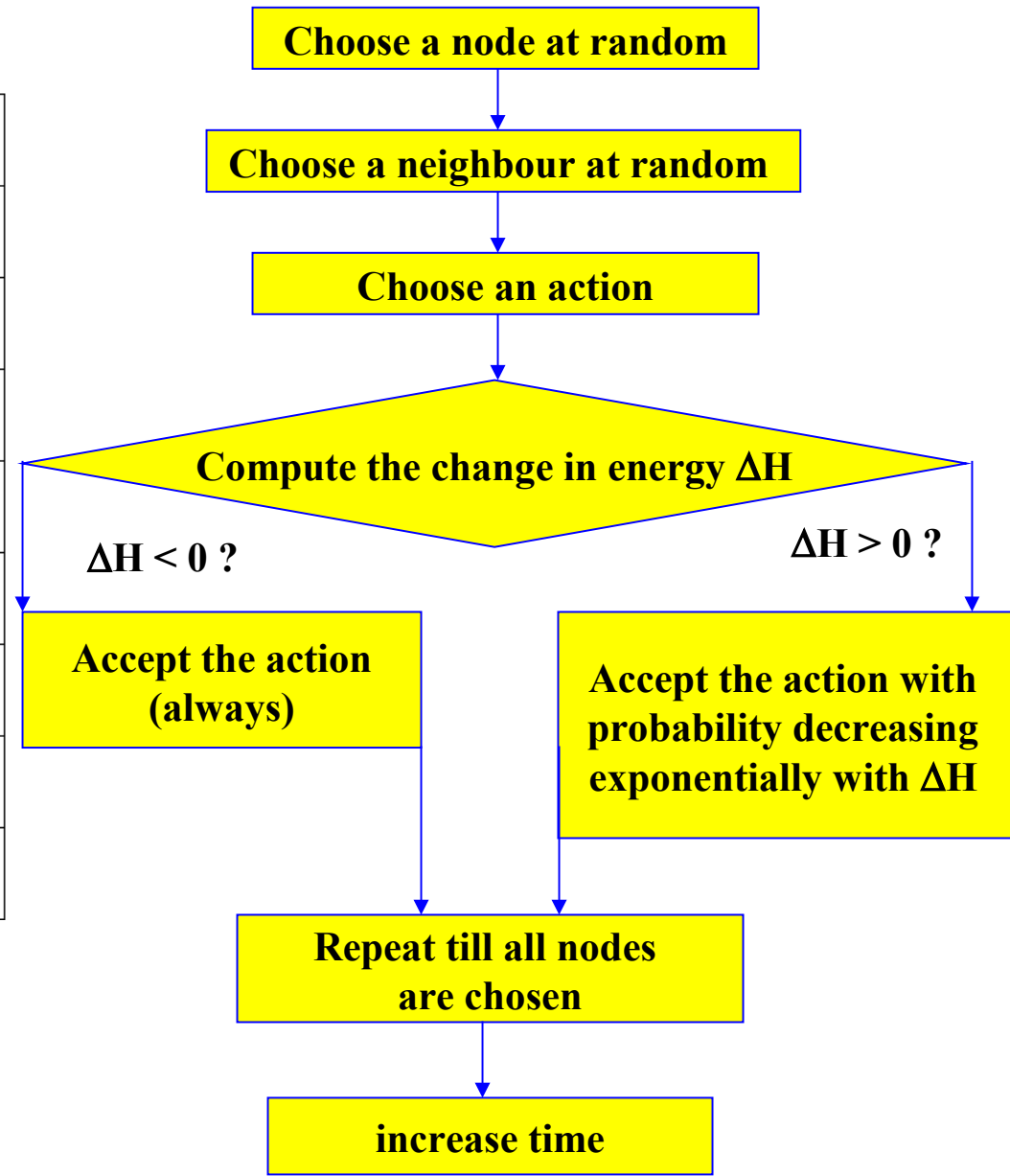
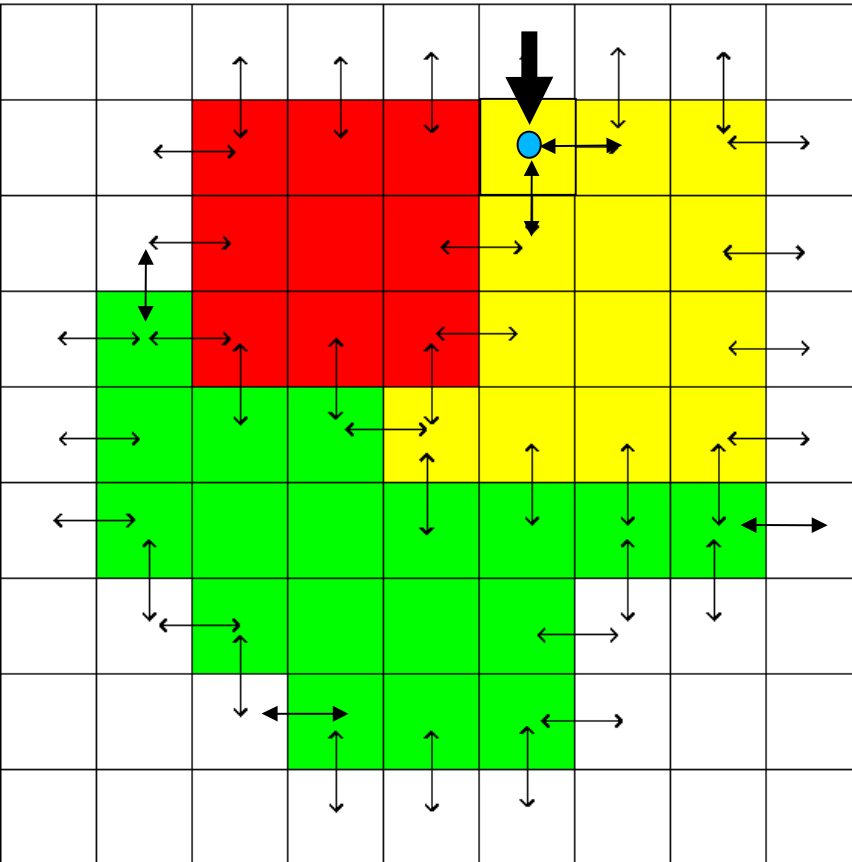
Generalized cellular Potts model

Taking into account of sub-cellular elements (e.g., nucleus)

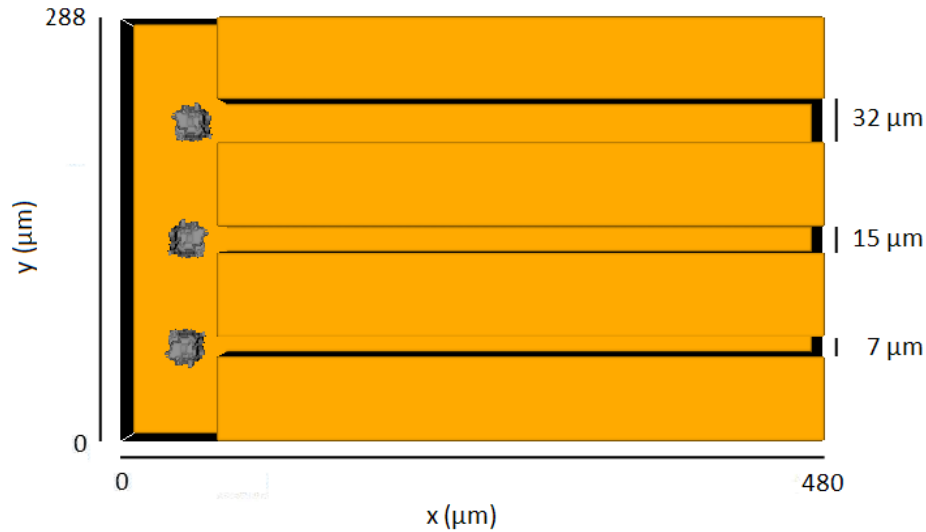




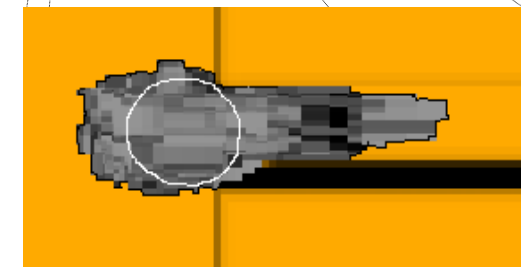
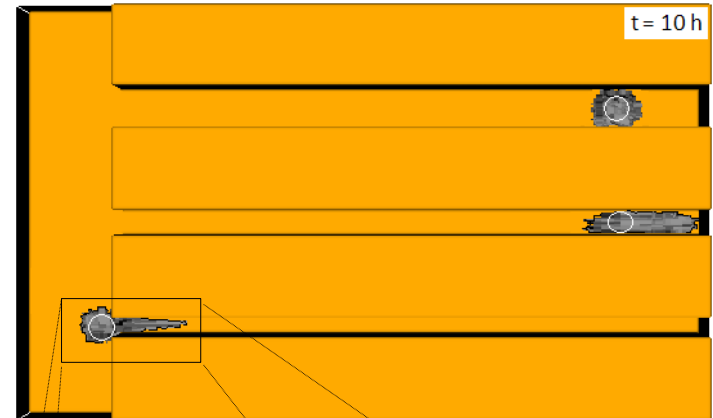
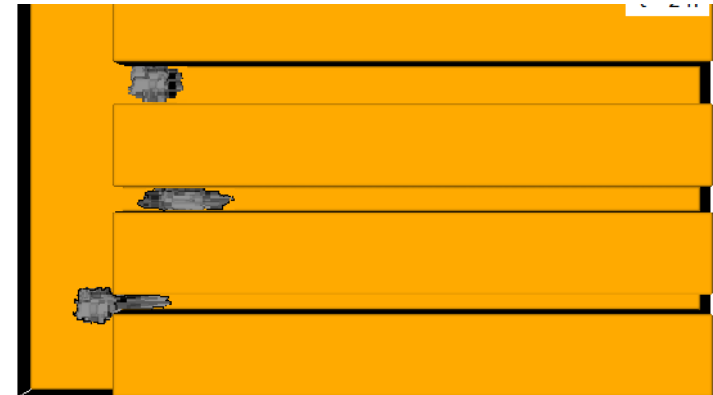
The cellular Potts model



Cells with stiff nuclei in microchannel

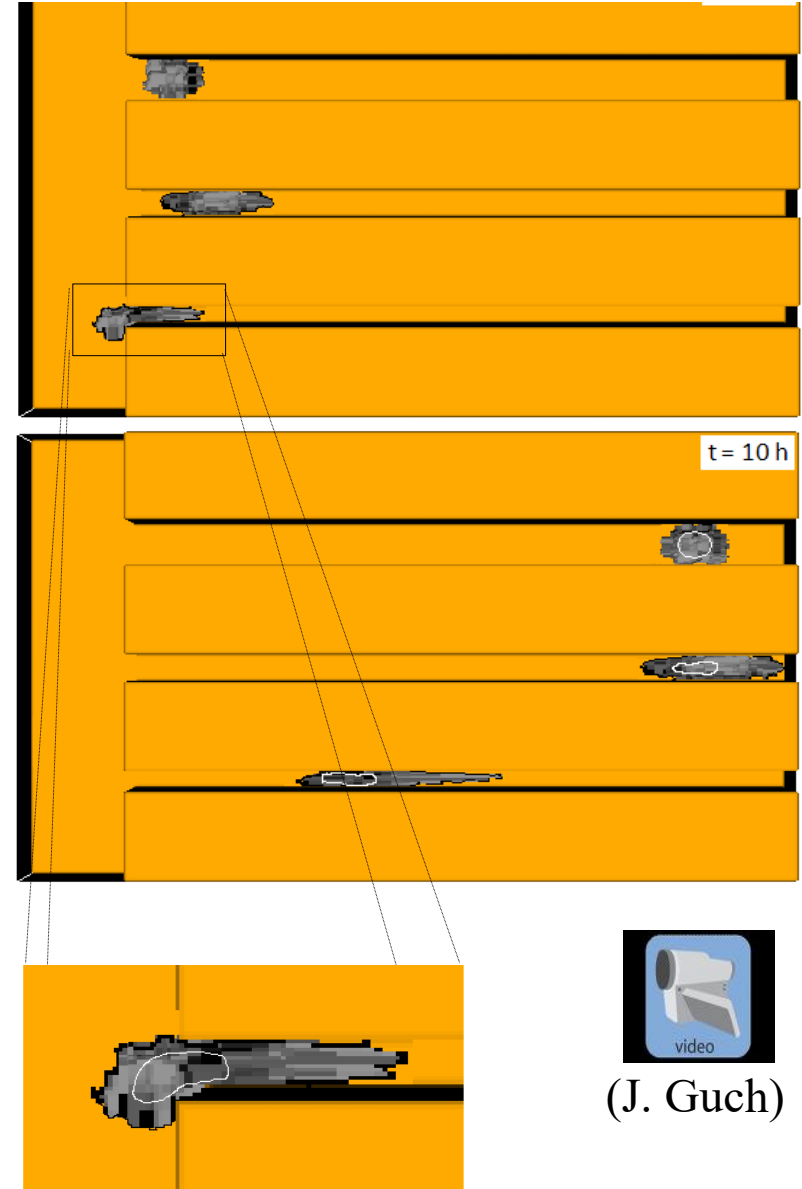
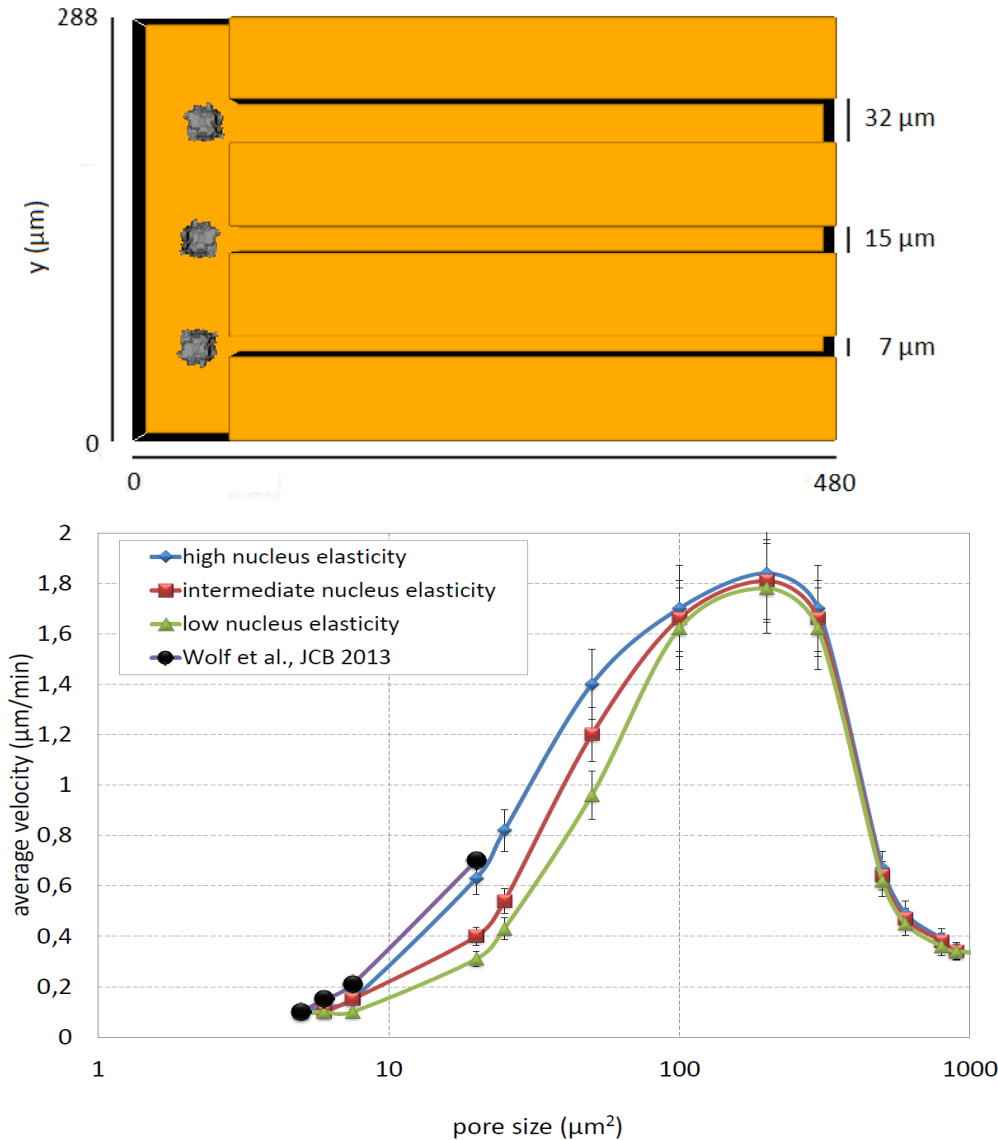


bottom channel size < nucleus diameter < middle channel size < cell diameter < top channel size



(J. Guch)

Cells with deformable nuclei in microchannel



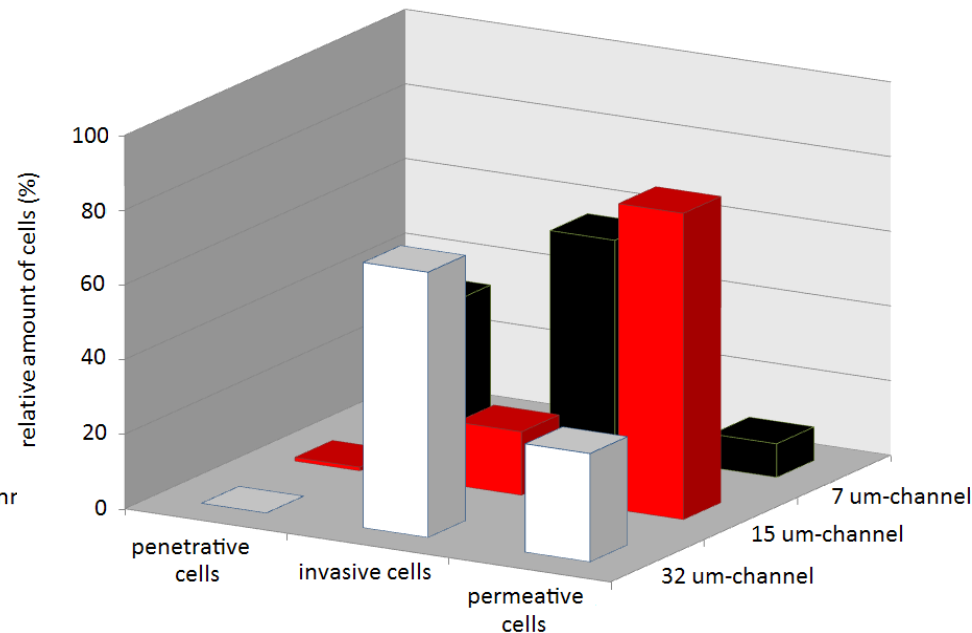
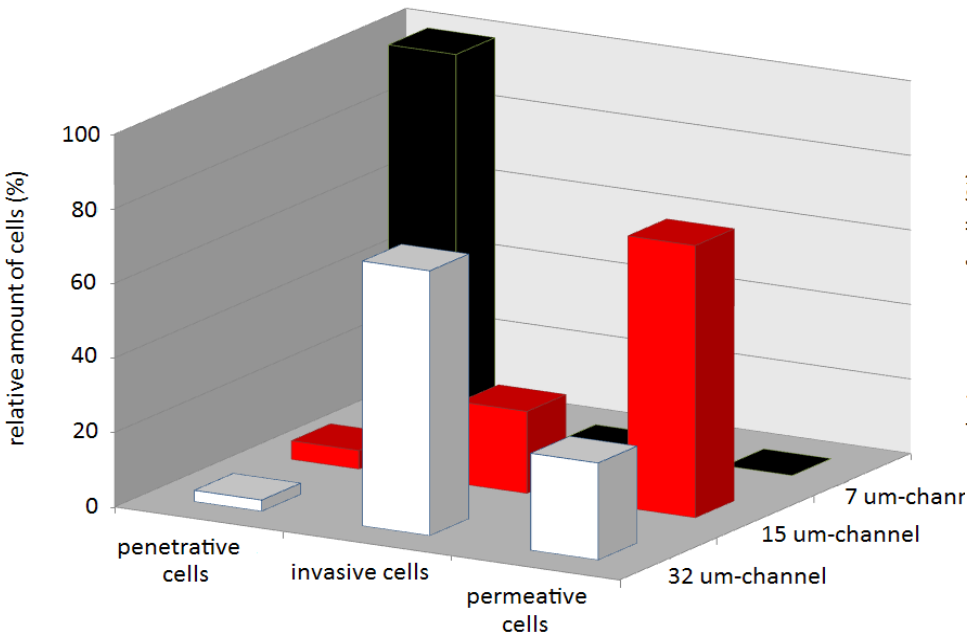
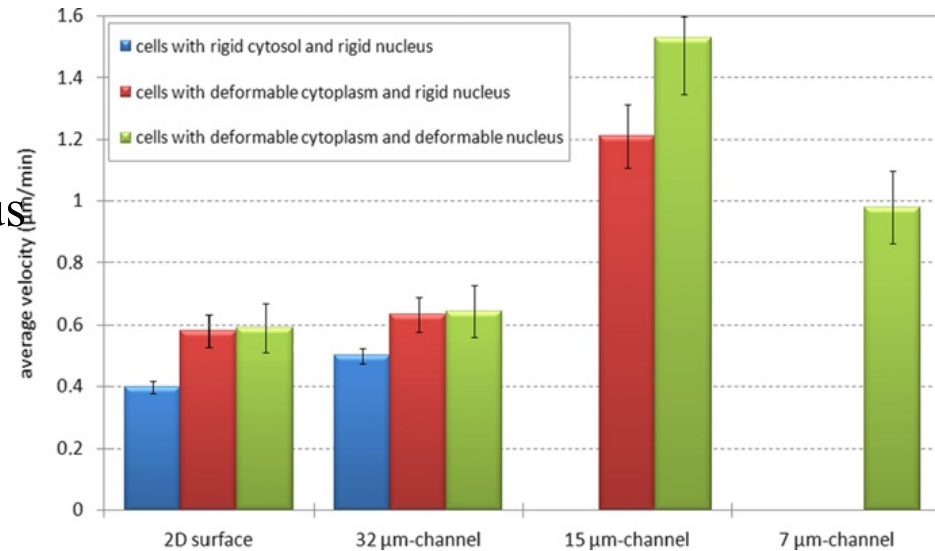
(J. Guch)

Influence of nucleus rigidity

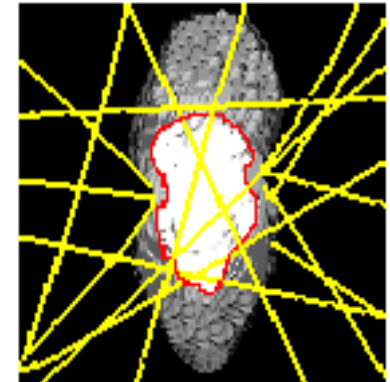
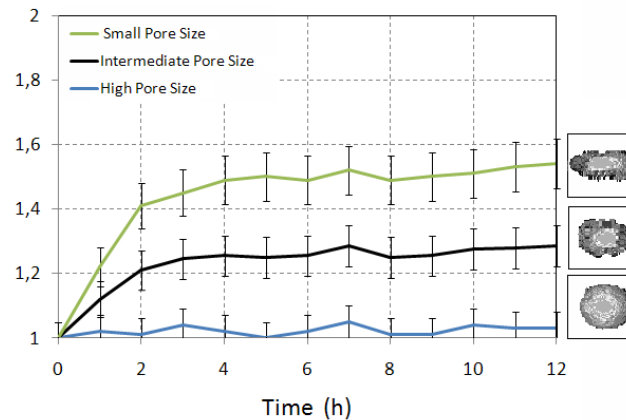
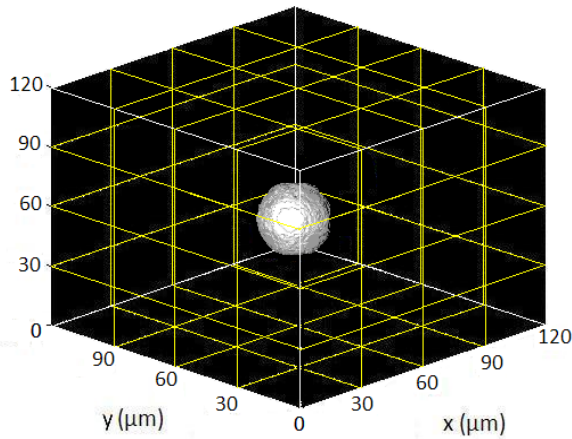
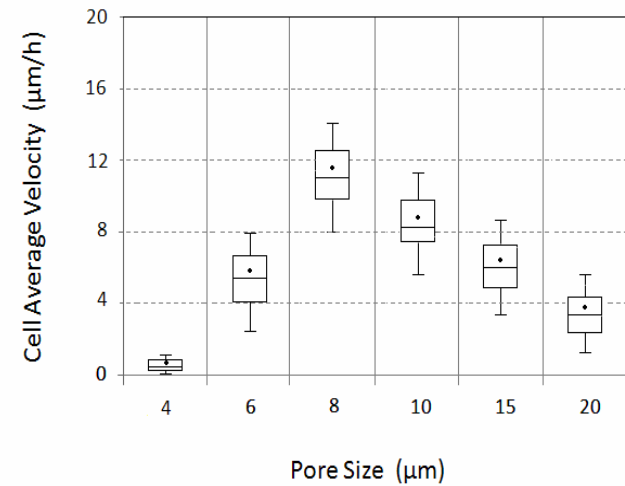
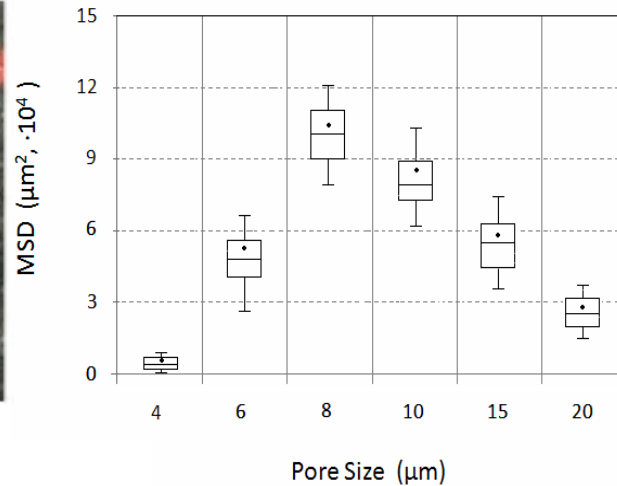
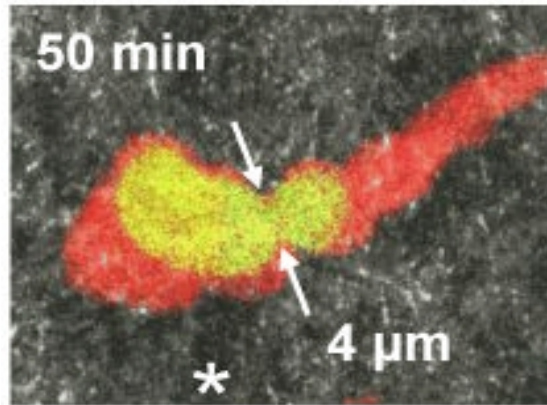
C. Rolli, *PlosOne* 5, e8726 (2010)



-  Penetrative = Stay out with the nucleus (not with the cytoplasm)
-  Invasive = Enter but do not reach the other side
-  Permeative = Enter and reach the other side

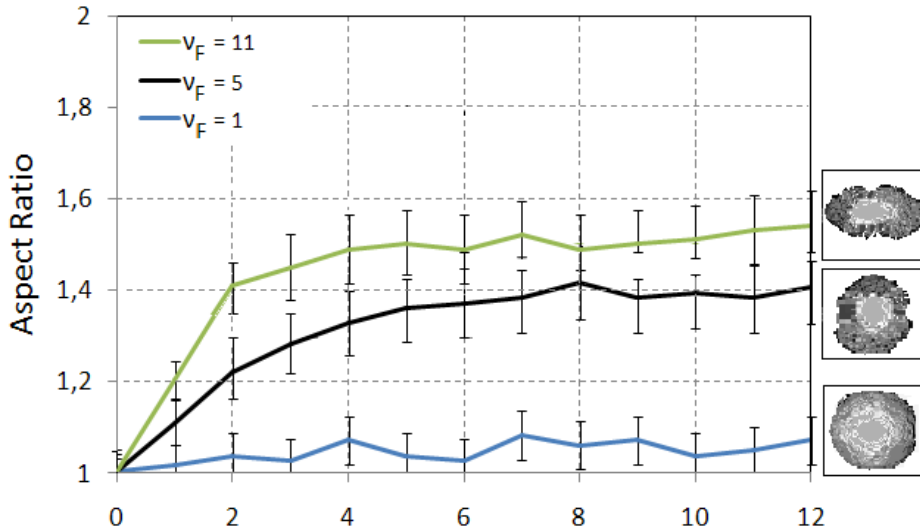


Effect of pore size in ECM

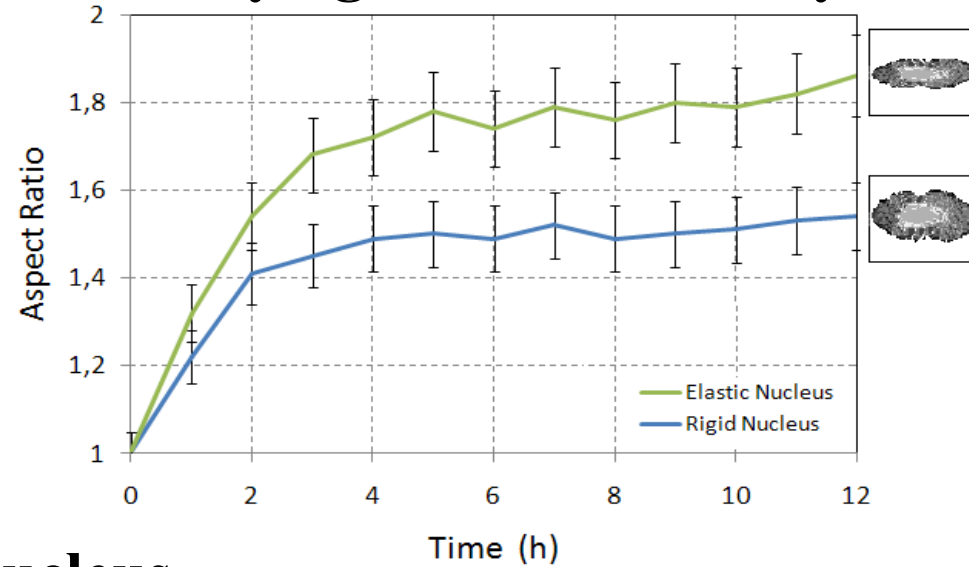


Effect of deformability

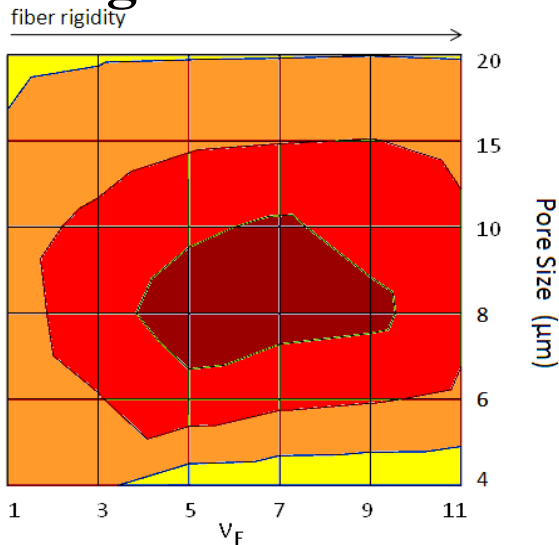
Varying fiber elasticity



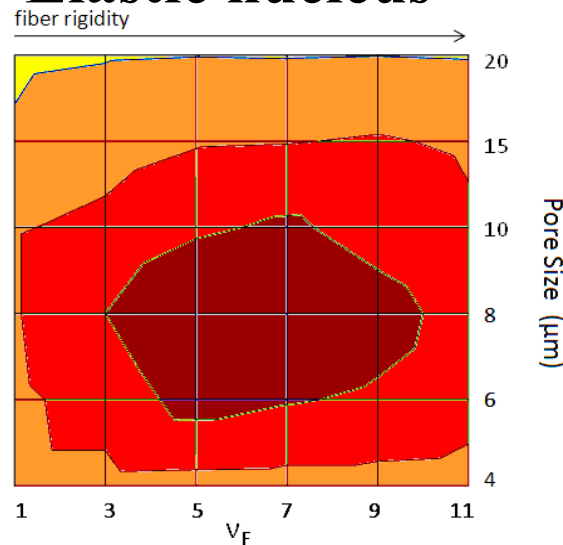
Varying nucleus elasticity



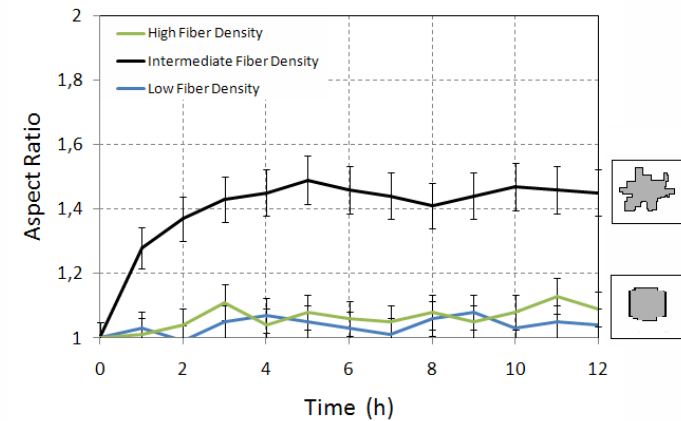
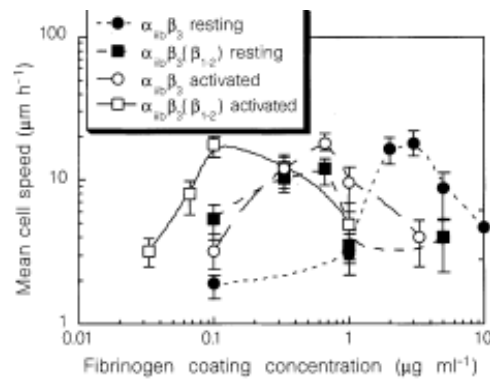
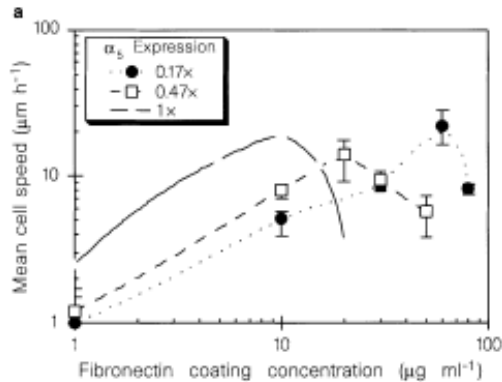
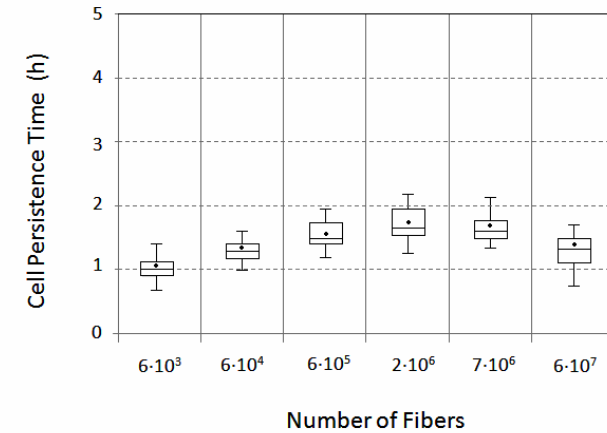
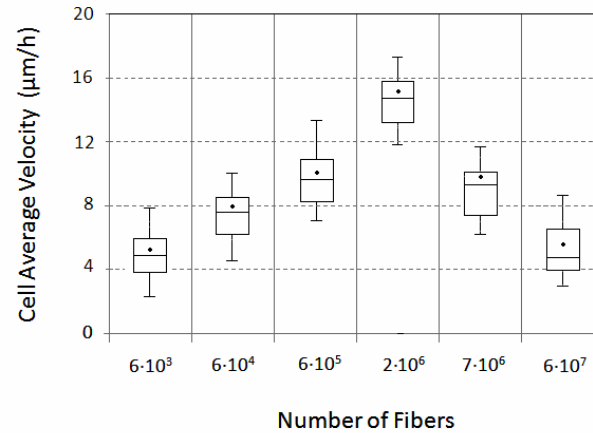
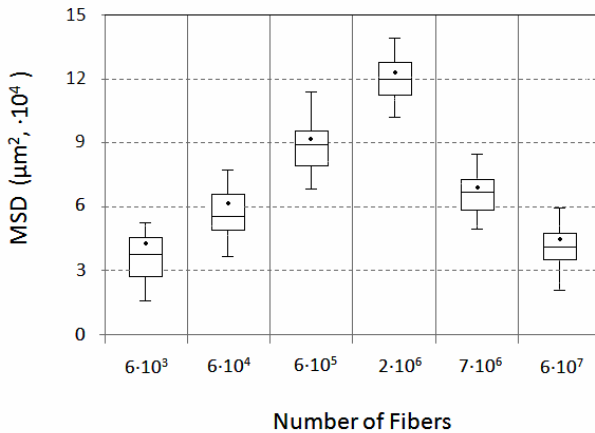
Rigid nucleus



Elastic nucleus



Effect of adhesion in 2D

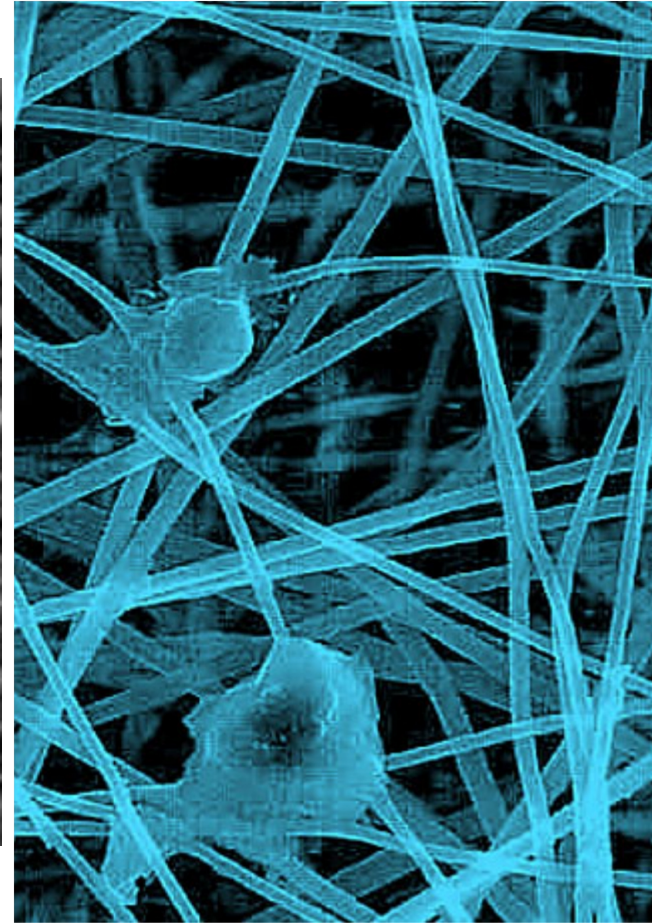
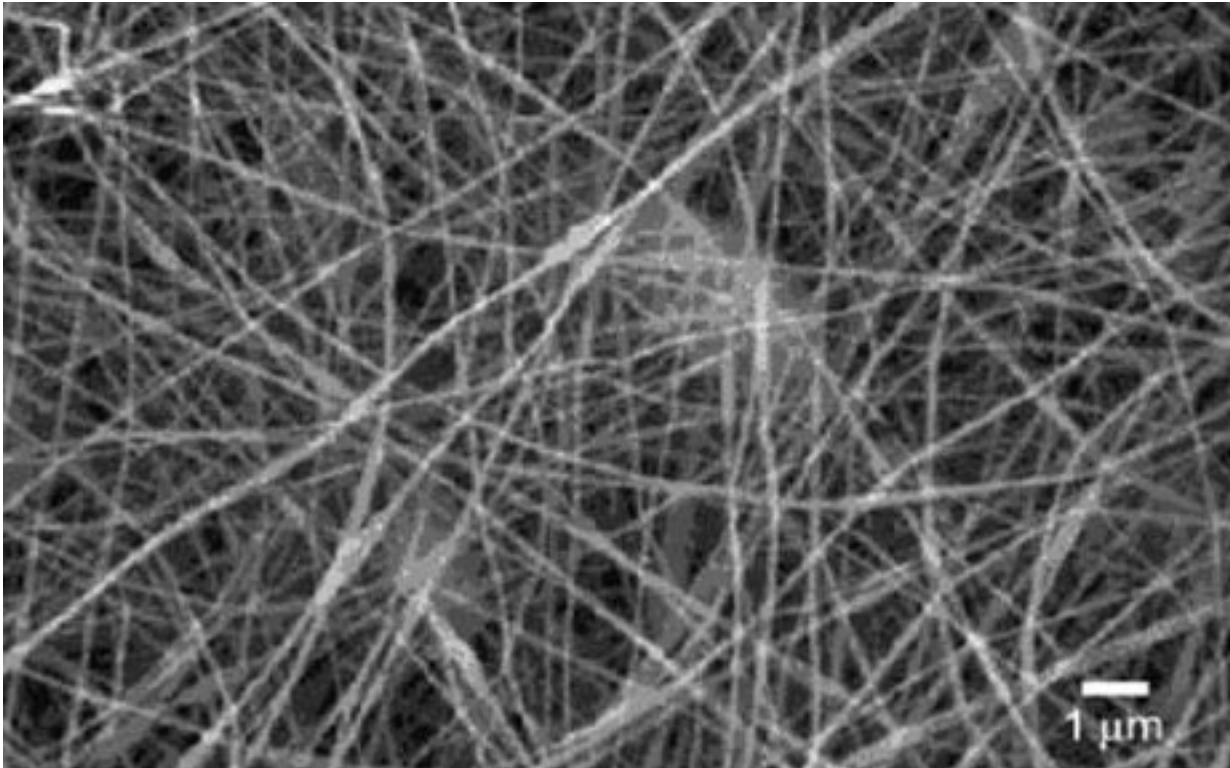


Palecek et al., *Nature* **385**, 537-540 (1997)

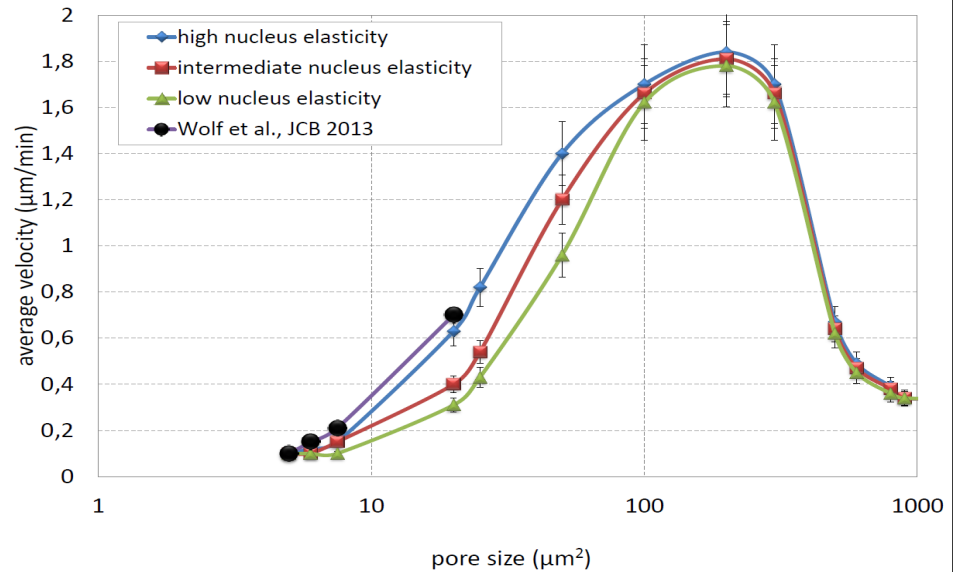
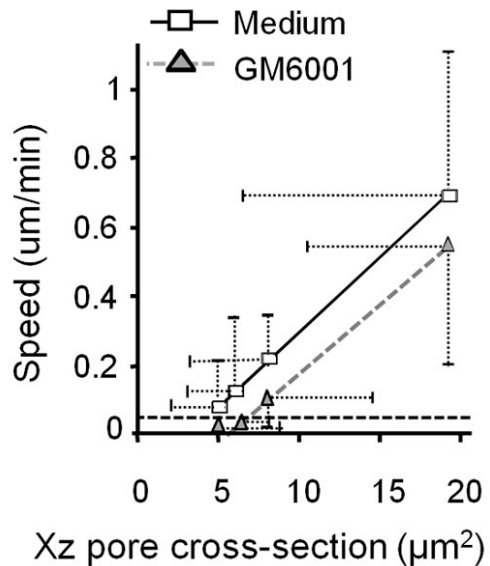
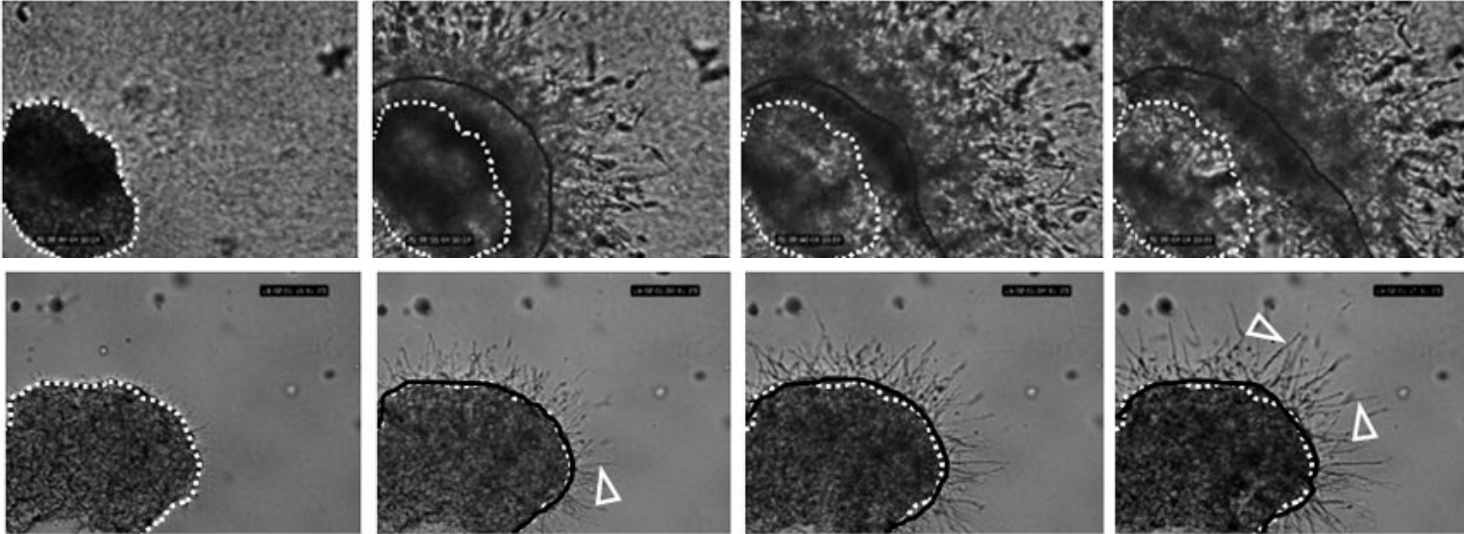


POLITECNICO
DI TORINO

Optimising motion in artificial ECM



Cell invasion in dense ECM

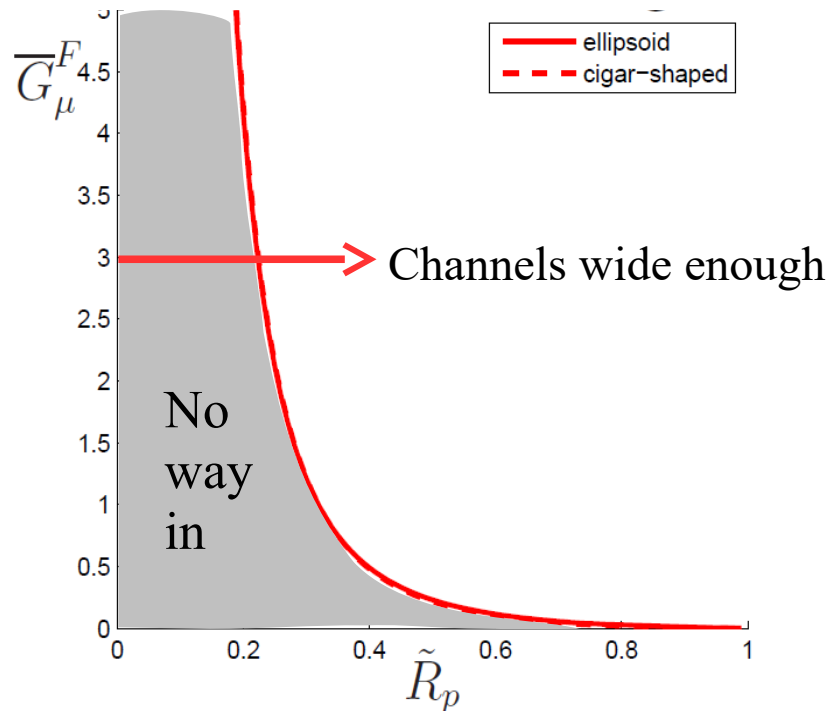


Criterion for invasion

Work done by traction > Energy required to squeeze the nucleus

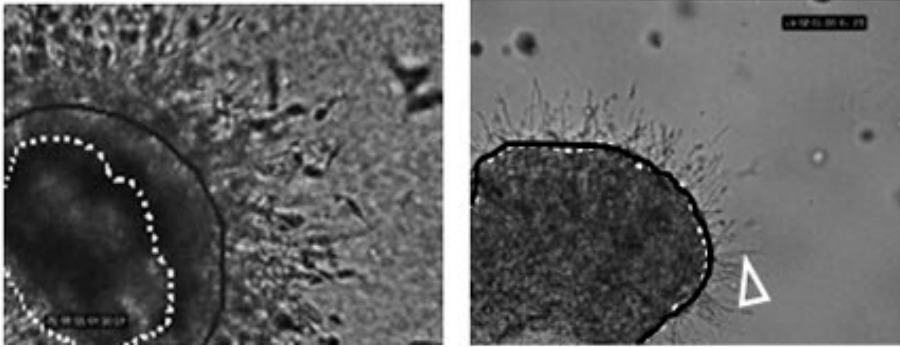
Elastic nucleus	Ellipsoid	$G_{\mu}^F \geq \frac{2}{3} \frac{2\tilde{R}_p^2 + \frac{1}{\tilde{R}_p^4} - 3}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{ellips}}$
	Cigar	$G_{\mu}^F \geq \frac{2}{3} \frac{\mathcal{I}(\tilde{R}_p)}{\tilde{R}_p \tilde{L}_b^{(*)} \Delta \tilde{L}_{cigar}}$

$$G_{\mu}^F = \frac{\text{Traction} \quad \rho_b \alpha_{ECM} F_b^M}{\text{Nucleus stiffness} \quad \mu}$$



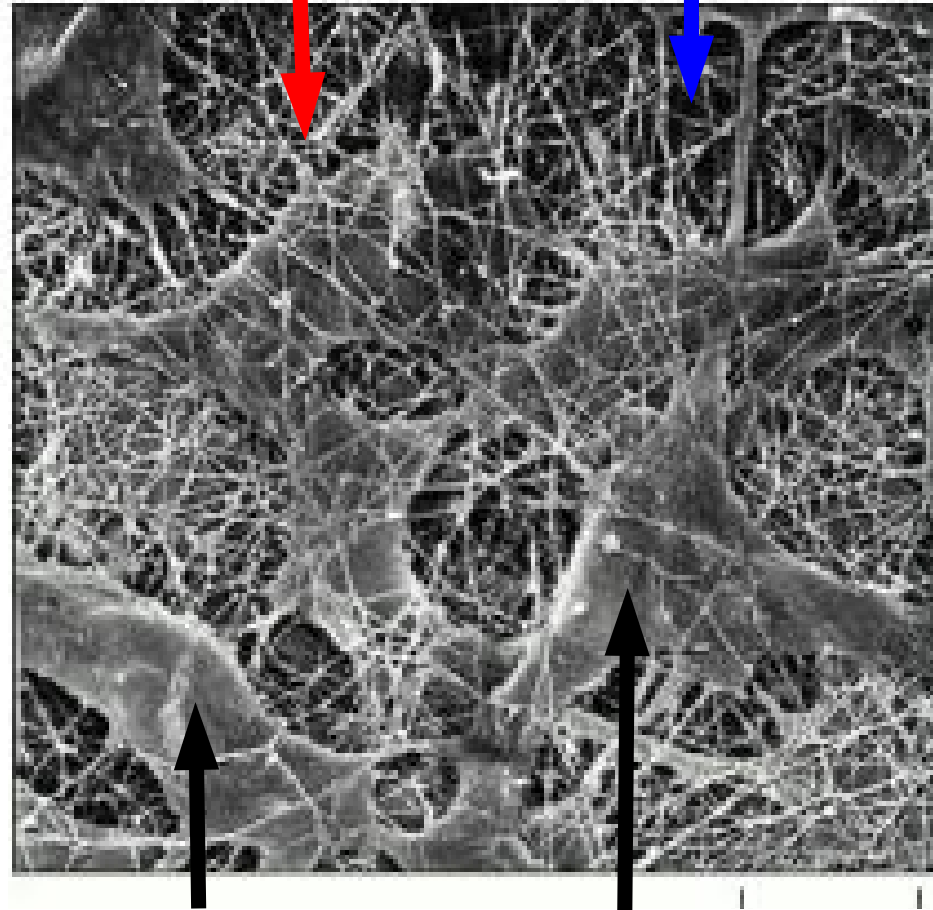
$$\tilde{R}_p = R_p / R_n$$

Upscaling the information

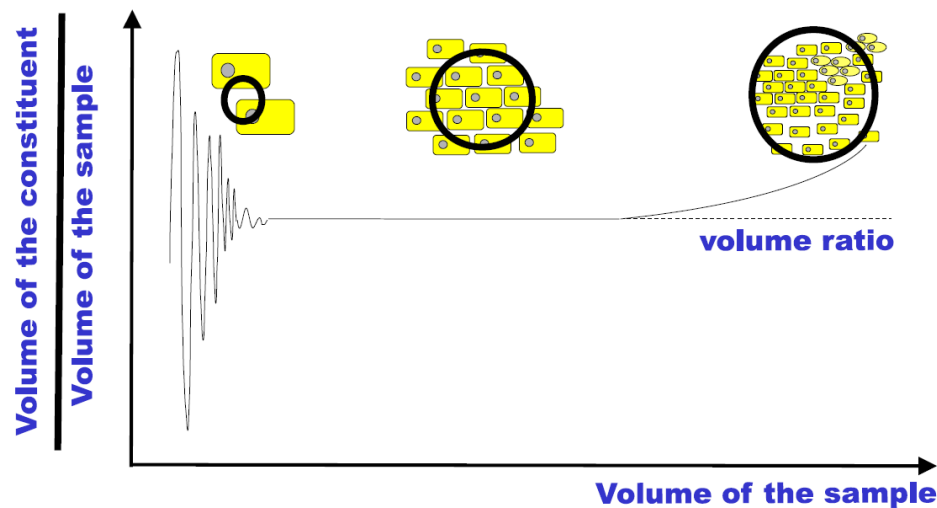


deformable and
degradable ECM

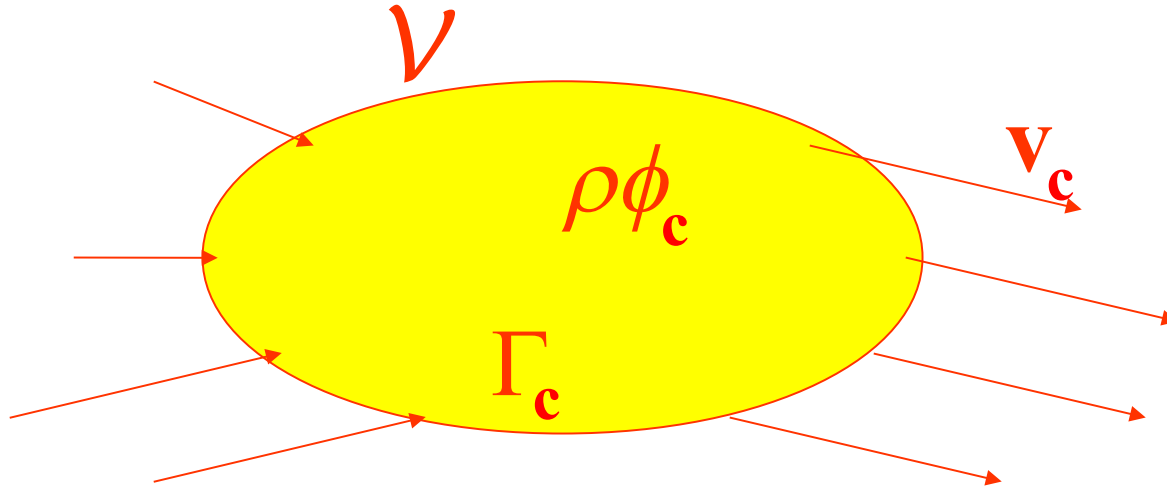
extracellular
liquid



host cells and tumour cells



Mass balance equations



$$\underbrace{\frac{d}{dt} \int_V \rho\phi_c dV}_{\text{Cell mass}} = - \underbrace{\int_{\partial V} \rho\phi_c \mathbf{v}_c \cdot \mathbf{n} d\Sigma}_{\text{Outflux}} + \underbrace{\int_V \rho\Gamma_c dV}_{\text{Growth/death}}$$



$$\frac{\partial}{\partial t}(\phi_c) + \nabla \cdot (\phi_c \mathbf{v}_c) = \Gamma_c \quad \longrightarrow \quad \frac{\partial \phi_{c_i}}{\partial t} + \nabla \cdot (\phi_{c_i} \mathbf{v}_{c_i}) = \Gamma_{c_i}$$

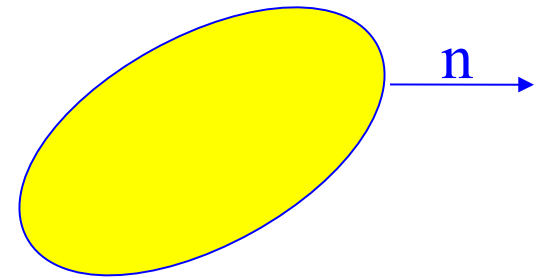
Only tumour cells in 3D

1. Constant density $\frac{\partial \bar{\varphi}}{\partial t} + \nabla \cdot (\bar{\varphi} \mathbf{v}) = \Gamma \implies \nabla \cdot \mathbf{v} = \frac{\Gamma}{\bar{\varphi}}$

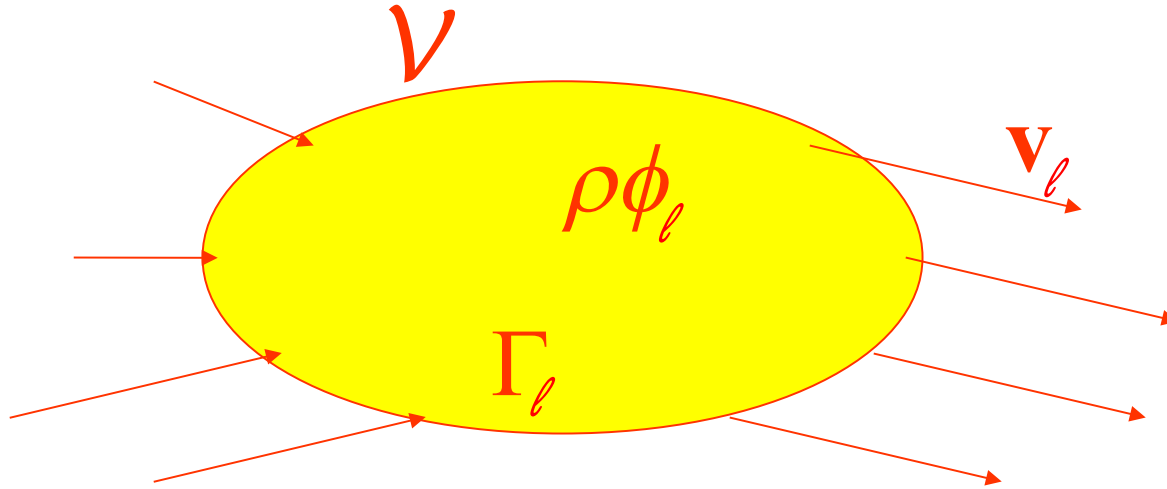
2. Potential flow assumption $\mathbf{v} = \nabla \Psi$



$$\left\{ \begin{array}{l} \nabla^2 \Psi = \frac{\Gamma}{\bar{\varphi}} \\ \mathbf{n} \cdot \frac{d\mathbf{x}_T}{dt} = \mathbf{n} \cdot \nabla \Psi \\ \Psi = 0, \quad \text{on free part of the boundary} \\ \mathbf{n} \cdot \nabla \Psi = 0, \quad \text{on obstacles} \end{array} \right.$$



Tumours as multiphase systems



Extracellular liquid

$$\frac{\partial \phi_\ell}{\partial t} + \nabla \cdot (\phi_\ell \mathbf{v}_\ell) = \Gamma_\ell$$

ECM components

$$\frac{\partial \phi_m}{\partial t} + \nabla \cdot (\phi_m \mathbf{v}_m) = \Gamma_m \quad \Rightarrow \quad \frac{\partial \phi_{m_j}}{\partial t} + \nabla \cdot (\phi_{m_j} \mathbf{v}_m) = \Gamma_{m_j}$$



Tumours as multiphase systems

$$\frac{\partial \phi_\alpha}{\partial t} + \nabla \cdot (\phi_\alpha \mathbf{v}_\alpha) = \Gamma_\alpha$$

saturation

$$\sum_{\alpha} \phi_\alpha = 1$$

closed mixture assumption

$$\nabla \cdot \sum_{\alpha=c,m,\ell,v} (\phi_\alpha \mathbf{v}_\alpha) = \sum_{\alpha=c,m,\ell,v} \Gamma_\alpha \stackrel{\text{closed mixture assumption}}{=} 0$$

Constrained
mixture
assumption

$$\mathbf{v}_\alpha = \mathbf{v} \quad \forall \alpha$$

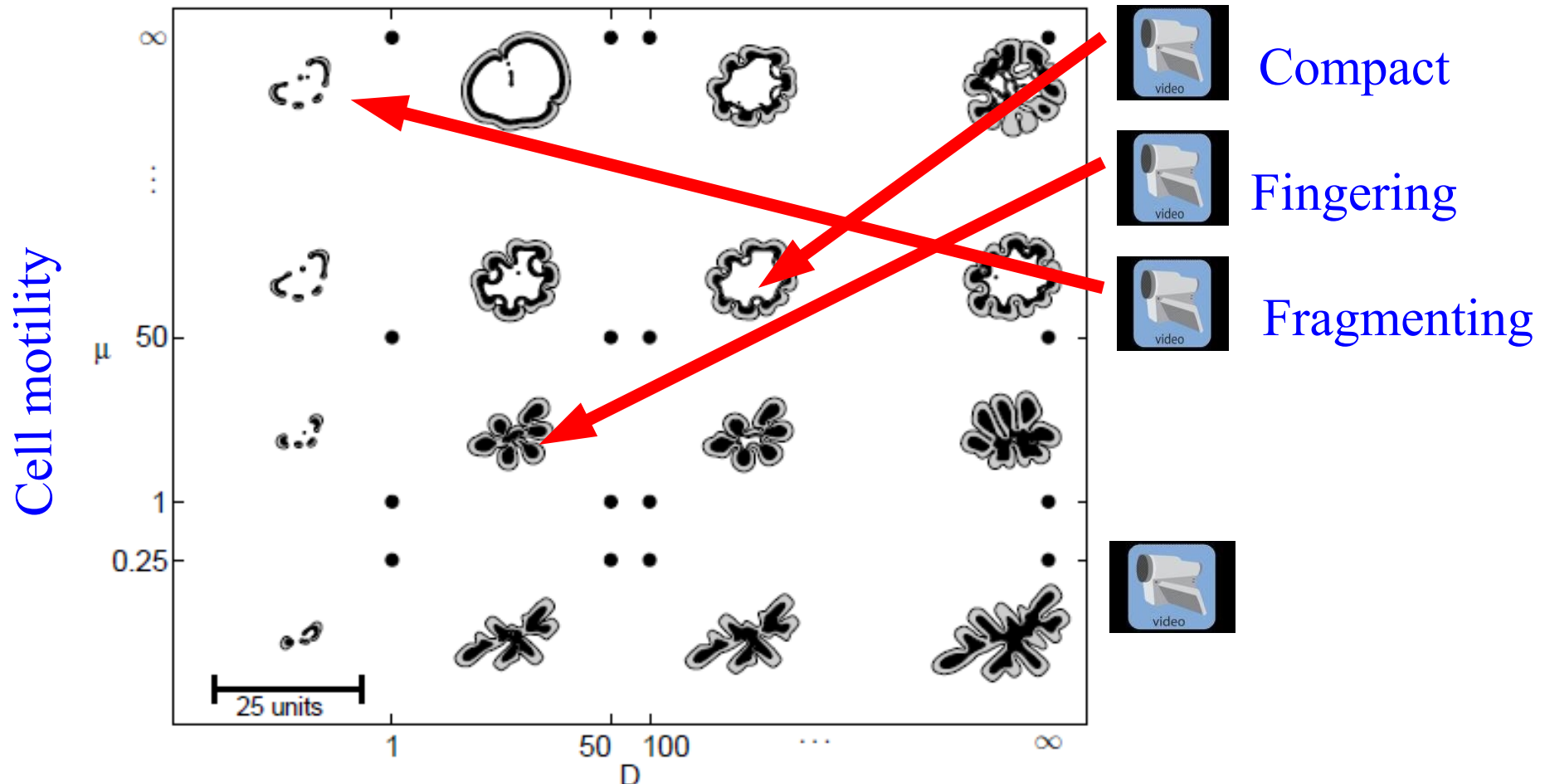
$$\nabla \cdot \mathbf{v} = \sum_{\alpha=c,m,\ell,v} \Gamma_\alpha = 0$$

Potential flow assumption

$$\mathbf{v} = \nabla \Psi$$

Only tumour cells in 3D

Macklin & Lowengrub JTB (2008)



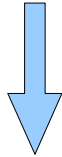
Nutrient diffusion

Original movies at

biomathematics.shis.uth.tmc.edu/Multimedia.php

Momentum balance equations

$$\begin{aligned} \frac{d}{dt} \int_V \rho \phi_c \mathbf{v}_c dV &= - \int_{\partial V} \rho \phi_c \mathbf{v}_c (\mathbf{v}_c \cdot \mathbf{n}) d\Sigma + \int_{\partial V} \tilde{\mathbf{T}}_c^T \mathbf{n} d\Sigma \\ &+ \int_V \tilde{\mathbf{m}}_c dV + \int_V \rho \Gamma_c \mathbf{v}_c dV + \int_V \rho \phi_c \mathbf{b}_c dV, \end{aligned}$$



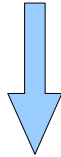
$$\rho \phi_c \left(\frac{\partial \mathbf{v}_c}{\partial t} + \mathbf{v}_c \cdot \nabla \mathbf{v}_c \right) = \nabla \cdot \tilde{\mathbf{T}}_c + \rho \phi_c \mathbf{b}_c + \tilde{\mathbf{m}}_c$$

$$\rho \phi_\ell \left(\frac{\partial \mathbf{v}_\ell}{\partial t} + \mathbf{v}_\ell \cdot \nabla \mathbf{v}_\ell \right) = \nabla \cdot \tilde{\mathbf{T}}_\ell + \rho \phi_\ell \mathbf{b}_\ell + \tilde{\mathbf{m}}_\ell$$

$$\rho \phi_m \left(\frac{\partial \mathbf{v}_m}{\partial t} + \mathbf{v}_m \cdot \nabla \mathbf{v}_m \right) = \nabla \cdot \tilde{\mathbf{T}}_m + \rho \phi_m \mathbf{b}_m + \tilde{\mathbf{m}}_m$$

Momentum balance equations

$$\begin{aligned} \frac{d}{dt} \int_V \rho \phi_c \mathbf{v}_c dV = & - \int_{\partial V} \rho \phi_c \mathbf{v}_c (\mathbf{v}_c \cdot \mathbf{n}) d\Sigma + \int_{\partial V} \tilde{\mathbf{T}}_c^T \mathbf{n} d\Sigma \\ & + \int_V \tilde{\mathbf{m}}_c dV + \int_V \rho \Gamma_c \mathbf{v}_c dV + \int_V \rho \phi_c \mathbf{b}_c dV, \end{aligned}$$



~~$$\rho \phi_c \left(\frac{\partial \mathbf{v}_c}{\partial t} + \mathbf{v}_c \cdot \nabla \mathbf{v}_c \right) = \nabla \cdot \tilde{\mathbf{T}}_c + \rho \phi_c \mathbf{b}_c + \tilde{\mathbf{m}}_c$$~~



$$\begin{cases} \frac{\partial \phi_\alpha}{\partial t} + \nabla \cdot (\phi_\alpha \mathbf{v}_\alpha) = \Gamma_\alpha, \\ \nabla \cdot \tilde{\mathbf{T}}_\alpha + \tilde{\mathbf{m}}_\alpha = \mathbf{0}, \end{cases}$$

Darcy's law

Interstitial
(fluid) pressure

Permeability
tensor

$$-\phi_\ell \nabla P$$

$$-\phi_\ell^2 \mathbf{K}^{-1} \mathbf{v}_\ell$$

$$\cancel{\rho \phi_\ell \left(\frac{\partial \mathbf{v}_\ell}{\partial t} + \mathbf{v}_\ell \cdot \nabla \mathbf{v}_\ell \right)} = \nabla \cdot \tilde{\mathbf{T}}_\ell + \cancel{\rho \phi_\ell \mathbf{b}_\ell} + \tilde{\mathbf{m}}_\ell$$

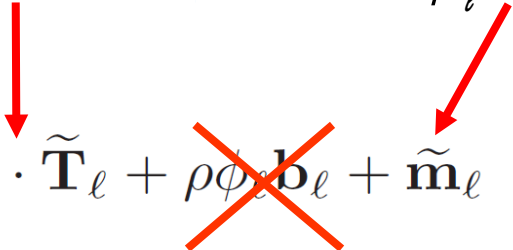


$$\mathbf{v}_\ell = -\frac{\mathbf{K}}{\mu \phi_\ell} \nabla P$$

Darcy's law

Brinkman equation

$$\rho\phi_\ell \left(\frac{\partial \mathbf{v}_\ell}{\partial t} + \mathbf{v}_\ell \cdot \nabla \mathbf{v}_\ell \right) = \nabla \cdot \tilde{\mathbf{T}}_\ell + \cancel{\rho\phi_\ell \mathbf{b}_\ell} + \tilde{\mathbf{m}}_\ell$$

$-\phi_\ell \nabla P + \mu \nabla^2 \mathbf{v}$ $-\phi_\ell^2 \mathbf{K}^{-1} \mathbf{v}_\ell$




Brinkman equation

Unsaturated cells in ECM

Cellular (solid) stress Chemotaxis Motility tensor

$-\Sigma_c(\phi_c)\mathbf{I}$ $\chi\nabla C$ $-\mathbf{K}^{-1}\mathbf{v}_c$

$\rho\phi_c \left(\frac{\partial \mathbf{v}_c}{\partial t} + \mathbf{v}_c \cdot \nabla \mathbf{v}_c \right) = \nabla \cdot \tilde{\mathbf{T}}_c + \rho\phi_c \mathbf{b}_c + \tilde{\mathbf{m}}_c$

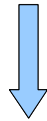
$\Rightarrow \mathbf{v}_c = \mathbf{K} (-\nabla \Sigma(\phi_c) + \chi \nabla C)$

Unsaturated cells in ECM

$$\mathbf{v}_c = \mathbf{K} (-\nabla \Sigma(\phi_c) + \chi \nabla C)$$



$$\frac{\partial \phi_c}{\partial t} + \nabla \cdot (\phi_c \mathbf{v}_c) = \Gamma_c$$



$$\frac{\partial \phi_c}{\partial t} + \nabla \cdot (\chi \phi_c \mathbf{K} \nabla C) = \nabla \cdot (\phi_c \mathbf{K} \nabla \Sigma_c) + \Gamma_c$$

Degenerate parabolic equation
Generalized Keller-Segel equation

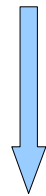


Saturated biphasic mixture

$$\frac{\partial \varphi_1}{\partial t} + \nabla \cdot (\varphi_1 \mathbf{v}_{\mathbf{x}}) = \Gamma_1$$

$$\frac{\partial \varphi_2}{\partial t} + \nabla \cdot (\varphi_2 \mathbf{v}_{\mathbf{x}}) = \Gamma_2$$

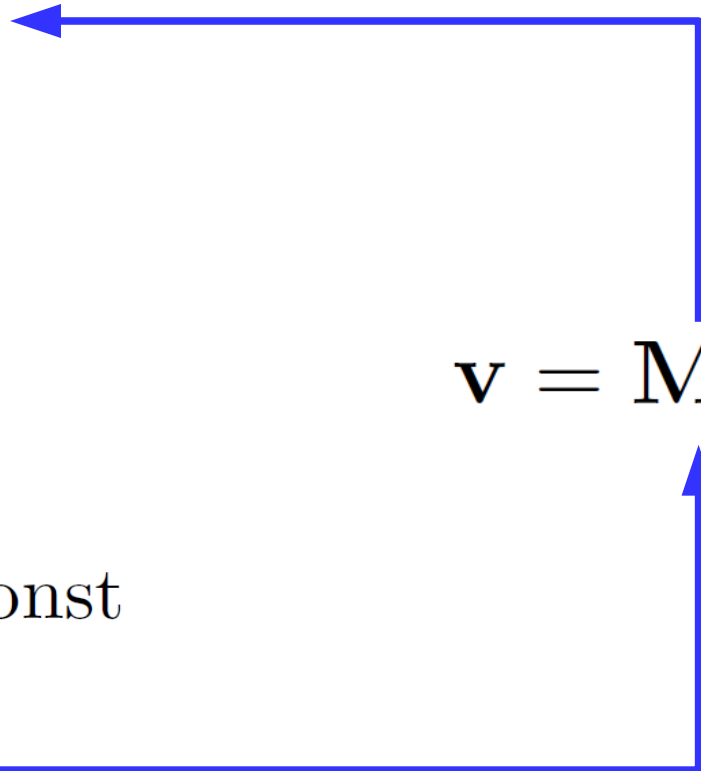
$$\nabla \cdot \mathbf{T} - \mathbf{M}\mathbf{v} = \mathbf{0}$$



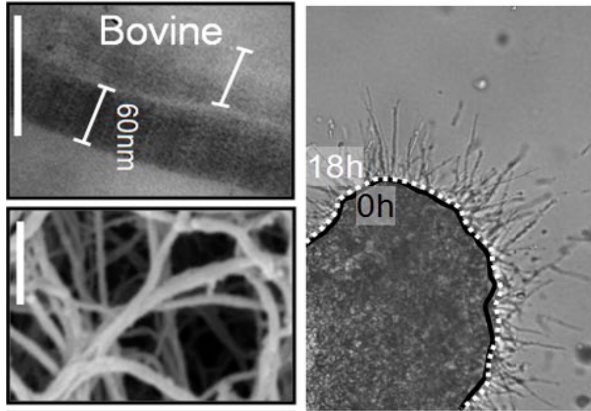
$$\varphi_1 + \varphi_2 = \text{const}$$

$$\mathbf{T} = \lambda \mathbf{I} + \dots$$

$$\mathbf{v} = \mathbf{M}^{-1} \nabla \lambda$$



Back to the continuous model



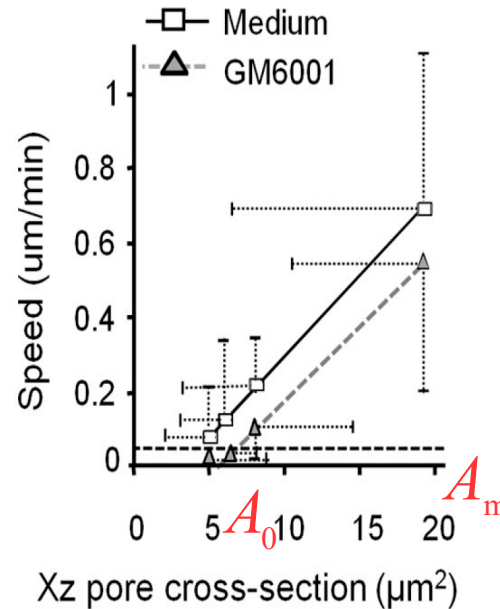
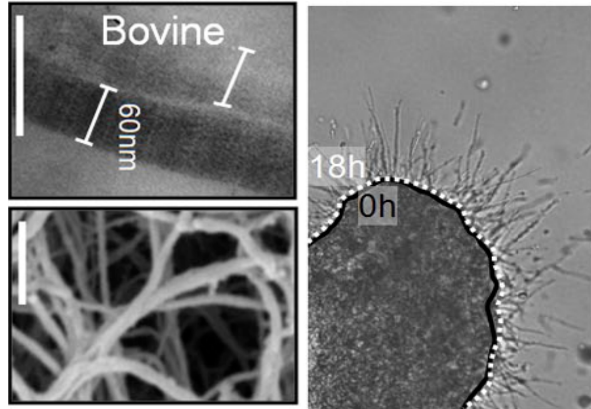
$$\frac{\partial \phi_c}{\partial t} + \nabla \cdot (\phi_c \mathbf{v}_c) = \Gamma_c ,$$

$$\nabla \cdot \mathbf{T}_c + \mathbf{m}_{cm} = 0$$

$$\mathbf{v}_c = -\mathbf{K} \nabla \cdot \mathbf{T}_c$$

Motility tensor

Back to the continuous model



Implications for
interaction force m_{cm}
and motility K ?

$$\frac{\partial \phi_c}{\partial t} + \nabla \cdot (\phi_c \mathbf{v}_c) = \Gamma_c,$$

$$\nabla \cdot \mathbf{T}_c + m_{cm} = 0$$

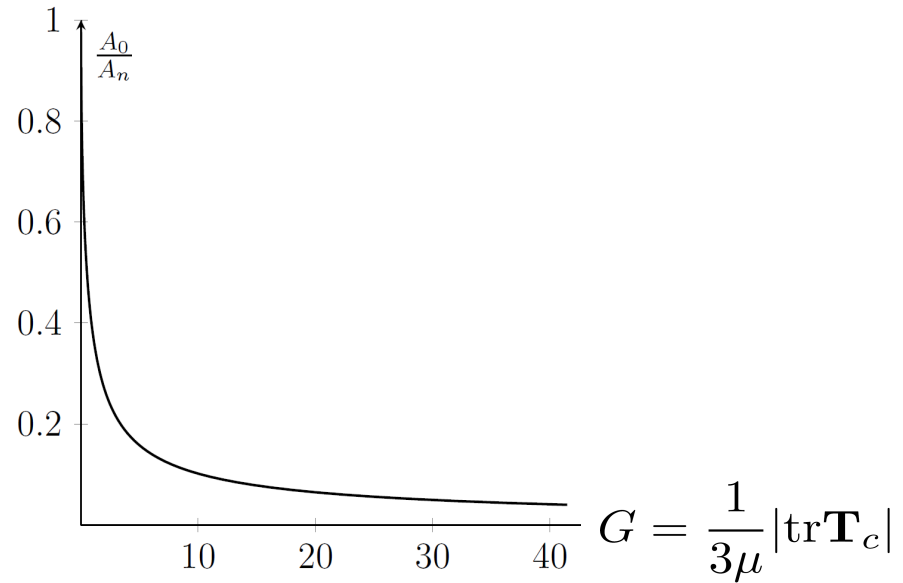
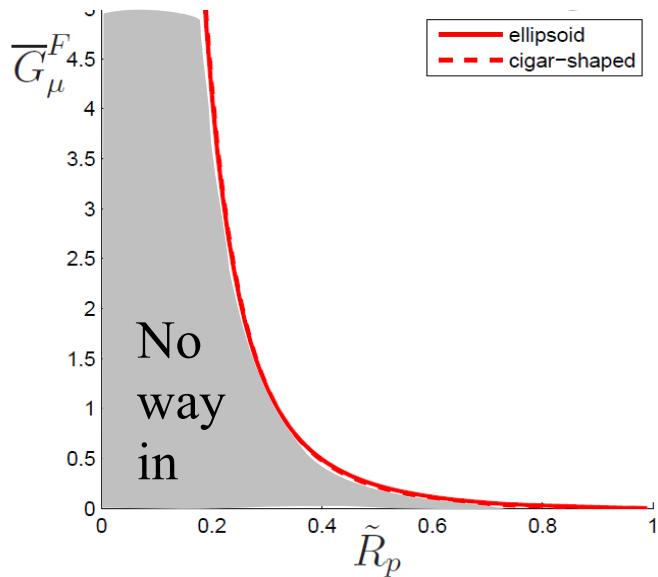
$$\mathbf{v}_c = \alpha \frac{[A_m(\phi_m) - A_0]_+}{\left(1 + \frac{A_m(\phi_m) - A_0}{A_1}\right)^n} \nabla \cdot \mathbf{T}_c$$

A_0 depends on:

- Pore vs. nucleus size
- Nucleus elasticit
- Cell adhesion
- Active traction
- Action of MMP

Back to the continuous model

$$G_{\mu}^F = \frac{\rho_b \alpha_{ECM} F_b^M}{\mu}$$

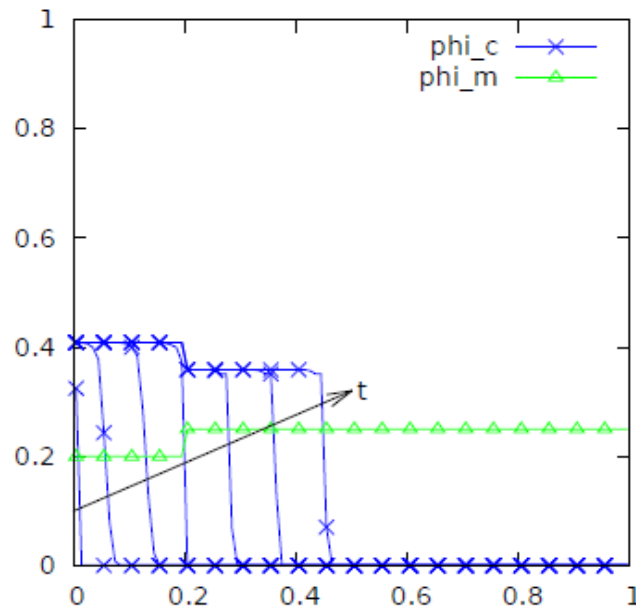
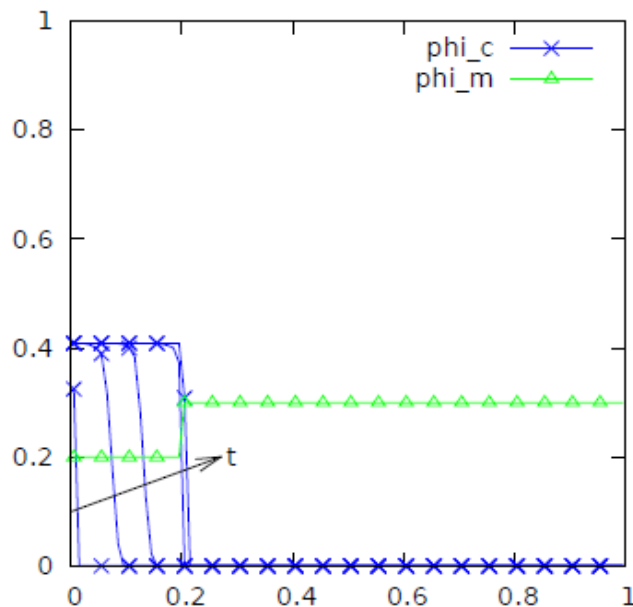


$$G = \frac{1}{3\mu} |\text{tr} \mathbf{T}_c|$$

One population

$$\frac{\partial \phi_c}{\partial t} + \nabla \cdot (\phi_c \mathbf{v}_c) = \Gamma_c \quad \leftarrow [\gamma_c H_\epsilon(\bar{\phi} - \phi_c) - \delta] \phi_c$$

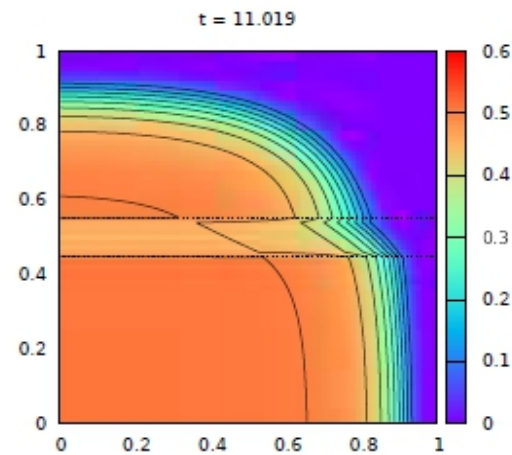
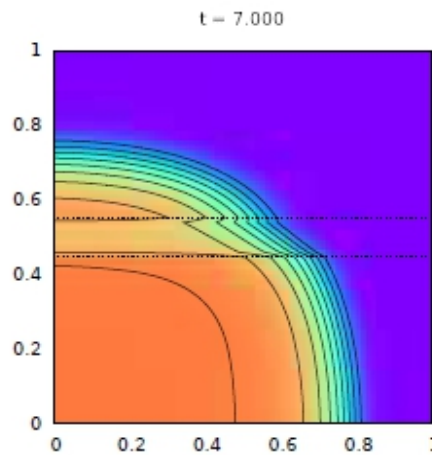
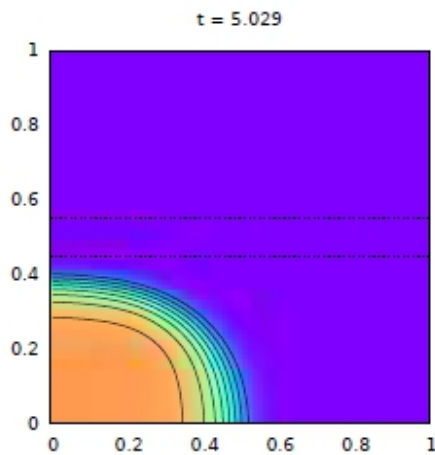
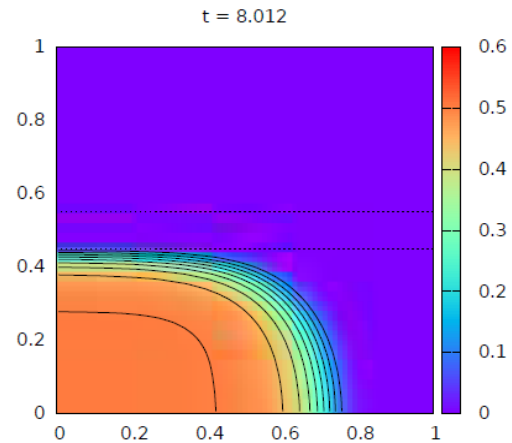
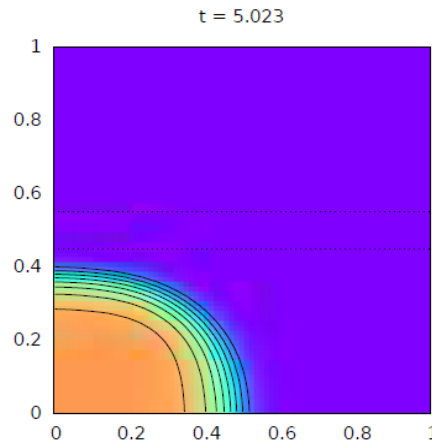
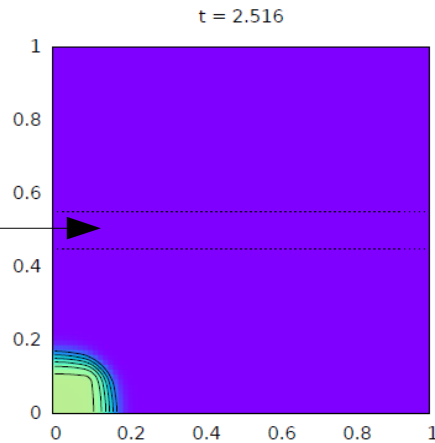
$$\mathbf{v}_c = \alpha \frac{[A_m(\phi_m) - A_0]_+}{\left(1 + \frac{A_m(\phi_m) - A_0}{A_1}\right)^n} \nabla \cdot \mathbf{T}_c \quad \leftarrow -\Sigma_c(\phi_c) \mathbf{I}$$





Growth below a thick region of ECM

$$\phi_m^+ = 0.3$$

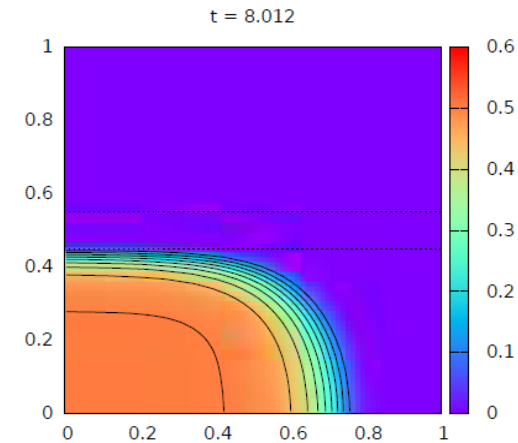
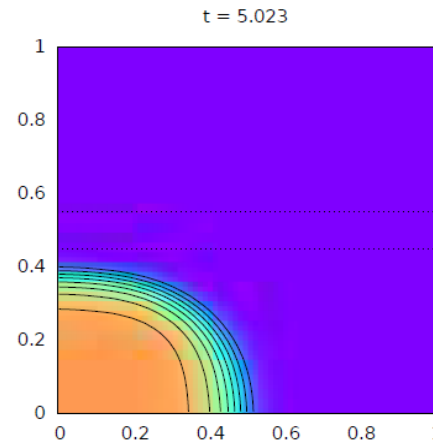
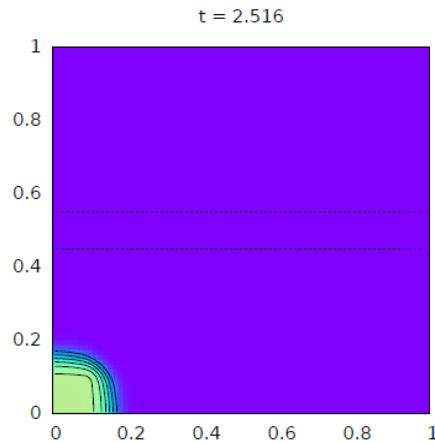


$$\phi_m^+ = 0.25$$

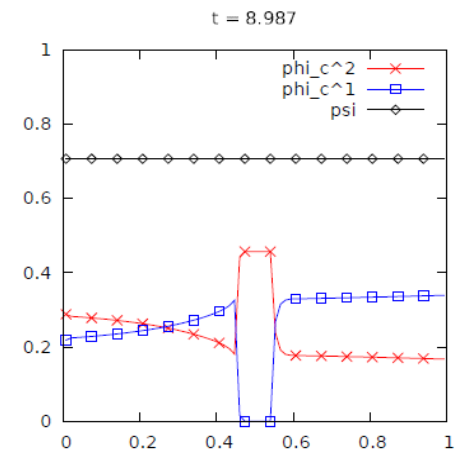
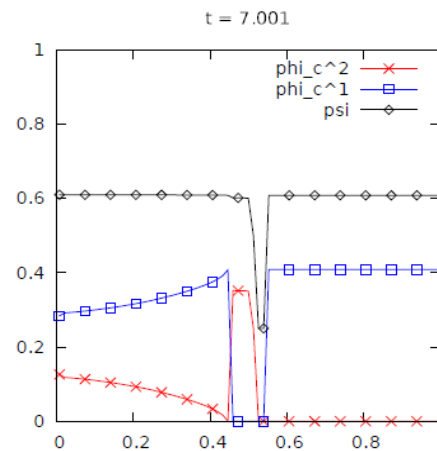
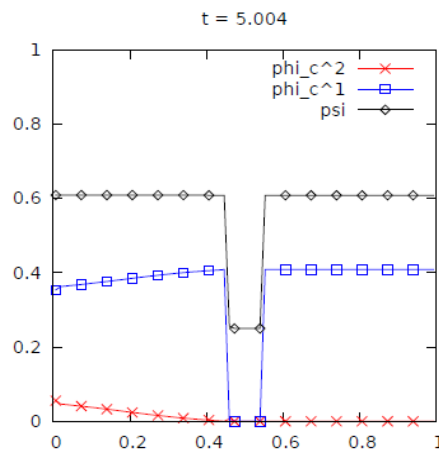


Effect of nucleus deformability

Stiffer nucleus



Softer nucleus



Nuclear membrane stiffness

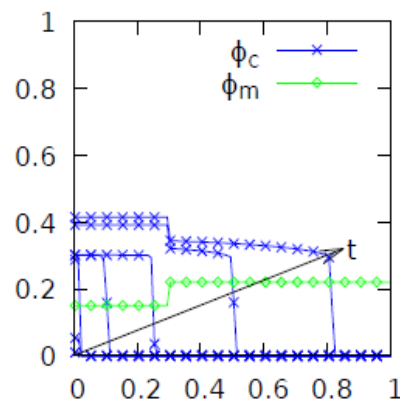
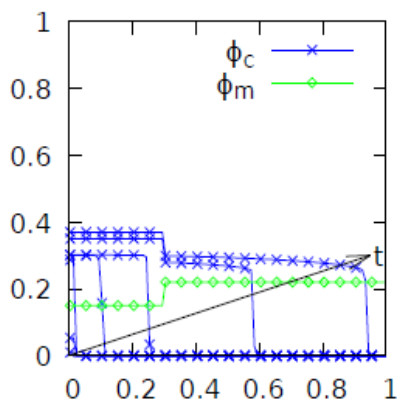
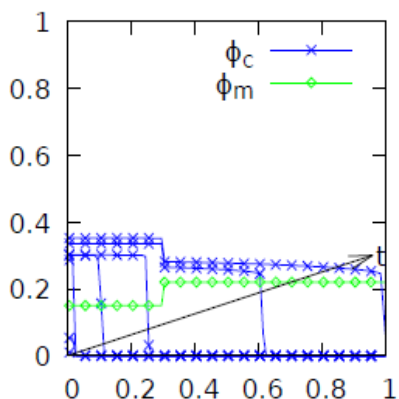
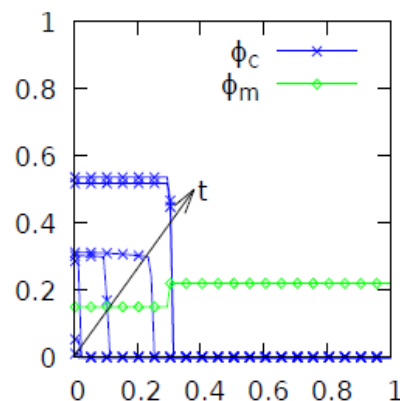
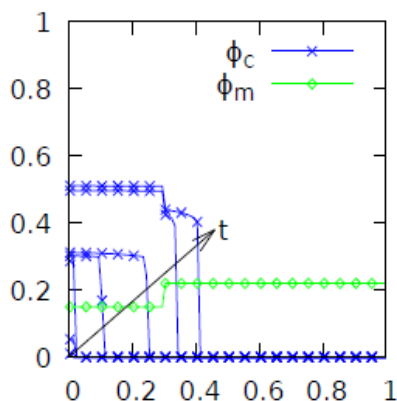
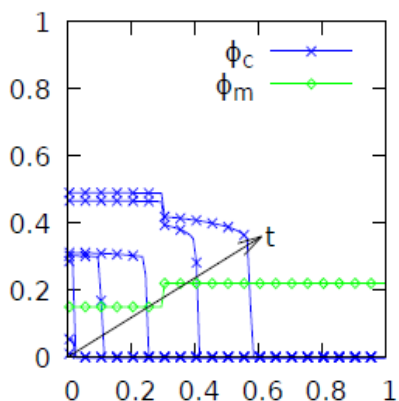
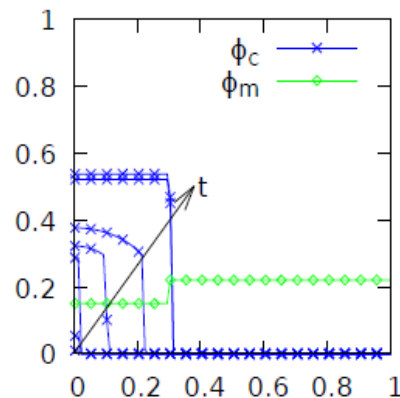
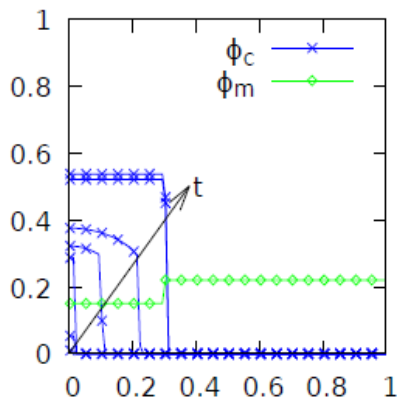
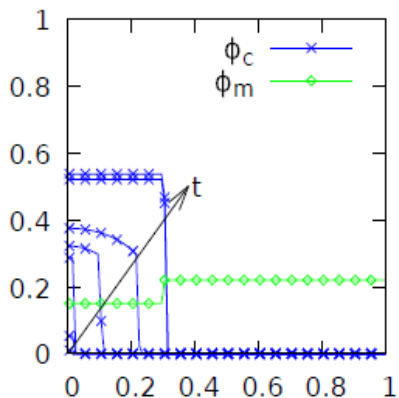
$\beta_0 = 0.5$

$\beta_0 = 2$

$\beta_0 = 8$

$$\beta := \frac{\lambda R_n}{\mu}$$

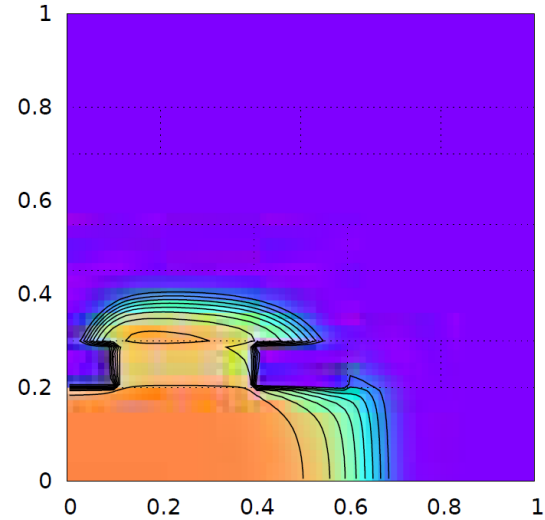
Bulk stiffness



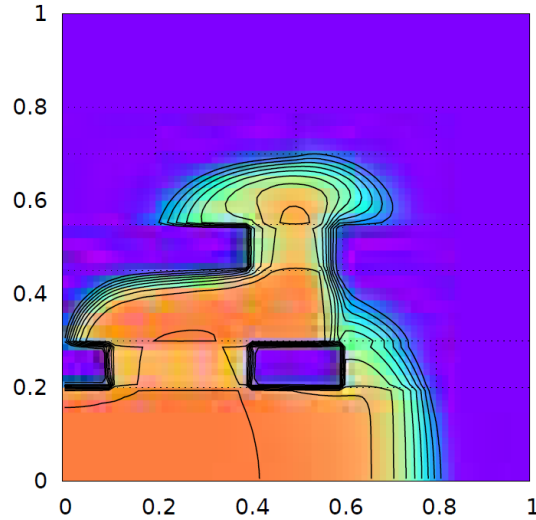


Heterogeneous ECM

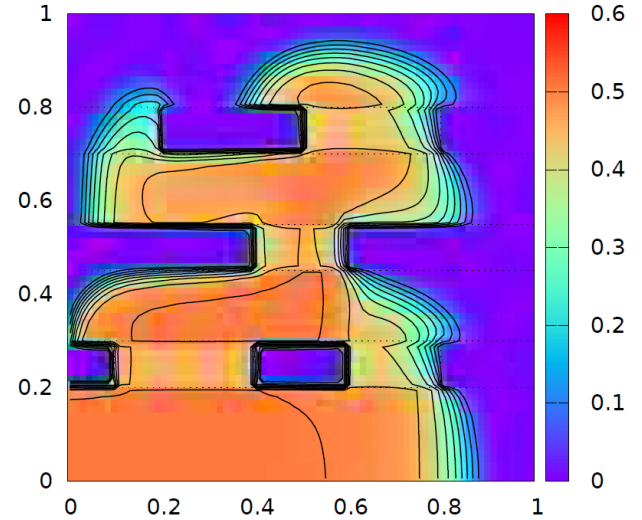
$t = 5.387$



$t = 7.023$

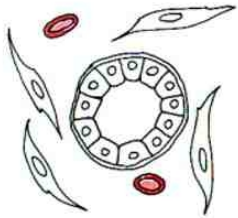


$t = 9.241$

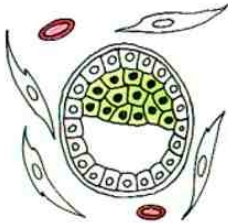


Tumour compartmentalization and invasion

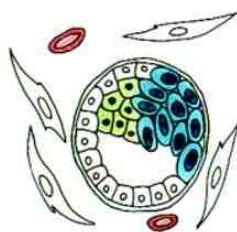
Normal
duct



Hyperplasia



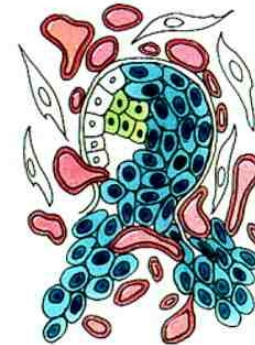
Dysplasia/
CIS



Angiogenic
CIS



Invasive
carcinoma



Breast

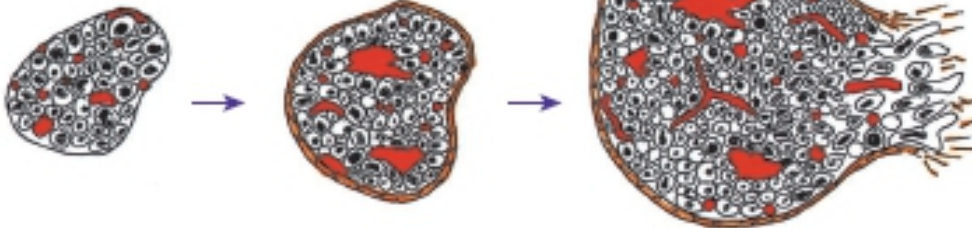
Ovary

Pancreas

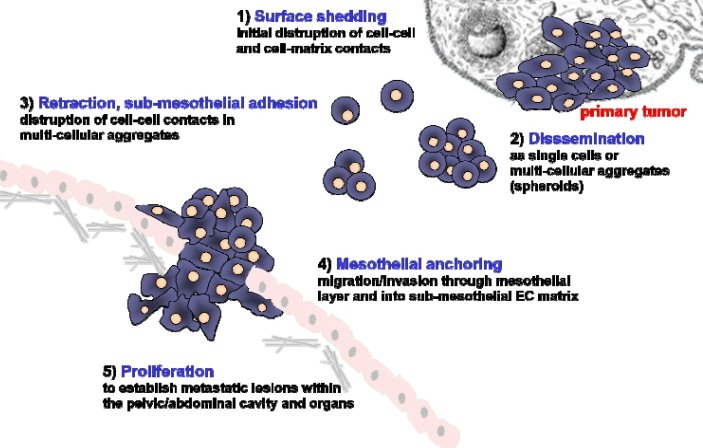
Angiogenic
Dysplasia/CIS

Small Tumor

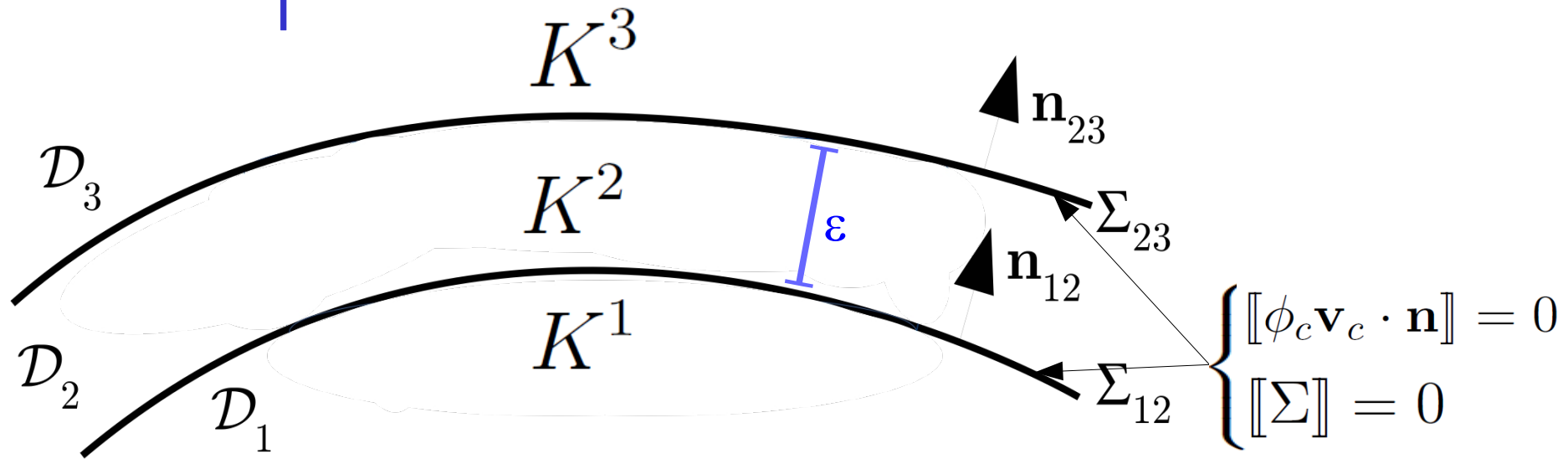
Large Tumor/
Invasive Carcinoma



Ovarian cancer dissemination



Membrane problem

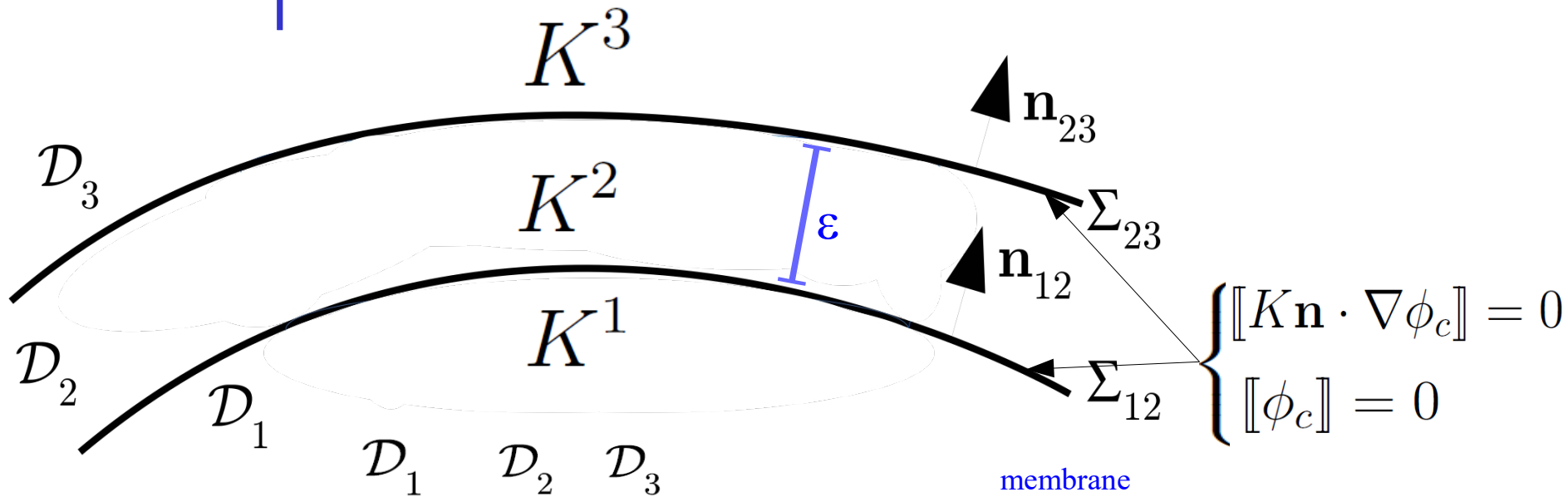


$$\frac{\partial \phi_c^i}{\partial t} + \nabla \cdot (\phi_c^i \mathbf{v}_c^i) = \Gamma_c^i$$

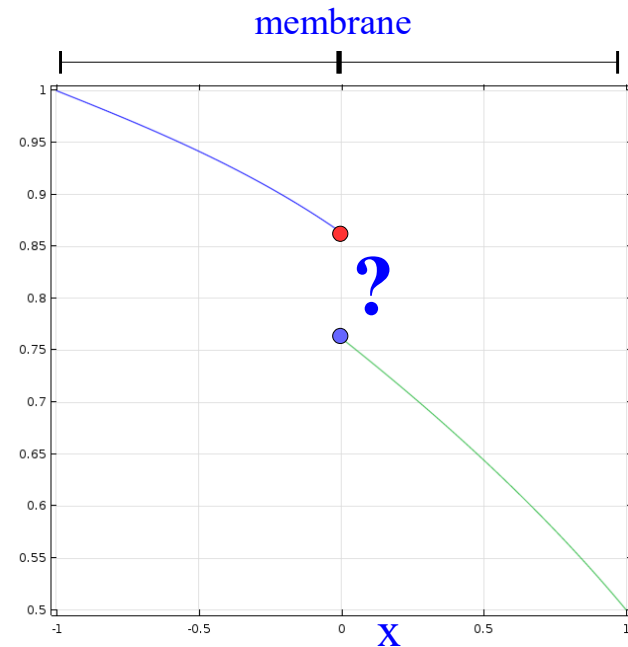
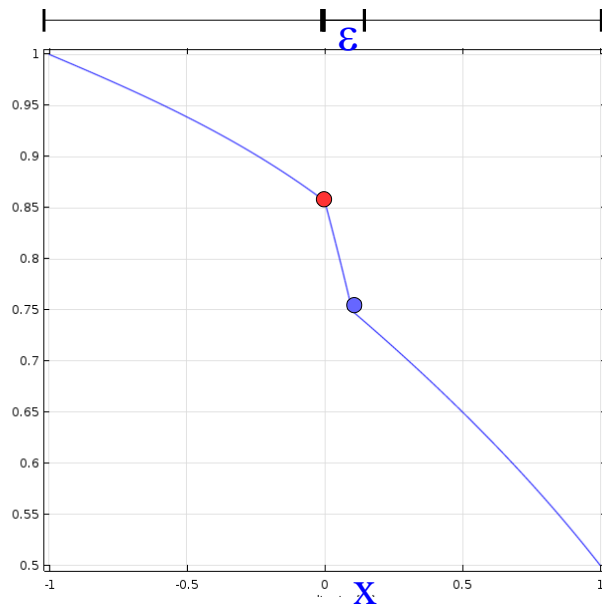
$$\mathbf{v}_c^i = -K^i \nabla \Sigma(\phi_c^i) = -K^i \Sigma'(\phi_c^i) \nabla \phi_c^i$$

$$\frac{\partial \phi_c^i}{\partial t} = \nabla \cdot [K^i \phi_c^i \nabla \Sigma(\phi_c^i)] + \Gamma_c^i$$

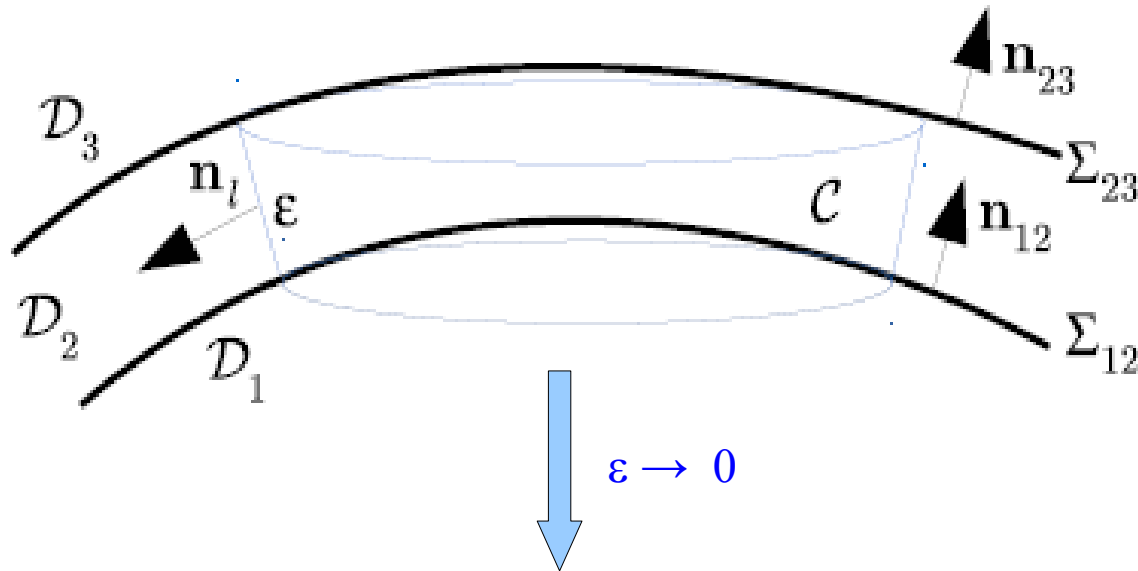
Membrane problem



$$\begin{cases} [[K \mathbf{n} \cdot \nabla \phi_c]] = 0 \\ [[\phi_c]] = 0 \end{cases}$$



Membrane problem



$$\tilde{K}_2[[\Pi]] = K^1 \phi_c^1 \mathbf{n} \cdot \nabla \Sigma(\phi_c^1) = K^3 \phi_c^3 \mathbf{n} \cdot \nabla \Sigma(\phi_c^3)$$

where $\Pi'(\phi_c) = \phi_c \Sigma'(\phi_c)$

$$\tilde{K}_2 = \lim_{\varepsilon \rightarrow 0} \frac{K^2}{\varepsilon}$$

Membrane problem

$$\frac{\partial \phi_c^i}{\partial t} = \nabla \cdot [K^i \phi_c^i \nabla \Sigma(\phi_c^i)] + \Gamma_c^i$$

- Scale perpendicular coordinate (η) with ε

- Expand $\phi_c^2 \approx \phi_0^2 + \varepsilon \phi_1^2$

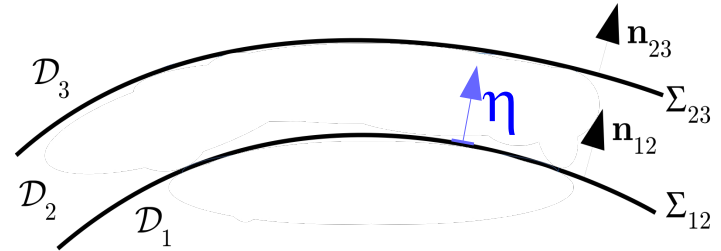
- Leading order $\frac{\partial}{\partial \eta} \left[\tilde{K}_2 \phi_0^2 \frac{\partial \Sigma(\phi_0^2)}{\partial \eta} \right] = 0$

$$\tilde{K}_2 \phi_0^2 \frac{\partial \Sigma(\phi_0^2)}{\partial \eta} = \text{const}$$

↓

$$\begin{aligned} & \llbracket \phi_c \mathbf{v}_c \cdot \mathbf{n} \rrbracket = 0 \quad \text{At the interfaces} \\ & \begin{aligned} & \rightarrow K^1 \phi_0^1 \mathbf{n}_{12} \cdot \nabla \Sigma(\phi_0^1) \\ & \parallel \\ & \rightarrow K^3 \phi_0^3 \mathbf{n}_{23} \cdot \nabla \Sigma(\phi_0^3) \end{aligned} \end{aligned}$$

$$\tilde{K}_2 = \lim_{\varepsilon \rightarrow 0} \frac{K^2}{\varepsilon}$$



Membrane problem

$$\frac{\partial \phi_c^i}{\partial t} = \nabla \cdot [K^i \phi_c^i \nabla \Sigma(\phi_c^i)] + \Gamma_c^i$$

At the interface

$$K^1 \phi_0^1 \Sigma'(\phi_0^1) \phi_0^1 \mathbf{n} \cdot \nabla \phi_0^1$$

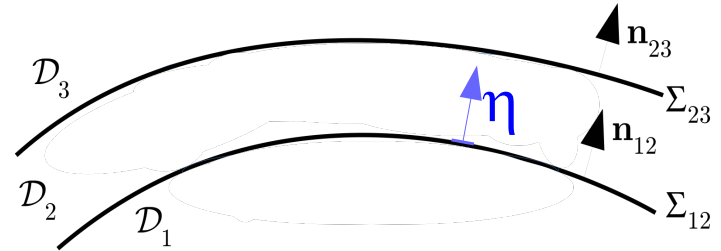
||

$$K^3 \phi_0^3 \Sigma'(\phi_0^3) \phi_0^1 \mathbf{n} \cdot \nabla \phi_0^3$$

$$\longrightarrow \int_0^1 \tilde{K}_2 \phi_0^2 \frac{\partial \Sigma(\phi_0^2)}{\partial \eta} d\eta = \text{const}$$

||

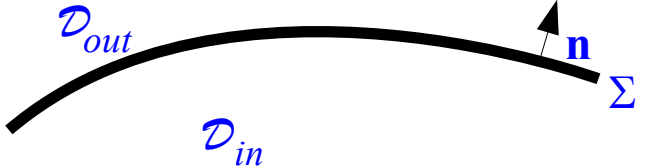
$$\int_0^1 \tilde{K}_2 \frac{\partial \Pi}{\partial \eta} d\eta = \tilde{K}_2 [[\Pi]]$$



Defining

$$\Pi'(\phi_c) = \phi_c \Sigma'(\phi_c)$$

Membrane problem

$$\left\{ \begin{array}{l} \frac{\partial \phi_c}{\partial t} = \nabla \cdot [K \Sigma'(\phi_c) \phi_c \nabla \phi_c] + \Gamma_c \\ \llbracket K \phi_c \mathbf{n} \cdot \nabla \Sigma(\phi_c) \rrbracket = 0 \quad \text{on } \Sigma, \\ \tilde{K} \llbracket \Pi \rrbracket = K \phi_c \mathbf{n} \cdot \nabla \Sigma(\phi_c) \quad \text{on } \Sigma, \end{array} \right.$$


where $\Pi'(\phi_c) = \phi_c \Sigma'(\phi_c)$

$$\text{if } \Sigma(\phi_c) = \Phi \ln \frac{\phi_c}{\phi_0} \longrightarrow \phi_c \Sigma'(\phi_c) = \Phi \longrightarrow \Pi = \Phi \phi_c$$

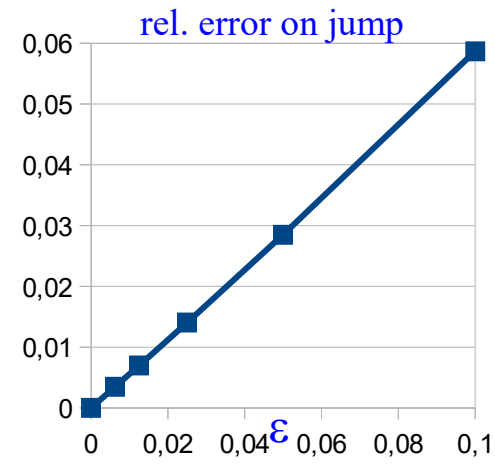
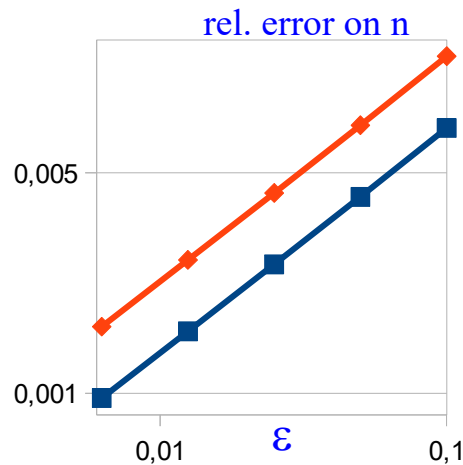
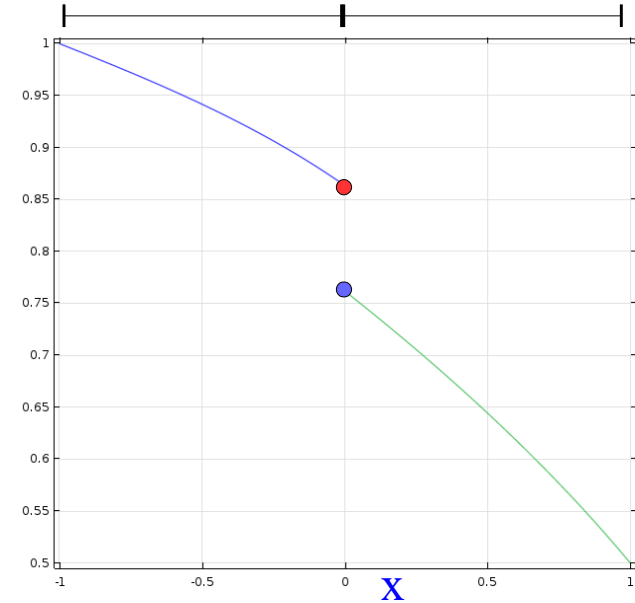
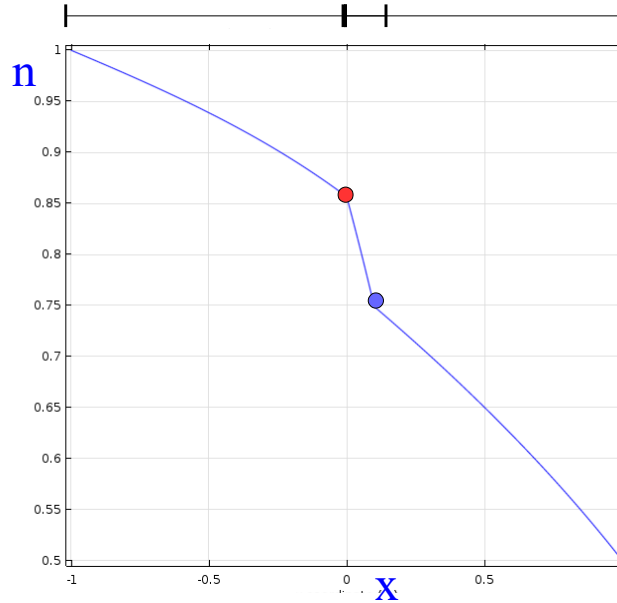
$$\longrightarrow \tilde{K} \llbracket \phi_c \rrbracket = K \mathbf{n} \cdot \nabla \phi_c \quad \text{Kadem-Katchalsky interface condition}$$



Stationary 1D problem

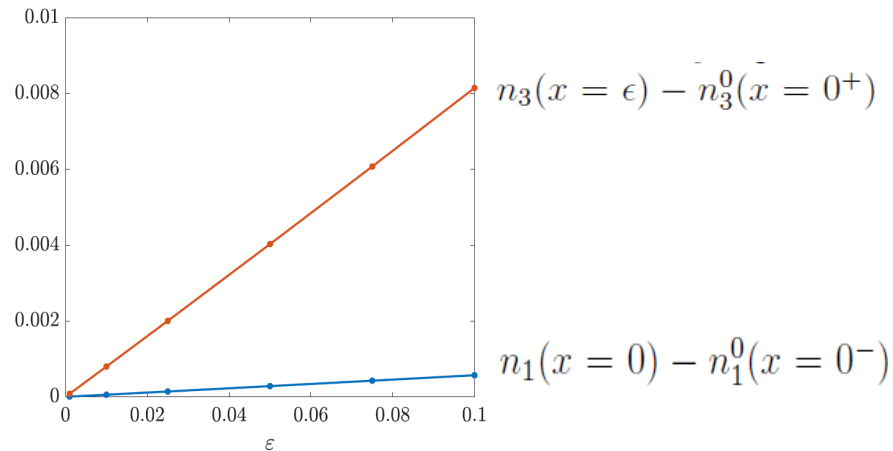
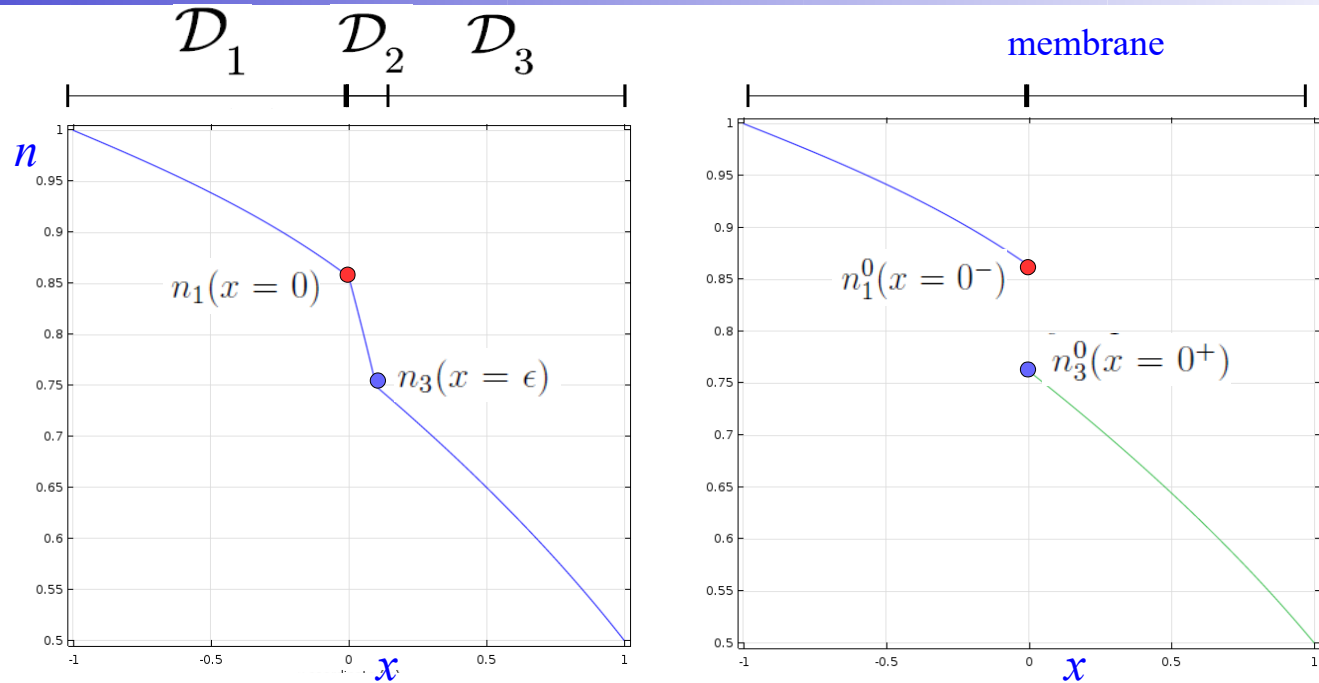
$\mathcal{D}_1$ $\mathcal{D}_2$ $\mathcal{D}_3$

membrane





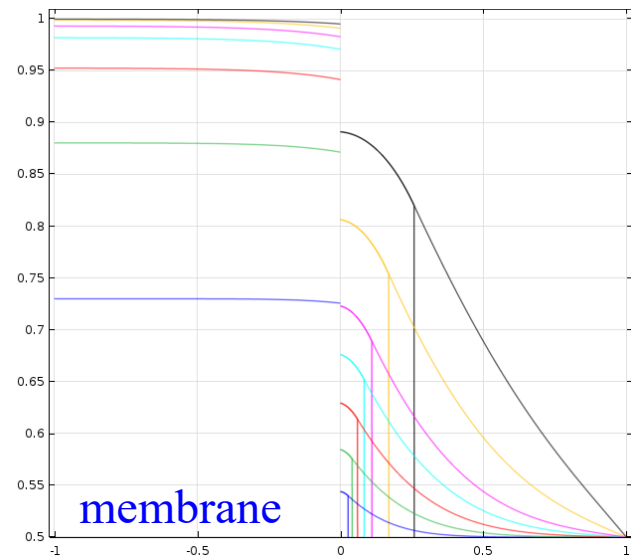
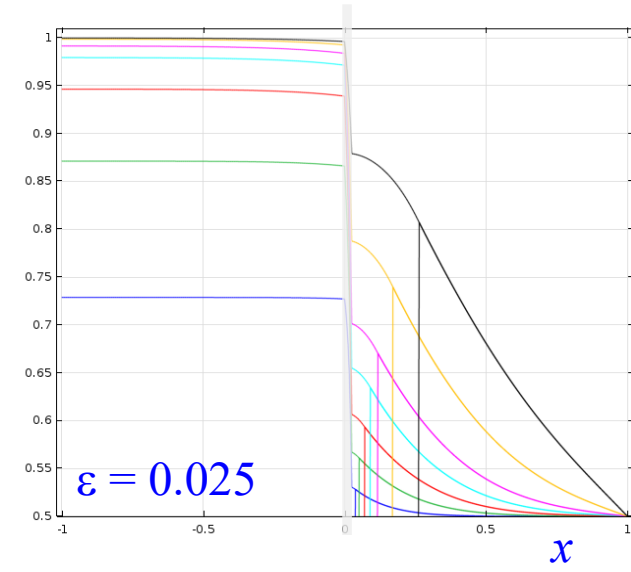
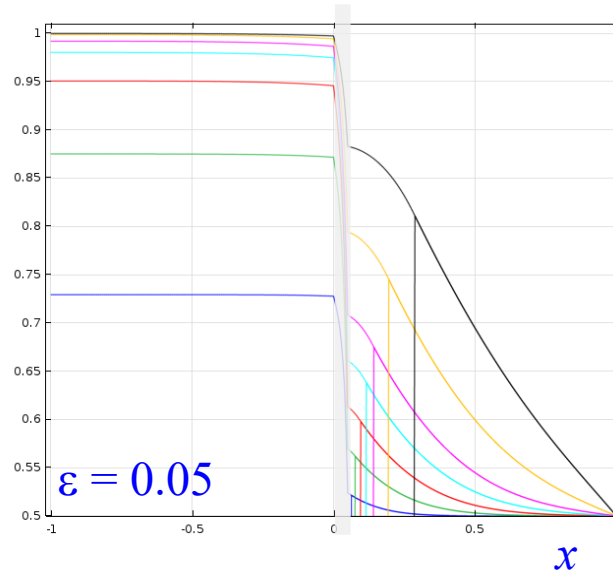
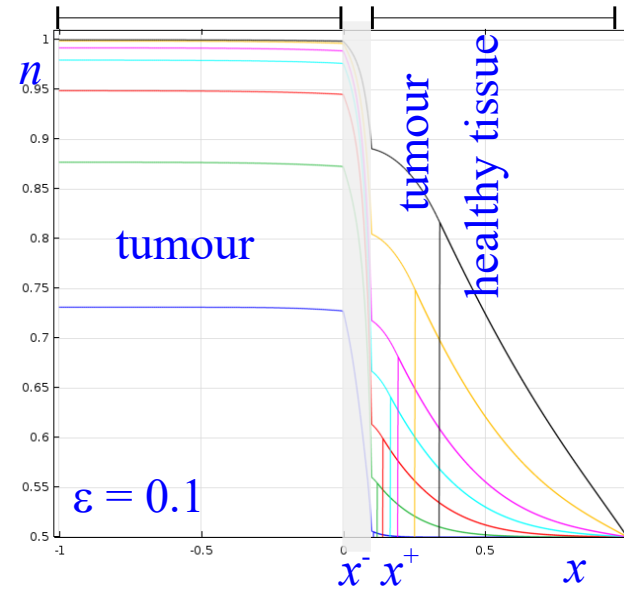
Stationary 1D problem



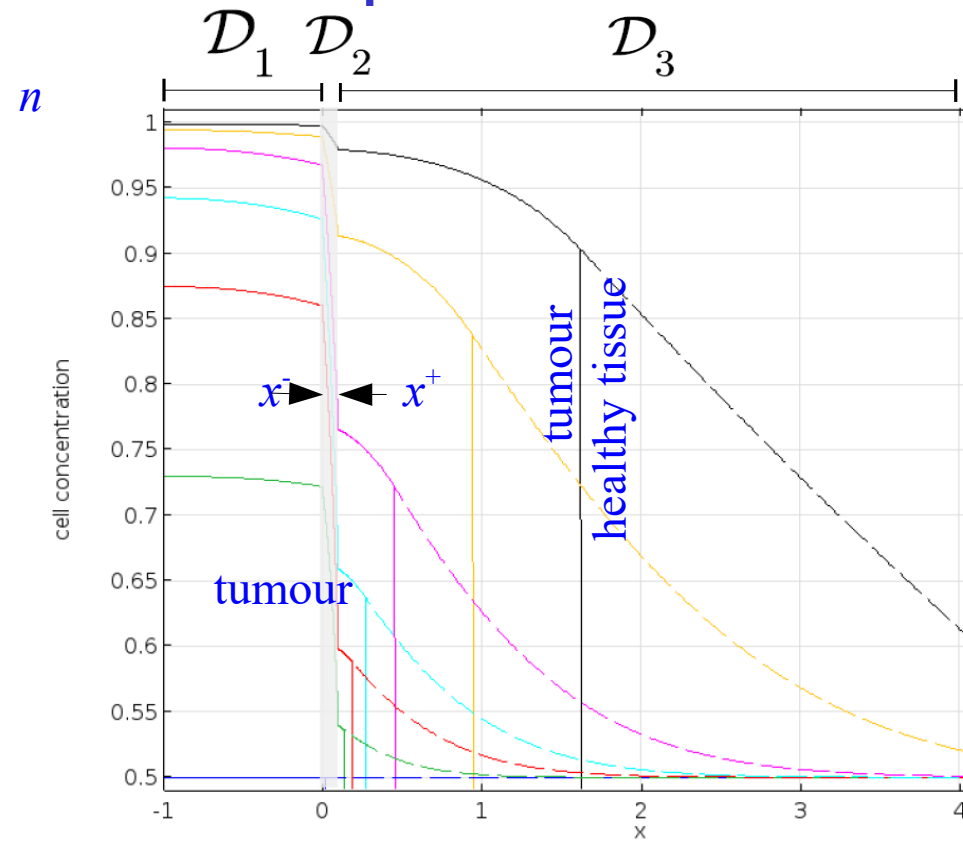


Unsteady 1D problem

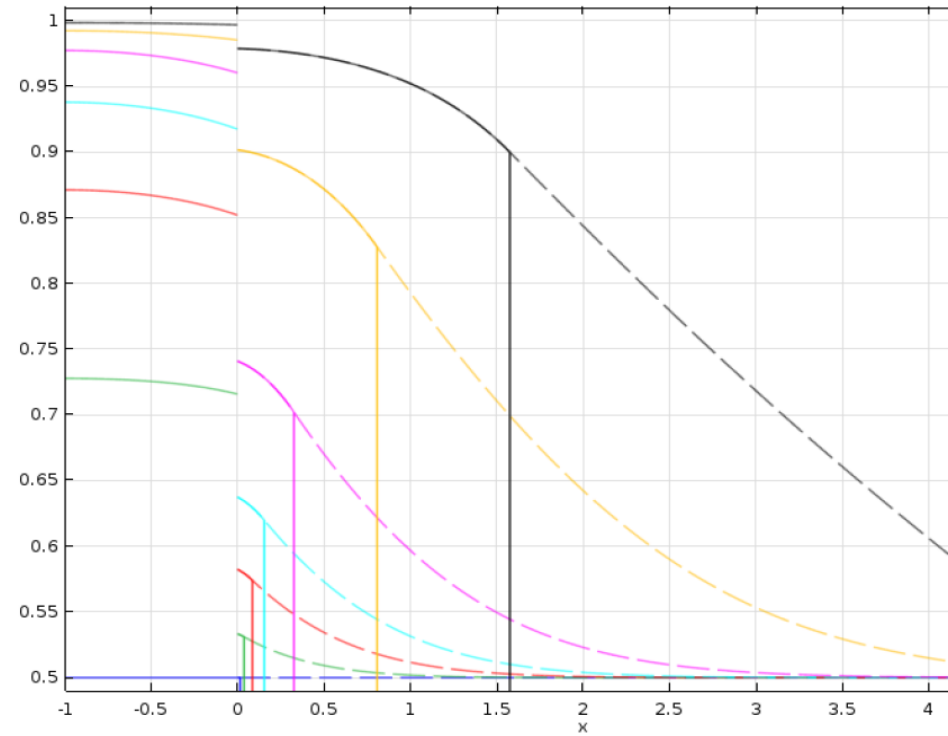
$\mathcal{D}_1$ $\mathcal{D}_2$ $\mathcal{D}_3$



Unsteady 1D problem



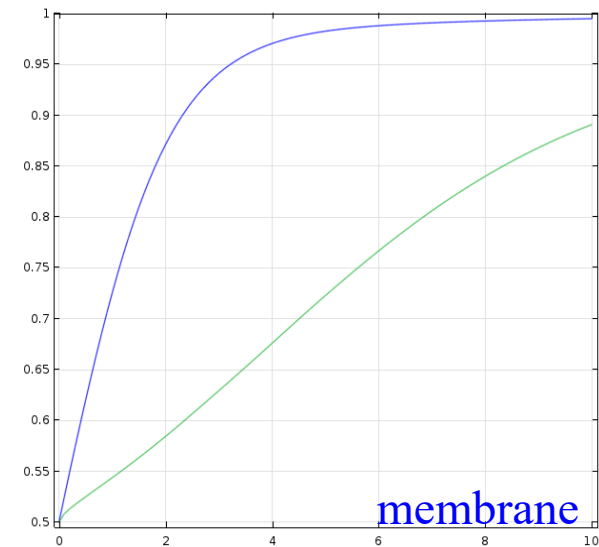
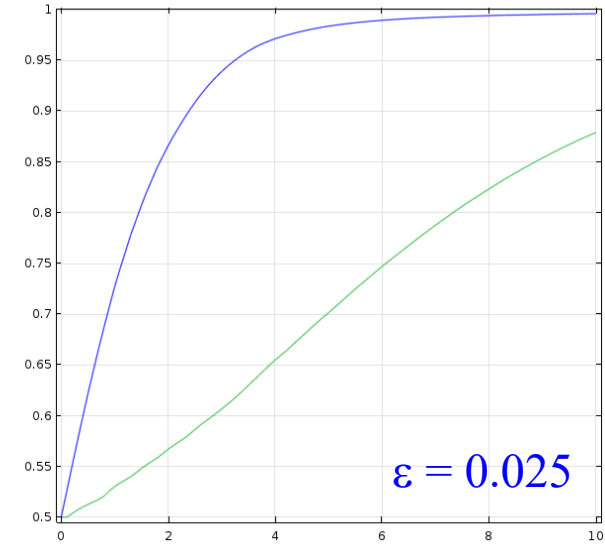
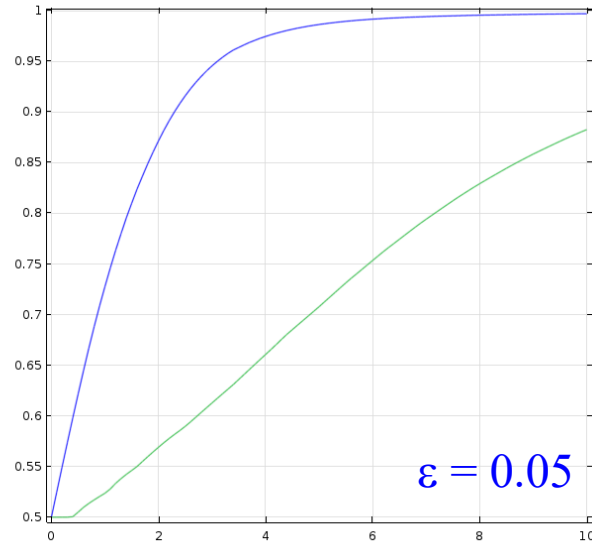
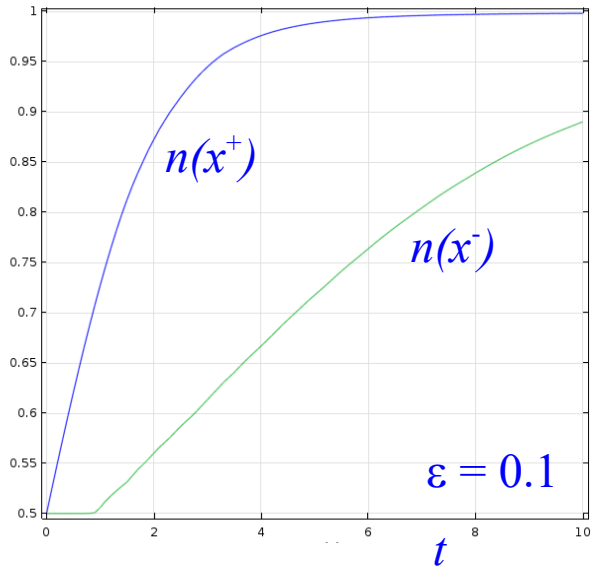
$\varepsilon = 0.1$



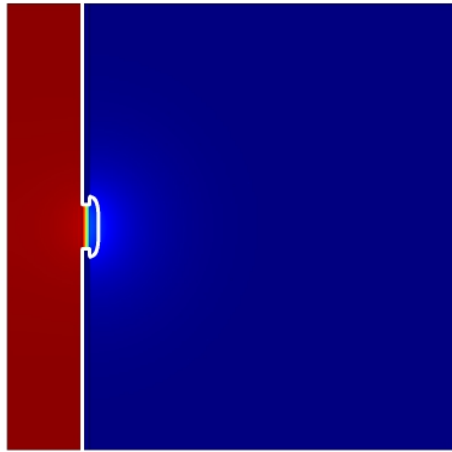
membrane



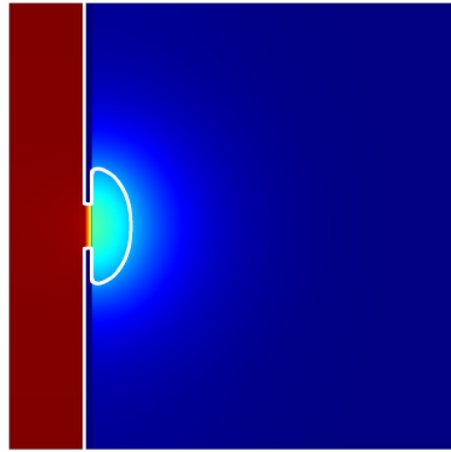
Unsteady 1D problem



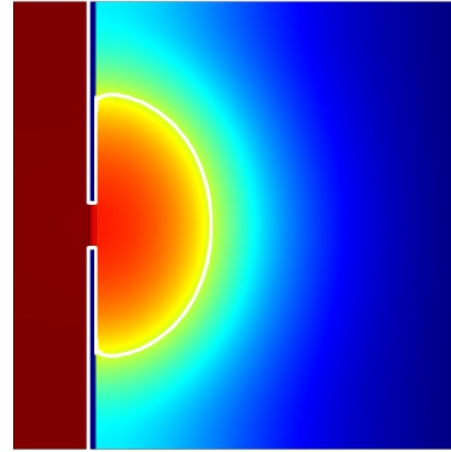
Invasion from a duct



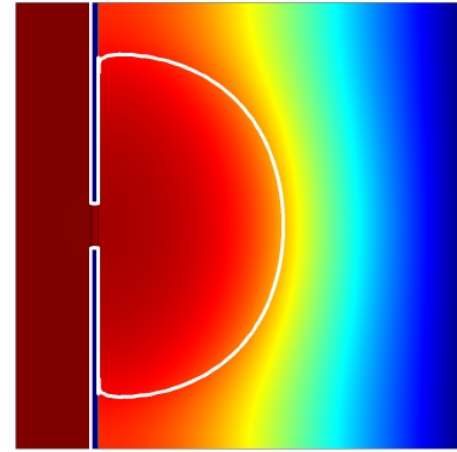
(a) $t = 5$



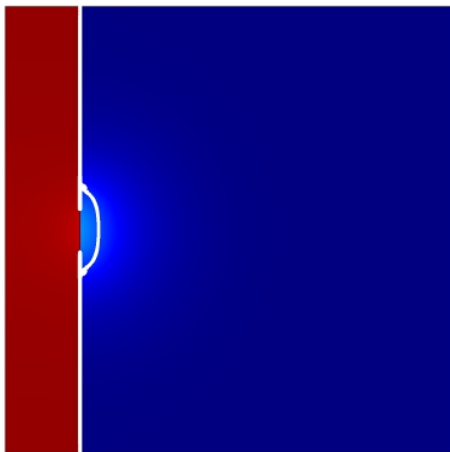
(b) $t = 10$



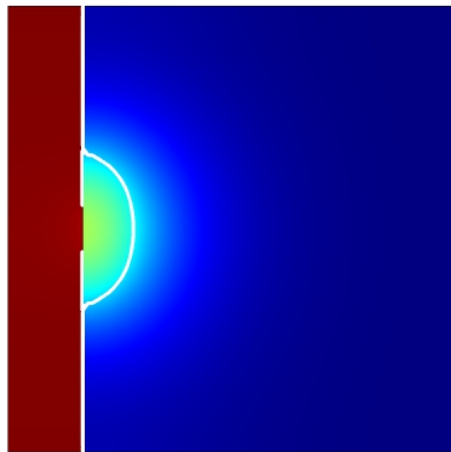
(c) $t = 20$



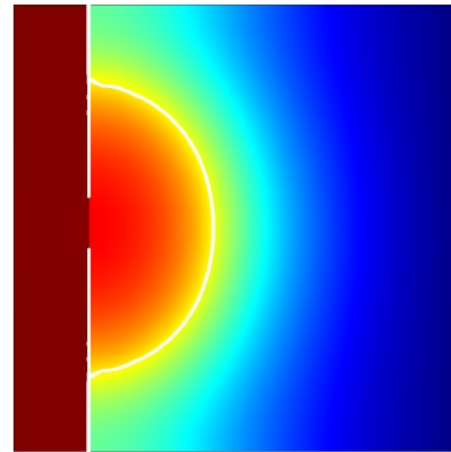
(d) $t = 30$



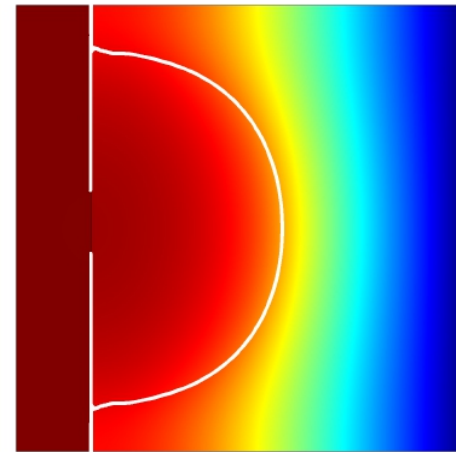
(e) $t = 5$



(f) $t = 10$



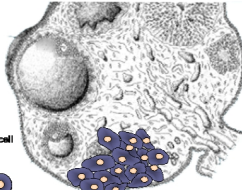
(g) $t = 20$



(h) $t = 30$

Invasion of ovary cancer cells

Ovarian cancer dissemination



1) **Surface shedding**
Initial disruption of cell-cell
and cell-matrix contacts

3) **Retraction, sub-mesothelial adhesion**
disruption of cell-cell contacts in
multi-cellular aggregates

2) **Dissemination**
as single cells or
multi-cellular aggregates
(spheroids)

4) **Mesothelial anchoring**
migration/invasion through mesothelial
layer and into sub-mesothelial EC matrix

5) **Proliferation**
to establish metastatic lesions within
the pelvic/abdominal cavity and organs

Adding tumour produced metallo-proteinases

$$\frac{dA}{dt} = \alpha (A_1 - A) + \beta c_{MMP}$$

$$\tilde{\mu} = \bar{\mu} \frac{[A - A_0]_+}{1 + (A - A_0)}$$

Invasion of ovary cancer cells

Ovarian cancer dissemination



1) Surface shedding
initial disruption of cell-cell
and cell-matrix contacts

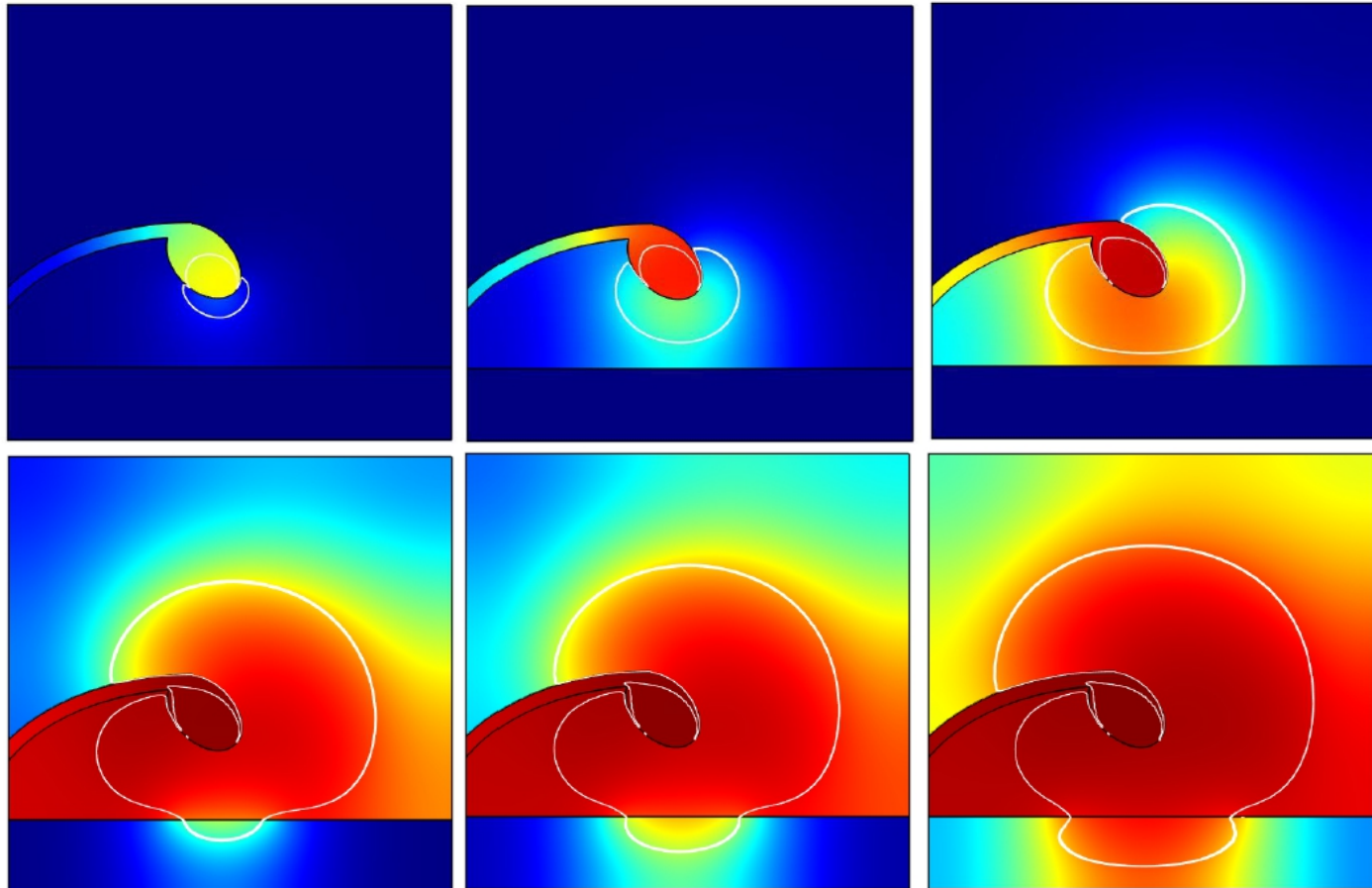
3) Retraction, sub-mesothelial adhesion
disruption of cell-cell contacts in
multi-cellular aggregates

4) Mesothelial anchoring
migration/invasion through mesothelial
layer and into sub-mesothelial EC matrix

5) Proliferation
to establish metastatic lesions within
the pelvic/abdominal cavity and organs



Adding tumour produced metallo-proteinases





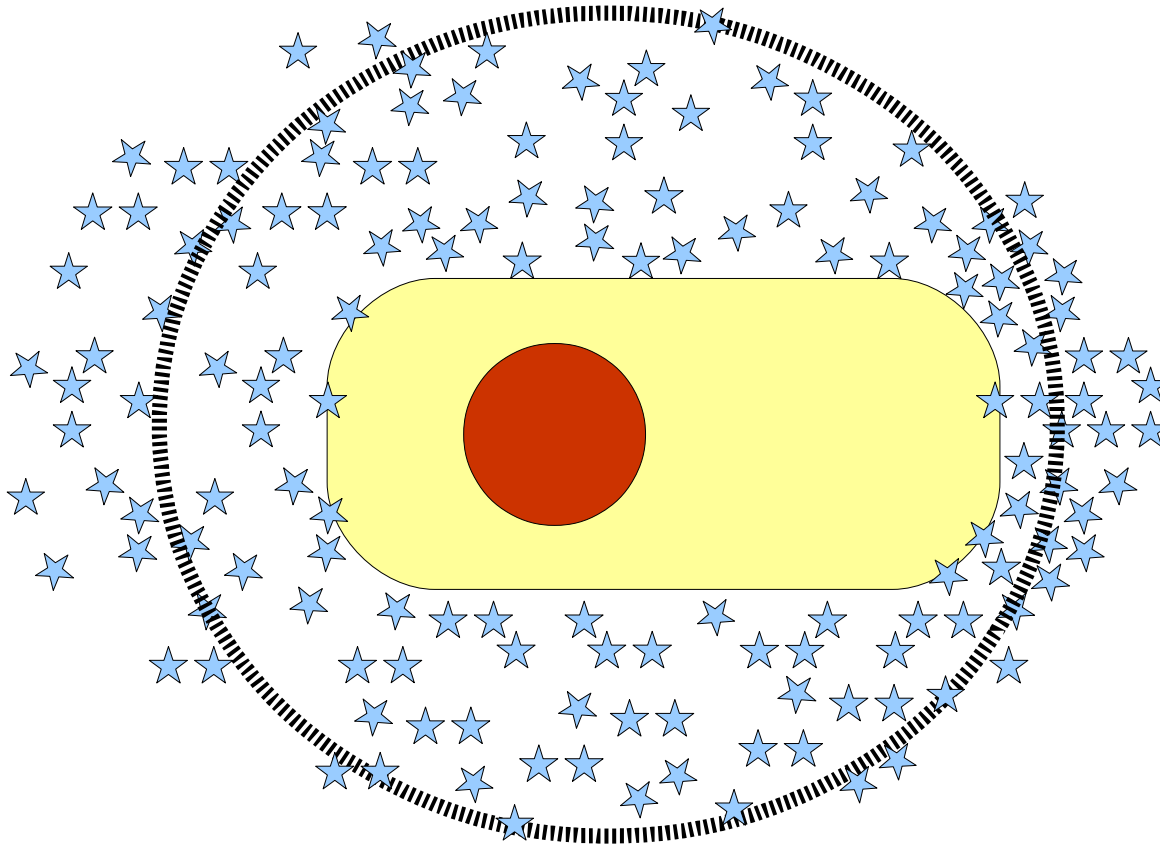
**POLITECNICO
DI TORINO**

Kinetic Model with Nonlocal Sensing

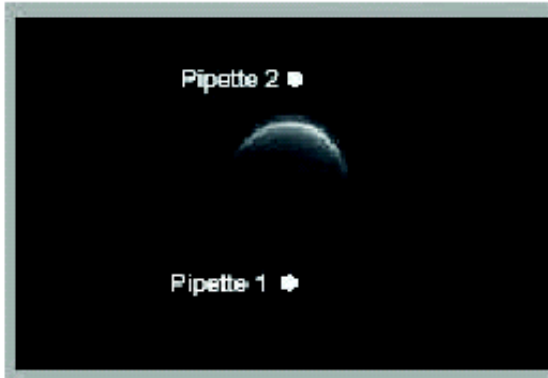


POLITECNICO
DI TORINO

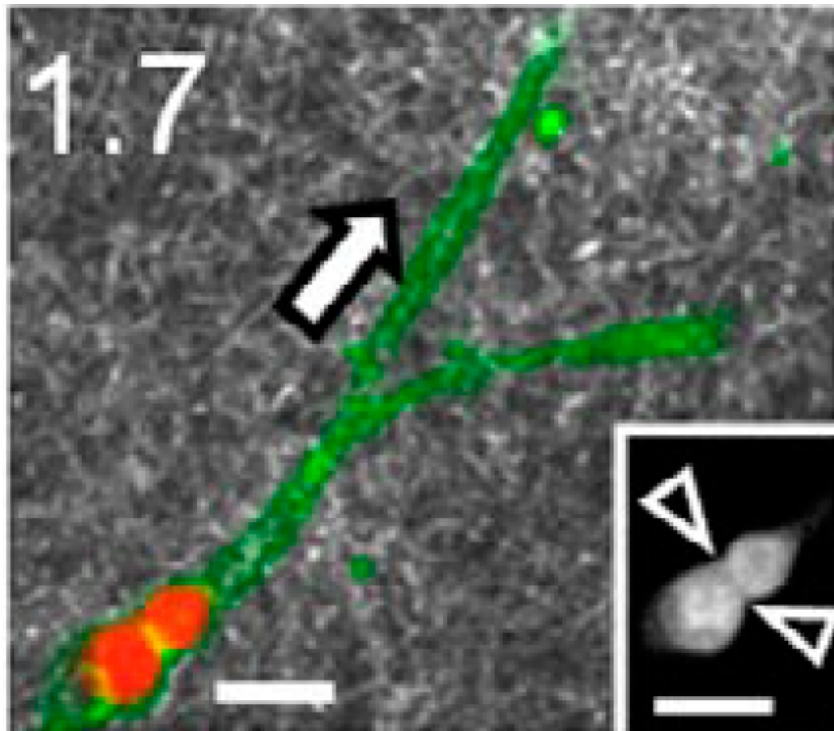
Scouting, polarization and motion



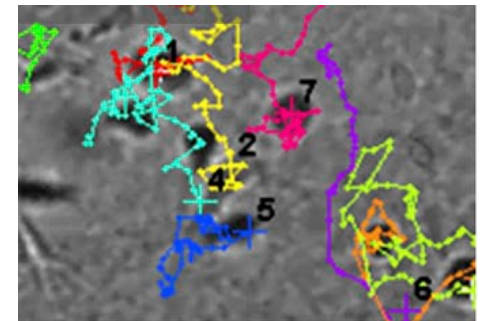
Scouting, polarization and motion



Devreotes,
Janetopoulos



Wolf
Friedl





Distribution function

$$p = p(t, \mathbf{x}, \mathbf{v}_p) \quad \mathbf{v}_p = (\hat{\mathbf{v}}, v) \in V_p = \mathbb{S}^{d-1} \times [0, U]$$

$$\rho(t, \mathbf{x}) = \int_{V_p} p(t, \mathbf{x}, \mathbf{v}_p) d\mathbf{v}_p$$

$$\mathbf{U}(t, \mathbf{x}) = \frac{1}{\rho(t, \mathbf{x})} \int_{V_p} p(t, \mathbf{x}, \mathbf{v}_p) \mathbf{v} d\mathbf{v}_p$$



Transport equation

$$p = p(t, \mathbf{x}, \mathbf{v}_p) \quad \mathbf{v}_p = (\hat{\mathbf{v}}, v) \in V_p = \mathbb{S}^{d-1} \times [0, U]$$

$$\frac{\partial p}{\partial t}(t, \mathbf{x}, \mathbf{v}_p) + \mathbf{v} \cdot \nabla p(t, \mathbf{x}, \mathbf{v}_p) = \mathcal{J}[p](t, \mathbf{x}, \mathbf{v}_p)$$

$$\mathcal{J}[p](\mathbf{x}, \mathbf{v}_p) = \mathcal{G}[p](\mathbf{x}, \mathbf{v}_p) - \mathcal{L}[p](\mathbf{x}, \mathbf{v}_p)$$



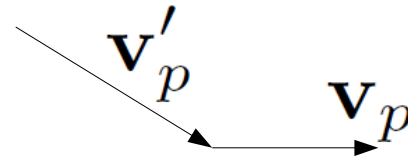
Turning operator

$$\mathcal{J}[p](\mathbf{x}, \mathbf{v}_p) = \mathcal{G}[p](\mathbf{x}, \mathbf{v}_p) - \mathcal{L}[p](\mathbf{x}, \mathbf{v}_p)$$

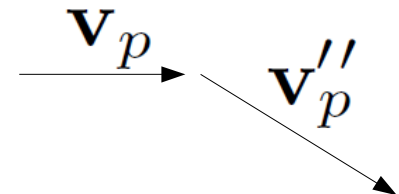
Turning Turning

rate frequency

$$\mathcal{G}[p](\mathbf{x}, \mathbf{v}_p) = \int_{V_p} \mu(\mathbf{x}, \mathbf{v}'_p) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p | \mathbf{v}'_p) p(t, \mathbf{x}, \mathbf{v}'_p) d\mathbf{v}'_p$$



$$\mathcal{L}[p](\mathbf{x}, \mathbf{v}_p) = \int_{V_p} \mu(\mathbf{x}, \mathbf{v}_p) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}''_p | \mathbf{v}_p) p(t, \mathbf{x}, \mathbf{v}_p) d\mathbf{v}''_p$$

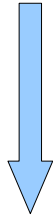




Turning operator

T is a transition probability $\int_{V_p} T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p'' | \mathbf{v}_p) d\mathbf{v}_p'' = 1$

$$\mathcal{L}[p](\mathbf{x}, \mathbf{v}_p) = \int_{V_p} \mu(\mathbf{x}, \mathbf{v}_p) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p'' | \mathbf{v}_p) p(t, \mathbf{x}, \mathbf{v}_p) d\mathbf{v}_p''$$



$$\mathcal{L}[p](\mathbf{x}, \mathbf{v}_p) = \mu(\mathbf{x}, \mathbf{v}_p) p(t, \mathbf{x}, \mathbf{v}_p)$$



Mass conservation

T is a transition probability

$$\int_{V_p} T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p'' | \mathbf{v}_p) d\mathbf{v}_p'' = 1$$

$$\mathcal{L}[p](\mathbf{x}, \mathbf{v}_p) = \mu(\mathbf{x}, \mathbf{v}_p) p(t, \mathbf{x}, \mathbf{v}_p)$$

Ensuring mass conservation

Integrate over the velocity space

$$\frac{\partial p}{\partial t}(t, \mathbf{x}, \mathbf{v}_p) + \mathbf{v} \cdot \nabla p(t, \mathbf{x}, \mathbf{v}_p) = \mathcal{J}[p](t, \mathbf{x}, \mathbf{v}_p)$$



Turning operator

T is independent from the pre-tumbling velocity

$$T = T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p)$$

$$\mathcal{G}[p](\mathbf{x}, \mathbf{v}_p) = \int_{V_p} \mu(\mathbf{x}, \mathbf{v}'_p) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p | \mathbf{v}'_p) p(t, \mathbf{x}, \mathbf{v}'_p) d\mathbf{v}'_p$$

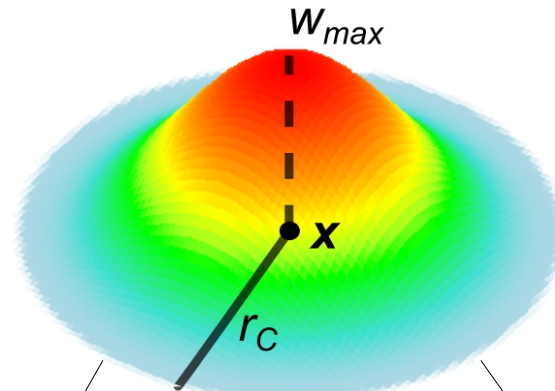
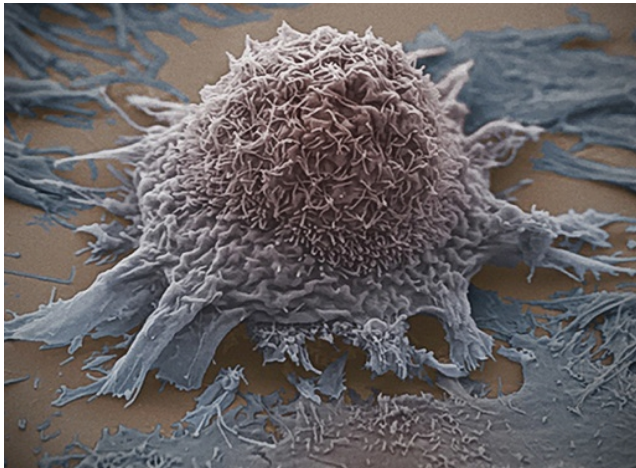
$$\mathcal{J}[p](\mathbf{x}, \mathbf{v}_p) = \int_{V_p} \mu(\mathbf{x}, \mathbf{v}'_p) p(t, \mathbf{x}, \mathbf{v}'_p) d\mathbf{v}'_p T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p) - \mu(\mathbf{x}, \mathbf{v}_p) p(t, \mathbf{x}, \mathbf{v}_p)$$

μ is independent from the pre-tumbling velocity

$$\mathcal{J}[p](t, \mathbf{x}, \mathbf{v}_p) = \mu(\mathbf{x}) \left(\rho(t, \mathbf{x}) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p) - p(t, \mathbf{x}, \mathbf{v}_p) \right)$$

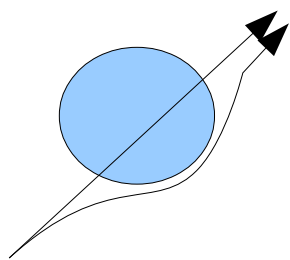
Nonlocal structure

$$\mathcal{J}[p](t, \mathbf{x}, \mathbf{v}_p) = \mu(\mathbf{x}) \left(\rho(t, \mathbf{x}) T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p) - p(t, \mathbf{x}, \mathbf{v}_p) \right)$$



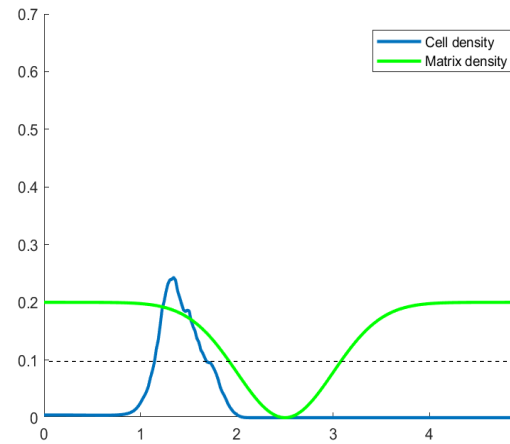
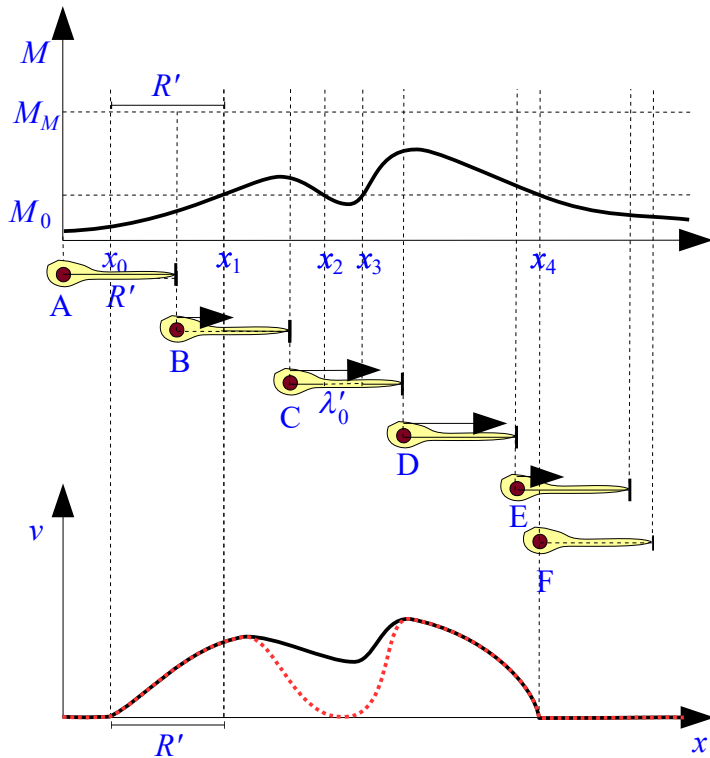
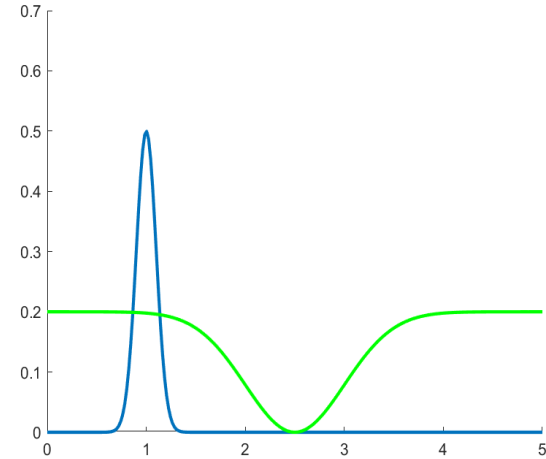
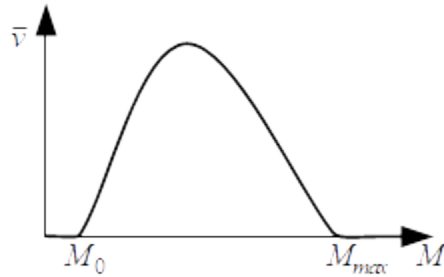
$$T[\mathcal{S}, \mathcal{S}'](\mathbf{x}, \mathbf{v}_p) = c(\mathbf{x}) \int_{\mathbb{R}_+} \gamma_{\mathcal{S}}(\lambda) \mathcal{T}_{\lambda}^{\hat{\mathbf{v}}}[\mathcal{S}](\mathbf{x}) d\lambda \int_{\mathbb{R}_+} \gamma_{\mathcal{S}'}(\lambda') \psi(\mathbf{x}, v | \mathcal{S}'(\mathbf{x} + \lambda' \hat{\mathbf{v}})) d\lambda'$$

$\downarrow$
 $b(\mathcal{S}(\mathbf{x} + \lambda \hat{\mathbf{v}}))$

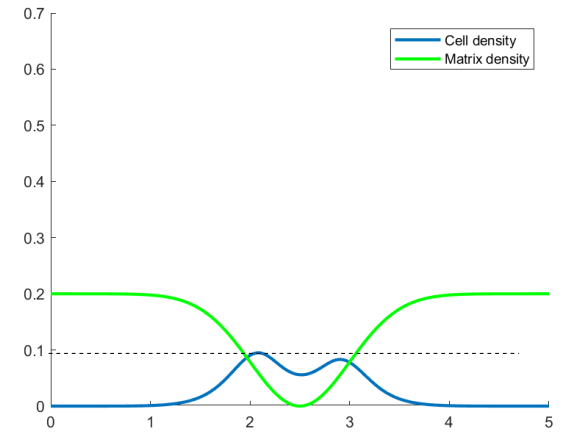




Poor ECM



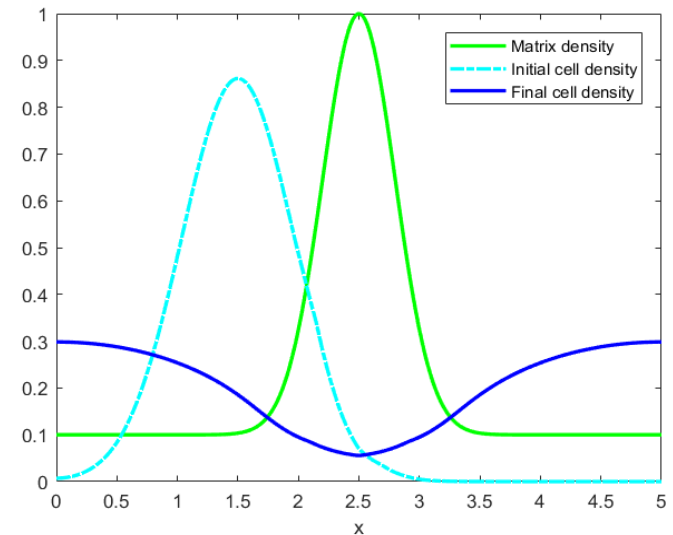
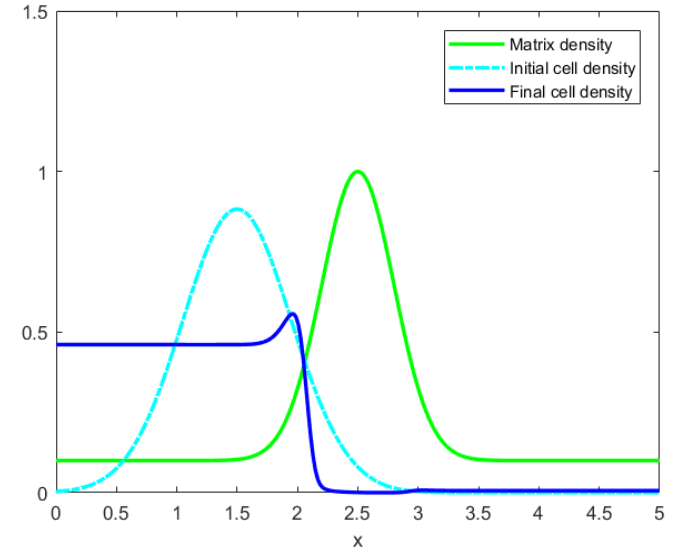
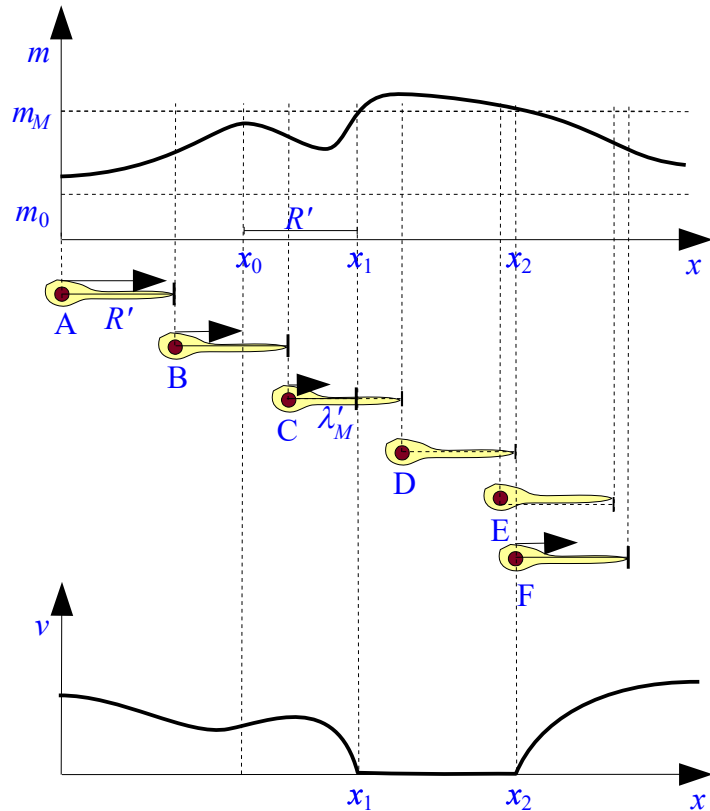
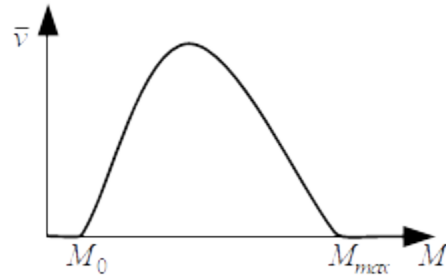
$$R_M^{max} = 0.2$$



$$R_M^{max} = 2$$

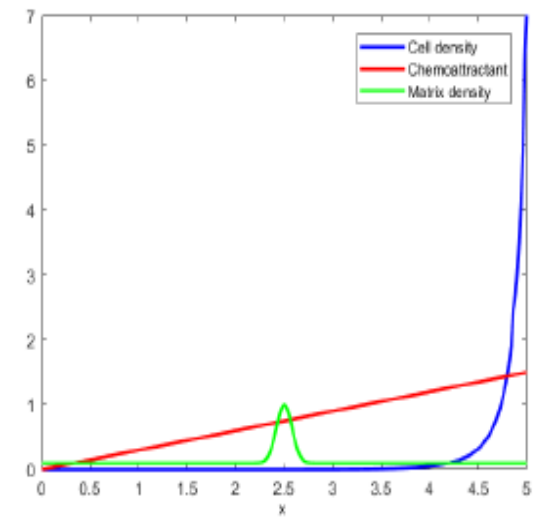
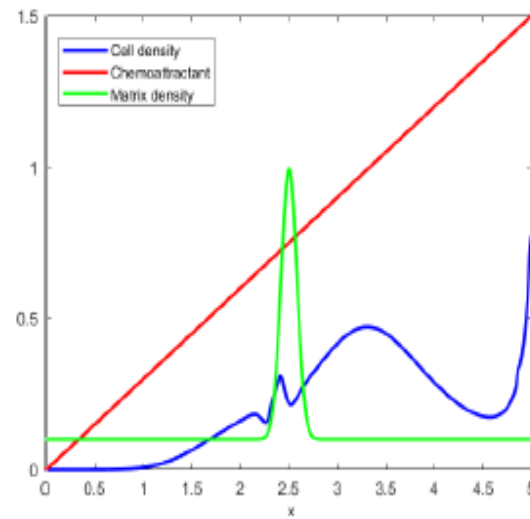
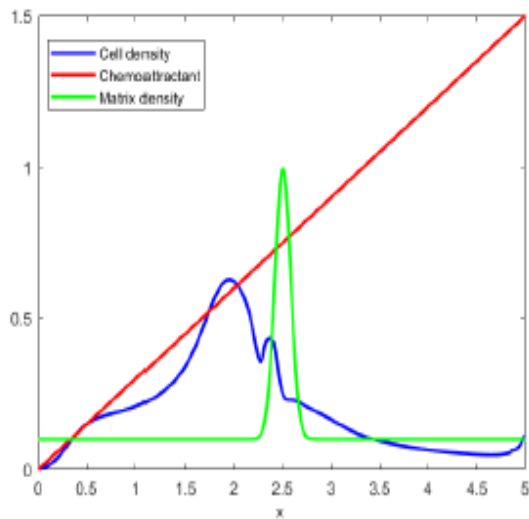
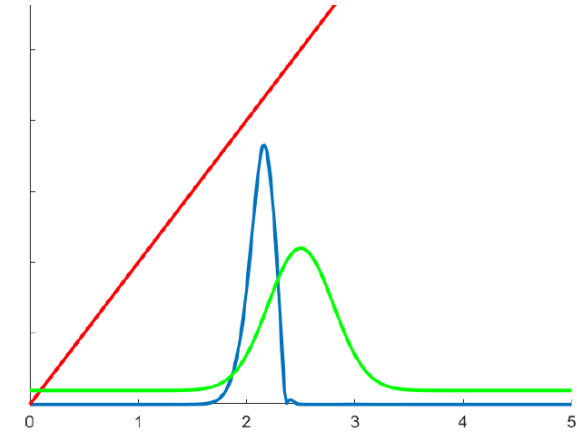
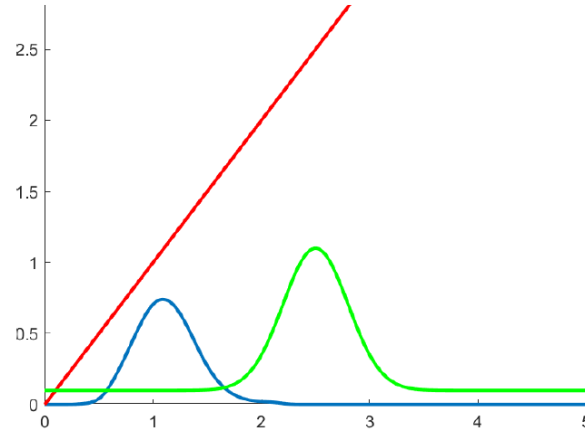
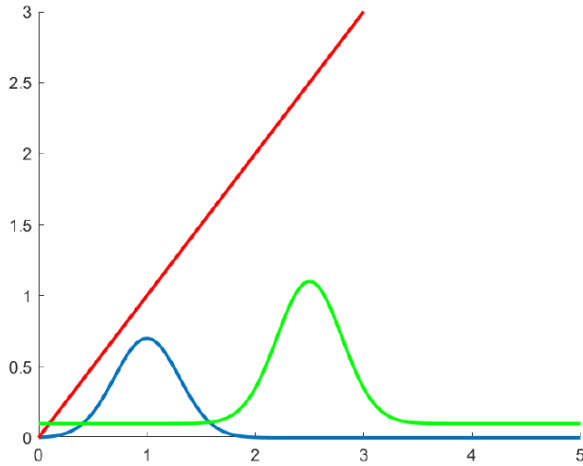


ECM barrier



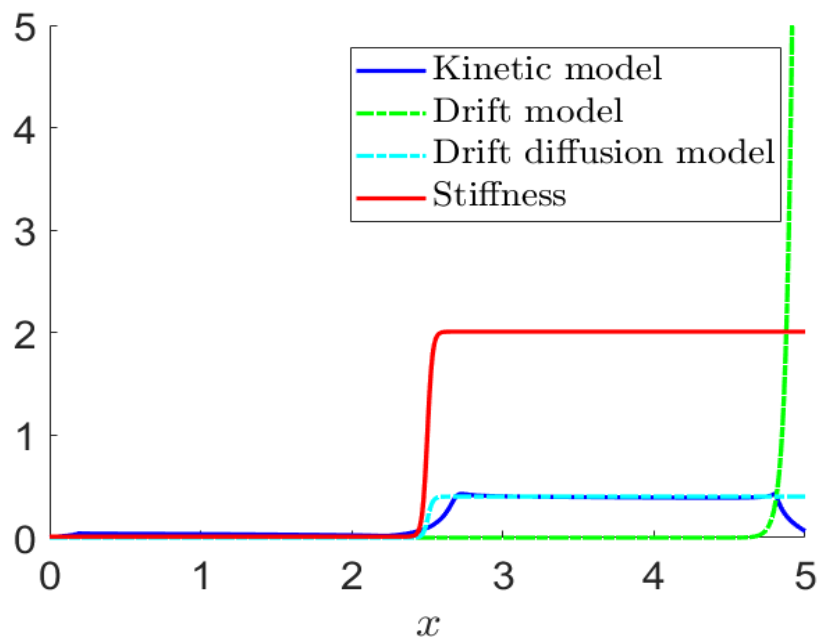
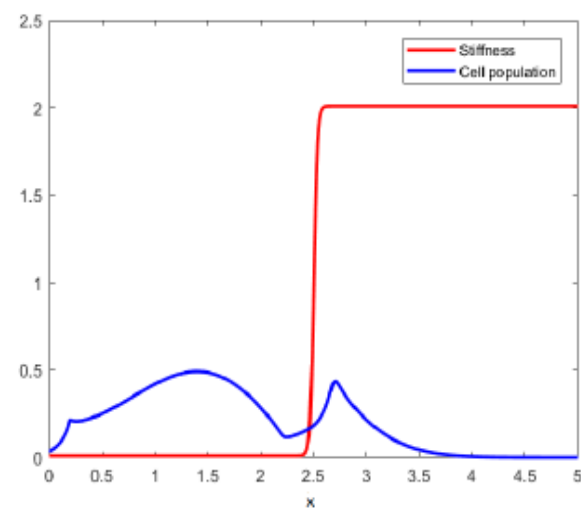
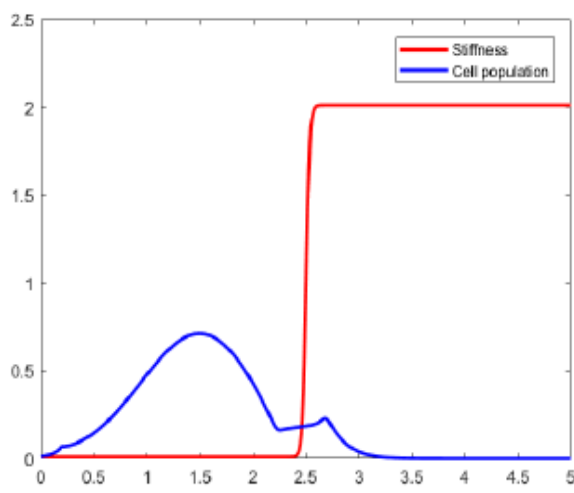
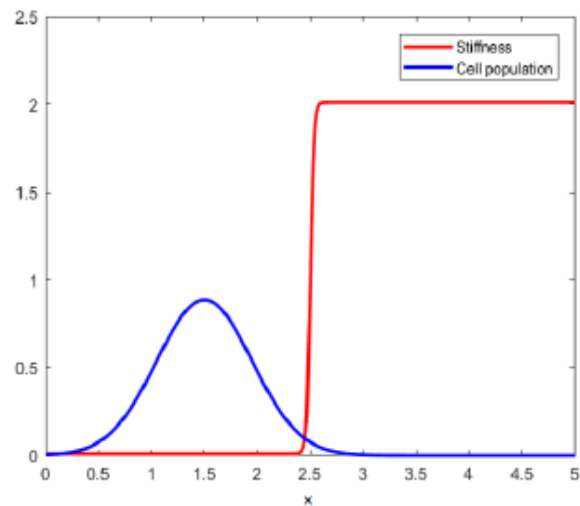


ECM barrier with chemotaxis





Durotaxis



Durotaxis

